

# MicroEJ Documentation



MicroEJ Corp.

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# CONTENTS

<b>1</b>	<b>MicroEJ Glossary</b>	<b>2</b>
<b>2</b>	<b>Overview</b>	<b>4</b>
2.1	MicroEJ Editions	4
2.1.1	Introduction	4
2.1.2	Determine the MicroEJ Studio/SDK Version	5
2.2	MicroEJ Runtime	7
2.2.1	Language	7
2.2.2	Scheduler	7
2.2.3	Garbage Collector	7
2.2.4	Foundation Libraries	7
2.3	MicroEJ Libraries	8
2.4	MicroEJ Central Repository	8
2.5	Embedded Specification Requests	9
2.6	MicroEJ Firmware	9
2.6.1	Bootable Binary with Core Services	9
2.6.2	Specification	10
2.7	Introducing MicroEJ SDK	10
2.8	Introducing MicroEJ Studio and Virtual Devices	11
2.9	Perform Online Getting Started	12
2.10	System Requirements	13
<b>3</b>	<b>Application Developer Guide</b>	<b>14</b>
3.1	Introduction	14
3.2	Licenses	14
3.2.1	Overview	14
3.2.2	Installation	15
3.2.3	Evaluation Licenses	15
3.2.4	Production Licenses	16
3.3	Local Workspaces and Repositories	19
3.4	Standalone Application	19
3.4.1	Download and Install a MicroEJ Platform	19
3.4.2	Build and Run an Application	22
3.4.3	MicroEJ Launch	27
3.4.4	Application Options	31
3.4.5	SOAR	56
3.5	Sandboxed Application	57
3.5.1	Sandboxed Application Structure	57
3.5.2	Application Publication	58
3.5.3	Shared Interfaces	58

3.6	Virtual Device	62
3.6.1	Using a Virtual Device for Simulation	62
3.6.2	Runtime Environment	62
3.7	MicroEJ Module Manager	63
3.7.1	Introduction	63
3.7.2	Specification	64
3.7.3	Module Project Skeleton	64
3.7.4	Module Description File	65
3.7.5	MicroEJ Module Manager Configuration	65
3.7.6	Build Kit	69
3.7.7	Former MicroEJ SDK Versions	69
3.8	Module Natures	71
3.8.1	Module Repository	71
3.9	MicroEJ Classpath	75
3.9.1	Application Classpath	75
3.9.2	Classpath Load Model	76
3.9.3	Classpath Elements	77
3.10	Development Tools	86
3.10.1	Testsuite with JUnit	87
3.10.2	Font Designer	89
3.10.3	Stack Trace Reader	97
3.10.4	Code Coverage Analyzer	104
3.10.5	Heap Dumper & Heap Analyzer	107
3.10.6	ELF to Map File Generator	118
3.10.7	Serial to Socket Transmitter	120
3.10.8	Memory Map Analyzer	122
3.10.9	Event Tracing	124
3.11	Advanced Tools	126
3.11.1	MicroEJ Linker	126
3.11.2	Testsuite Engine	139
<b>4</b>	<b>Platform Developer Guide</b>	<b>143</b>
4.1	Introduction	143
4.1.1	Scope	143
4.1.2	Intended Audience	143
4.1.3	MicroEJ Architecture Modules Overview	143
4.2	MicroEJ Platform	145
4.2.1	Process Overview	145
4.2.2	Concepts	146
4.2.3	New MicroEJ Platform Creation	151
4.3	MicroEJ Core Engine	161
4.3.1	Functional Description	161
4.3.2	Architecture	162
4.3.3	Capabilities	163
4.3.4	Implementation	163
4.3.5	Generic Output	166
4.3.6	Link	166
4.3.7	Dependencies	166
4.3.8	Installation	166
4.3.9	Use	167
4.4	Multi-Sandbox	167
4.4.1	Principle	167
4.4.2	Functional Description	167
4.4.3	Firmware Linker	168

4.4.4	Memory Considerations	169
4.4.5	Dependencies	169
4.4.6	Installation	169
4.4.7	Use	169
4.5	Tiny application	169
4.5.1	Principle	169
4.5.2	Installation	169
4.5.3	Limitations	170
4.6	Native Interface Mechanisms	170
4.6.1	Simple Native Interface (SNI)	170
4.6.2	Shielded Plug (SP)	173
4.6.3	MicroEJ Java H	177
4.7	External Resources Loader	178
4.7.1	Principle	178
4.7.2	Functional Description	178
4.7.3	Implementations	178
4.7.4	External Resources Folder	179
4.7.5	Dependencies	179
4.7.6	Installation	179
4.7.7	Use	180
4.8	Serial Communications	180
4.8.1	ECOM	180
4.8.2	ECOM Comm	182
4.9	Graphics User Interface	189
4.9.1	Principle	189
4.9.2	MicroUI	191
4.9.3	Static Initialization	194
4.9.4	LEDs	197
4.9.5	Inputs	198
4.9.6	Display	201
4.9.7	Images	216
4.9.8	Fonts	227
4.9.9	Simulation	234
4.10	Networking	237
4.10.1	Principle	237
4.10.2	Network Core Engine	237
4.10.3	SSL	239
4.11	File System	239
4.11.1	Principle	239
4.11.2	Functional Description	239
4.11.3	Dependencies	240
4.11.4	Installation	240
4.11.5	Use	240
4.12	Hardware Abstraction Layer	240
4.12.1	Principle	240
4.12.2	Functional Description	240
4.12.3	Identifier	241
4.12.4	Configuration	242
4.12.5	Dependencies	242
4.12.6	Installation	242
4.12.7	Use	242
4.13	Device Information	242
4.13.1	Principle	242
4.13.2	Dependencies	242



4.13.3	Installation	242
4.13.4	Use	243
4.14	Simulation	243
4.14.1	Principle	243
4.14.2	Functional Description	243
4.14.3	Dependencies	244
4.14.4	Installation	245
4.14.5	Use	245
4.14.6	Mock	245
4.14.7	Shielded Plug Mock	249
4.14.8	Front Panel Mock	250
4.14.9	Bluetooth LE Mock	258
4.15	Limitations	264
4.16	Appendices	264
4.16.1	Appendix A: Low Level API	264
4.16.2	Appendix B: MicroEJ Foundation Libraries	275
4.16.3	Appendix C: Tools Options and Error Codes	286
4.16.4	Appendix D: Architectures MCU / Compiler	304
<b>5</b>	<b>Kernel Developer Guide</b>	<b>308</b>
5.1	Overview	308
5.1.1	Introduction	308
5.1.2	Terms and Definitions	308
5.1.3	Overall Architecture	309
5.1.4	Firmware Build Flow	313
5.1.5	Virtual Device Build Flow	314
5.2	Kernel & Features Specification	314
5.3	Getting Started	315
5.3.1	Online Getting Started	315
5.3.2	Create an Empty Firmware from Scratch	315
5.3.3	MicroEJ Demo VEE Flavors	318
5.4	Build Firmware	319
5.4.1	Workspace Build	321
5.4.2	Headless Build	323
5.4.3	Runtime Environment	324
5.4.4	Resident Applications	324
5.4.5	Advanced	325
5.5	Writing Kernel APIs	327
5.5.1	Default Kernel APIs Derivation	327
5.5.2	Build a Kernel API Module	328
5.5.3	Kernel API Generator	328
5.6	Communication between Features	330
5.6.1	Kernel Type Converters	330
5.7	API Documentation	330
5.8	Multi-Sandbox Enabled Libraries	330
5.8.1	MicroUI	330
5.8.2	ECOM	331
5.8.3	ECOM-COMM	331
5.8.4	FS	331
5.8.5	NET	331
5.8.6	SSL	331
5.9	Setup a KF Testsuite	331
5.9.1	Enable the Testsuite	331
5.9.2	Add a KF Test	332

5.9.3	KF Testsuite Options	334
<b>6</b>	<b>Tutorials</b>	<b>335</b>
6.1	Understand How to Build a MicroEJ Firmware and its Dependencies	335
6.1.1	The Components	335
6.1.2	How to Build	338
6.1.3	Get Support	340
6.2	Create a MicroEJ Platform for a Custom Device	340
6.2.1	Introduction	340
6.2.2	A MicroEJ Platform Project is already available for the same MCU/RTOS/C Compiler	341
6.2.3	A MicroEJ Platform Project is not available for the same MCU/RTOS/C Compiler	342
6.2.4	Platform Validation	343
6.2.5	Further Assistance Needed	343
6.3	Create a MicroEJ Firmware From Scratch	343
6.3.1	Intended Audience	343
6.3.2	Introduction	343
6.3.3	Prerequisites	344
6.3.4	Overview	344
6.3.5	Setup the Development Environment	345
6.3.6	Get Running BSP	345
6.3.7	FreeRTOS Hello World	347
6.3.8	Create a MicroEJ Platform	349
6.3.9	Create MicroEJ Application HelloWorld	353
6.3.10	Configure BSP Connection in MicroEJ Application	356
6.3.11	MicroEJ and FreeRTOS Integration	358
6.4	Setup an Automated Build using Jenkins and Artifactory	369
6.4.1	Intended Audience	369
6.4.2	Introduction	369
6.4.3	Prerequisites	370
6.4.4	Overview	370
6.4.5	Install the Build Tools	371
6.4.6	Get a Module Repository	371
6.4.7	Setup Artifactory	372
6.4.8	Setup Jenkins	375
6.4.9	Build a new Module using Jenkins	377
6.4.10	Appendix	380
	<b>Index</b>	<b>382</b>

Welcome to MicroEJ developer documentation. Browse the following chapters to familiarize yourself with MicroEJ Technology and understand the principles of app and platform development with MicroEJ.

- The [Glossary](#) chapter describes MicroEJ terminology.
- The [Overview](#) chapter introduces MicroEJ products and technology.
- The [Application Developer Guide](#) presents Java applications development and debugging tools.
- The [Platform Developer Guide](#) teaches you how to integrate a C Board Support as well as simulation configurations.
- The [Kernel Developer Guide](#) introduces you to advanced concepts, such as partial updates and dynamic app life cycle workflows.
- The [Tutorials](#) chapter covers a variety of topics related to developing with the MicroEJ ecosystem.

## MICROEJ GLOSSARY

This glossary defines the technical terms upon which the **MicroEJ Virtual Execution Environment** is built.

**Add-On Library** A MicroEJ Add-On Library is a pure **managed code** (Java) library. It runs over one or more MicroEJ Foundation Libraries.

**Application** A MicroEJ Application is a software program that runs on a Powered by MicroEJ device.

**Standalone Application** MicroEJ Standalone Application is a MicroEJ Application that is directly linked to the C code to produce a MicroEJ Firmware. It is edited using MicroEJ SDK.

**Sandboxed Application** A MicroEJ Sandboxed Application is a MicroEJ Application that can run over a MicroEJ Multi-Sandbox Firmware. It can be linked either statically or dynamically.

**System Application** A MicroEJ System Application is a MicroEJ Sandboxed Application that is statically linked to the MicroEJ Firmware, as it is part of the initial image and cannot be removed.

**Kernel Application** A MicroEJ Kernel Application is a MicroEJ Standalone Application that implements the ability to be extended to produce a MicroEJ Multi-Sandbox Firmware.

**Architecture** A MicroEJ Architecture is a software package that includes the MicroEJ Core Engine port to a target instruction set and a C compiler, core MicroEJ Foundation Libraries (EDC, **[BON]**, **[SNI]**, **[KF]**) and the MicroEJ Simulator. MicroEJ Architectures are distributed either as evaluation or production version.

**Core Engine** MicroEJ Core Engine is a scalable runtime for resource-constrained embedded devices running on 32-bit microcontrollers or microprocessors. MicroEJ Core Engine allows devices to run multiple and mixed Java and C software applications.

**Firmware** A MicroEJ Firmware is the result of the binary link of a MicroEJ Standalone Application with a MicroEJ Platform. The firmware is a binary program that can be programmed into the flash memory of a device.

**Mono-Sandbox Firmware** A MicroEJ Mono-Sandbox Firmware is a MicroEJ Firmware that implements an unmodifiable set of functions. (previously MicroEJ Single-app Firmware)

**Multi-Sandbox Firmware** A MicroEJ Multi-Sandbox Firmware is a MicroEJ Firmware that implements the ability to be extended, by exposing a set of APIs and a memory space to link MicroEJ Sandboxed Applications. (previously MicroEJ Multi-app Firmware)

**Foundation Library** A MicroEJ Foundation Library is a library that provides core or hardware-dependent functionalities. A Foundation Library combines **managed code** (Java) and low-level APIs (C) implemented by one or more Abstraction Layers through a native interface (**SNI**).

**Mock** A MicroEJ Mock is a mockup of a Board Support Package capability that mimics an hardware functionality for the MicroEJ Simulator.

**Module Manager** MicroEJ Module Manager downloads, installs and controls the consistency of all the dependencies and versions required to build and publish a MicroEJ asset. It is based on **Semantic Versioning** specification.

**Platform** A MicroEJ Platform integrates a MicroEJ Architecture, one or more Foundation Libraries with their respective Abstraction Layers and the board support package (BSP) for the target Device. It also includes associated MicroEJ Mocks for the MicroEJ Simulator.

**SDK** MicroEJ SDK allows MicroEJ Firmware developers to build a MicroEJ-ready device, by integrating a MicroEJ Architecture with both Java and C software on their device.

**Simulator** MicroEJ Simulator allows running MicroEJ Applications on a target hardware simulator on the developer's desktop computer. The MicroEJ Simulator runs one or more MicroEJ mock that mimics the hardware functionality. It enables developers to develop their MicroEJ Applications without the need of hardware.

**Studio** MicroEJ Studio allows application developers to write a MicroEJ Sandboxed Application, run it on a Virtual Device, deploy it on a MicroEJ-ready device, and publish it to a [MicroEJ Forge](#) instance.

**Virtual Device** A MicroEJ Virtual Device is a software package that includes the simulation part of a MicroEJ Firmware: runtime, libraries and application(s). It can be run on any PC without the need of MicroEJ Studio. In case a MicroEJ Multi-Sandbox Firmware, it is also used for testing a MicroEJ Sandboxed Application in MicroEJ Studio.

## OVERVIEW

## 2.1 MicroEJ Editions

### 2.1.1 Introduction

MicroEJ offers a comprehensive toolset to build the embedded software of a device. The toolset covers two levels in device software development:

- MicroEJ SDK for device firmware development
- MicroEJ Studio for application development

The firmware will generally be produced by the device OEM, it includes all device drivers and a specific set of MicroEJ functionalities useful for application developers targeting this device.

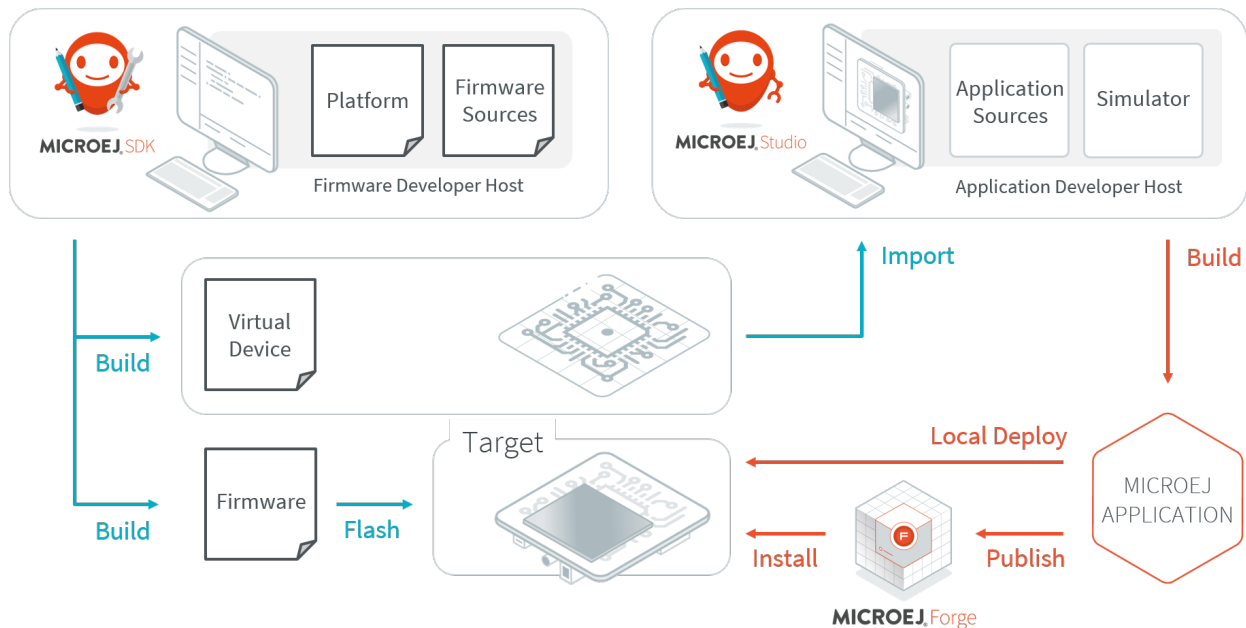


Fig. 1: MicroEJ Development Tools Overview

Using the MicroEJ SDK tool, a firmware developer will produce two versions of the MicroEJ binary, each one able to run applications created with the MicroEJ Studio tool:

- A MicroEJ Firmware binary to be flashed on OEM devices;

- A Virtual Device which will be used as a device simulator by application developers.

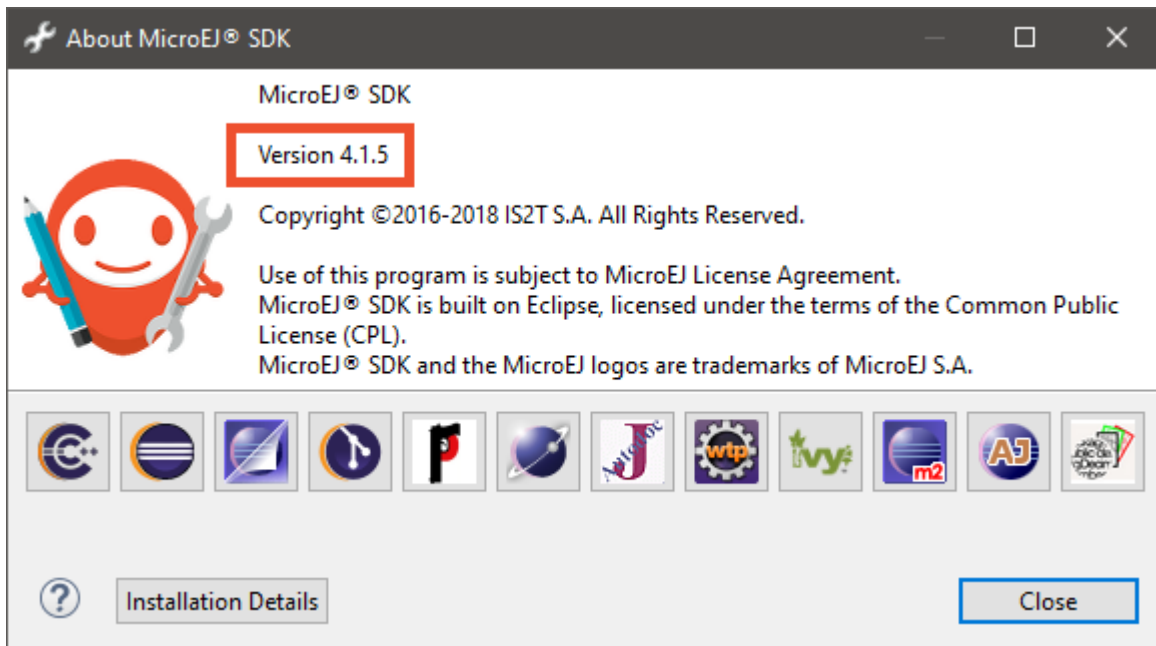
Using the MicroEJ Studio tool, an application developer will be able to:

- Import Virtual Devices matching his target hardware in order to develop and test applications on the Simulator;
- Deploy the application locally on an hardware device equipped with the MicroEJ Firmware;
- Package and publish the application on a MicroEJ Forge Instance, enabling remote end users to install it on their devices. For more information about MicroEJ Forge, please consult <https://www.microej.com/product/forge>.

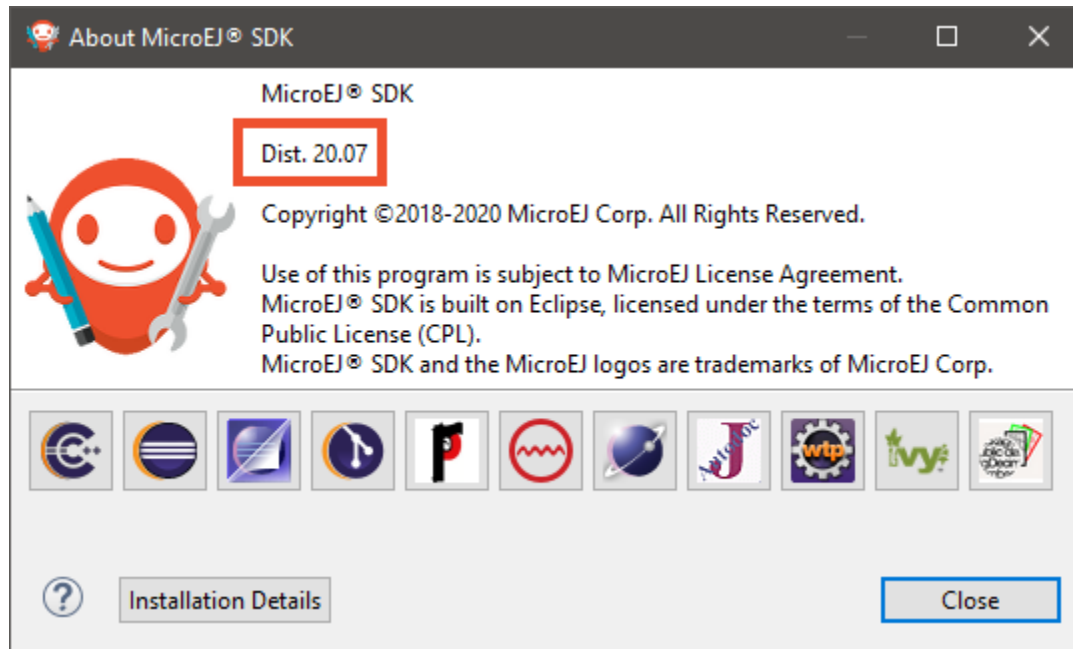
### 2.1.2 Determine the MicroEJ Studio/SDK Version

In MicroEJ Studio/SDK, go to **Help > About MicroEJ SDK** menu.

In case of MicroEJ SDK 4.1.x, the MicroEJ SDK version is directly displayed, such as 4.1.5 :

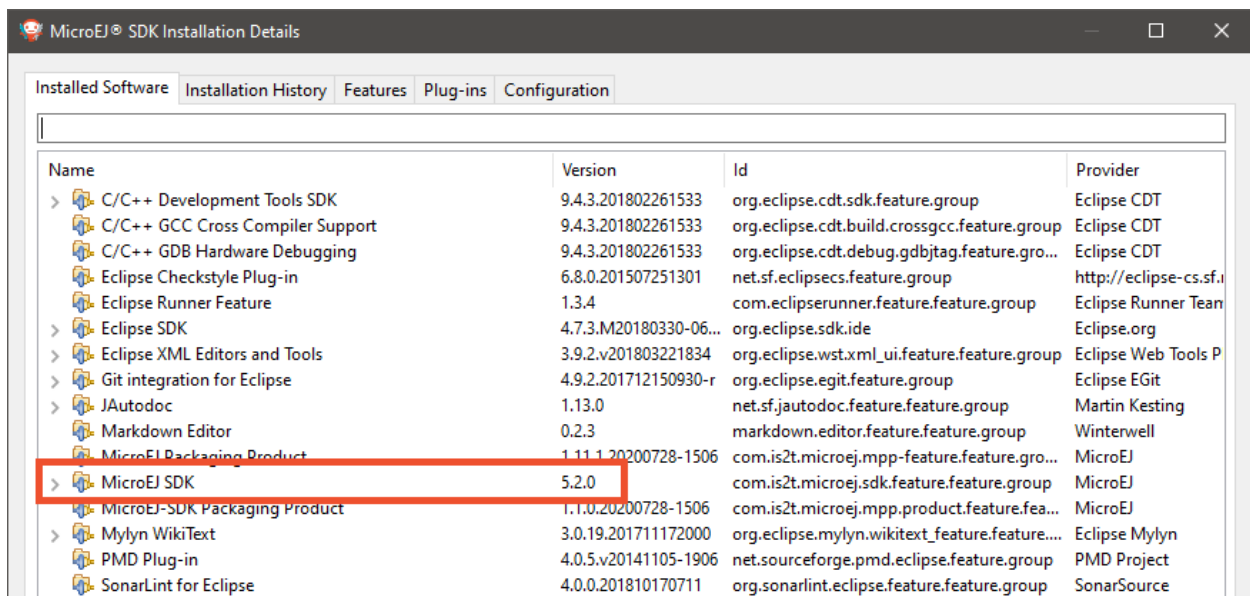


In case of MicroEJ SDK 5.x, the value displayed is the MicroEJ SDK distribution, such as 19.05 or 20.07 :



To retrieve the MicroEJ SDK version that is currently installed in this distribution, proceed with the following steps:

- Click on the **Installation Details** button,
- Click on the **Installed Software** tab,
- Retrieve the version of entry named **MicroEJ SDK** (or **MicroEJ Studio**).





## 2.2 MicroEJ Runtime

### 2.2.1 Language

MicroEJ is compatible with the Java language version 7.

Java source code is compiled by the Java compiler<sup>1</sup> into the binary format specified in the JVM specification<sup>2</sup>. This binary code needs to be linked before execution: .class files and some other application-related files (see *MicroEJ Classpath*) are compiled to produce the final application that the MicroEJ Runtime can execute.

MicroEJ complies with the deterministic class initialization (<clinit>) order specified in *[BON]*. The application is statically analyzed from its entry points in order to generate a clinit dependency graph. The computed clinit sequence is the result of the topological sort of the dependency graph. An error is thrown if the clinit dependency graph contains cycles.

### 2.2.2 Scheduler

The MicroEJ Architecture features a green thread platform that can interact with the C world *[SNI]*. The (green) thread policy is as follows:

- preemptive for different priorities,
- round-robin for same priorities,
- “priority inheritance protocol” when priority inversion occurs.<sup>3</sup>

MicroEJ stacks (associated with the threads) automatically adapt their sizes according to the thread requirements: Once the thread has finished, its associated stack is reclaimed, freeing the corresponding RAM memory.

### 2.2.3 Garbage Collector

The MicroEJ Architecture includes a state-of-the-art memory management system, the Garbage Collector (GC). It manages a bounded piece of RAM memory, devoted to the Java world. The GC automatically frees dead Java objects, and defragments the memory in order to optimize RAM usage. This is done transparently while the MicroEJ Applications keep running.

### 2.2.4 Foundation Libraries

#### Embedded Device Configuration (EDC)

The Embedded Device Configuration specification defines the minimal standard runtime environment for embedded devices. It defines all default API packages:

- java.io
- java.lang
- java.lang.annotation
- java.lang.ref
- java.lang.reflect

---

<sup>1</sup> The JDT compiler from the Eclipse IDE.

<sup>2</sup> Tim Lindholm & Frank Yellin, The Java™ Virtual Machine Specification, Second Edition, 1999

<sup>3</sup> This protocol raises the priority of a thread (that is holding a resource needed by a higher priority task) to the priority of that task.

- java.util

### Beyond Profile (BON)

[BON] defines a suitable and flexible way to fully control both memory usage and start-up sequences on devices with limited memory resources. It does so within the boundaries of Java semantics. More precisely, it allows:

- Controlling the initialization sequence in a deterministic way.
- Defining persistent, immutable, read-only objects (that may be placed into non-volatile memory areas), and which do not require copies to be made in RAM to be manipulated.
- Defining immortal, read-write objects that are always alive.
- Defining and accessing compile-time constants.

## 2.3 MicroEJ Libraries

A MicroEJ Foundation Library is a MicroEJ Core library that provides core runtime APIs or hardware-dependent functionality. A Foundation library is divided into an API and an implementation. A Foundation library API is composed of a name and a 2 digits version (e.g. `EDC-1.3`) and follows the semantic versioning (<http://semver.org>) specification. A Foundation Library API only contains prototypes without code. Foundation Library implementations are provided by MicroEJ Platforms. From a MicroEJ Classpath, Foundation Library APIs dependencies are automatically mapped to the associated implementations provided by the Platform or the Virtual Device on which the application is being executed.

A MicroEJ Add-On Library is a MicroEJ library that is implemented on top of MicroEJ Foundation Libraries (100% full Java code). A MicroEJ Add-On Library is distributed in a single JAR file, with a 3 digits version and provides its associated source code.

Foundation and Add-On Libraries are added to MicroEJ Classpath by the application developer as module dependencies (see *MicroEJ Module Manager*).

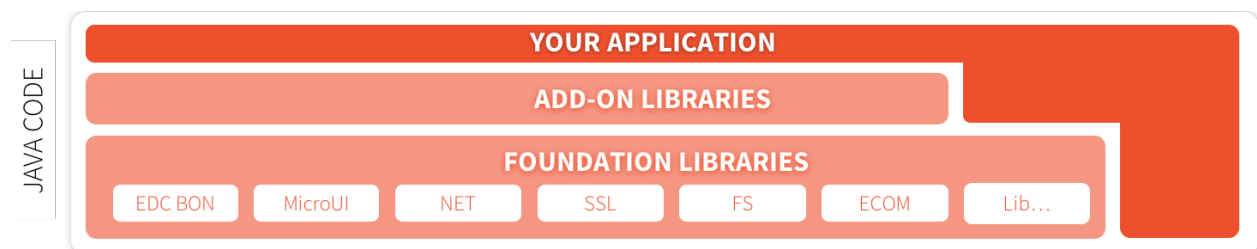


Fig. 2: MicroEJ Foundation Libraries and Add-On Libraries

MicroEJ Corp. provides a large number of libraries through the *MicroEJ Central Repository*. To consult its libraries APIs documentation, please visit <https://developer.microej.com/microej-apis/>.

## 2.4 MicroEJ Central Repository

The MicroEJ Central Repository is the binary repository maintained by MicroEJ Corp. It contains Foundation Library APIs and numerous Add-On Libraries. Foundation Libraries APIs are distributed under the organization `ej.api` and `com.microej.api`. All other artifacts are Add-On Libraries.

By default, MicroEJ SDK is configured to connect online MicroEJ Central Repository. The MicroEJ Central Repository can be downloaded locally for offline use. Please follow the steps described at <https://developer.microej.com/central-repository/>.

To consult its *libraries* APIs documentation, please visit <https://developer.microej.com/microej-apis/>.

## 2.5 Embedded Specification Requests

MicroEJ implements the following **ESR Consortium** specifications:

[BON]	<a href="http://e-s-r.net/download/specification/ESR-SPE-0001-BON-1.2-F.pdf">http://e-s-r.net/download/specification/ESR-SPE-0001-BON-1.2-F.pdf</a>
[SNI]	<a href="http://e-s-r.net/download/specification/ESR-SPE-0012-SNI_GT-1.2-H.pdf">http://e-s-r.net/download/specification/ESR-SPE-0012-SNI_GT-1.2-H.pdf</a>
[SP]	<a href="http://e-s-r.net/download/specification/ESR-SPE-0014-SP-2.0-A.pdf">http://e-s-r.net/download/specification/ESR-SPE-0014-SP-2.0-A.pdf</a>
[MUI]	<a href="http://e-s-r.net/download/specification/ESR-SPE-0002-MICROUI-2.0-B.pdf">http://e-s-r.net/download/specification/ESR-SPE-0002-MICROUI-2.0-B.pdf</a>
[KF]	<a href="http://e-s-r.net/download/specification/ESR-SPE-0020-KF-1.4-F.pdf">http://e-s-r.net/download/specification/ESR-SPE-0020-KF-1.4-F.pdf</a>

## 2.6 MicroEJ Firmware

### 2.6.1 Bootable Binary with Core Services

A MicroEJ Firmware is a binary software program that can be programmed into the flash memory of a device. A MicroEJ Firmware includes an instance of a MicroEJ runtime linked to:

- underlying native libraries and BSP + RTOS,
- MicroEJ libraries and application code (C and Java code).

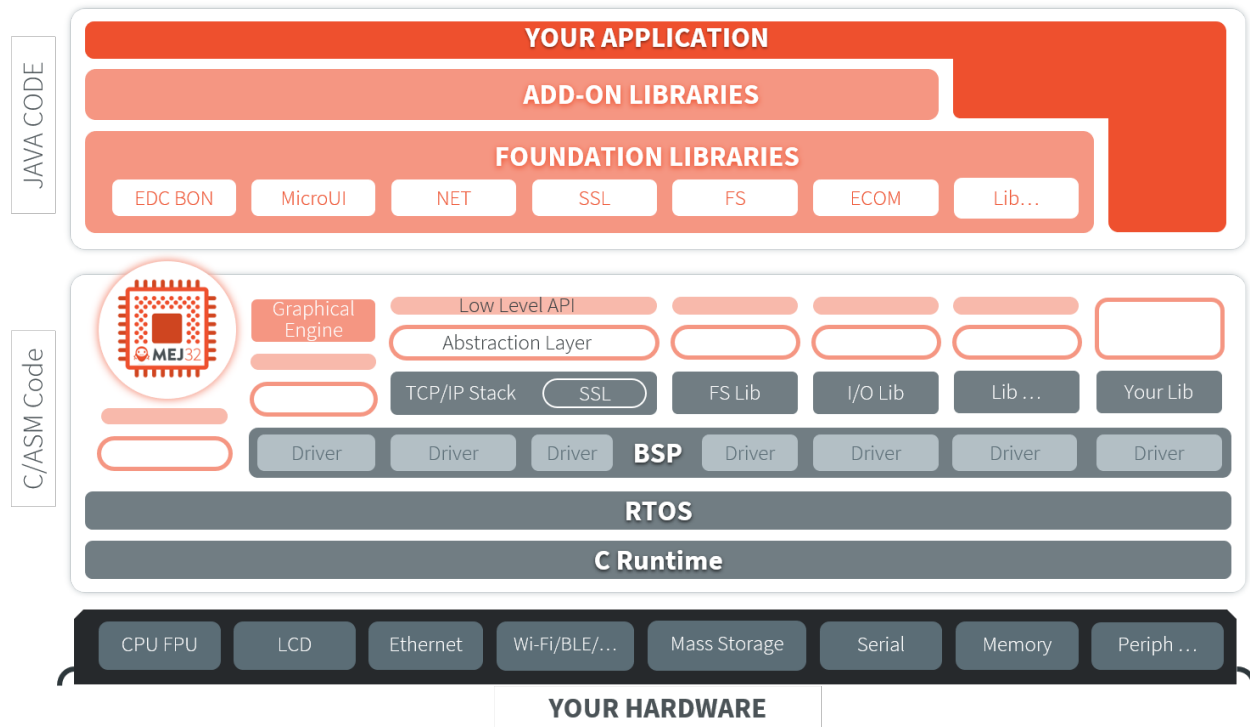


Fig. 3: MicroEJ Firmware Architecture

## 2.6.2 Specification

The set of libraries included in the firmware and its dimensioning limitations (maximum number of simultaneous threads, open connections, ...) are firmware specific. Please refer to <https://developer.microej.com/5/getting-started-studio.html> for evaluation firmware release notes.

## 2.7 Introducing MicroEJ SDK

MicroEJ SDK provides tools based on Eclipse to develop software applications for MicroEJ-ready devices. MicroEJ SDK allows application developers to write MicroEJ Applications and run them on a virtual (simulated) or real device.

This document is a step-by-step introduction to application development with MicroEJ SDK. The purpose of MicroEJ SDK is to develop for targeted MCU/MPU computers (IoT, wearable, etc.) and it is therefore a cross-development tool.

Unlike standard low-level cross-development tools, MicroEJ SDK offers unique services like hardware simulation and local deployment to the target hardware.

Application development is based on the following elements:

- MicroEJ SDK, the integrated development environment for writing applications. It is based on Eclipse and relies on the integrated Java compiler (JDT). It also provides a dependency manager for managing MicroEJ Libraries (see *MicroEJ Module Manager*). The current distribution of MicroEJ SDK ( 19.05 ) is built on top of Eclipse Oxygen (<https://www.eclipse.org/oxygen/>).
- MicroEJ Platform, a software package including the resources and tools required for building and testing an application for a specific MicroEJ-ready device. MicroEJ Platforms are imported into MicroEJ SDK within a

local folder called MicroEJ Platforms repository. Once a MicroEJ Platform is imported, an application can be launched and tested on Simulator. It also provides a means to locally deploy the application on a MicroEJ-ready device.

- MicroEJ-ready device, an hardware device that will be programmed with a MicroEJ Firmware. A MicroEJ Firmware is a binary instance of MicroEJ runtime for a target hardware board.

Starting from scratch, the steps to go through the whole process are detailed in the following sections of this chapter :

- Download and install a MicroEJ Platform
- Build and run your first application on Simulator
- Build and run your first application on target hardware

## 2.8 Introducing MicroEJ Studio and Virtual Devices

MicroEJ Studio provides tools based on Eclipse to develop software applications for MicroEJ-ready devices. MicroEJ Studio allows application developers to write MicroEJ Applications, run them on a virtual (simulated) or real device, and publish them to a MicroEJ Forge instance.

This document is an introduction to application development with MicroEJ Studio. The purpose of MicroEJ Studio is to develop for targeted MCU/MPU computers (IoT, wearable, etc.) and it is therefore a cross-development tool.

Unlike standard low-level cross-development tools, MicroEJ Studio offers unique services like hardware simulation, deployment to the target hardware and final publication to a MicroEJ Forge instance.

Application development is based on the following elements:

- MicroEJ Studio, the integrated development environment for writing applications. It is based on Eclipse and relies on the integrated Java compiler (JDT). It also provides a dependency manager for managing MicroEJ Libraries (see *MicroEJ Module Manager*). The current distribution of MicroEJ Studio ( 19.05 ) is built on top of Eclipse Oxygen (<https://www.eclipse.org/oxygen/>).
- MicroEJ Virtual Device, a software package including the resources and tools required for building and testing an application for a specific MicroEJ-ready device. A Virtual Device will simulate all capabilities of the corresponding hardware board:
  - Computation and Memory,
  - Communication channels (e.g. Network, USB ...),
  - Display,
  - User interaction.

Virtual Devices are imported into MicroEJ Studio within a local folder called MicroEJ Repository. Once a Virtual Device is imported, an application can be launched and tested on Simulator. It also provides a mean to locally deploy the application on a MicroEJ-ready device.

- MicroEJ-ready device, a hardware device that has been previously programmed with a MicroEJ Firmware. A MicroEJ Firmware is a binary instance of MicroEJ runtime for a target hardware board. MicroEJ-ready devices are built using MicroEJ SDK. MicroEJ Virtual Devices and MicroEJ Firmwares share the same version (there is a 1:1 mapping).

The following figure gives an overview of MicroEJ Studio possibilities:

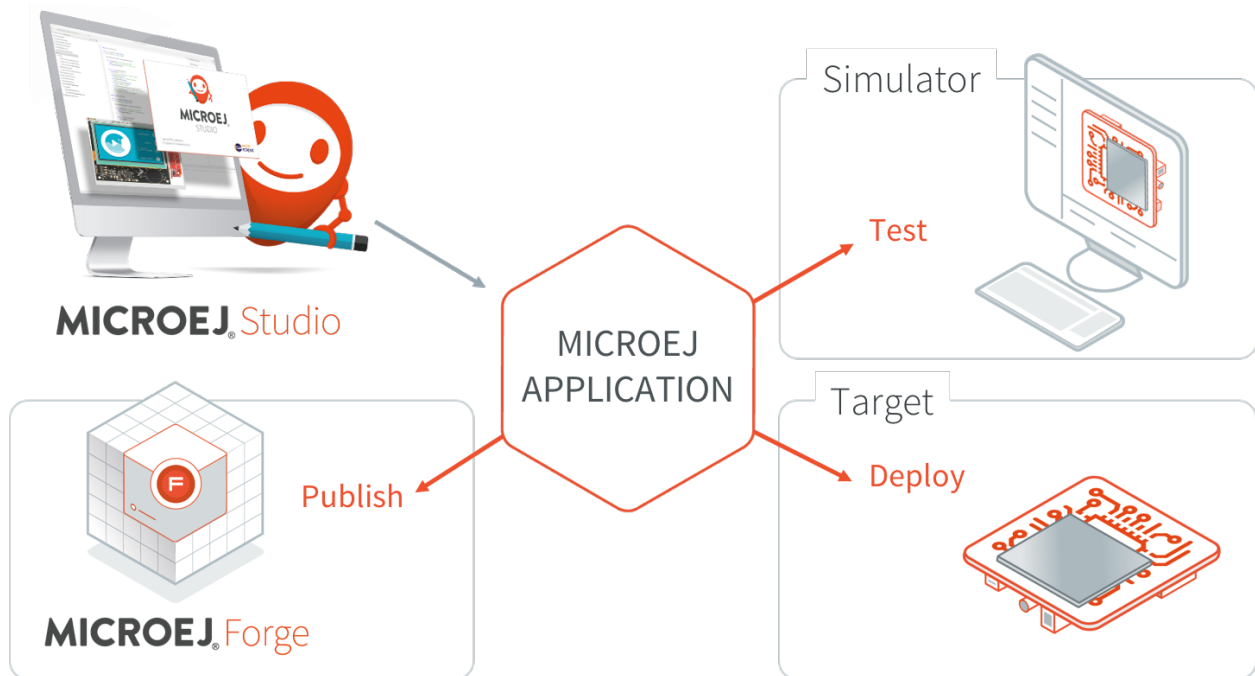


Fig. 4: MicroEJ Application Development Overview

## 2.9 Perform Online Getting Started

MicroEJ Studio Getting Started is available on <https://developer.microej.com/5/getting-started-studio.html>.

Starting from scratch, the steps to go through the whole process are:

1. Setup a board and test a MicroEJ Firmware:
  - Select between one of the available boards;
  - Download and install a MicroEJ Firmware on the target hardware;
  - Deploy and run a MicroEJ demo on board.
2. Setup and learn to use development tools:
  - Download and install MicroEJ Studio;
  - Download and install the corresponding Virtual Device for the target hardware;
  - Download, build and run your first application on Simulator;
  - Build and run your first application on target hardware.

The following figure gives an overview of the MicroEJ software components required for both host computer and target hardware:

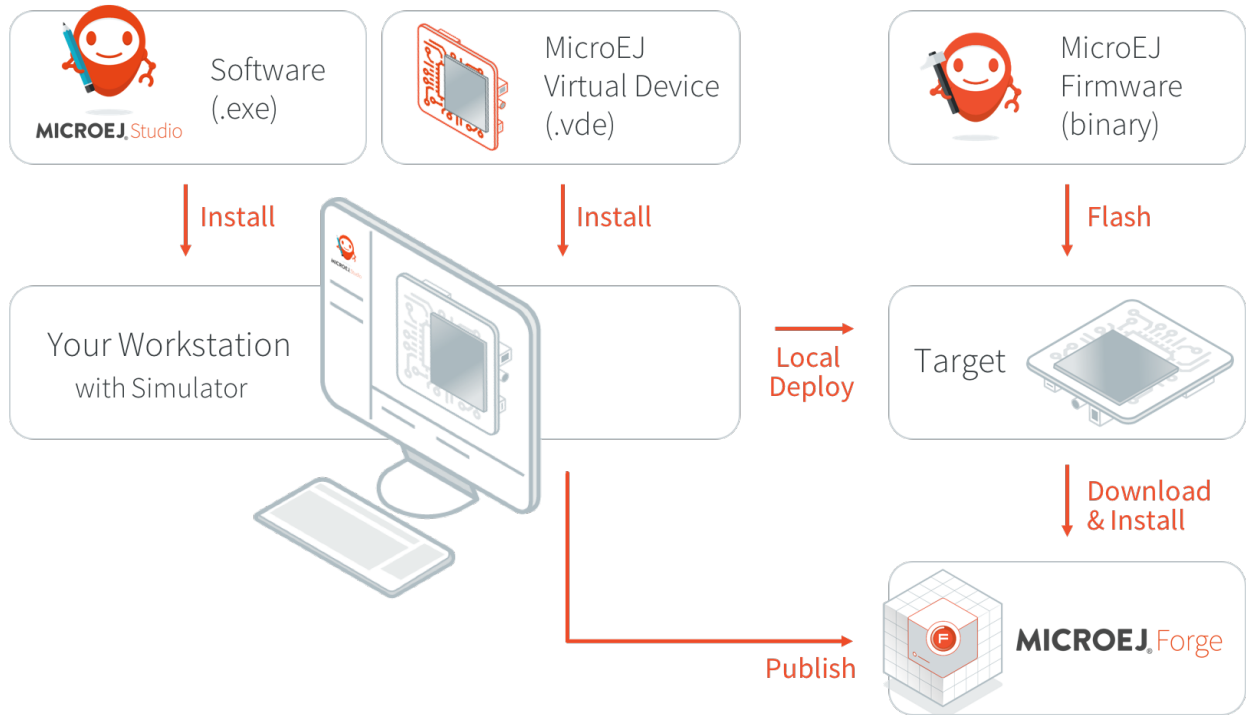


Fig. 5: MicroEJ Studio Development Imported Elements

## 2.10 System Requirements

### MicroEJ SDK and MicroEJ Studio

- **Intel x64 PC with minimum :**
  - Dual-core Core i5 processor
  - 4GB RAM
  - 2GB Disk
- **Operating Systems :**
  - Windows 10, Windows 8.1 or Windows 8
  - Linux distributions (tested on Ubuntu 16.04, 18.04 and 20.04)
  - Mac OS X (tested on version 10.13 High Sierra, 10.14 Mojave)
- **Java :**
  - JRE or JDK 8 (OpenJDK or Oracle JDK)

## APPLICATION DEVELOPER GUIDE

### 3.1 Introduction

The following sections of this document shall prove useful as a reference when developing applications for MicroEJ. They cover concepts essential to MicroEJ Applications design.

In addition to these sections, by going to <https://developer.microej.com/>, you can access a number of helpful resources such as:

- Libraries from the MicroEJ Central Repository (<https://developer.microej.com/central-repository/>);
- Application Examples as source code from MicroEJ Github Repositories (<https://github.com/MicroEJ>);
- Documentation (HOWTOs, Reference Manuals, APIs javadoc...).

MicroEJ Applications are developed as standard Java applications on Eclipse JDT, using Foundation Libraries. MicroEJ SDK allows you to run / debug / deploy MicroEJ Applications on a MicroEJ Platform.

Two kinds of applications can be developed on MicroEJ: MicroEJ Standalone Applications and MicroEJ Sanboxed Applications.

A MicroEJ Standalone Application is a MicroEJ Application that is directly linked to the C code to produce a MicroEJ Firmware. Such application must define a main entry point, i.e. a class containing a `public static void main(String[])` method. MicroEJ Standalone Applications are developed using MicroEJ SDK.

A MicroEJ Sandboxed Application is a MicroEJ Application that can run over a Multi-Sandbox Firmware. It can be linked either statically or dynamically. If it is statically linked, it is then called a System Application as it is part of the initial image and cannot be removed. MicroEJ Sandboxed Applications are developed using MicroEJ Studio.

### 3.2 Licenses

#### 3.2.1 Overview

MicroEJ Architectures are distributed in two different versions:

- Evaluation Architectures, associated with a software license key
- Production Architectures, associated with an hardware license key stored on a USB dongle

Licenses list is available in MicroEJ preferences dialog page in **Window** > **Preferences** > **MicroEJ**



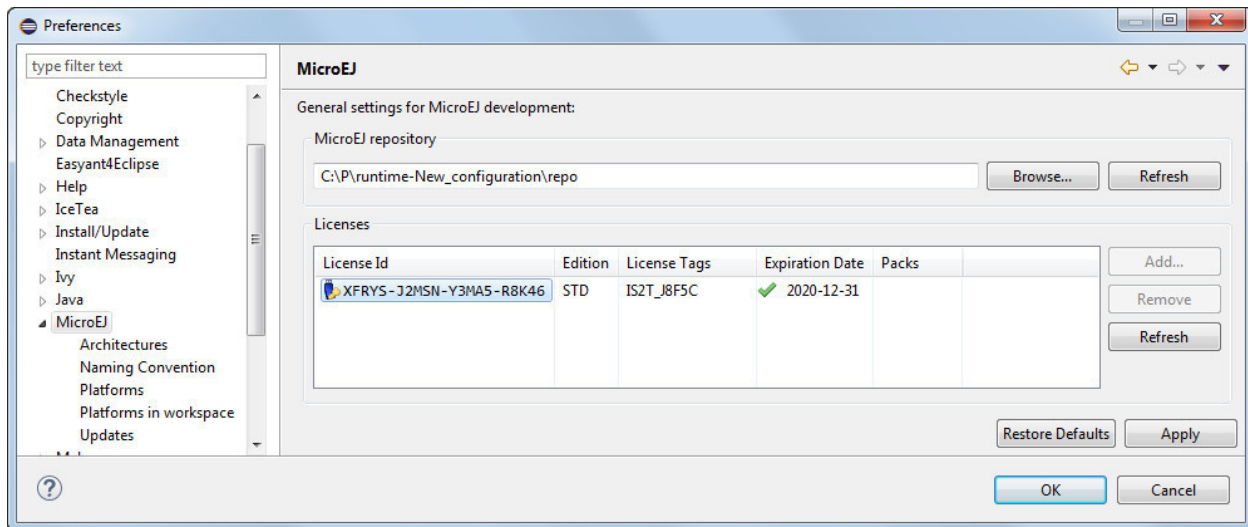


Fig. 1: MicroEJ Licenses View

Note that :

- Evaluation licenses will be shown only if architectures requiring an evaluation license are detected in your MicroEJ repository.
- Production licenses will be shown only if architectures requiring a production license are detected in your MicroEJ repository.

See section [Installation](#) for more information.

### 3.2.2 Installation

For more information about the licenses protection, please refer to section [Overview](#).

### 3.2.3 Evaluation Licenses

This section should be considered when using evaluation platforms, which use software license keys.

#### Installing License Keys

License keys can be added and removed from MicroEJ preferences main page. License keys are added to MicroEJ repository key-store using the **Add...** button. A dialog prompts for entering a license key. If an error message appears, the license key could not be installed. (see section [License Keys Troubleshooting](#)). A license key can be removed from key-store by selecting it and by clicking on **Remove** button.

#### Generating Machine UID

To activate an evaluation platform, a machine UID needs to be provided to the key server. This information is available from the **Window > Preferences > MicroEJ > Architectures** or **Window > Preferences > MicroEJ > Platforms** preferences page. Click on **Get UID** button to get the generated machine identifier.

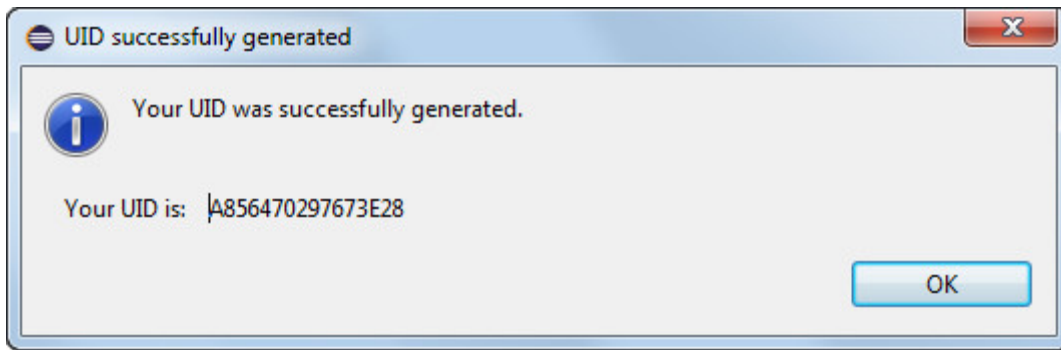


Fig. 2: Generated Machine Identifier for Evaluation License

### License Keys Troubleshooting

Consider this section when an error message appears while adding the license key. Before contacting MicroEJ support, please check the following conditions:

- Key is corrupted (wrong copy/paste, missing characters or extra characters)
- Key has not been generated for the installed environment
- Key has not been generated with the machine UID
- Machine UID has changed since submitting license request and no longer matches license key
- Key has not been generated for one of the installed platforms (no license manager able to load this license)

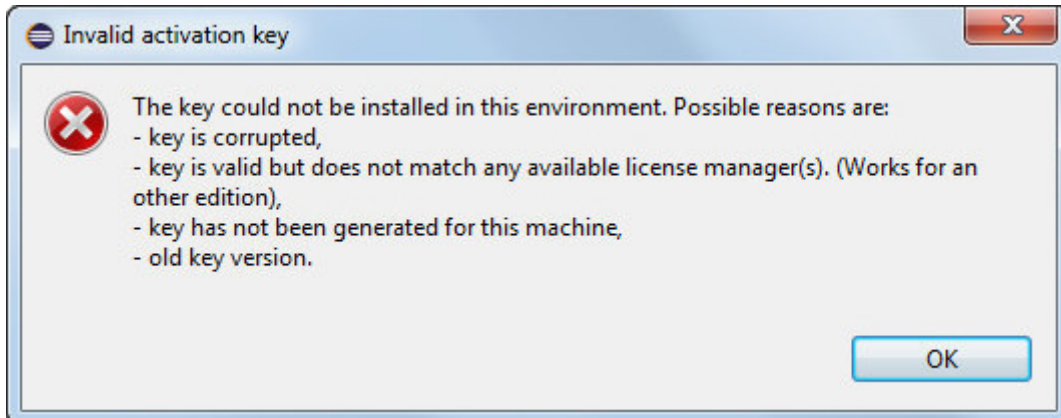


Fig. 3: Invalid License Key Error Message

### 3.2.4 Production Licenses

This section should be considered when using production platforms, which use hardware license keys.

#### USB Dongles Update

This section contains instructions that will allow to flash your hardware dongle with the proper activation key.

You shall ensure that the following prerequisites are met :

- The USB dongle is plugged and recognized by your operating system (see *USB Dongles Recognition* section)
- No more than one dongle is plugged to the computer while running the update tool
- The update tool is not launched from a Network drive or from a USB key
- The activation key you downloaded is the one for the dongle UID on the sticker attached to the dongle (each activation key is tied to the unique hardware ID of the dongle).

You can then proceed to the dongle update by running the activation key executable. Just press **Update** (no key is required).

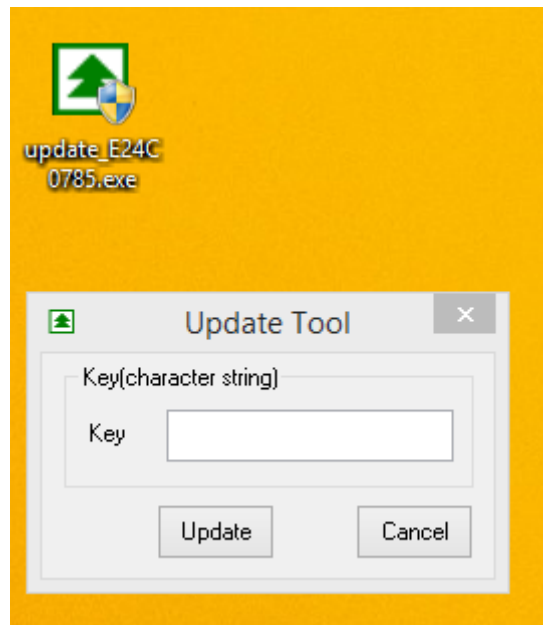


Fig. 4: Dongle Update Tool

On success, an **Update successfully** message shall appear. On failure, an **Error key or no proper rocky** message may appear.

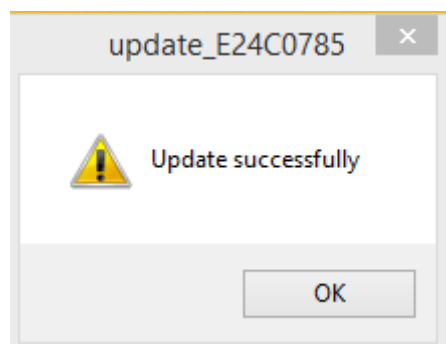


Fig. 5: Successful dongle update

Once you have successfully updated your dongle, from MicroEJ, go to **Window > Preferences > MicroEJ > Platforms**. You shall see that the license status for the platforms you installed with the **License tag** matching the one on the sticker attached to your USB dongle has turned from a red cross to a green tick.

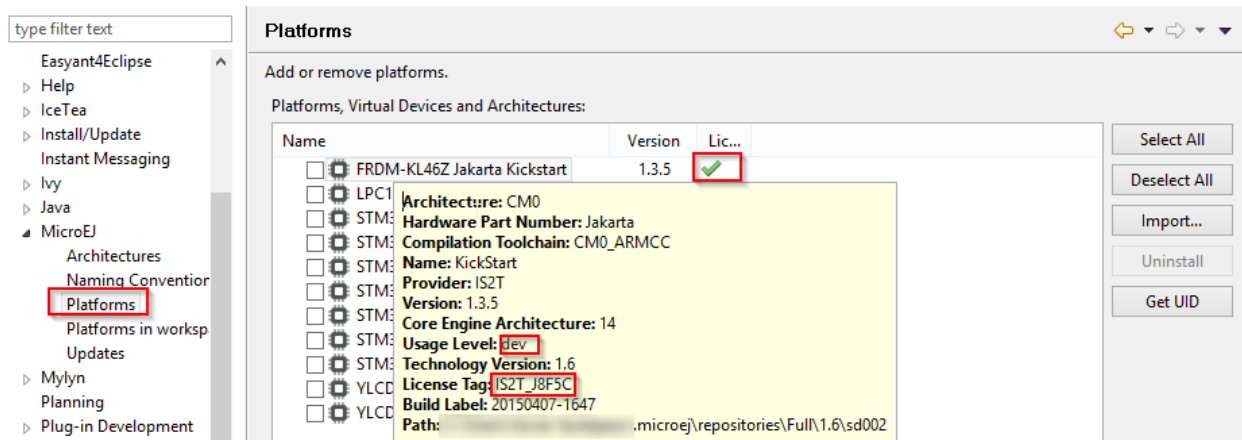


Fig. 6: Platform License Status OK

## USB Dongles Recognition

This section contains instructions that will allow to check that your hardware dongle is actually recognized by your operating system

## GNU/Linux Troubleshooting

For GNU/Linux Users (Ubuntu at least), by default, the dongle access has not been granted to the user, you have to modify udev rules. Please create a `/etc/udev/rules.d/91-usb dongle.rules` file with the following contents:

```
ACTION!="add", GOTO="usb dongle_end"
SUBSYSTEM=="usb", GOTO="usb dongle_start"
SUBSYSTEMS=="usb", GOTO="usb dongle_start"
GOTO="usb dongle_end"

LABEL="usb dongle_start"

ATTRS{idVendor}=="096e", ATTRS{idProduct}=="0006", MODE="0666"

LABEL="usb dongle_end"
```

Then, restart udev: `/etc/init.d/udev restart`

You can check that the device is recognized by running the `lsusb` command. The output of the command should contain a line similar to the one below for each dongle : `Bus 002 Device 003: ID 096e:0006 Feitian Technologies, Inc.`

## Windows Troubleshooting

For Windows users, each dongle shall be recognized with the following hardware ID :

```
HID\VID_096E&PID_0006&REV_0109
```

On Windows 8.1, go to **Device Manager** > **Human Interface Devices** and check among the **USB Input Device** entries that the **Details** > **Hardware Ids** property match the ID mentioned before.

## VirtualBox Troubleshooting

In a VirtualBox virtual machine, USB drives must be enabled to be recognized correctly. So make sure to enable the USB dongle by clicking on it in the VirtualBox menu **Devices** > **USB**.

In order to make this setting persistent, go to **Devices** > **USB** > **USB Settings...** and add the USB dongle in the **USB Devices Filters** list.

## 3.3 Local Workspaces and Repositories

When starting MicroEJ SDK, it prompts you to select the last used workspace or a default workspace on the first run. A workspace is a main folder where to find a set of projects containing MicroEJ source code.

When loading a new workspace, MicroEJ SDK prompts for the location of the MicroEJ repository, where the MicroEJ Architectures, Platforms or Virtual Devices will be imported. By default, MicroEJ SDK suggests to point to the default MicroEJ repository on your operating system, located at `${user.home}/.microej/repositories/[version]`. You can select an alternative location. Another common practice is to define a local repository relative to the workspace, so that the workspace is self-contained, without external file system links and can be shared within a zip file.

## 3.4 Standalone Application

### 3.4.1 Download and Install a MicroEJ Platform

MicroEJ SDK being a cross development tool, it does not build software targeted to your host desktop platform. In order to run MicroEJ Applications, a target hardware is required. Several commercial targets boards from main MCU/MPU chip manufacturers can be prepared to run MicroEJ Applications, you can also run your applications without one of these boards with the help of a MicroEJ Simulator.

A MicroEJ Platform is a software package including the resources and tools required for building and testing an application for a specific MicroEJ-ready device. MicroEJ Platforms are available at <https://developer.microej.com/5/getting-started-sdk.html>.

After downloading the MicroEJ Platform, launch MicroEJ SDK on your desktop to start the process of Platform installation :

- Open the Platform view in MicroEJ SDK, select **Window** > **Preferences** > **MicroEJ** > **Platforms** . The view should be empty on a fresh install of the tool

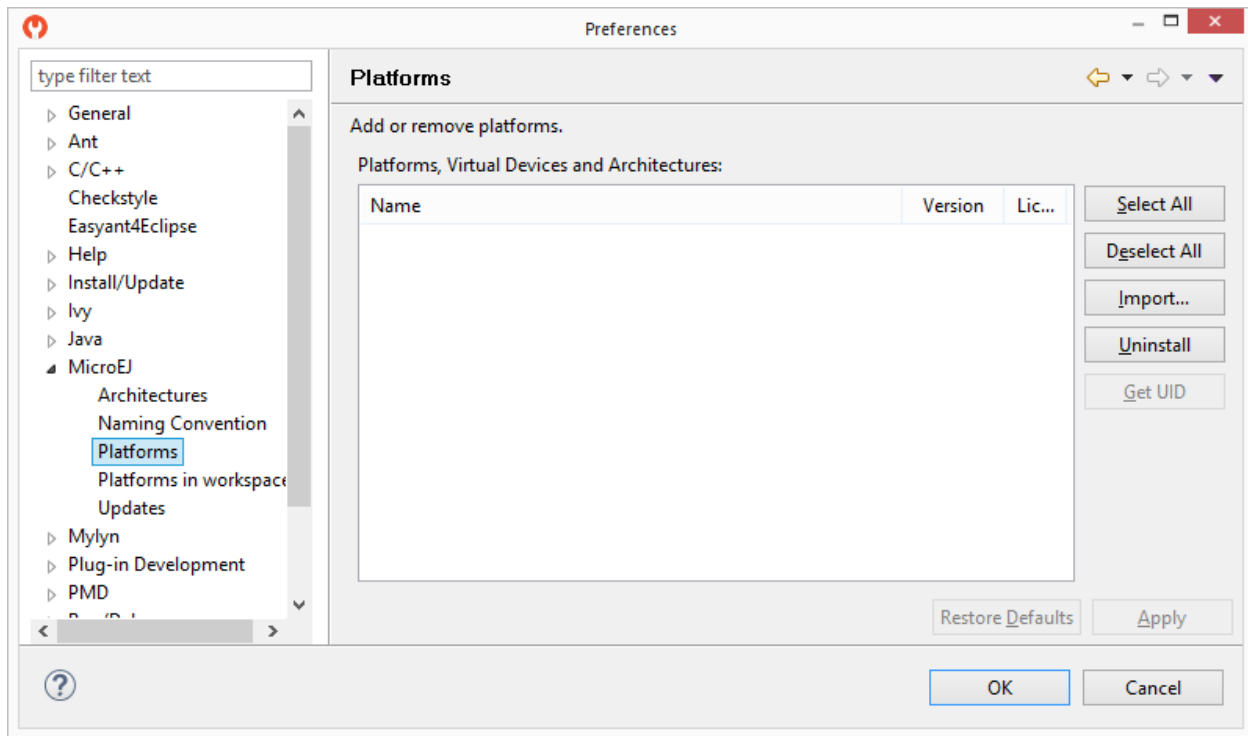


Fig. 7: MicroEJ Platform Import

- Press **Import...** button.
- Choose **Select File...** and use the **Browse** option to navigate to the **.jpf** file containing your MicroEJ Platform, then read and accept the license agreement to proceed.

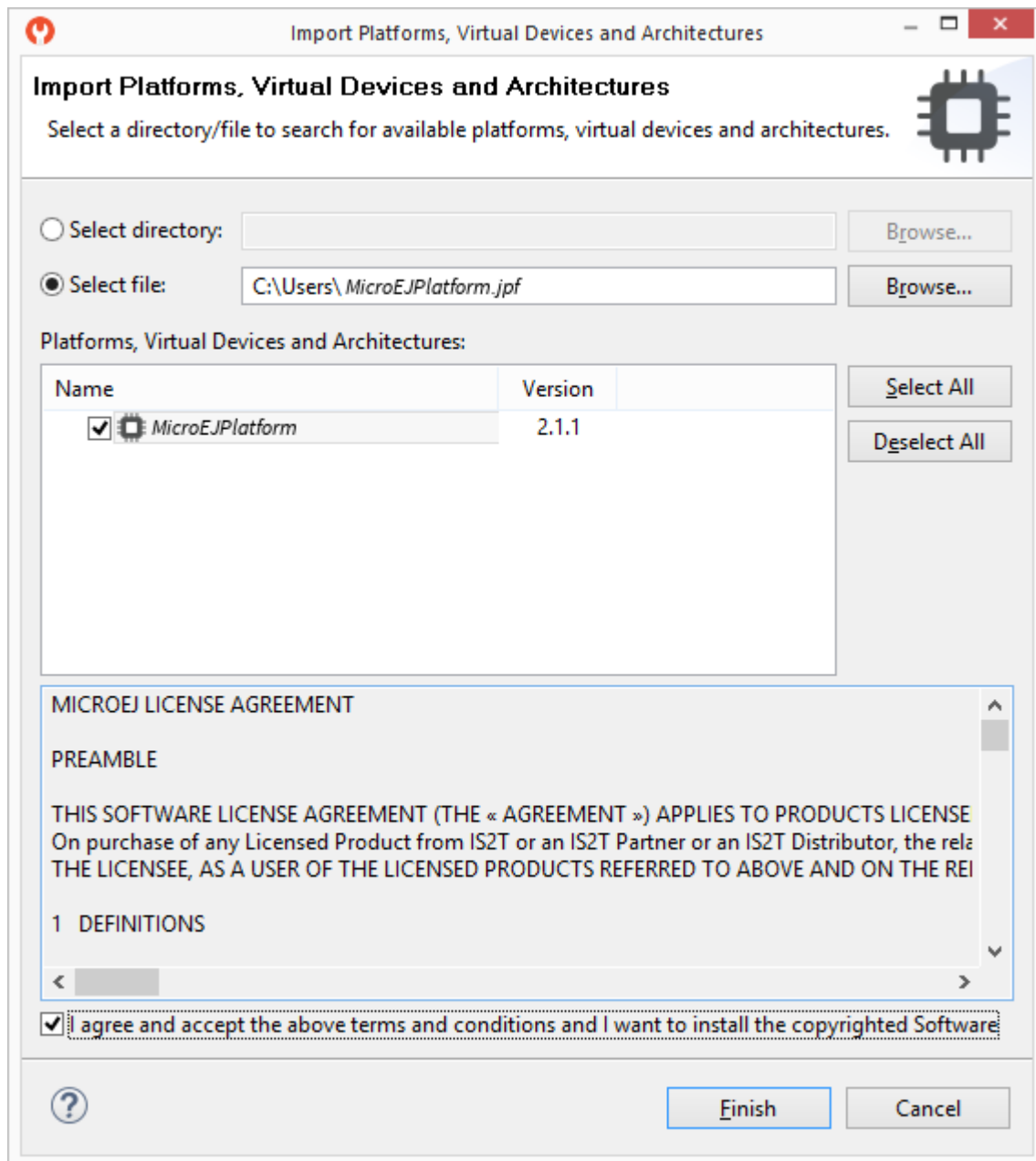


Fig. 8: MicroEJ Platform Selection

- The MicroEJ Platform should now appear in the **Platforms** view, with a green valid mark.

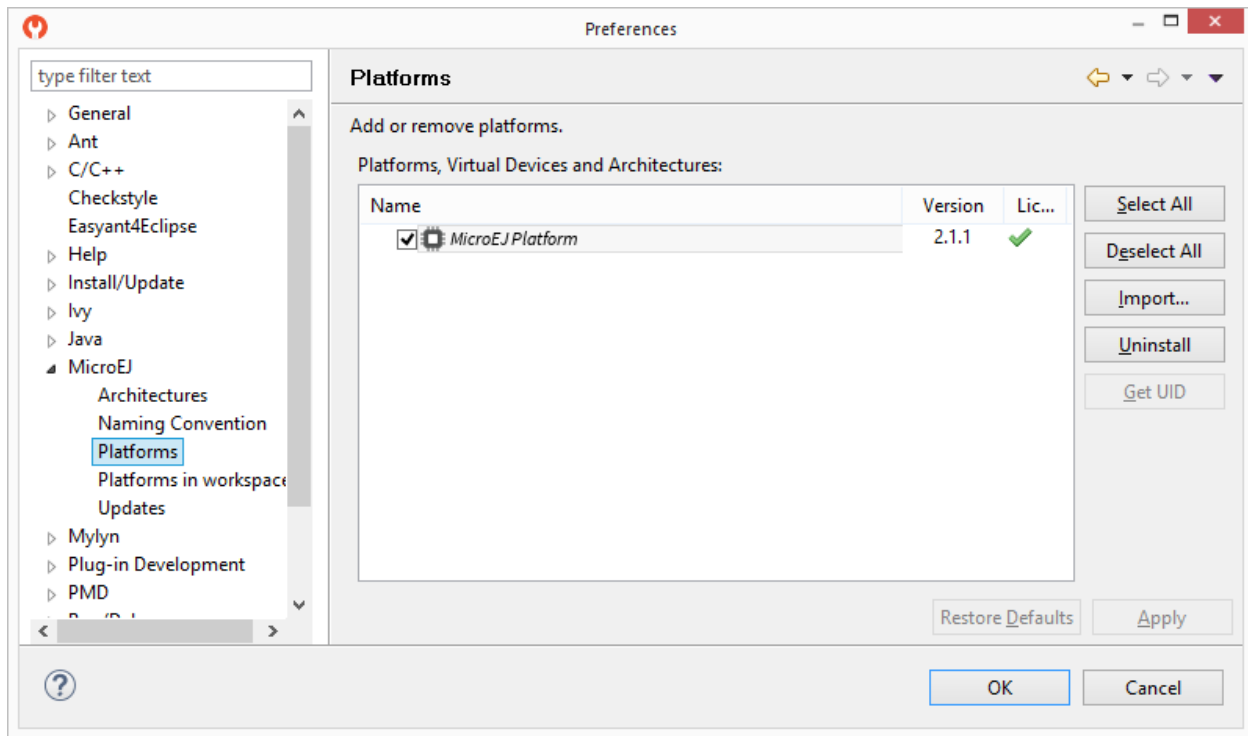


Fig. 9: MicroEJ Platform List

### 3.4.2 Build and Run an Application

#### Create a MicroEJ Standalone Application

- Create a project in your workspace. Select **File** > **New** > **MicroEJ Standalone Application Project**.

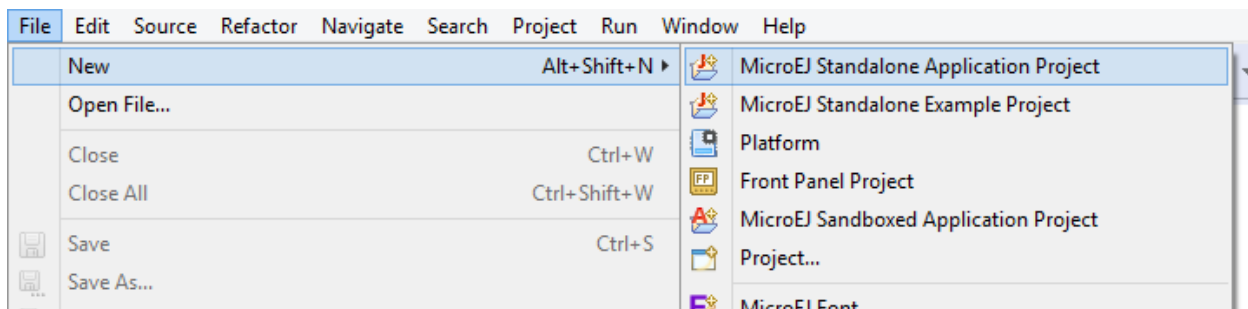


Fig. 10: New MicroEJ Standalone Application Project

- Fill in the application template fields, the Project name field will automatically duplicate in the following fields. Click on **Finish**. A template project is automatically created and ready to use, this project already contains all folders wherein developers need to put content:
  - `src/main/java`: Folder for future sources
  - `src/main/resources`: Folder for future resources (images, fonts etc.)



- `META-INF` : Sandboxed Application configuration and resources
- `module.ivy` : Ivy input file, dependencies description for the current project
- Right click on the source folder `src/main/java` and select **New** > **Package** . Give a name: `com.mycompany` . Click on **Finish** .

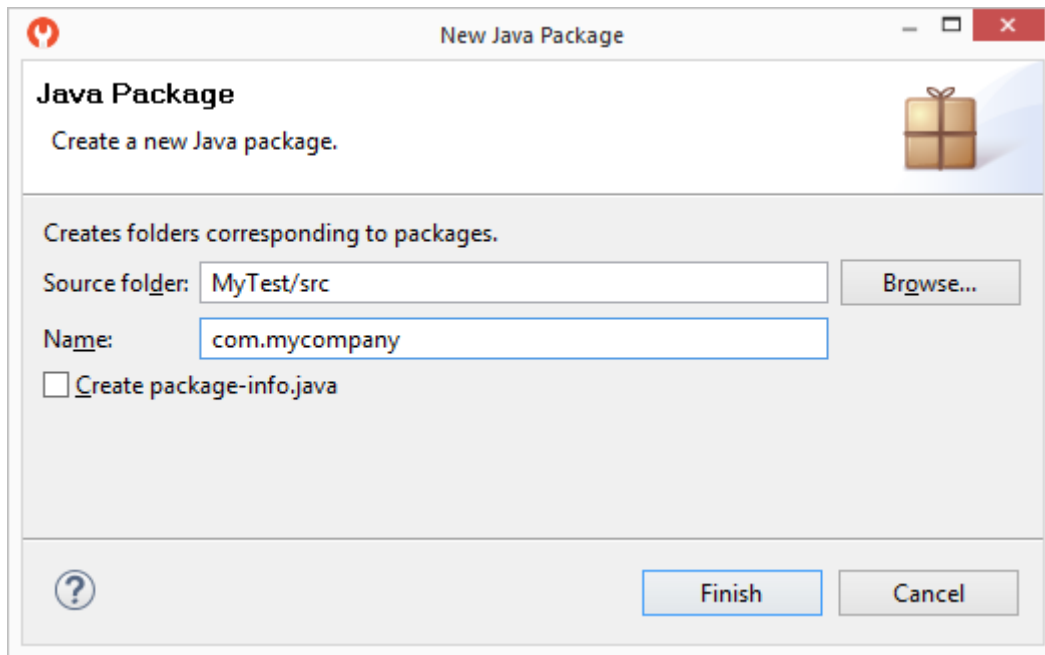


Fig. 11: New Package

- The package `com.mycompany` is available under `src/main/java` folder. Right click on this package and select **New** > **Class** . Give a name: `Test` and check the box `public static void main(String[] args)` . Click on **Finish** .

**Java Class**  
Create a new Java class.

Source folder:

Package:

☐ Enclosing type:

---

Name:

Modifiers: ☒ public ☐ package ☐ private ☐ protected  
☐ abstract ☐ final ☐ static

Superclass:

Interfaces:

Which method stubs would you like to create?

☒ `public static void main(String[] args);`

☐ Constructors from superclass

☒ Inherited abstract methods

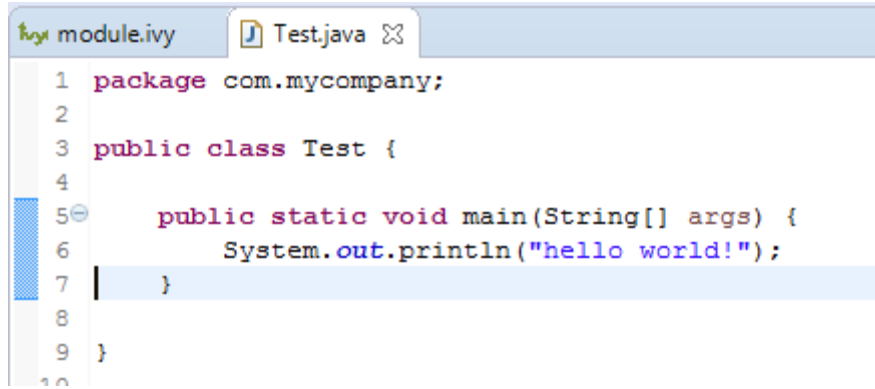
Do you want to add comments? (Configure templates and default value [here](#))

☐ Generate comments

Fig. 12: New Class

- The new class has been created with an empty `main()` method. Fill the method body with the following lines:

```
System.out.println("hello world!");
```



```
1 package com.mycompany;
2
3 public class Test {
4
5     public static void main(String[] args) {
6         System.out.println("hello world!");
7     }
8
9 }
```

Fig. 13: MicroEJ Application Content

The test application is now ready to be executed. See next sections.

### Run on the Simulator

To run the sample project on Simulator, select it in the left panel then right-click and select **Run** > **Run as** > **MicroEJ Application** .

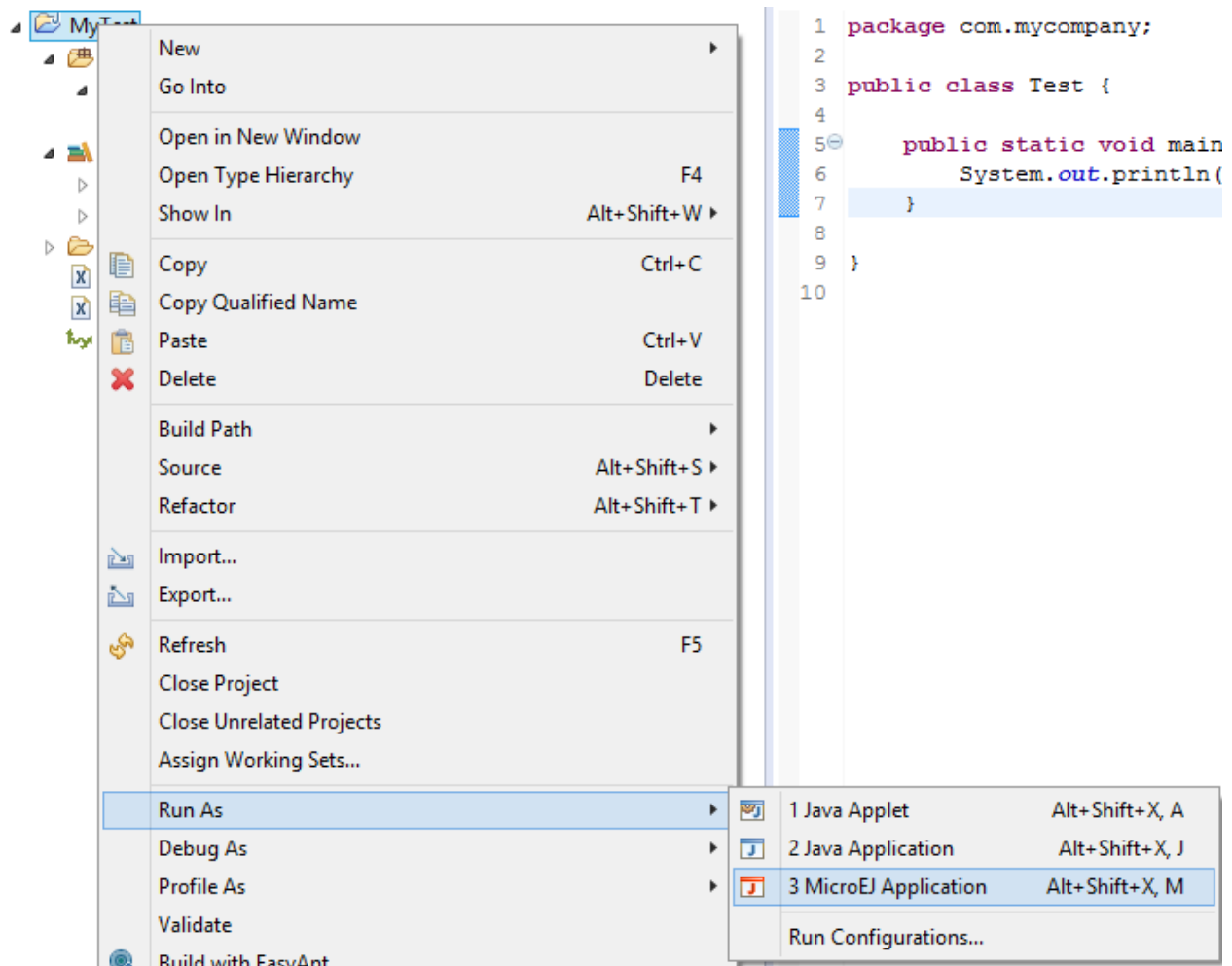


Fig. 14: MicroEJ Development Tools Overview

MicroEJ SDK console will display Launch steps messages.

```

===== [ Initialization Stage ] =====
===== [ Launching on Simulator ] =====
hello world!
===== [ Completed Successfully ] =====

SUCCESS

```

### Run on the Hardware Device

Compile an application, connect the hardware device and deploy on it is hardware dependant. These steps are described in dedicated documentation available inside the MicroEJ Platform. This documentation is accessible from the MicroEJ Resources Center view.

**Note:** MicroEJ Resources Center view may have been closed. Click on **Help** > **MicroEJ Resources Center** to reopen it.

Open the menu **Manual** and select the documentation **[hardware device] MicroEJ Platform**, where **[hardware device]** is the name of the hardware device. This documentation features a guide to run a built-in application on MicroEJ Simulator and on hardware device.

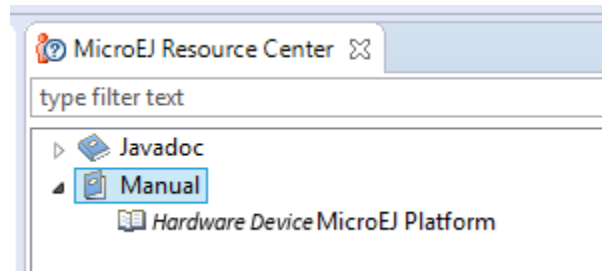


Fig. 15: MicroEJ Platform Guide

### 3.4.3 MicroEJ Launch

The MicroEJ launch configuration sets up the *MicroEJ Applications* environment (main class, resources, target platform, and platform-specific options), and then launches a MicroEJ launch script for execution.

Execution is done on either the MicroEJ Platform or the MicroEJ Simulator. The launch operation is platform-specific. It may depend on external tools that the platform requires (such as target memory programming). Refer to the platform-specific documentation for more information about available launch settings.

#### Main Tab

The **Main** tab allows you to set in order:

1. The main project of the application.
2. The main class of the application containing the main method.
3. Types required in your application that are not statically embedded from the main class entry point. Most required types are those that may be loaded dynamically by the application, using the `Class.forName()` method.
4. Binary resources that need to be embedded by the application. These are usually loaded by the application using the `Class.getResourceAsStream()` method.
5. Immutable objects' description files. See the *[BON 1.2] ESR documentation* for use of immutable objects.



Fig. 16: MicroEJ Launch Application Main Tab

### Execution Tab

The next tab is the **Execution** tab. Here the target needs to be selected. Choose between execution on a MicroEJ Platform or on a MicroEJ Simulator. Each of them may provide multiple launch settings. This page also allows you to keep generated, intermediate files and to print verbose options (advanced debug purpose options).

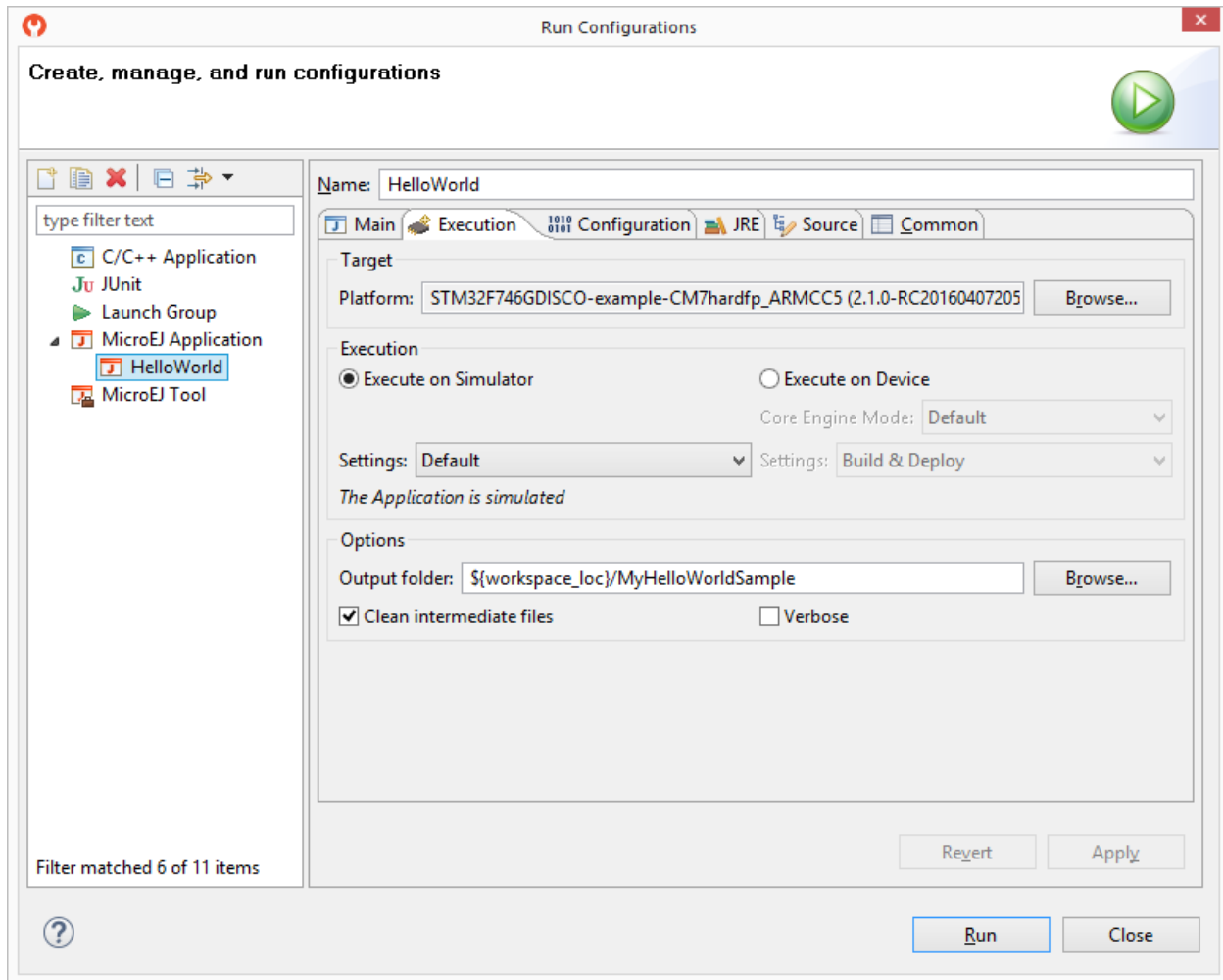


Fig. 17: MicroEJ Launch Application Execution Tab

### Configuration Tab

The next tab is the **Configuration** tab. This tab contains all platform-specific options.



Fig. 18: Configuration Tab

### JRE Tab

The next tab is the **JRE** tab. This tab allows you to configure the Java Runtime Environment used for running the underlying launch script. It does not configure the MicroEJ Application execution. The **VM Arguments** text field allows you to set vm-specific options, which are typically used to increase memory spaces:

- To modify heap space to 1024MB, set the **-Xmx1024M** option.
- To modify string space (also called PermGen space) to 256MB, set the **-XX:PermSize=256M** **-XX:MaxPermSize=256M** options.
- To set thread stack space to 512MB, set the **-Xss512M** option.

### Other Tabs

The next tabs (**Source** and **Common** tabs) are the default Eclipse launch tabs. Refer to Eclipse help for more details on how to use these launch tabs.



### 3.4.4 Application Options

To run a MicroEJ Standalone Application on a MicroEJ Platform, a set of options must be defined. Options can be of different types:

- Memory Allocation options (e.g. set the Java Heap size). These options are usually called link-time options.
- Simulator & Debug options (e.g. enable periodic Java Heap dump).
- Deployment options (e.g. copy `microejapp.o` to a suitable BSP location).
- Foundation Library specific options (e.g. embed UTF-8 encoding).

The following section describes options provided by MicroEJ Architecture. Please consult the appropriate MicroEJ Pack documentation for options related to other Foundation Libraries (MicroUI, NET, SSL, FS, ...) integrated to the Platform.

Notice that some options may not be available, in the following cases:

- Option is specific to the MicroEJ Core Engine capability (*tiny/single/multi*) which is integrated in the targeted Platform.
- Option is specific to the target (MicroEJ Core Engine on Device or Simulator).
- Option has been introduced in a newer version of the MicroEJ Architecture which is integrated in the targeted Platform.
- Options related to *Board Support Package (BSP) connection*.

#### Category: Runtime

<ul style="list-style-type: none"> <li>▼ Device           <ul style="list-style-type: none"> <li>▼ Core Engine               <ul style="list-style-type: none"> <li>Kernel</li> <li>Watchdog</li> <li>Deploy</li> </ul> </li> <li>▼ Feature               <ul style="list-style-type: none"> <li>Dynamic Download</li> </ul> </li> <li>▼ Libraries               <ul style="list-style-type: none"> <li>▼ ECOM                   <ul style="list-style-type: none"> <li>Comm Connection</li> <li>EDC</li> <li>External Resources Loader</li> <li>Shielded Plug</li> </ul> </li> </ul> </li> <li>▼ Runtime</li> <li>▼ Simulator               <ul style="list-style-type: none"> <li>Code Coverage</li> <li>Com Port</li> <li>Debug</li> <li>Device</li> <li>Heap Dumper</li> <li>Logs</li> </ul> </li> </ul> </li> </ul>	<div>Types</div> <div><input type="checkbox"/> Embed all type names</div> <div>Assertions</div> <div><input type="checkbox"/> Execute assertions on Simulator</div> <div><input type="checkbox"/> Execute assertions on Device</div> <div>Trace</div> <div><input type="checkbox"/> Enable execution traces</div> <div><input type="checkbox"/> Start execution traces automatically</div>
--	--

#### Group: Types

**Option(checkbox): Embed all type names**

Option Name: `soar.generate.classnames`

Default value: `true`

Description:

Embed the name of all types. When this option is disabled, only names of declared required types are embedded.

**Group: Assertions****Option(checkbox): Execute assertions on Simulator**

Option Name: `core.assertions.sim.enabled`

Default value: `false`

Description:

When this option is enabled, `assert` statements are executed. Please note that the executed code may produce side effects or throw `java.lang.AssertionError`.

**Option(checkbox): Execute assertions on Device**

Option Name: `core.assertions.emb.enabled`

Default value: `false`

Description:

When this option is enabled, `assert` statements are executed. Please note that the executed code may produce side effects or throw `java.lang.AssertionError`.

**Group: Trace****Option(checkbox): Enable execution traces**

Option Name: `core.trace.enabled`

Default value: `false`

**Option(checkbox): Start execution traces automatically**

Option Name: `core.trace.autostart`

Default value: `false`

**Category: Memory**

<ul style="list-style-type: none"> <li>▼ Device           <ul style="list-style-type: none"> <li>▼ Core Engine               <ul style="list-style-type: none"> <li>Kernel</li> <li>Watchdog</li> <li>Deploy</li> </ul> </li> <li>▼ Feature               <ul style="list-style-type: none"> <li>Dynamic Download</li> </ul> </li> <li>▼ Libraries               <ul style="list-style-type: none"> <li>▼ ECOM                   <ul style="list-style-type: none"> <li>Comm Connection</li> <li>EDC</li> <li>External Resources Loader</li> <li>Shielded Plug</li> </ul> </li> </ul> </li> <li>▼ Runtime               <ul style="list-style-type: none"> <li><b>Memory</b></li> </ul> </li> <li>▼ Simulator               <ul style="list-style-type: none"> <li>Code Coverage</li> <li>Com Port</li> <li>Debug</li> <li>Device</li> <li>Heap Dumper</li> <li>Logs</li> </ul> </li> </ul> </li> </ul>	<b>Heaps</b>	
	Java heap size (in bytes)	<input type="text"/>
	Immortal heap size (in bytes)	<input type="text"/>
	<b>Threads</b>	
	Number of threads	<input type="text"/>
	Number of blocks in pool	<input type="text"/>
	Block size (in bytes)	<input type="text"/>
	Maximum size of thread stack (in blocks)	<input type="text"/>

**Group: Heaps****Option(text): Java heap size (in bytes)**

Option Name: `core.memory.javaheap.size`

Default value: `65536`

Description:

Specifies the Java heap size in bytes.

A Java heap contains live Java objects. An OutOfMemory error can occur if the heap is too small.

**Option(text): Immortal heap size (in bytes)**

Option Name: `core.memory.immortal.size`

Default value: `4096`

Description:

Specifies the Immortal heap size in bytes.

The Immortal heap contains allocated Immortal objects. An OutOfMemory error can occur if the heap is too small.

**Group: Threads**

Description:

This group allows the configuration of application and library thread(s). A thread needs a stack to run. This stack is allocated from a pool and this pool contains several blocks. Each block has the same size. At thread startup the thread uses only one block for its stack. When the first block is full it uses another block. The maximum number of blocks per thread must be specified. When the maximum number of blocks for a thread is reached or when there is no free block in the pool, a `StackOverflow` error is thrown. When a thread terminates all associated blocks are freed. These blocks can then be used by other threads.

**Option(text): Number of threads**

*Option Name:* `core.memory.threads.size`

*Default value:* `5`

*Description:*

Specifies the number of threads the application will be able to use at the same time.

**Option(text): Number of blocks in pool**

*Option Name:* `core.memory.threads.pool.size`

*Default value:* `15`

*Description:*

Specifies the number of blocks in the stacks pool.

**Option(text): Block size (in bytes)**

*Option Name:* `core.memory.thread.block.size`

*Default value:* `512`

*Description:*

Specifies the thread stack block size (in bytes).

**Option(text): Maximum size of thread stack (in blocks)**

*Option Name:* `core.memory.thread.max.size`

*Default value:* `4`

*Description:*

Specifies the maximum number of blocks a thread can use. If a thread requires more blocks a `StackOverflow` error will occur.

**Category: Simulator**

The screenshot shows the MicroEJ Simulator configuration window. On the left, a tree view lists categories: Device, Core Engine (Kernel, Watchdog, Deploy), Feature (Dynamic Download), Libraries (ECOM, Comm Connection, EDC, External Resources Loader, Shielded Plug), Runtime (Memory), and Simulator (selected). The main panel displays configuration options for the Simulator. It includes a checkbox for 'Use target characteristics', a text field for 'Slowing factor (0 means disabled)' set to 0, a checkbox for 'Specify a port' under 'HIL Connection', a text field for 'HIL connection port' set to 8001, a text field for 'HIL connection timeout' set to 10, and a text field for 'Server socket port' set to 10082 under 'Shielded Plug server configuration'.

**Group: Options***Description:*

This group specifies options for MicroEJ Simulator.

**Option(checkbox): Use target characteristics**

Option Name: `s3.board.compliant`

Default value: `false`

*Description:*

When selected, this option forces the MicroEJ Simulator to use the MicroEJ Platform exact characteristics. It sets the MicroEJ Simulator scheduling policy according to the MicroEJ Platform one. It forces resources to be explicitly specified. It enables log trace and gives information about the RAM memory size the MicroEJ Platform uses.

**Option(text): Slowing factor (0 means disabled)**

Option Name: `s3.slow`

Default value: `0`

*Description:*

Format: Positive `integer`

This option allows the MicroEJ Simulator to be slowed down in order to match the MicroEJ Platform execution speed. The greater the slowing factor, the slower the MicroEJ Simulator runs.

**Group: HIL Connection***Description:*

This group enables the control of HIL (Hardware In the Loop) connection parameters (connection between MicroEJ Simulator and the Mocks).

**Option(checkbox): Specify a port**

*Option Name:* `s3.hil.use.port`

*Default value:* `false`

*Description:*

When selected allows the use of a specific HIL connection port, otherwise a random free port is used.

**Option(text): HIL connection port**

*Option Name:* `s3.hil.port`

*Default value:* `8001`

*Description:*

*Format:* Positive `integer`

*Values:* [1024-65535]

It specifies the port used by the MicroEJ Simulator to accept HIL connections.

**Option(text): HIL connection timeout**

*Option Name:* `s3.hil.timeout`

*Default value:* `10`

*Description:*

*Format:* Positive `integer`

It specifies the time the MicroEJ Simulator should wait before failing when it invokes native methods.

**Group: Shielded Plug server configuration***Description:*

This group allows configuration of the Shielded Plug database.

**Option(text): Server socket port**

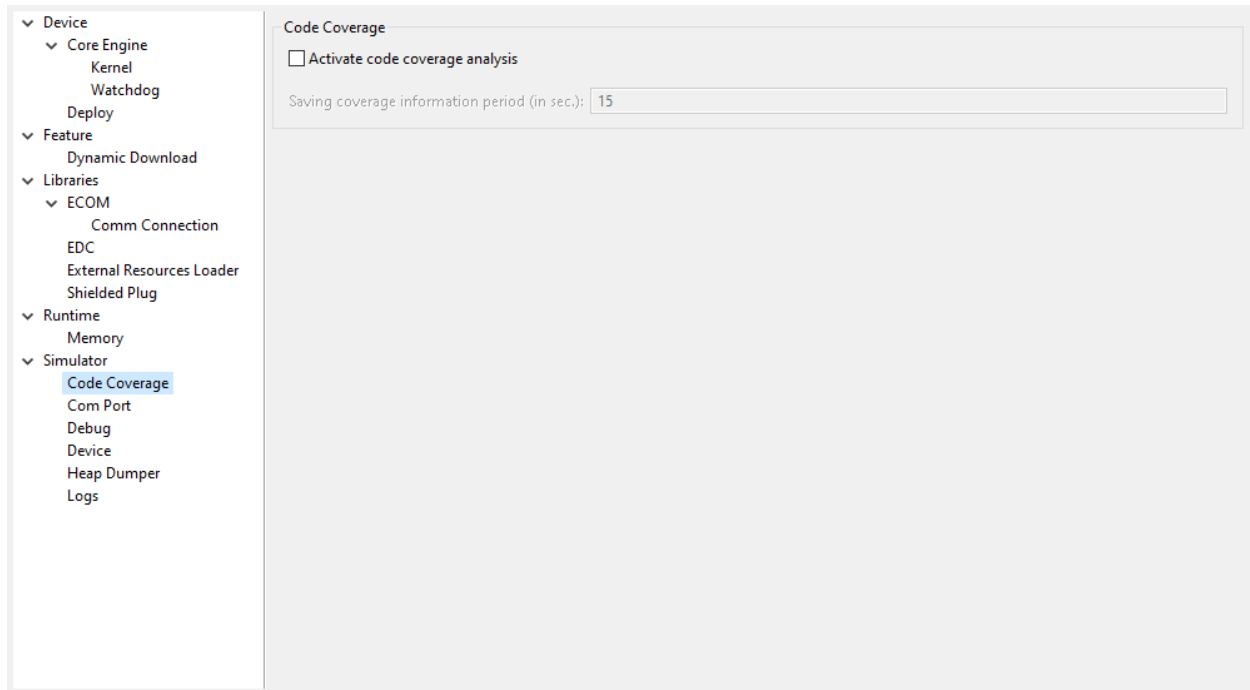
*Option Name:* `sp.server.port`

*Default value:* `10082`

*Description:*

Set the Shielded Plug server socket port.

### Category: Code Coverage



### Group: Code Coverage

#### Description:

This group is used to set parameters of the code coverage analysis tool.

#### Option(checkbox): Activate code coverage analysis

Option Name: `s3.cc.activated`

Default value: `false`

#### Description:

When selected it enables the code coverage analysis by the MicroEJ Simulator. Resulting files are output in the cc directory inside the output directory.

#### Option(text): Saving coverage information period (in sec.)

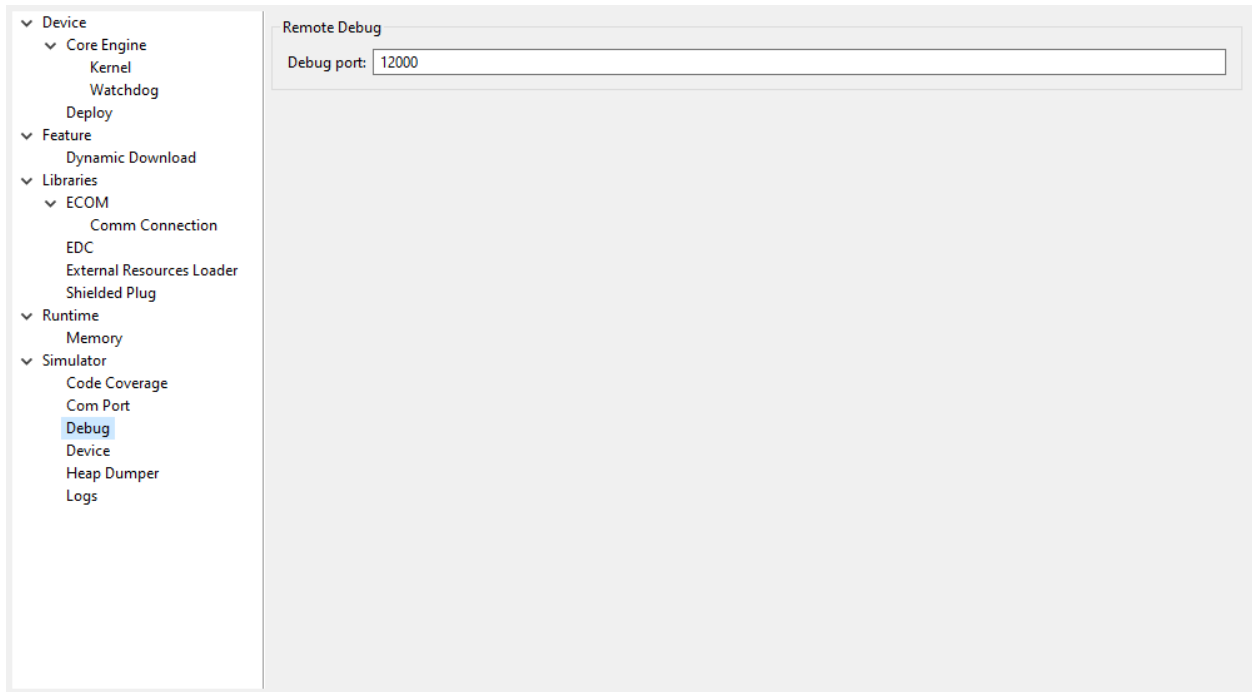
Option Name: `s3.cc.thread.period`

Default value: `15`

#### Description:

It specifies the period between the generation of .cc files.

## Category: Debug



### Group: Remote Debug

#### Option(text): Debug port

*Option Name:* debug.port

*Default value:* 12000

*Description:*

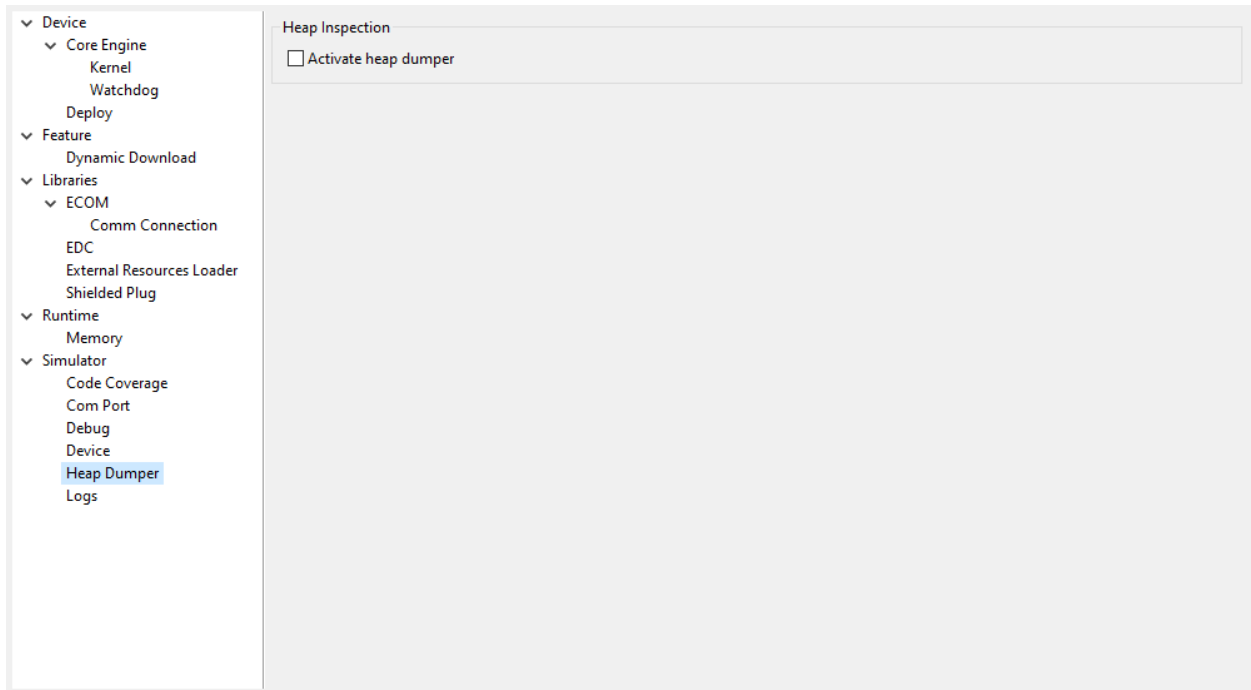
Configures the JDWP debug port.

*Format:* Positive integer

*Values:* [1024-65535]



## Category: Heap Dumper



### Group: Heap Inspection

#### Description:

This group is used to specify heap inspection properties.

#### Option(checkbox): Activate heap dumper

Option Name: `s3.inspect.heap`

Default value: `false`

#### Description:

When selected, this option enables a dump of the heap each time the `System.gc()` method is called by the MicroEJ Application.

## Category: Logs

The screenshot shows the MicroEJ configuration window. On the left, a tree view lists various categories, with 'Logs' highlighted under the 'Simulator' section. The main area on the right is titled 'Logs' and contains several checkboxes: 'system', 'thread', 'monitoring', 'memory', 'schedule', and 'monitors'. Below these checkboxes is a text input field labeled 'period (in sec.):' with the value '2' entered.

## Group: Logs

### Description:

This group defines parameters for MicroEJ Simulator log activity. Note that logs can only be generated if the **Simulator > Use target characteristics** option is selected.

Some logs are sent when the platform executes some specific action (such as start thread, start GC, etc), other logs are sent periodically (according to defined log level and the log periodicity).

### Option(checkbox): system

Option Name: `console.logs.level.low`

Default value: `false`

### Description:

When selected, System logs are sent when the platform executes the following actions:

- start and terminate a thread
- start and terminate a GC
- exit

### Option(checkbox): thread

Option Name: `console.logs.level.thread`

*Default value:* `false`

*Description:*

When selected, thread information is sent periodically. It gives information about alive threads (status, memory allocation, stack size).

#### **Option(checkbox): monitoring**

*Option Name:* `console.logs.level.monitoring`

*Default value:* `false`

*Description:*

When selected, thread monitoring logs are sent periodically. It gives information about time execution of threads.

#### **Option(checkbox): memory**

*Option Name:* `console.logs.level.memory`

*Default value:* `false`

*Description:*

When selected, memory allocation logs are sent periodically. This level allows to supervise memory allocation.

#### **Option(checkbox): schedule**

*Option Name:* `console.logs.level.schedule`

*Default value:* `false`

*Description:*

When selected, a log is sent when the platform schedules a thread.

#### **Option(checkbox): monitors**

*Option Name:* `console.logs.level.monitors`

*Default value:* `false`

*Description:*

When selected, monitors information is sent periodically. This level permits tracing of all thread state by tracing monitor operations.

#### **Option(text): period (in sec.)**

*Option Name:* `console.logs.period`

*Default value:* `2`

*Description:*

*Format:* Positive `integer`

Values: [0-60]

Defines the periodicity of periodical logs.

### Category: Device

The screenshot shows the MicroEJ configuration window. On the left, a tree view lists various categories under 'Device', with 'Device' itself selected. The main area on the right is divided into two sections:

- Device Architecture:** Contains a checkbox labeled 'Use a custom device architecture'. If checked, it reveals a text input field labeled 'Architecture Name:'.
- Device Unique ID:** Contains a checkbox labeled 'Use a custom device unique ID'. If checked, it reveals a text input field labeled 'Unique ID (hexadecimal value):'.

### Group: Device Architecture

#### Option(checkbox): Use a custom device architecture

Option Name: `s3.mock.device.architecture.option.use`

Default value: `false`

#### Option(text): Architecture Name

Option Name: `s3.mock.device.architecture.option`

Default value: `(empty)`

### Group: Device Unique ID

#### Option(checkbox): Use a custom device unique ID

Option Name: `s3.mock.device.id.option.use`

Default value: `false`

**Option(text): Unique ID (hexadecimal value)**

*Option Name:* `s3.mock.device.id.option`

*Default value:* `(empty)`

**Category: Com Port**

## Category: Libraries



## Category: EDC



## Group: Java System.out

**Option(checkbox): Use a custom Java output stream**

*Option Name:* `core.outputstream.disable.uart`

*Default value:* `false`

*Description:*

Select this option to specify another Java `System.out` print stream.

If selected, the default Java output stream is not used by the Java application. the JPF will not use the default Java output stream at startup.

**Option(text): Class**

*Option Name:* `core.outputstream.class`

*Default value:* `(empty)`

*Description:*

*Format:* Java class like `packageA.packageB.className`

Defines the Java class used to manage `System.out`.

At startup the JPF will try to load this class using the `Class.forName()` method. If the given class is not available, the JPF will use the default Java output stream as usual. The specified class must be available in the application classpath.

**Group: Runtime options**

*Description:*

Specifies the additional classes to embed at runtime.

**Option(checkbox): Embed UTF-8 encoding**

*Option Name:* `cldc.encoding.utf8.included`

*Default value:* `true`

*Description:*

Embed UTF-8 encoding.

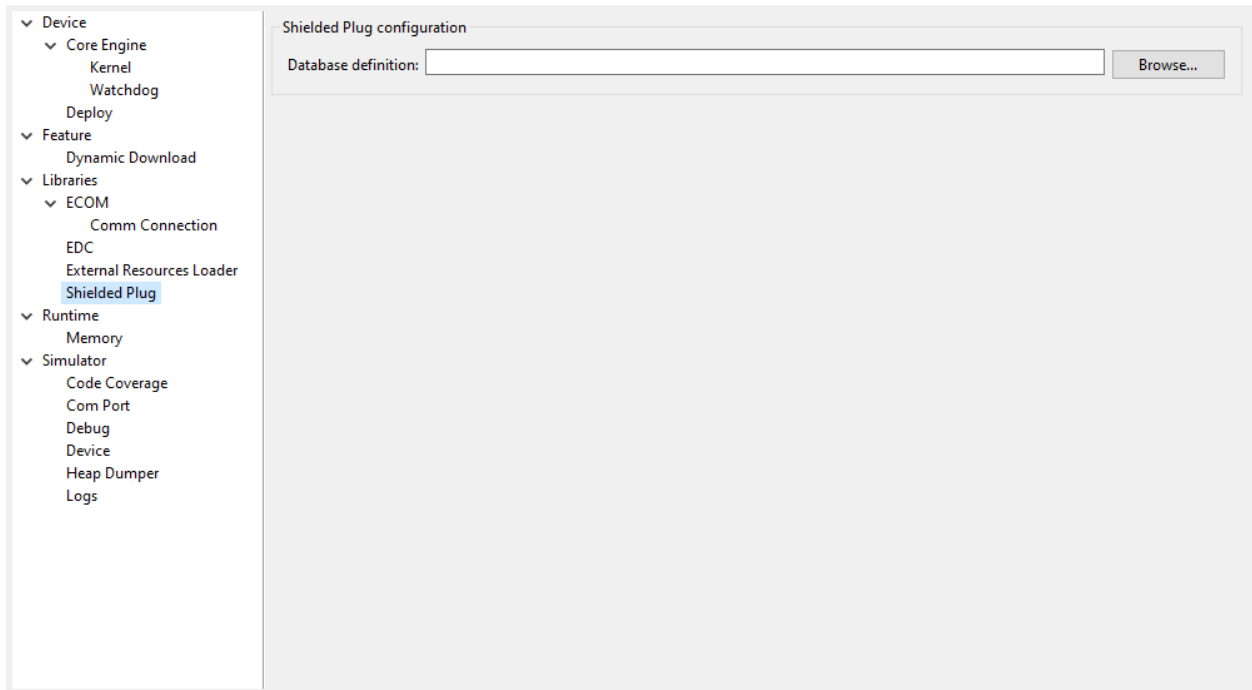
**Option(checkbox): Enable SecurityManager checks**

*Option Name:* `com.microej.library.edc.securitymanager.enabled`

*Default value:* `false`

*Description:*

Enable the security manager runtime checks.

**Category: Shielded Plug****Group: Shielded Plug configuration***Description:*

Choose the database XML definition.

**Option(browse): Database definition**

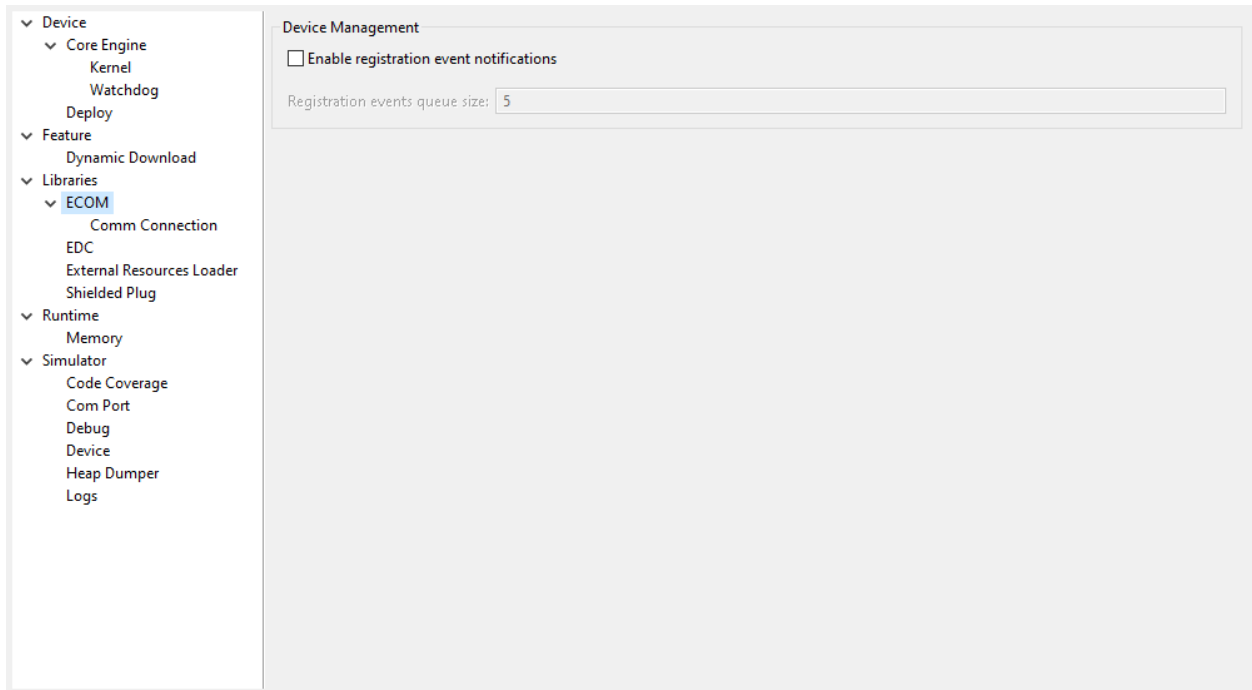
*Option Name:* `sp.database.definition`

*Default value:* `(empty)`

*Description:*

Choose the database XML definition.



**Category: ECOM****Group: Device Management****Option(checkbox): Enable registration event notifications**

*Option Name:* `com.is2t.ecom.eventpump.enabled`

*Default value:* `false`

*Description:*

Enables notification of listeners when devices are registered or unregistered. When a device is registered or unregistered, a new `ej.ecom.io.RegistrationEvent` is added to an event queue. Then events are processed by a dedicated thread that notifies registered listeners.

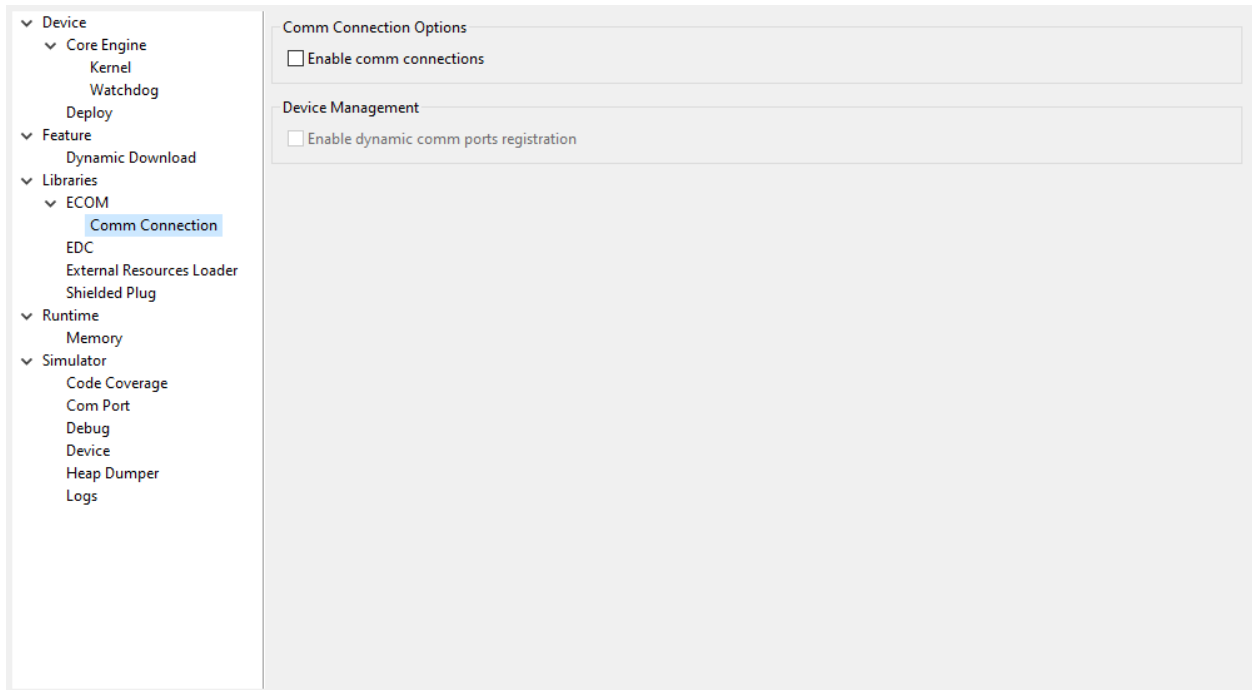
**Option(text): Registration events queue size**

*Option Name:* `com.is2t.ecom.eventpump.size`

*Default value:* `5`

*Description:*

Specifies the size (in number of events) of the registration events queue.

**Category: Comm Connection****Group: Comm Connection Options***Description:*

This group allows comm connections to be enabled and application-platform mappings set.

**Option(checkbox): Enable comm connections**

*Option Name:* `use.comm.connection`

*Default value:* `false`

*Description:*

When checked application is able to open a `CommConnection`.

**Group: Device Management****Option(checkbox): Enable dynamic comm ports registration**

*Option Name:* `com.is2t.ecom.comm.registryPump.enabled`

*Default value:* `false`

*Description:*

Enables registration (or unregistration) of ports dynamically added (or removed) by the platform. A dedicated thread listens for ports dynamically added (or removed) by the platform and adds (or removes) their `CommPort` representation to the ECOM `DeviceManager`.

**Category: External Resources Loader****Group: External Resources Loader***Description:*

This group allows to specify the external resources input folder. The content of this folder will be copied in an application output folder and used by SOAR and the Simulator. If empty, the default location will be [output folder]/externalResources, where [output folder] is the location defined in Execution tab.

**Option(browse):**

*Option Name:* `ej.externalResources.input.dir`

*Default value:* `(empty)`

*Description:*

Browse to specify the external resources folder..

**Category: Device**

<ul style="list-style-type: none"><li>▼ Device<ul style="list-style-type: none"><li>▼ Core Engine<ul style="list-style-type: none"><li>Kernel</li><li>Watchdog</li><li>Deploy</li></ul></li><li>▼ Feature<ul style="list-style-type: none"><li>Dynamic Download</li></ul></li><li>▼ Libraries<ul style="list-style-type: none"><li>▼ ECOM<ul style="list-style-type: none"><li>Comm Connection</li><li>EDC</li><li>External Resources Loader</li><li>Shielded Plug</li></ul></li></ul></li><li>▼ Runtime<ul style="list-style-type: none"><li>Memory</li></ul></li><li>▼ Simulator<ul style="list-style-type: none"><li>Code Coverage</li><li>Com Port</li><li>Debug</li><li>Device</li><li>Heap Dumper</li><li>Logs</li></ul></li></ul></li></ul>	Specify target options
--	------------------------

**Category: Core Engine**

<ul style="list-style-type: none"><li>▼ Device<ul style="list-style-type: none"><li>▼ Core Engine<ul style="list-style-type: none"><li>Kernel</li><li>Watchdog</li><li>Deploy</li></ul></li><li>▼ Feature<ul style="list-style-type: none"><li>Dynamic Download</li></ul></li><li>▼ Libraries<ul style="list-style-type: none"><li>▼ ECOM<ul style="list-style-type: none"><li>Comm Connection</li><li>EDC</li><li>External Resources Loader</li><li>Shielded Plug</li></ul></li></ul></li><li>▼ Runtime<ul style="list-style-type: none"><li>Memory</li></ul></li><li>▼ Simulator<ul style="list-style-type: none"><li>Code Coverage</li><li>Com Port</li><li>Debug</li><li>Device</li><li>Heap Dumper</li><li>Logs</li></ul></li></ul></li></ul>	<div>Memory</div> <div>Maximum number of monitors per thread <input type="text"/></div> <div>Maximum number of frames dumped on OutOfMemoryError <input type="text"/></div>
--	---

**Group: Memory**

**Option(text):**

*Option Name:* `core.memory.thread.max.nb.monitors`

*Default value:* `8`

*Description:*

Specifies the maximum number of monitors a thread can own at the same time.

**Option(text):**

*Option Name:* `core.memory.oome.nb.frames`

*Default value:* `5`

*Description:*

Specifies the maximum number of stack frames that can be dumped to the standard output when Core Engine throws an OutOfMemoryError.

**Category: Kernel**

The screenshot shows the MicroEJ configuration window. On the left, a tree view shows the 'Kernel' category selected under 'Core Engine'. The right pane displays the following settings:

- ☐ Check APIs allowed by Kernel
- Threads**
  - Maximum number of threads per Feature:
- Installed Features**
  - Maximum number of installed Features:
  - Code Size (in bytes):
  - Runtime Size (in bytes):

**Option(checkbox): Check APIs allowed by Kernel**

*Option Name:* `apis.check.enable`

*Default value:* `true`

**Group: Threads****Option(text):**

*Option Name:* `core.memory.feature.max.threads`

*Default value:* `5`

*Description:*

Specifies the maximum number of threads a Feature is allowed to use at the same time.

**Group: Installed Features****Option(text):**

*Option Name:* `core.memory.installed.features.max`

*Default value:* `0`

*Description:*

Specifies the maximum number of installed Features that can be added to this Kernel.

**Option(text):**

*Option Name:* `core.memory.installed.features.text.size`

*Default value:* `0`

*Description:*

Specifies the size in bytes reserved for installed Features code.

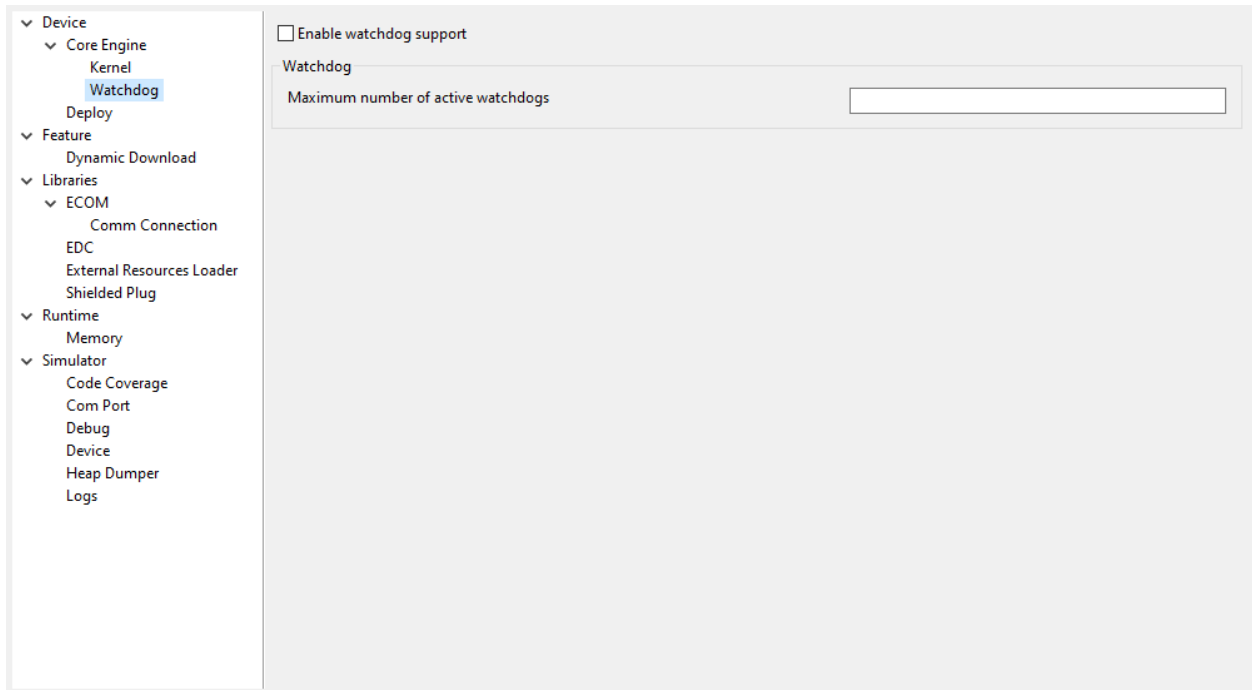
**Option(text):**

*Option Name:* `core.memory.installed.features.bss.size`

*Default value:* `0`

*Description:*

Specifies the size in bytes reserved for installed Features runtime memory.

**Category: Watchdog****Option(checkbox): Enable watchdog support**

*Option Name:* `enable.watchdog.support`

*Default value:* `true`

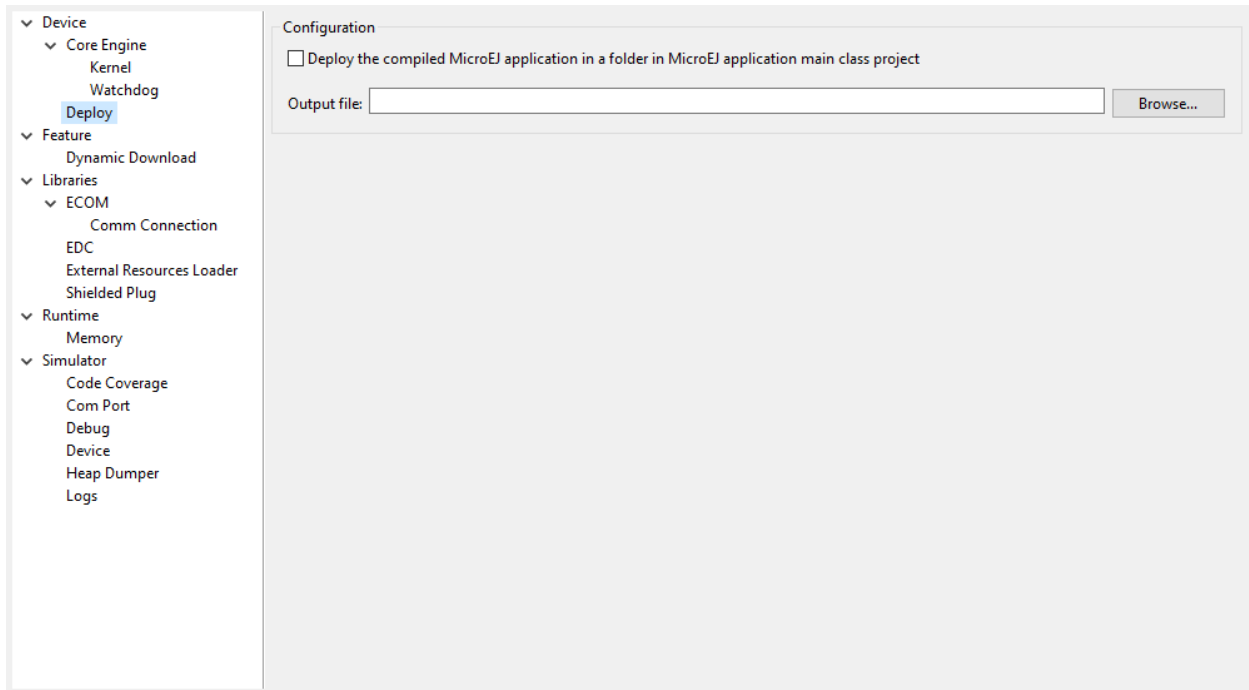
**Group: Watchdog****Option(text):**

*Option Name:* `maximum.active.watchdogs`

*Default value:* `4`

*Description:*

Specifies the maximum number of active watchdogs at the same time.

**Category: Deploy***Description:*

Configures the output location where store the MicroEJ Application, the MicroEJ platform libraries and header files.

**Group: Configuration**

**Option(checkbox): Deploy the compiled MicroEJ Application in a folder in MicroEJ Application main class project**

*Default value:* `true`

*Description:*

Deploy the compiled MicroEJ Application in a folder in MicroEJ Application's main class project.

**Option(browse): Output file**

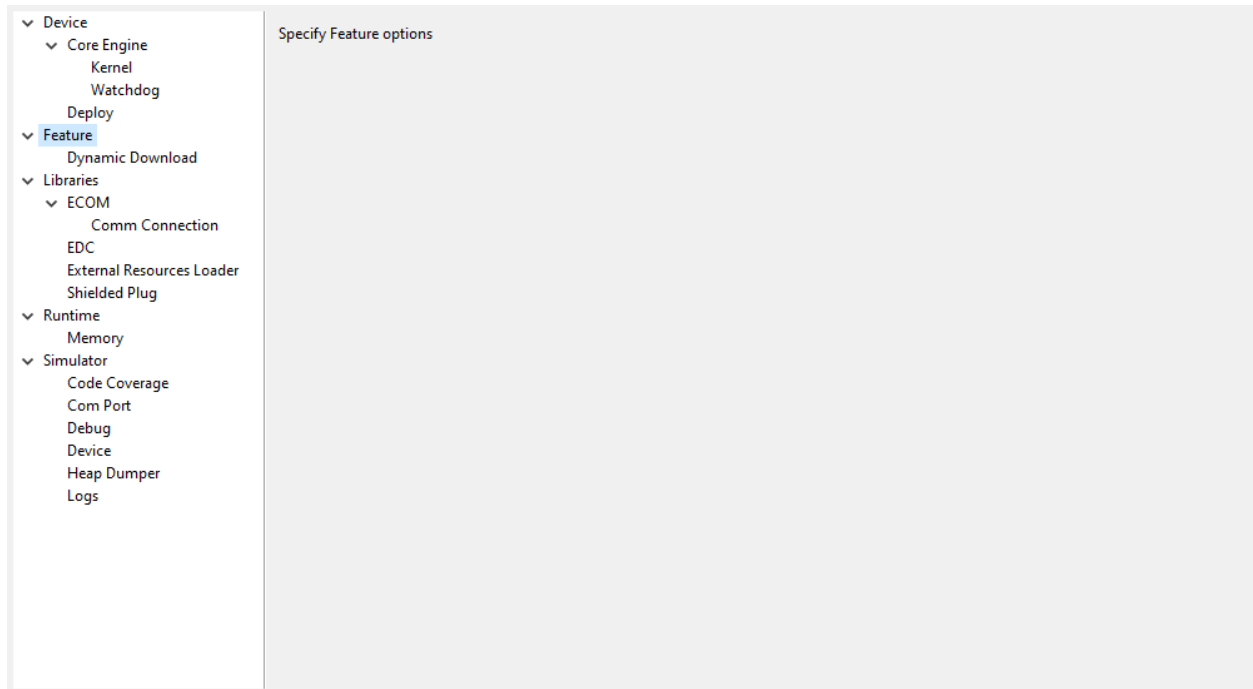
*Option Name:* `deploy.copy.filename`

*Default value:* `(empty)`

*Description:*

Choose an output file location where copy the compiled MicroEJ Application.



**Category: Feature***Description:*

Specify Feature options

**Category: Dynamic Download**
**Group: Dynamic Download****Option(text): Output Name**

*Option Name:* `feature.output.basename`

*Default value:* `application`

**Option(browse): Kernel**

*Option Name:* `kernel.filename`

*Default value:* `(empty)`

**3.4.5 SOAR**

SOAR complies with the deterministic class initialization ( `<clinit>` ) order specified in [\[BON\]](#). The application is statically analyzed from its entry points in order to generate a clinit dependency graph. The computed clinit sequence is the result of the topological sort of the dependency graph. An error is thrown if the clinit dependency graph contains cycles.

An explicit clinit dependency can be declared by creating an XML file with the `.clinitdesc` extension in the application classpath. The file has the following format:

```
<?xml version='1.0' encoding='UTF-8'?>
<clinit>
```

(continues on next page)

(continued from previous page)

```
<type name="T1" depends="T2"/>
</clinit>
```

where **T1** and **T2** are fully qualified names on the form **a.b.C**. This explicitly forces SOAR to create a dependency from **T1** to **T2**, and therefore cuts a potentially detected dependency from **T2** to **T1**.

A clinit map file (ending with extension **.clinitmap**) is generated beside the SOAR object file. It describes for each clinit dependency:

- the types involved
- the kind of dependency
- the stack calls between the two types

## 3.5 Sandboxed Application

### 3.5.1 Sandboxed Application Structure

#### Application Skeleton Creation

The first step to explore a Sandboxed Application structure is to create a new project.

First select **File** > **New** > **MicroEJ Sandboxed Application Project** :

Fill in the application template fields, the **Project name** field will automatically duplicate in the following fields.

A template project is automatically created and ready to use, this project already contains all folders wherein developers need to put content:

- src/main/java** Folder for future sources;
- src/main/resources** Folder for future resources (images, fonts etc.);
- META-INF** Sandboxed Application configuration and resources;
- module.ivy** Ivy input file, dependencies description for the current project.

#### Sources Folder

The project source folder (**src/main**) contains two subfolders: **java** and **resources**. **java** folder will contain all **\*.java** files of the project, whereas **resources** folder will contain elements that the application needs at runtime like raw resources, images or character fonts.

#### META-INF Folder

The **META-INF** folder contains several folders and a manifest file. They are described hereafter.

- certificate (folder)** Contains certificate information used during the application deployment.
- libraries (folder)** Contains a list of additional libraries useful to the application and not resolved through the regular transitive dependency check.
- properties (folder)** Contains an **application.properties** file which contains application specific properties that can be accessed at runtime.

**services (folder)** Contains a list of files that describe local services provided by the application. Each file name represents a service class fully qualified name, and each file contains the fully qualified name of the provided service implementation.

**wpk (folder)** Contains a set of applications ( **.wpk** files) that will be started when the application is executed on the Simulator.

**MANIFEST.MF (file)** Contains the information given at project creation, extra information can be added to this file to declare the entry points of the application.

#### module.ivy File

The **module.ivy** file describes all the libraries required by the application at runtime. The Ivy classpath container lists all the modules that have been automatically resolved from the content of **module.ivy**. See *MicroEJ Module Manager* for more informations about MicroEJ Module Manager.

### 3.5.2 Application Publication

#### Build the WPK

When the application is ready for deployment, the last step in MicroEJ Studio is to create the WPK (Wadapps Package) file that is intended to be published on a MicroEJ Forge instance for end users.

In MicroEJ Studio, right-click on the Sandboxed Application project name and select **Build Module**.

The WPK build process will display messages in MicroEJ console, ending up the following message:

```
[echo] project hello published locally with version 0.1.0-RC201907091602
BUILD SUCCESSFUL
Total time: 1 minute 6 seconds
```

#### Publish on a MicroEJ Forge Instance

The WPK file produced by the build process is located in a dedicated **target~/artifacts** folder in the project.

The **.wpk** file is ready to be uploaded to a MicroEJ Forge instance. Please consult <https://community.microej.com> for more information.

### 3.5.3 Shared Interfaces

#### Principle

The Shared Interface mechanism provided by MicroEJ Core Engine is an object communication bus based on plain Java interfaces where method calls are allowed to cross MicroEJ Sandboxed Applications boundaries. The Shared Interface mechanism is the cornerstone for designing reliable Service Oriented Architectures on top of MicroEJ. Communication is based on the sharing of interfaces defining APIs (Contract Oriented Programming).

The basic schema:

- A provider application publishes an implementation for a shared interface into a system registry.
- A user application retrieves the implementation from the system registry and directly calls the methods defined by the shared interface.

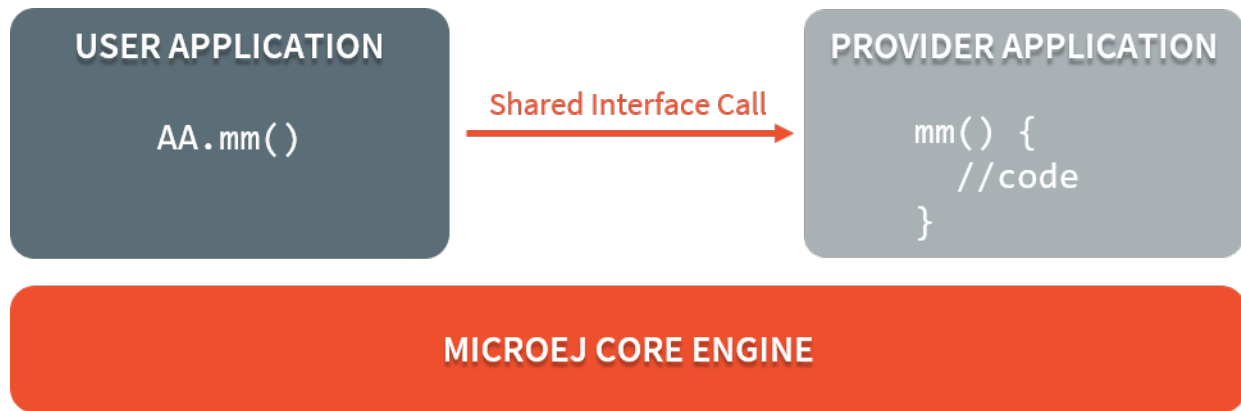


Fig. 19: Shared Interface Call Mechanism

### Shared Interface Creation

Creation of a shared interface follows three steps:

- Interface definition,
- Proxy implementation,
- Interface registration.

### Interface Definition

The definition of a shared interface starts by defining a standard Java interface.

```
package mypackage;
public interface MyInterface{
    void foo();
}
```

To declare an interface as a shared interface, it must be registered in a shared interfaces identification file. A shared interface identification file is an XML file with the `.si` suffix with the following format:

```
<sharedInterfaces>
  <sharedInterface name="mypackage.MyInterface"/>
</sharedInterfaces>
```

Shared interface identification files must be placed at the root of a path of the application classpath. For a MicroEJ Sandboxed Application project, it is typically placed in `src/main/resources` folder.

Some restrictions apply to shared interface compared to standard java interfaces:

- Types for parameters and return values must be transferable types;
- Thrown exceptions must be classes owned by the MicroEJ Firmware.

### Transferable Types

In the process of a cross-application method call, parameters and return value of methods declared in a shared interface must be transferred back and forth between application boundaries.



Fig. 20: Shared Interface Parameters Transfer

*Shared Interface Types Transfer Rules* describes the rules applied depending on the element to be transferred.

Table 1: Shared Interface Types Transfer Rules

Type	Owner	Instance Owner	Rule
Base type	N/A	N/A	Passing by value. ( <code>boolean</code> , <code>byte</code> , <code>short</code> , <code>char</code> , <code>int</code> , <code>long</code> , <code>double</code> , <code>float</code> )
Any Class, Array or Interface	Kernel	Kernel	Passing by reference
Any Class, Array or Interface	Kernel	Application	Kernel specific or forbidden
Array of base types	Any	Application	Clone by copy
Arrays of references	Any	Application	Clone and transfer rules applied again on each element
Shared Interface	Application	Application	Passing by indirect reference (Proxy creation)
Any Class, Array or Interface	Application	Application	Forbidden

Objects created by an application which class is owned by the Kernel can be transferred to another application if this has been authorized by the Kernel. The list of eligible types that can be transferred is Kernel specific, so you have to consult the firmware specification. *MicroEJ Evaluation Firmware Example of Transfer Types* lists Kernel types allowed to be transferred through a shared interface call. When an argument transfer is forbidden, the call is abruptly stopped and a `java.lang.IllegalAccessError` is thrown by MicroEJ Core Engine.

Table 2: MicroEJ Evaluation Firmware Example of Transfer Types

Type	Rule
<code>java.lang.String</code>	Clone by copy
<code>java.io.InputStream</code>	Proxy reference creation
<code>java.util.Map&lt;String,String&gt;</code>	Clone by deep copy

### Proxy Class Implementation

The Shared Interface mechanism is based on automatic proxy objects created by the underlying MicroEJ Core Engine, so that each application can still be dynamically stopped and uninstalled. This offers a reliable way for users and providers to handle the relationship in case of a broken link.

Once a Java interface has been declared as Shared Interface, a dedicated implementation is required (called the Proxy class implementation). Its main goal is to perform the remote invocation and provide a reliable implemen-

tation regarding the interface contract even if the remote application fails to fulfill its contract (unexpected exceptions, application killed...). The MicroEJ Core Engine will allocate instances of this class when an implementation owned by another application is being transferred to this application.

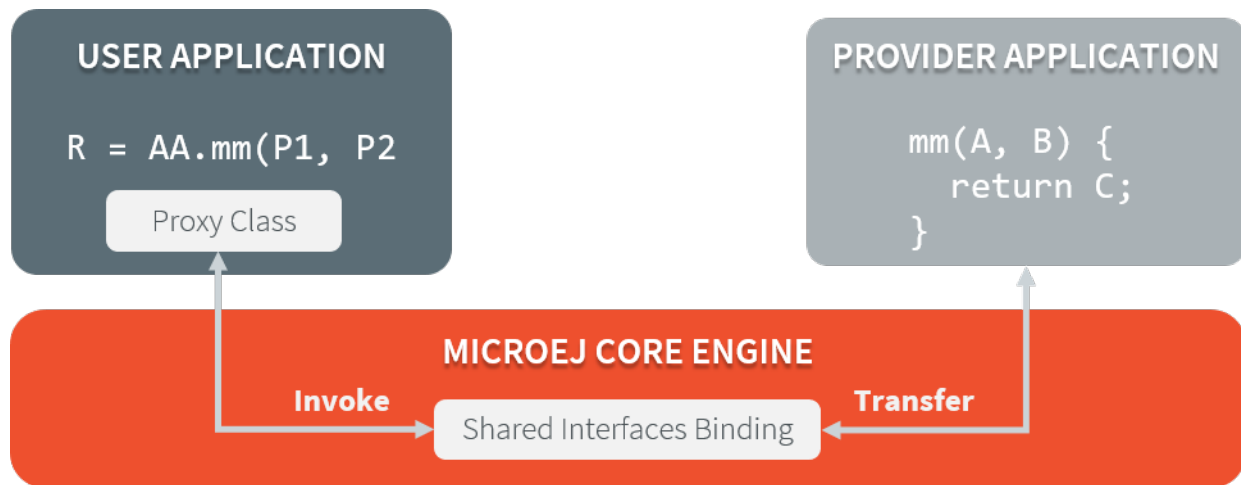


Fig. 21: Shared Interfaces Proxy Overview

A proxy class is implemented and executed on the client side, each method of the implemented interface must be defined according to the following pattern:

```

package mypackage;

public class MyInterfaceProxy extends Proxy<MyInterface> implements MyInterface {

    @Override
    public void foo(){
        try {
            invoke(); // perform remote invocation
        } catch (Throwable e) {
            e.printStackTrace();
        }
    }
}

```

Each implemented method of the proxy class is responsible for performing the remote call and catching all errors from the server side and to provide an appropriate answer to the client application call according to the interface method specification (contract). Remote invocation methods are defined in the super class `ej.kf.Proxy` and are named `invokeXXX()` where `XXX` is the kind of return type. As this class is part of the application, the application developer has the full control on the Proxy implementation and is free to insert additional code such as logging calls and errors for example.

Table 3: Proxy Remote Invocation Built-in Methods

Invocation Method	Usage
<code>void invoke()</code>	Remote invocation for a proxy method that returns void
<code>Object invokeRef()</code>	Remote invocation for a proxy method that returns a reference
<code>boolean invokeBoolean()</code> , <code>byte invokeByte()</code> , <code>char invokeChar()</code> , <code>short invokeShort()</code> , <code>int invokeInt()</code> , <code>long invokeLong()</code> , <code>double invokeDouble()</code> , <code>float invokeFloat()</code>	Remote invocation for a proxy method that returns a base type

## 3.6 Virtual Device

### 3.6.1 Using a Virtual Device for Simulation

The Virtual Device includes the same custom MicroEJ Core, libraries and System Applications as the real device. The Virtual Device allows developers to run their applications either on the Simulator, or directly on the real device through local deployment.

The Simulator runs a mockup board support package (BSP Mock) that mimics the hardware functionality. An application on the Simulator is run as a Standalone Application.

Before an application is locally deployed on device, MicroEJ Studio ensures that it does not depend on any API that is unavailable on the device.

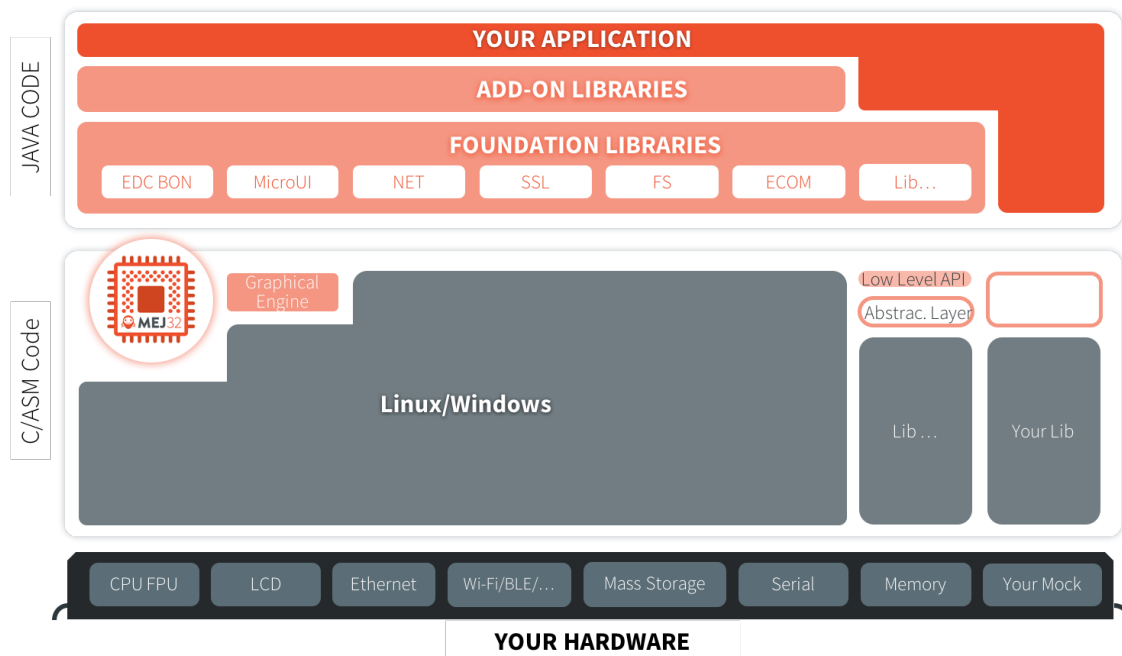


Fig. 22: MicroEJ Virtual Device Architecture

### 3.6.2 Runtime Environment

The set of MicroEJ APIs exposed by a Virtual Device (and therefore provided by its associated firmware) is documented in Javadoc format in the MicroEJ Resource Center ([Window](#) > [Show View](#) > [MicroEJ Resource Center](#)).



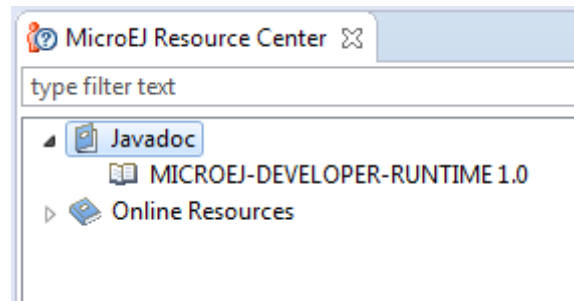


Fig. 23: MicroEJ Resource Center APIs

## 3.7 MicroEJ Module Manager

### 3.7.1 Introduction

Modern electronic device design involves many parts and teams to collaborate to finally obtain a product to be sold on its market. MicroEJ encourages modular design which involves various stake holders: hardware engineers, UX designers, graphic designers, drivers/BSP engineers, software engineers, etc.

Modular design is a design technique that emphasizes separating the functionality of an application into independent, interchangeable modules. Each module contains everything necessary to execute only one aspect of the desired functionality. In order to have team members collaborate internally within their team and with other teams, MicroEJ provides a powerful modular design concept, with smart module dependencies, controlled by the MicroEJ Module Manager (MMM). MMM frees engineers from the difficult task of computing module dependencies. Engineers specify the bare minimum description of the module requirements.

The following schema introduces the main concepts detailed in this chapter.

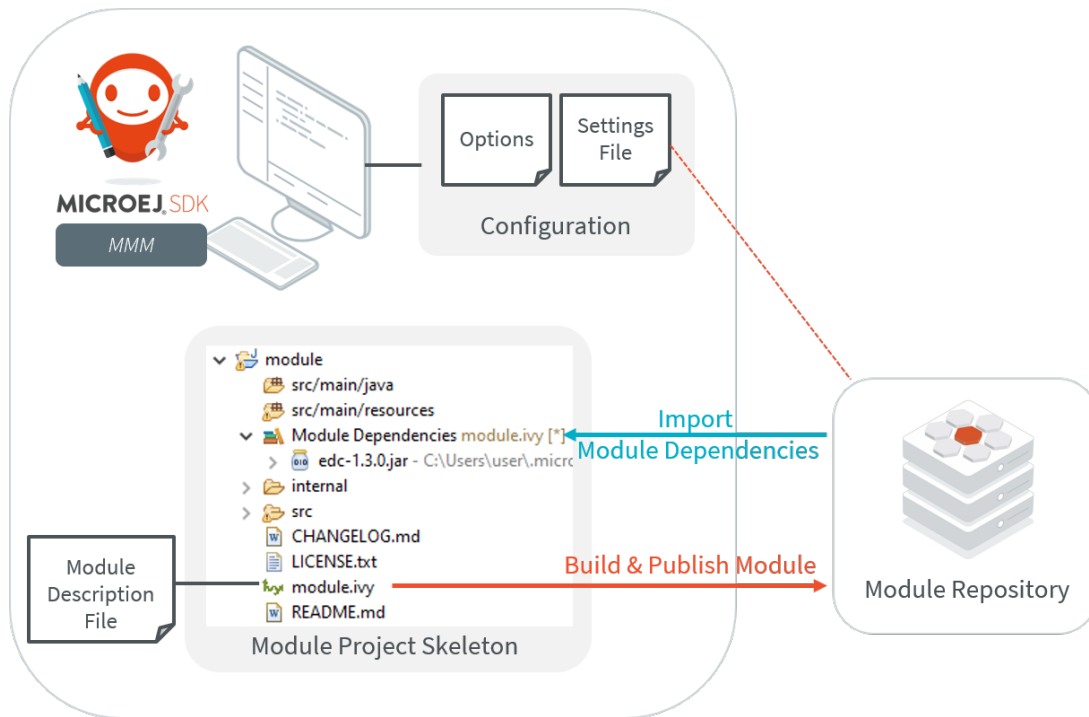


Fig. 24: MMM Overview

MMM is based on the following tools:

- Apache Ivy (<http://ant.apache.org/ivy>) for dependencies resolution and module publication;
- Apache EasyAnt (<https://ant.apache.org/easyant/history/trunk/reference.html>) for module build from source code.

### 3.7.2 Specification

MMM provides a non ambiguous semantic for dependencies resolution. Please consult the MMM specification available on <https://developer.microej.com/packages/documentation/TLT-0831-SPE-MicroEJModuleManager-2.0-D.pdf>.

#### 3.7.3 Module Project Skeleton

In MicroEJ SDK, a new MicroEJ module project is created as following:

- Select **File** > **New** > **Project...** ,
- Select **MicroEJ** > **MicroEJ Module Project** <sup>1</sup>,
- Fill the module information (project name, module organization, name and revision),
- Select one of the suggested skeletons depending on the desired *module nature*,
- Click on **Finish** .

<sup>1</sup> If using MicroEJ SDK versions lower than 5.2.0 , please refer to the *following section*.

The project is created and a set of files and directories are generated from the selected skeleton.

**Note:** When an empty Eclipse project already exists or when the skeleton has to be created within an existing directory, the MicroEJ module is created as following:

- In the *Package Explorer*, click on the parent project or directory,
- Select **File** > **New** > **Other...** ,
- Select **EasyAnt** > **EasyAnt Skeleton** .

### 3.7.4 Module Description File

A module description file is an Ivy configuration file named `module.ivy`, located at the root of each MicroEJ module project. It describes the *module nature* (also called build type) and dependencies to other modules.

```
<ivy-module version="2.0" xmlns:ea="http://www.easyant.org" xmlns:m="http://ant.apache.org/ivy/extra"
            xmlns:ej="https://developer.microej.com" ej:version="2.0.0">
  <info organisation="[organisation]" module="[name]" status="integration" revision="[version]">
    <ea:build organisation="com.is2t.easyant.buildtypes" module="[buildtype_name]" revision=
    ↪ "[buildtype_version]">
      <ea:property name="[buildoption_name]" value="[buildoption_value]" />
    </ea:build>
  </info>

  <configurations defaultconfmapping="default->default;provided->provided">
    <conf name="default" visibility="public" />
    <conf name="provided" visibility="public" />
    <conf name="documentation" visibility="public" />
    <conf name="source" visibility="public" />
    <conf name="dist" visibility="public" />
    <conf name="test" visibility="private" />
  </configurations>

  <publications>
</publications>

  <dependencies>
    <dependency org="[dep_organisation]" name="[dep_name]" rev="[dep_version]" />
  </dependencies>
</ivy-module>
```

### 3.7.5 MicroEJ Module Manager Configuration

By default, when starting an empty workspace, MicroEJ SDK is configured to import dependencies from *MicroEJ Central Repository* and to publish built modules to a local folder. The repository configuration is stored in a *settings file* ( `ivysettings.xml` ), and the default one is located at `$USER_HOME\.microej\microej-ivysettings-[VERSION].xml`

#### Preferences Page

The MMM preferences page is available at **Window** > **Preferences** > **MicroEJ** > **Module Manager** <sup>1</sup>.

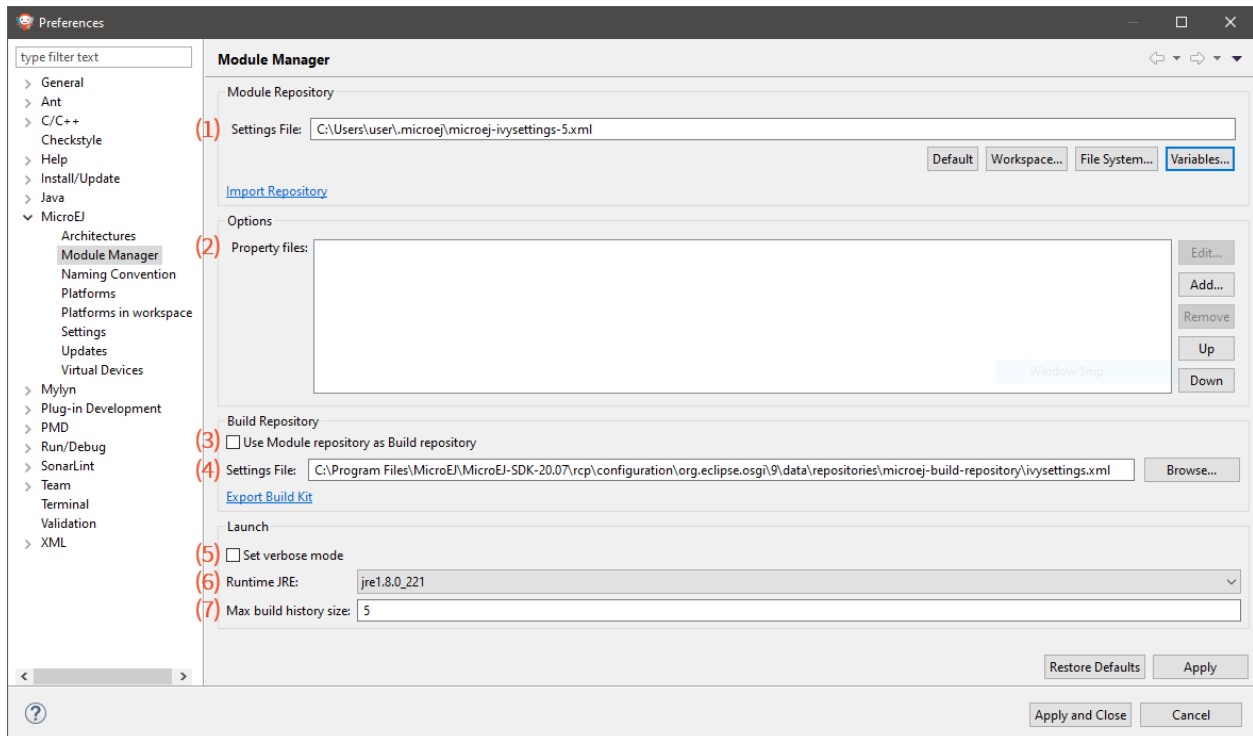
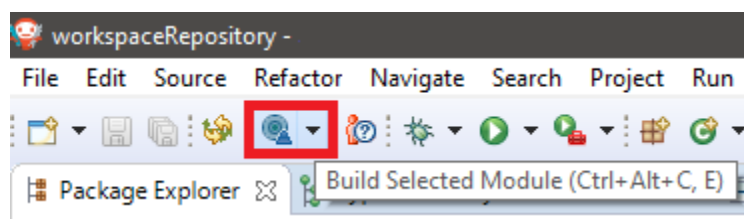


Fig. 25: MMM Preferences Page

This page allows to configure the following elements:

1. **Settings File** : the file describing how to connect *module repositories*. See the *settings file* section.
2. **Options** : files declaring MMM options. See the *Options* section.
3. **Use Module repository as Build repository** : the *settings file* for connecting the build repository in place of the one bundled in MicroEJ SDK. This option shall not be enabled by default and is reserved for advanced configuration.
4. **Build repository Settings File** : the *settings file* for connecting the build repository in place of the one bundled in MicroEJ SDK. This option is automatically initialized the first time MicroEJ SDK is launched. It shall not be modified by default and is reserved for advanced configuration.
5. **Set verbose mode** : to enable advanced debug traces when building a module.
6. **Runtime JRE** : the Java Runtime Environment that executes the build process.
7. **Max build history size** : the maximum number of previous builds available in **Build Module** shortcut list:



## Settings File

The settings file is an XML file that describes how MMM connects local or online *module repositories*. The file format is described in [Apache Ivy documentation](#).

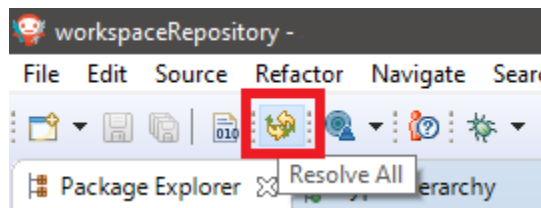
To configure MMM to a custom settings file (usually from an *offline repository*):

1. Set **Settings file** to a custom `ivysettings.xml` settings file<sup>1</sup>,
2. Click on **Apply and Close** button

If the workspace is not empty, it is recommended to trigger a full resolution and rebuild all the projects using this new repository configuration:

1. Clean caches
  - In the Package Explorer, right-click on a project;
  - Select **Ivy** > **Clean all caches** .
2. Resolve projects using the new repository

To resolve all the workspace projects, click on the **Resolve All** button in the toolbar:



To only resolve a subset of the workspace projects:

- In the Package Explorer, select the desired projects,
  - Right-click on a project and select **Ivy** > **Clean all caches** .
3. Trigger Add-On Library processors for automatically generated source code
    - Select **Project** > **Clean...** ,
    - Select **Clean all projects** ,
    - Click on **Clean** button.

## Options

Options can be used to parameterize a *module description file* or a *settings file*. Options are declared as key/value pairs in a *standard Java properties file*, and are expanded using the `${my_property}` notation.

A typical usage in a *settings file* is for extracting repository server credentials, such as HTTP Basic access authentication:

1. Declare options in a properties file

```

credentials.properties
1 # User specific credentials
2 artifactory.username=myusername
3 artifactory.password=AKCKLzp2JHRLDyFvmTPMXocXiiU1Cna47ei9UcC9iE65UdgJrJu24ZTYieX9CwwMa3WYkjCD9
4

```

2. Register this property file to MMM options

```

Options
Property files: ${workspace_loc:test/credentials.properties}

```

3. Use this option in a *settings file*

```

38
39 <credentials host="artifactory.corp" realm="Artifactory Realm" username="${artifactory.username}" passwd="${artifactory.password}" />
40

```

A typical usage in a *module description file* is for factorizing dependency versions across multiple modules projects:

1. Declare an option in a properties file

```

versions.properties
1 # Specify the EDC version used in this workspace
2 edc.version=1.3.0
3

```

2. Register this property file to MMM options

```

Options
Property files: ${workspace_loc:test/versions.properties}

```

3. Use this option in a *module description file*

```

22 <dependencies>
23   <!--
24     Use the EDC version defined by MMM configuration
25   -->
26   <dependency org="ej.api" name="edc" rev="${edc.version}" />
27 </dependencies>
28 </ivy-module>

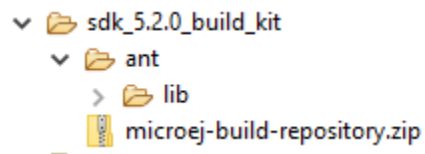
```

### 3.7.6 Build Kit

The Module Manager build kit is the consistent set of tools and scripts required for building modules. It is bundled with MicroEJ SDK and can be exported to run in headless mode using the following steps:<sup>1</sup>

- Select **File** > **Export** > **MicroEJ** > **Module Manager Build Kit** ,
- Choose an empty **Target directory** ,
- Click on the **Finish** button.

Once the build kit is fully exported, the directory content shall look like:



To go further with headless builds, please consult [Tool-CommandLineBuild](#) for command line builds, and this tutorial to setup MicroEJ modules build in continuous integration environments).

### 3.7.7 Former MicroEJ SDK Versions

This section describes MMM configuration elements for MicroEJ SDK versions lower than 5.2.0.

#### New MicroEJ Module Project

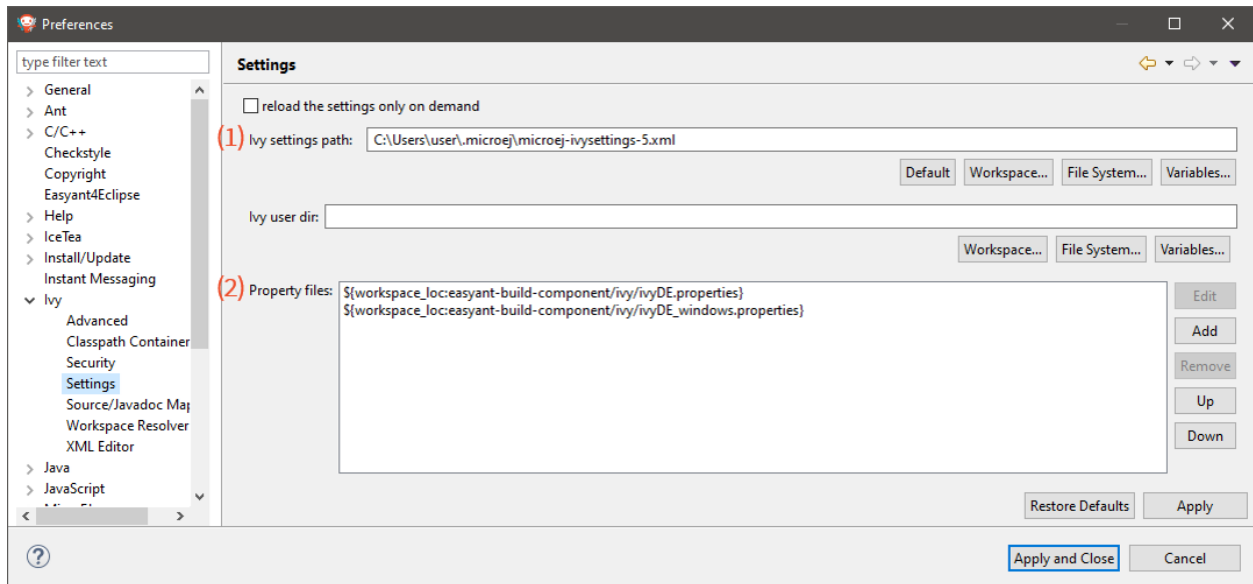
The New MicroEJ Module Project wizard is available at **File** > **New** > **Project...** , **EasyAnt** > **EasyAnt Project** .

#### Preferences Pages

MMM Preferences Pages are located in two dedicated pages. The following pictures show the options mapping using the same options numbers declared in [Preferences Page](#).

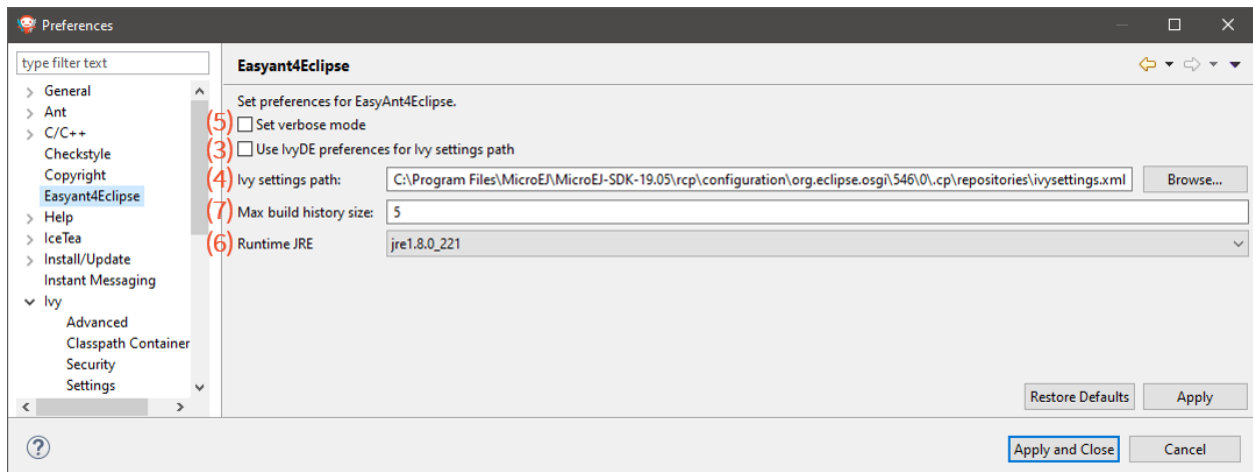
#### Ivy Preferences Page

The Ivy Preferences Page is available at **Window** > **Preferences** > **Ivy** > **Settings** .



## Easyant Preferences Page

The Easyant Preferences Page is available at **Window** > **Preferences** > **EasyAnt4Eclipse**.



## Export the Build Kit

- Create an empty directory (e.g. `mmm_sdk_[version]_build_kit`),
- Locate your SDK installation plugins directory (by default, `C:\Program Files\MicroEJ\MicroEJ SDK-[version]\rcp\plugins` on Windows OS),
- Open the file `com.is2t.eclipse.plugin.easyant4e_[version].jar` with an archive manager,
- Extract the directory `lib` to the target directory,
- Open the file `com.is2t.eclipse.plugin.easyant4e.offlinerepo_[version].jar` with an archive manager,
- Navigate to directory `repositories`,



- Extract the file named `microej-build-repository.zip` for MicroEJ SDK 5.x or `is2t_repo.zip` for MicroEJ SDK 4.1.x to the target directory.

## 3.8 Module Natures

The following table describes the *project skeleton* name for most common MicroEJ Module Natures.

Table 4: MicroEJ Module Natures Summary

Module Nature	Skeleton Name	Direct Wizard
Add-On Library	<i>microej-javalib</i>	File > New > MicroEJ Add-On Library Project
<i>Module Repository</i>	<i>artifact-repository</i>	
<i>Standalone Application</i>	<i>firmware-singleapp</i>	File > New > MicroEJ Standalone Application Project
<i>Sandboxed Application</i>	<i>application</i>	File > New > MicroEJ Sandboxed Application Project

### 3.8.1 Module Repository

A module repository is a module that bundles a set of modules in a portable ZIP file. It is a tree structure where modules organizations and names are mapped to folders.



Fig. 26: Example of MicroEJ Module Repository Tree

A module repository takes its input modules from other repositories, usually the *MicroEJ Central Repository* which is itself built by MicroEJ Corp. as a module repository.

A module repository is often called an offline repository as it includes the settings file for a local configuration in MicroEJ SDK. It can also be imported in [MicroEJ Forge](#).

## Create a Repository Project

In MicroEJ SDK, first create a new *module project* using the *artifact-repository* skeleton.

- The *ivysettings.xml settings file* describes how to import the modules of this repository when it is extracted locally on file system. This file will be packaged at the root of the zip file and does not need to be modified.
- The *module.ivy* file describes how to build repository and lists the module dependencies that will be included in this repository.

## Configure Resolver for Input Modules

MicroEJ Module Manager (MMM) needs to import dependencies to build the module repository. The location fetched by MMM is defined by a resolver. The resolver is configured with the parameter *bar.populate.from.resolver*. The preset value is the resolver provided by default in MicroEJ SDK configuration, which is connected to *MicroEJ Central Repository*.

```
<ea:property name="bar.populate.from.resolver" value="MicroEJChainResolver"/>
```

The *MicroEJChainResolver* is a URL resolver defined in *\$USER\_HOME\microej\microej-ivysettings-[VERSION].xml* that points to MicroEJ Central Repository.

To ensure the repository will be compliant with the *MMM specification*, add the following option:

```
<ea:property name="bar.check.as.v2.module" value="true"/>
```

There are other advanced options that do not need to be modified by default. These options are described in the *module.ivy* generated by the skeleton.

## Include Modules

Modules bundled into the module repository must be declared in the *dependencies* element of the *module.ivy* file.

## Include a Single Module

To add a module, declare the module dependency using the *artifacts* configuration:

```
<dependencies>
  <dependency conf="artifacts->*" transitive="false" org="[module_org]" name="[module_name]" rev=
    "[module_version]" />

  <!-- ... other dependencies ... -->
</dependencies>
```

For example, to add the *ej.api.edc* library version *1.2.3*, write the following line:

```
<dependency conf="artifacts->*" transitive="false" org="ej.api" name="edc" rev="1.2.3" />
```

**Note:** We recommended to manually describe each dependency of the module repository, in order to keep full control of the included modules as well as included modules versions. Module dependencies can still be transitively included by setting the dependency attribute `transitive` to `true`. In this case, the included module versions are those that have been resolved when the module was built.

Multiple versions of the same module can be included by declaring each dependency using a different configuration. The `artifacts` configuration has to be derived with a new name as many times as there are different versions to include.

```
<configurations defaultconfmapping="default->default;provided->provided">
  <conf name="artifacts" visibility="private"/>
  <conf name="artifacts_1" visibility="private"/>
  <conf name="artifacts_2" visibility="private"/>

  <!-- ... other configurations ... -->
</configurations>

<dependencies>
  <dependency conf="artifacts->*" transitive="false" org="[module_org]" name="[module_name]" rev=
    ↪ "[module_version_1]" />
  <dependency conf="artifacts_1->*" transitive="false" org="[module_org]" name="[module_name]" rev=
    ↪ "[module_version_2]" />
  <dependency conf="artifacts_2->*" transitive="false" org="[module_org]" name="[module_name]" rev=
    ↪ "[module_version_3]" />

  <!-- ... other dependencies ... -->
</dependencies>
```

### Include a Module Repository

To add all the modules already included in an other module repository, declare the module repository dependency using the `repository` configuration:

```
<dependencies>
  <dependency conf="repository->*" transitive="false" org="[repository_org]" name="[repository_name]"_
    ↪ rev="[repository_version]" />

  <!-- ... other dependencies ... -->
</dependencies>
```

### Build the Repository

In the Package Explorer, right-click on the repository project and select **Build Module**.

The build consists of two steps:

1. Gathers all module dependencies. The whole repository content is created under `target~/mergedArtifactsRepository` folder.
2. Checks the repository consistency. For each module, it tries to import it from this repository and fails the build if at least one of the dependencies cannot be resolved.

The module repository `.zip` file is built in the `target~/artifacts/` folder. This file may be published along with a `CHANGELOG.md`, `LICENSE.txt` and `README.md`.

## Use the Offline Repository

By default, when starting an empty workspace, MicroEJ SDK is configured to import dependencies from *MicroEJ Central Repository*.

To configure MicroEJ SDK to import dependencies from a local module repository:

1. Unzip the module repository *.zip* file to the folder of your choice,
2. *Configure MMM settings file* using the *ivysettings.xml* file located at the root of the folder where the repository has been extracted.

## 3.9 MicroEJ Classpath

MicroEJ Applications run on a target device and their footprint is optimized to fulfill embedded constraints. The final execution context is an embedded device that may not even have a file system. Files required by the application at runtime are not directly copied to the target device, they are compiled to produce the application binary code which will be executed by MicroEJ Core Engine.

As a part of the compile-time trimming process, all types not required by the embedded application are eliminated from the final binary.

MicroEJ Classpath is a developer defined list of all places containing files to be embedded in the final application binary. MicroEJ Classpath is made up of an ordered list of paths. A path is either a folder or a zip file, called a JAR file (JAR stands for Java ARchive).

- *Application Classpath* explains how the MicroEJ Classpath is built from a MicroEJ Application project.
- *Classpath Load Model* explains how the application contents is loaded from MicroEJ Classpath.
- *Classpath Elements* specifies the different elements that can be declared in MicroEJ Classpath to describe the application contents.

### 3.9.1 Application Classpath

The following schema shows the classpath mapping from a MicroEJ Application project to the MicroEJ Classpath ordered list of folders and JAR files. The classpath resolution order (left to right) follows the project appearance order (top to bottom).



Fig. 27: MicroEJ Application Classpath Mapping

### 3.9.2 Classpath Load Model

A MicroEJ Application classpath is created via the loading of :

- an entry point type,
- all `*.[extension].list` files declared in a MicroEJ Classpath.

The different elements that constitute an application are described in *Classpath Elements*. They are searched within MicroEJ Classpath from left to right (the first file found is loaded). Types referenced by previously loaded MicroEJ Classpath elements are loaded transitively.



Fig. 28: Classpath Load Principle

### 3.9.3 Classpath Elements

The MicroEJ Classpath contains the following elements:

- An entrypoint described in section *Application Entry Points*;
- Types in `.class` files, described in section *Types*;
- Raw resources, described in section *Raw Resources*;
- Immutable Object data files, described in Section *Immutable Objects*;
- Images and Fonts resources;
- `*.[extension].list` files, declaring contents to load. Supported list file extensions and format is specific to declared application contents and is described in the appropriate section.

At source level, Java types are stored in `src/main/java` folder of the **module project**, any other kind of resources and list files are stored in the `src/main/resources` folder.

#### Application Entry Points

MicroEJ Application entry point declaration differs depending on the application kind:

- In case of a MicroEJ Standalone Application, it is a class that contains a `public static void main(String[])` method, declared using the option `application.main.class`.

- In case of a MicroEJ Sandboxed Application, it is a class that implements `ej.kf.FeatureEntryPoint`, declared in the `Application-EntryPoint` entry in `META-INF/MANIFEST.MF` file.

## Types

MicroEJ types (classes, interfaces) are compiled from source code ( `.java` ) to classfiles ( `.class` ). When a type is loaded, all types dependencies found in the classfile are loaded (transitively).

A type can be declared as a *Required type* in order to enable the following usages:

- to be dynamically loaded from its name (with a call to `Class.forName(String)` );
- to retrieve its fully qualified name (with a call to `Class.getName()` ).

A type that is not declared as a *Required type* may not have its fully qualified name (FQN) embedded. Its FQN can be retrieved using the stack trace reader tool (see *Stack Trace Reader*).

Required Types are declared in MicroEJ Classpath using `*.types.list` files. The file format is a standard Java properties file, each line listing the fully qualified name of a type. Example:

```
# The following types are marked as MicroEJ Required Types
com.mycompany.MyImplementation
java.util.Vector
```

## Raw Resources

Raw resources are binary files that need to be embedded by the application so that they may be dynamically retrieved with a call to `Class.getResourceAsStream(java.io.InputStream)` . Raw Resources are declared in MicroEJ Classpath using `*.resources.list` files. The file format is a standard Java properties file, each line is a relative `/` separated name of a file in MicroEJ Classpath to be embedded as a resource. Example:

```
# The following resource is embedded as a raw resource
com/mycompany/MyResource.txt
```

## Immutable Objects

Immutable objects are regular read-only objects that can be retrieved with a call to `ej.bon.Immutables.get(String)` . Immutable objects are declared in files called *immutable objects data files*, which format is described in the *[BON] specification*. Immutable objects data files are declared in MicroEJ Classpath using `*.immutables.list` files. The file format is a standard Java properties file, each line is a `/` separated name of a relative file in MicroEJ Classpath to be loaded as an Immutable objects data file. Example:

```
# The following file is loaded as an Immutable objects data files
com/mycompany/MyImmutables.data
```

## System Properties

System Properties are key/value string pairs that can be accessed with a call to `System.getProperty(String)` . System properties are declared in MicroEJ Classpath `*.properties.list` files. The file format is a standard Java properties file. Example:



Listing 1: Example of Contents of a MicroEJ Properties File

```
# The following property is embedded as a System property
com.mycompany.key=com.mycompany.value
microedition.encoding=ISO-8859-1
```

System Properties are resolved at runtime, and all declared keys and values are embedded as intern Strings.

System Properties can also be defined using Applications Options. This can be done by setting the option with a specific prefix in their name:

- Properties for both the MicroEJ Core Engine and the MicroEJ Simulator : name starts with `microej.java.property.*`
- Properties for the MicroEJ Simulator : name starts with `sim.java.property.*`
- Properties for the MicroEJ Core Engine : name starts with `emb.java.property.*`

For example, to define the property `myProp` with the value `theValue` , set the following option :

Listing 2: Example of MicroEJ Property Definition in Launch Configuration

```
microej.java.property.myProp=theValue
```

Option can also be set in the `VM arguments` field of the `JRE` tab of the launch using the -D option (e.g. `-Dmicroej.java.property.myProp=theValue` ).

## Constants

**Note:** This feature require `[BON]` version `1.4` which is available in MicroEJ Runtime starting from MicroEJ Architecture version `7.11.0` .

Constants are key/value string pairs that can be accessed with a call to `ej.bon.Constants.get[Type](String)` , where `Type` if one of:

- Boolean,
- Byte,
- Char,
- Class,
- Double,
- Float,
- Int,
- Long,
- Short,
- String.

Constants are declared in MicroEJ Classpath `*.constants.list` files. The file format is a standard Java properties file. Example:

Listing 3: Example of Contents of a BON constants File

```
# The following property is embedded as a constant
com.mycompany.myconstantkey=com.mycompany.myconstantvalue
```

Constants are resolved at binary level without having to recompile the sources.

At link time, constants are directly inlined at the place of `Constants.get[Type]` method calls with no cost.

The String key parameter must be resolved as an inlined String:

- either a String literal `"com.mycompany.myconstantkey"`
- or a `static final String` field resolved as a String constant

The String value is converted to the desired type using conversion rules described by the [\[BON\]](#) API.

A boolean constant declared in an `if` statement condition can be used to fully remove portions of code. This feature is similar to C pre-processors `#ifdef` directive with the difference that this optimization is performed at binary level without having to recompile the sources.

Listing 4: Example of `if` code removal using a BON boolean constant

```
if (Constants.getBoolean("com.mycompany.myconstantkey")) {
    System.out.println("this code and the constant string will be fully removed when the constant is_
↳ resolved to 'false'")
}
```

**Note:** In *Multi-Sandbox* environment, constants are processed locally within each context. In particular, constants defined in the Kernel are not propagated to *Sandboxed Applications*.

## Images

### Overview

Images are graphical resources that can be accessed with a call to `ej.microui.display.Image.createImage()`. To be displayed, these images have to be converted from their source format to the display raw format. The conversion can either be done at :

- build-time (using the image generator tool),
- run-time (using the relevant decoder library).

Images that must be processed by the image generator tool are declared in MicroEJ Classpath `*.images.list` files. The file format is a standard Java properties file, each line representing a `/` separated resource path relative to the MicroEJ classpath root referring to a standard image file (e.g. `.png`, `.jpg`). The resource may be followed by an optional parameter (separated by a `:`) which defines and/or describes the image output file format (raw format). When no option is specified, the image is embedded as-is and will be decoded at run-time (although listing files without format specifier has no impact on the image generator processing, it is advised to specify them in the `*.images.list` files anyway, as it makes the run-time processing behavior explicit). Example:

```
# The following image is embedded
# as a PNG resource (decoded at run-time)
com/mycompany/MyImage1.png
```

(continues on next page)

(continued from previous page)

```
# The following image is embedded
# as a 16 bits format without transparency (decoded at build-time)
com/mycompany/MyImage2.png:RGB565

# The following image is embedded
# as a 16 bits format with transparency (decoded at build-time)
com/mycompany/MyImage3.png:ARGB1555
```

## Output Formats

### No Compression

When no output format is set in the images list file, the image is embedded without any conversion / compression. This allows you to embed the resource as well, in order to keep the source image characteristics (compression, bpp etc.). This option produces the same result as specifying an image as a resource in the MicroEJ launcher.

Advantages:

- Preserves the image characteristics.

Disadvantages:

- Requires an image runtime decoder;
- Requires some RAM in which to store the decoded image.

```
image1
```

### Display Output Format

This format encodes the image into the exact display memory representation. If the image to encode contains some transparent pixels, the output file will embed the transparency according to the display's implementation capacity. When all pixels are fully opaque, no extra information will be stored in the output file in order to free up some memory space.

Advantages:

- Drawing an image is very fast;
- Supports alpha encoding.

Disadvantages:

- No compression: the image size in bytes is proportional to the number of pixels.

```
image1:display
```

### Generic Output Formats

Depending on the target hardware, several generic output formats are available. Some formats may be directly managed by the BSP display driver. Refer to the platform specification to retrieve the list of natively supported formats.

Advantages:

- The pixels layout and bits format are standard, so it is easy to manipulate these images on the C-side;
- Drawing an image is very fast when the display driver recognizes the format (with or without transparency);
- Supports or not the alpha encoding: select the most suitable format for the image to encode.

Disadvantages:

- No compression: the image size in bytes is proportional to the number of pixels, the transparency, and the bits-per-pixel.

Select one the following format to use a generic format:

- ARGB8888: 32 bits format, 8 bits for transparency, 8 per color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return c;
}
```

- RGB888: 24 bits format, 8 per color. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return c & 0xffffff;
}
```

- ARGB4444: 16 bits format, 4 bits for transparency, 4 per color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((c & 0xf0000000) >> 16)
        | ((c & 0x00f00000) >> 12)
        | ((c & 0x0000f000) >> 8)
        | ((c & 0x000000f0) >> 4)
        ;
}
```

- ARGB1555: 16 bits format, 1 bit for transparency, 5 per color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | (((c & 0xff000000) == 0xff000000) ? 0x8000 : 0)
        | ((c & 0xf80000) >> 9)
        | ((c & 0x00f800) >> 6)
        | ((c & 0x0000f8) >> 3)
        ;
}
```

- RGB565: 16 bits format, 5 or 6 per color. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((c & 0xf80000) >> 8)
        | ((c & 0x00fc00) >> 5)
        | ((c & 0x0000f8) >> 3)
        ;
}
```

- A8: 8 bits format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0xff - (toGrayscale(c) & 0xff);
}
```

- A4: 4 bits format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (0xff - (toGrayscale(c) & 0xff)) / 0x11;
}
```

- A2: 2 bits format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (0xff - (toGrayscale(c) & 0xff)) / 0x55;
}
```

- A1: 1 bit format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (0xff - (toGrayscale(c) & 0xff)) / 0xff;
}
```

- C4: 4 bits format with grayscale conversion. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (toGrayscale(c) & 0xff) / 0x11;
}
```

- C2: 2 bits format with grayscale conversion. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (toGrayscale(c) & 0xff) / 0x55;
}
```

- C1: 1 bit format with grayscale conversion. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (toGrayscale(c) & 0xff) / 0xff;
}
```

- AC44: 4 bits for transparency, 4 bits with grayscale conversion.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((color >> 24) & 0xf0)
        | ((toGrayscale(color) & 0xff) / 0x11)
        ;
}
```

- AC22: 2 bits for transparency, 2 bits with grayscale conversion.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((color >> 28) & 0xc0)

```

(continues on next page)

(continued from previous page)

```

        | ((toGrayscale(color) & 0xff) / 0x55)
        ;
    }

```

- AC11: 1 bit for transparency, 1 bit with grayscale conversion.

```

u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((c & 0xff000000) == 0xff000000 ? 0x2 : 0x0)
        | ((toGrayscale(color) & 0xff) / 0xff)
        ;
}

```

```

image1:ARGB8888
image2:RGB565
image3:A4

```

## RLE1 Output Format

The image engine can display embedded images that are encoded into a compressed format which encodes several consecutive pixels into one or more 16-bits words. This encoding manages a maximum alpha level of 2 (alpha level is always assumed to be 2, even if the image is not transparent).

- Several consecutive pixels have the same color (2 words):
  - First 16-bit word specifies how many consecutive pixels have the same color;
  - Second 16-bit word is the pixels' color.
- Several consecutive pixels have their own color (1 + n words):
  - First 16-bit word specifies how many consecutive pixels have their own color;
  - Next 16-bit word is the next pixel color.
- Several consecutive pixels are transparent (1 word):
  - 16-bit word specifies how many consecutive pixels are transparent.

Advantages:

- Supports 0 & 2 alpha encoding.
- Good compression when several consecutive pixels respect one of the three previous rules.

Disadvantages:

- Drawing an image is slightly slower than when using Display format.

```

image1:RLE1

```

## Fonts

### Overview

Fonts are graphical resources that can be accessed with a call to `ej.microui.display.Font.getFont()`. To be displayed, these fonts have to be converted at build-time from their source format to the display raw format by the

font generator tool. Fonts that must be processed by the font generator tool are declared in MicroEJ Classpath `*.fonts.list` files. The file format is a standard Java properties file, each line representing a `/` separated resource path relative to the MicroEJ classpath root referring to a MicroEJ font file (usually with a `.ejf` file extension). The resource may be followed by optional parameters which define :

- some ranges of characters to embed in the final raw file;
- the required pixel depth for transparency.

By default, all characters available in the input font file are embedded, and the pixel depth is `1` (i.e 1 bit-per-pixel). Example:

```
# The following font is embedded with all characters
# without transparency
com/mycompany/MyFont1.ejf

# The following font is embedded with only the latin
# unicode range without transparency
com/mycompany/MyFont2.ejf:latin

# The following font is embedded with all characters
# with 2 levels of transparency
com/mycompany/MyFont2.ejf::2
```

MicroEJ font files conventionally end with the `.ejf` suffix and are created using the Font Designer (see *Font Designer*).

## Font Range

The first parameter is for specifying the font ranges to embed. Selecting only a specific set of characters to embed reduces the memory footprint. Several ranges can be specified, separated by `;`. There are two ways to specify a character range: the custom range and the known range.

### Custom Range

Allows the selection of raw Unicode character ranges.

Examples:

- `myfont:0x21-0x49` : Embed all characters from 0x21 to 0x49 (included);
- `myfont:0x21-0x49,0x55` : Embed all characters from 0x21 to 0x49 and character 0x55;
- `myfont:0x21-0x49;0x55` : Same as previous, but done by declaring two ranges.

### Known Range

A known range is a range defined by the “Unicode Character Database” version 9.0.0 available on <https://home.unicode.org/>. Each range is composed of sub ranges that have a unique id.

- `myfont:basic_latin` : Embed all *Basic Latin* characters;
- `myfont:basic_latin;arabic` : Embed all *Basic Latin* characters, and all *Arabic* characters.

## Transparency

The second parameter is for specifying the font transparency level ( 1 , 2 , 4 or 8 ).

Examples:

- `myfont:latin:4` : Embed all latin characters with 4 levels of transparency
- `myfont::2` : Embed all characters with 2 levels of transparency

## 3.10 Development Tools

MicroEJ provides a number of tools to assist with various aspects of development. Some of these tools are run using MicroEJ Tool configurations, and created using the Run Configurations dialog of the MicroEJ SDK. A configuration must be created for the tool before it can be used.

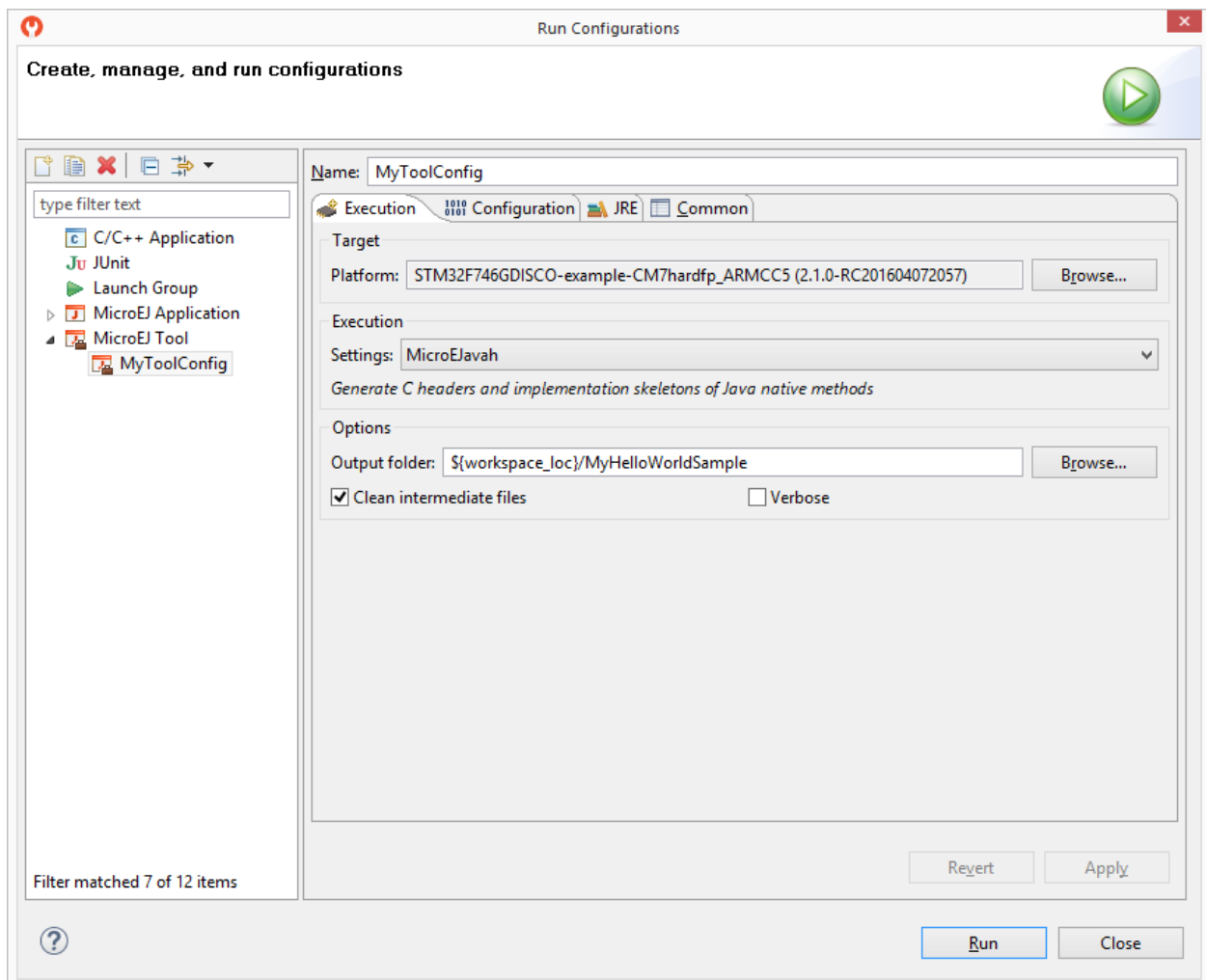


Fig. 29: MicroEJ Tool Configuration

*The above figure* shows a tool configuration being created. In the figure, the MicroEJ Platform has been selected, but the selection of which tool to run has not yet been made. That selection is made in the Execution Settings...



box. The Configuration tab then contains the options relevant to the selected tool.

### 3.10.1 Testsuite with JUnit

MicroEJ allows to run unit tests using the standard JUnit API during the build process of a MicroEJ library or a MicroEJ Application. The MicroEJ testsuite engine runs tests on a target Platform and outputs a JUnit XML report.

#### Principle

JUnit testing can be enabled when using the `microej-javalib` (MicroEJ Add-On Library) or the `microej-application` (MicroEJ Applications) build type. JUnit test cases processing is automatically enabled when the following dependency is declared in the `module.ivy` file of the project.

```
<dependency conf="test->*" org="ej.library.test" name="junit" rev="1.5.0"/>
```

When a new JUnit test case class is created in the `src/test/java` folder, a JUnit processor generates MicroEJ compliant classes into a specific source folder named `src-adpgenerated/junit/java`. These files are automatically managed and must not be edited manually.

#### JUnit Compliance

MicroEJ is compliant with a subset of JUnit version 4. MicroEJ JUnit processor supports the following annotations: `@After`, `@AfterClass`, `@Before`, `@BeforeClass`, `@Ignore`, `@Test`.

Each test case entry point must be declared using the `org.junit.Test` annotation (`@Test` before a method declaration). Please refer to JUnit documentation to get details on usage of other annotations.

#### Setup a Platform for Tests

Before running tests, a target platform must be configured in the MicroEJ workspace. The following steps assume that a platform has been previously imported into the MicroEJ Platform repository.

Go to **Window** > **Preferences** > **MicroEJ** > **Platforms** and select the desired platform on which to run the tests.

Press **F2** to expand the details.

Select the the platform path and copy it to the clipboard.

Go to **Window** > **Preferences** > **Ant** > **Runtime** and select the **Properties** tab.

Click on **Add Property...** button and set a new property named `target.platform.dir` with the platform path pasted from the clipboard.

#### Setup a Project with a JUnit Test Case

This section describes how to create a new JUnit Test Case starting from a new MicroEJ library project.

First create a new *module project* using the `microej-javalib` skeleton. A new project named `mylibrary` is created in the workspace.

Right-click on the `src/test/java` folder and select **New** > **Other...** menu item.

Select the **Java** > **JUnit** > **New JUnit Test Case** wizard. Enter a test name and press **Finish** . A new JUnit test case class is created with a default failing test case.

### Build and Run a JUnit Testsuite

Right-click on the **mylibrary** project and select **Build Module** . After the library is built, the testsuite engine launches available test cases and the build process fails in the console view.

On the **mylibrary** project, right-click and select **Refresh** .

A **target~** folder appears with intermediate build files. The JUnit report is available at **target~\test\xml\TEST-test-report.xml** .

Double-click on the file to open the JUnit testsuite report.

Modify the test case by replacing

```
fail("Not yet implemented");
```

with

```
Assert.assertTrue(true);
```

Right-click again on the **mylibrary** project and select **Build Module** . The test is now successfully executed on the target platform so the MicroEJ Add-On Library is fully built and published without errors.

Double-click on the JUnit testsuite report to see the test has been successfully executed.

### Advanced Configurations

#### Autogenerated Test Classes

The JUnit processor generates test classes into the **src-adpgenerated/junit/java** folder. This folder contains:

**\_AllTestClasses.java file** A single class with a main entry point that sequentially calls all declared test methods of all JUnit test case classes.

**\_AllTests\_[TestCase].java files** For each JUnit test case class, a class with a main entry point that sequentially calls all declared test methods.

**\_SingleTest\_[TestCase]\_[TestMethod].java files** For each test method of each JUnit test case class, a class with a main entry point that calls the test method.

#### JUnit Test Case to MicroEJ Test Case

The MicroEJ testsuite engine allows to select the classes that will be executed, by setting the following property in the project **module.ivy** file.

```
<ea:property name="test.run.includes.pattern" value="[MicroEJ Test Case Include Pattern]"/>
```

The following line consider all JUnit test methods of the same class as a single MicroEJ test case (default behaviour). If at least one JUnit test method fails, the whole test case fails in the JUnit report.

```
<ea:property name="test.run.includes.pattern" value="**/_AllTests_*.class"/>
```

The following line consider each JUnit test method as a dedicated MicroEJ test case. Each test method is viewed independently in the JUnit report, but this may slow down the testsuite execution because a new deployment is done for each test method.

```
<ea:property name="test.run.includes.pattern" value="**/_SingleTest_*.class"/>
```

### Run a Single Test Manually

Each test can be run independently as each class contains a main entry point.

In the `src-adpgenerated/junit/java` folder, right-click on the desired autogenerated class ( `_SingleTest_[TestCase][TestMethod].java` ) and select **Run As** > **MicroEJ Application** .

The test is executed on the selected Platform and the output result is dumped into the console.

### Testsuite Options

The MicroEJ testsuite engine can be configured with specific options which can be added to the `module.ivy` file of the project running the testsuite, within the `<ea:build>` XML element.

- Application Option Injection

It is possible to inject an *Application Option* for all the tests, by adding to the original option the `microej.testsuite.properties.` prefix:

```
<ea:property name="microej.testsuite.properties.[application_option_name]" value="[application_↵option_value]"/>
```

- Retry Mechanism

A test execution may not be able to produce the success trace for an external reason, for example an unreliable harness script that may lose some trace characters or crop the end of the trace. For all these unlikely reasons, it is possible to configure the number of retries before a test is considered to have failed:

```
<ea:property name="microej.testsuite.retry.count" value="[nb_of_retries]"/>
```

By default, when a test has failed, it is not executed again (option value is set to `0` ).

### Test Specific Options

The MicroEJ testsuite engine allows to define MicroEJ Launch options specific to each test case. This can be done by defining a file with the same name as the generated test case file with the `.properties` extension instead of the `.java` extension. The file must be put in the `src/test/resources` folder and within the same package than the test case file.

Consult the Application Launch Options Appendix of the Device Developer's Guide to get the list of available options properties.

## 3.10.2 Font Designer

## Principle

The Font Designer module is a graphical tool (Eclipse plugin) that runs within the MicroEJ Workbench used to build and edit MicroUI fonts. It stores fonts in a platform-independent format.

## Functional Description

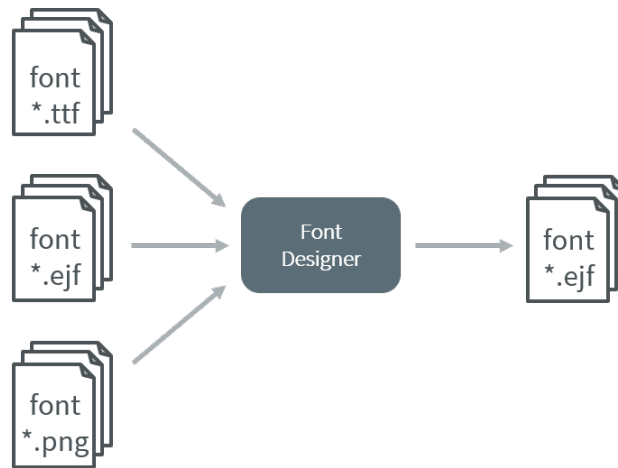


Fig. 30: Font Generation

## Font Management

### Create a MicroEJ Font

To create a MicroEJ font, follow the steps below:

1. Open the Eclipse wizard: **File** > **New** > **Other** > **MicroEJ** > **MicroEJ Font**.
2. Select a directory and a name.
3. Click Finish.

Once the font is created, a new editor is opened: the MicroEJ Font Designer Editor.

### Edit a MicroEJ Font

You can edit your font with the MicroEJ Font Designer Editor (by double-clicking on a **\*.ejf** file or after running the new MicroEJ Font wizard).

This editor is divided into three main parts:

- The top left part manages the main font properties.
- The top right part manages the character to embed in your font.
- The bottom part allows you to edit a set of characters or an individual character.

## Main Properties

The main font properties are:

- font size: height and width (in pixels).
- baseline (in pixels).
- space character size (in pixels).
- styles and filters.
- identifiers.

Refer to the following sections for more information about these properties.

## Font Height

A font has a fixed height. This height includes the white pixels at the top and at the bottom of each character simulating line spacing in paragraphs.

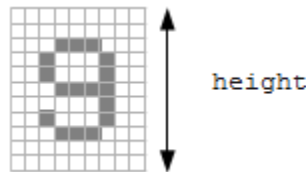


Fig. 31: Font Height

## Font Width: Proportional and Monospace Fonts

A monospace font is a font in which all characters have the same width. For example a '!' representation will be the same width as a 'w' (they will be in the same size rectangle of pixels). In a proportional font, a 'w' will be wider than a '!'.

A monospace font usually offers a smaller memory footprint than a proportional font because the Font Designer does not need to store the size of each character. As a result, this option can be useful if the difference between the size of the smallest character and the biggest one is small.

## Baseline

Characters have a baseline: an imaginary line on top of which the characters seem to stand. Note that characters can be partly under the line, for example, 'g' or '}'.

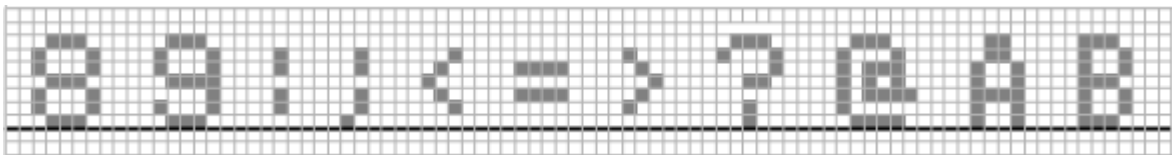


Fig. 32: The Baseline

## Space Character

The Space character (0x20) is a specific character because it has no filled pixels. From the Main Properties Menu you can fix the space character size in pixels.

---

**Note:** When the font is monospace, the space size is equal to the font width.

---

## Styles and Filters

A MicroUI font holds a style: PLAIN, BOLD, ITALIC, UNDERLINED, and the combinations between BOLD, ITALIC and UNDERLINED. Font Designer can use one file to describe several MicroUI fonts.

For example, a font file that describes a PLAIN font can also describe an UNDERLINED font because the MicroUI implementation just has to draw a line under the characters. In this way, from a developer's point of view, there are two fonts: a PLAIN font and an UNDERLINED font. From the Font Designer point of view, there are also two fonts, but they use the same data file. Font Designer adds a tag to describe the UNDERLINED font in the generated font file.

This tag is a *filter*. When a file contains one or more filters, MicroUI implementation knows that it has to perform post processing to obtain a specific MicroUI font from the encoded font.

Alternatively, the user can create two distinct files to describe the two fonts. From the MicroUI application point of view, there are always two fonts: a PLAIN font and an UNDERLINED font, but no post-processing step is required (no filter tag).

Examples:

1. A font file contains the styles PLAIN and UNDERLINED and the filters PLAIN and UNDERLINED. The MicroUI implementation detects two MicroUI fonts. To draw each font, the PLAIN filter or the UNDERLINED filter is used accordingly.
2. A font file contains the styles PLAIN and UNDERLINED and the filter PLAIN. The MicroUI implementation detects two MicroUI fonts. To draw the underlined font, it will not apply the underlining process (the filter UNDERLINED is absent). So the MicroUI underlined font will have the same rendering as the MicroUI plain font.

Font Designer features three drop-downs, one for each of BOLD, ITALIC and UNDERLINED. Each drop-down has three options:

- None – Font Designer will not set this style, nor include a filter for it.
- Built-in – Font Designer will set this style, but not include a filter for it.
- Dynamic – Font Designer will set this style, and include a filter for it.

If all three drop-downs are set to None, only a plain font is generated.

The number of fonts that will result is shown below the drop-downs.

## Identifiers

A number of identifiers can be attached to a MicroUI font. At least one identifier is required to specify the font. Identifiers are a mechanism for specifying the contents of the font – the set or sets of characters it contains. The identifier may be a standard identifier (for example, LATIN) or a user-defined identifier. Identifiers are numbers, but standard identifiers, which are in the range 0 to 80, are typically associated with a handy name. A user-defined identifier is an identifier with a value of 81 or higher.

## Character List

The list of characters can be populated through the import button, which allows you to import characters from system fonts, images or another MicroEJ font.

### Import from System Font

This page allows you to select the system font to use (left part) and the range of characters. There are predefined ranges of characters below the font selection, as well as a custom selection picker (for example 0x21 to 0xfe for Latin characters).

The right part displays the selected characters with the selected font. If the background color of a displayed character is red, it means that the character is too large for the defined height, or in the case of a monospace font, it means the character is too high or too wide. You can then adjust the font properties (font size and style) to ensure that characters will not be truncated.

When your selection is done, click the Finish button to import this selection into your font.

### Import from Images

This page allows the loading of images from a directory. The images must be named as follows: `0x[UTF-8].[extension]`.

When your selection is done, click the Finish button to import the images into your font.

### Character Editor

When a single character is selected in the list, the character editor is opened.

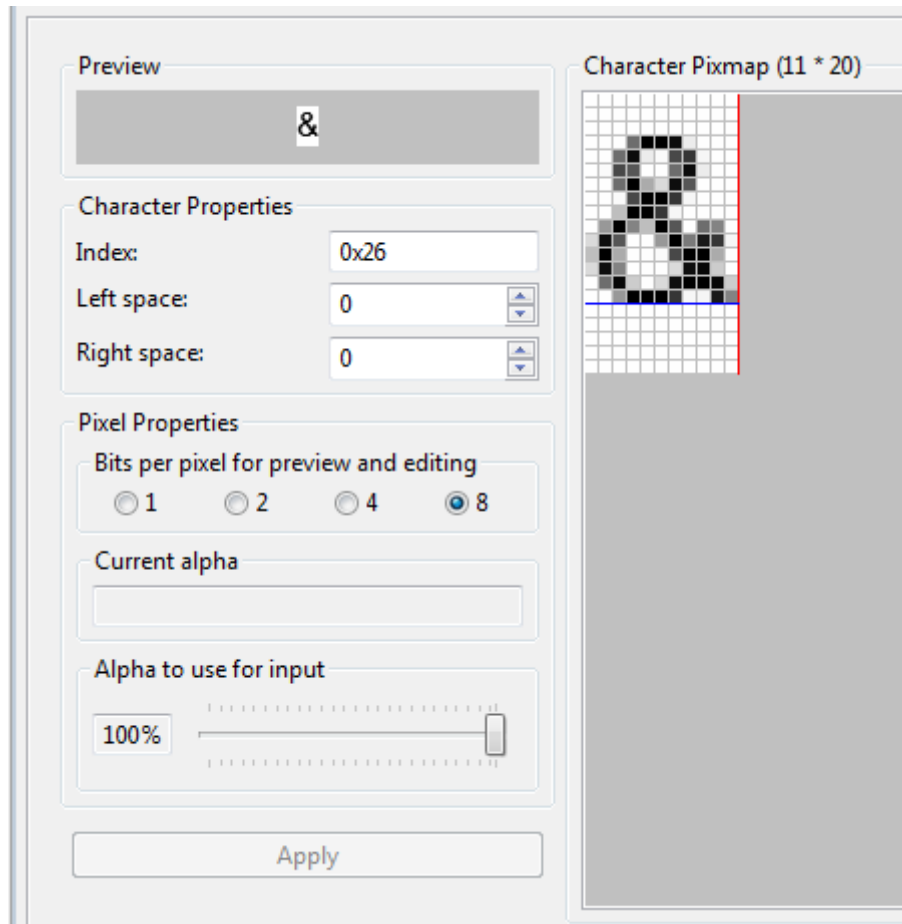


Fig. 33: Character Editor

You can define specific properties, such as left and right space, or index. You can also draw the character pixel by pixel - a left-click in the grid draws the pixel, a right-click erases it.

The changes are not saved until you click the Apply button. When changes are applied to a character, the editor shows that the font has changed, so you can now save it.

The same part of the editor is also used to edit a set of characters selected in the top right list. You can then edit the common editable properties (left and right space) for all those characters at the same time.

### Working With Anti-Aliased Fonts

By default, when characters are imported from a system font, each pixel is either fully opaque or fully transparent. Fully opaque pixels show as black squares in the character grid in the right-hand part of the character editor; fully transparent pixels show as white squares.

However, the pixels stored in an **ejf** file can take one of 256 grayscale values. A fully-transparent pixel has the value 255 (the RGB value for white), and a fully-opaque pixel has the value 0 (the RGB value for black). These grayscale values are shown in parentheses at the end of the text in the Current alpha field when the mouse cursor hovers over a pixel in the grid. That field also shows the transparency level of the pixel, as a percentage, where 100% means fully opaque.

It is possible to achieve better-looking characters by using a combination of fully-opaque and partially-transparent pixels. This technique is called *anti-aliasing*. Anti-aliased characters can be imported from system fonts by checking



the anti aliasing box in the import dialog. The ‘&’ character shown in the screenshot above was imported using anti aliasing, and you can see the various gray levels of the pixels.

When the Font Generator converts an `ejf` file into the raw format used at runtime, it can create fonts with characters that have 1, 2, 4 or 8 bits-per-pixel (bpp). If the raw font has 8 bpp, then no conversion is necessary and the characters will render with the same quality as seen in the character editor. However, if the raw font has less than 8 bpp (the default is 1 bpp) any gray pixels in the input file are compressed to fit, and the final rendering will be of lower quality (but less memory will be required to hold the font).

It is useful to be able to see the effects of this compression, so the character editor provides radio buttons that allow the user to preview the character at 1, 2, 4, or 8 bpp. Furthermore, when 2, 4 or 8 bpp is selected, a slider allows the user to select the transparency level of the pixels drawn when the left mouse button is clicked in the grid.

### Previewing a Font

You can preview your font by pressing the Preview... button, which opens the Preview wizard. In the Preview wizard, press the Select File button, and select a text file which contains text that you want to see rendered using your font. Characters that are in the selected text file but not available in the font will be shown as red rectangles.



Fig. 34: Font Preview

## Removing Unused Characters

In order to reduce the size of a font file, you can reduce the number of characters in your font to be only those characters used by your application. To do this, create a file which contains all the characters used by your application (for example, concatenating all your NLS files is a good starting point). Then open the Preview wizard as described above, selecting that file. If you select the check box Delete unused on finish, then those characters that are in the font but not in the text file will be deleted from the font when you press the Finish button, leaving your font containing the minimum number of characters. As this font will contain only characters used by a specific application, it is best to prepare a “complete” font, and then apply this technique to a copy of that font to produce an application specific cut-down version of the font.

## Use a MicroEJ Font

A MicroEJ Font must be converted to a format which is specific to the targeted platform. The Font Generator tool performs this operation for all fonts specified in the list of fonts configured in the application launch.

## Dependencies

No dependency.

## Installation

The Font Designer module is already installed in the MicroEJ environment. The module is optional for the platform, and allows the platform user to create new fonts.

---

**Note:** When the platform user already has a MicroEJ environment which provides the Font Designer module, he/she will be able to create a new font even if the platform does not provide the Font Designer module.

---

In the platform configuration file, check `UI > Font Designer` to install the Font Designer module.

## Use

Create a new `ejf` font file or open an existing one in order to open the Font Designer plugin.

## 3.10.3 Stack Trace Reader

### Principle

Stack Trace Reader is a MicroEJ tool which reads and decodes the MicroEJ stack traces. When an exception occurs, the MicroEJ Core Engine prints the stack trace on the standard output `System.out`. The class names, non required types (see *Types*) names and method names obtained are encoded with a MicroEJ internal format. This internal format prevents the embedding of all class names and method names in the flash, in order to save some memory space. The Stack Trace Reader tool allows you to decode the stack traces by replacing the internal class names and method names with their real names. It also retrieves the line number in the MicroEJ Application.

## Functional Description

The Stack Trace Reader reads the debug info from the fully linked ELF file (the ELF file that contains the MicroEJ Core Engine, the other libraries, the BSP, the OS, and the compiled MicroEJ Application). It prints the decoded stack trace.

## Dependencies

No dependency.

## Installation

This tool is a built-in platform tool.

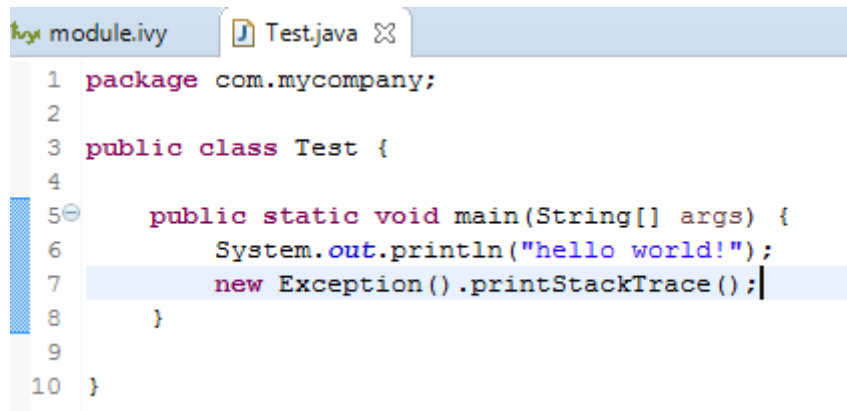
## Use

Write a new line to dump the currently executed stack trace on the standard output.

```
public class MyBackgroundCode implements BackgroundService {
    @Override
    public void onStart() {
        // TODO Auto-generated method stub
        System.out.println("MyBackgroundCode: Hello World");
        new Throwable().printStackTrace();
    }
}
```

Fig. 35: Code to Dump a Stack Trace

Write a new line to dump the currently executed stack trace on the standard output.



```
module.ivy Test.java
1 package com.mycompany;
2
3 public class Test {
4
5     public static void main(String[] args) {
6         System.out.println("hello world!");
7         new Exception().printStackTrace();
8     }
9
10 }
```

Fig. 36: Code to Dump a Stack Trace

To be able to decode an application stack trace, the stack trace reader tool requires the application binary file with debug information ( `application.fodbg` in the output folder). Note that the file which is uploaded on the device is `application.fo` (stripped version without debug information).

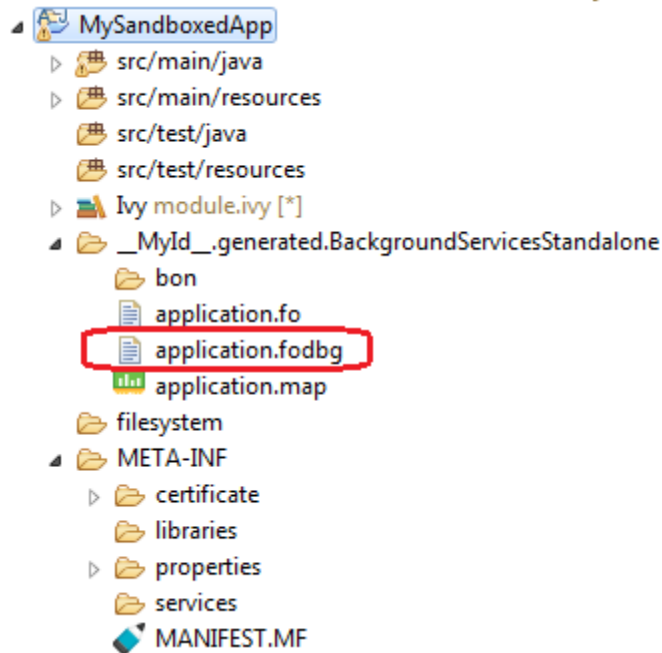


Fig. 37: Application Binary File with Debug Information

On successful deployment, the application is started on the device and the following trace is dumped on standard output.

```
MyBackgroundCode: Hello World
Exception in thread "ej.wadapps.app.default" java.lang.Throwable
  at java.lang.System.@M:0x803b334:0x803b344@
  at java.lang.Throwable.@M:0x8046aec:0x8046b02@
  at java.lang.Throwable.@M:0x805a0fc:0x805a11d@
  at appEntry.MyBackgroundCode.@F:1d48b23d5b01000d37548f1e20224d0b875cb968936fb41:0xc03800e0@M:0xc0380bf8:0xc0380c20@
```

Fig. 38: Stack Trace Output

To create a new MicroEJ Tool configuration, right-click on the application project and click on **Run As...** > **Run Configurations...** .

In **Execution** tab, select the **Stack Trace Reader** tool.

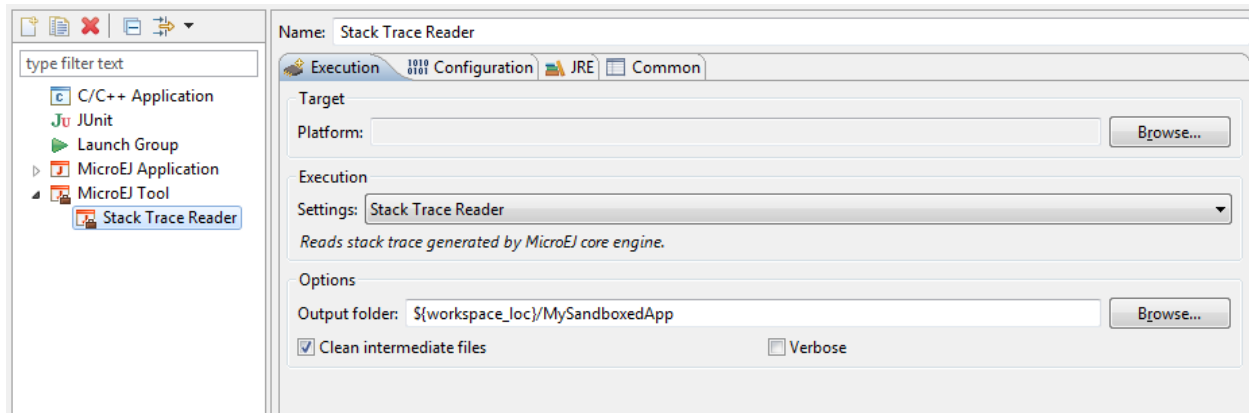


Fig. 39: Select Stack Trace Reader Tool

In **Configuration** tab, browse the previously generated application binary file with debug information (**application.fodbg** in case of a Sandboxed Application or **application.out** in case of a Standalone Application)

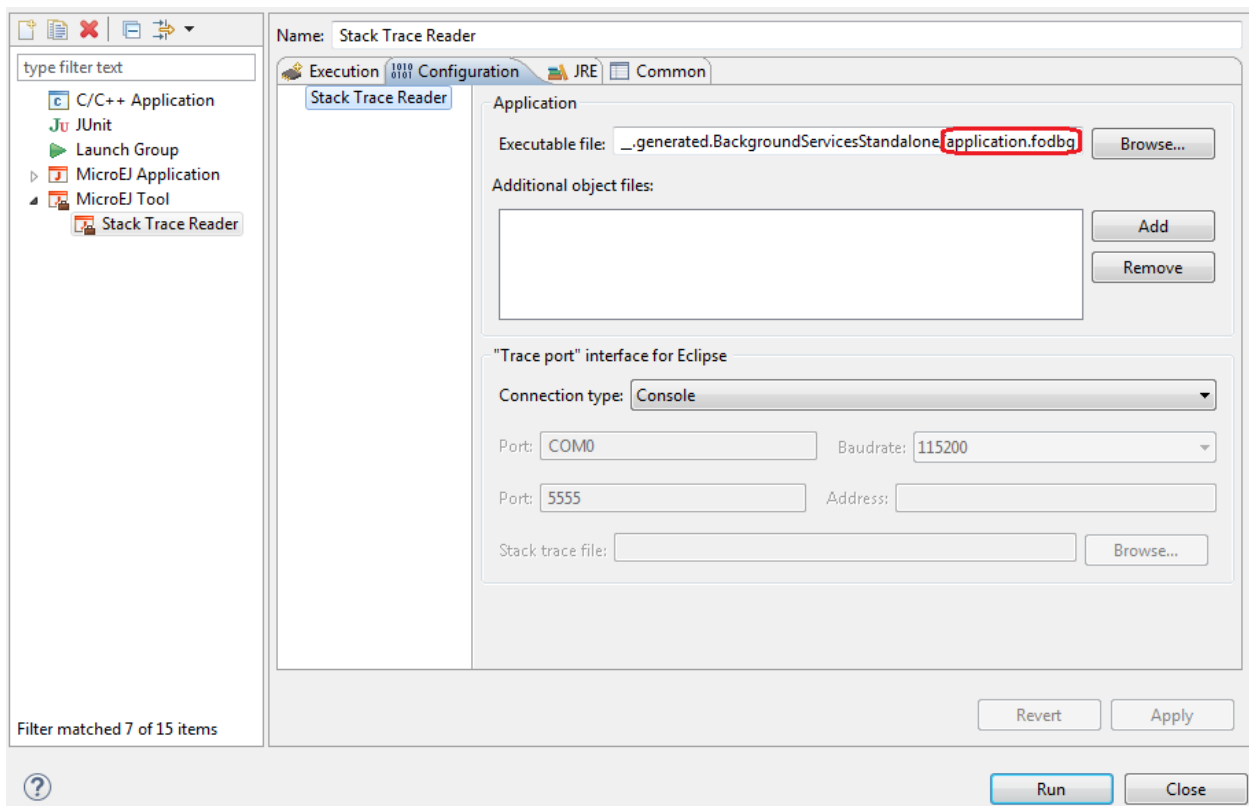


Fig. 40: Stack Trace Reader Tool Configuration (Sandboxed Application)

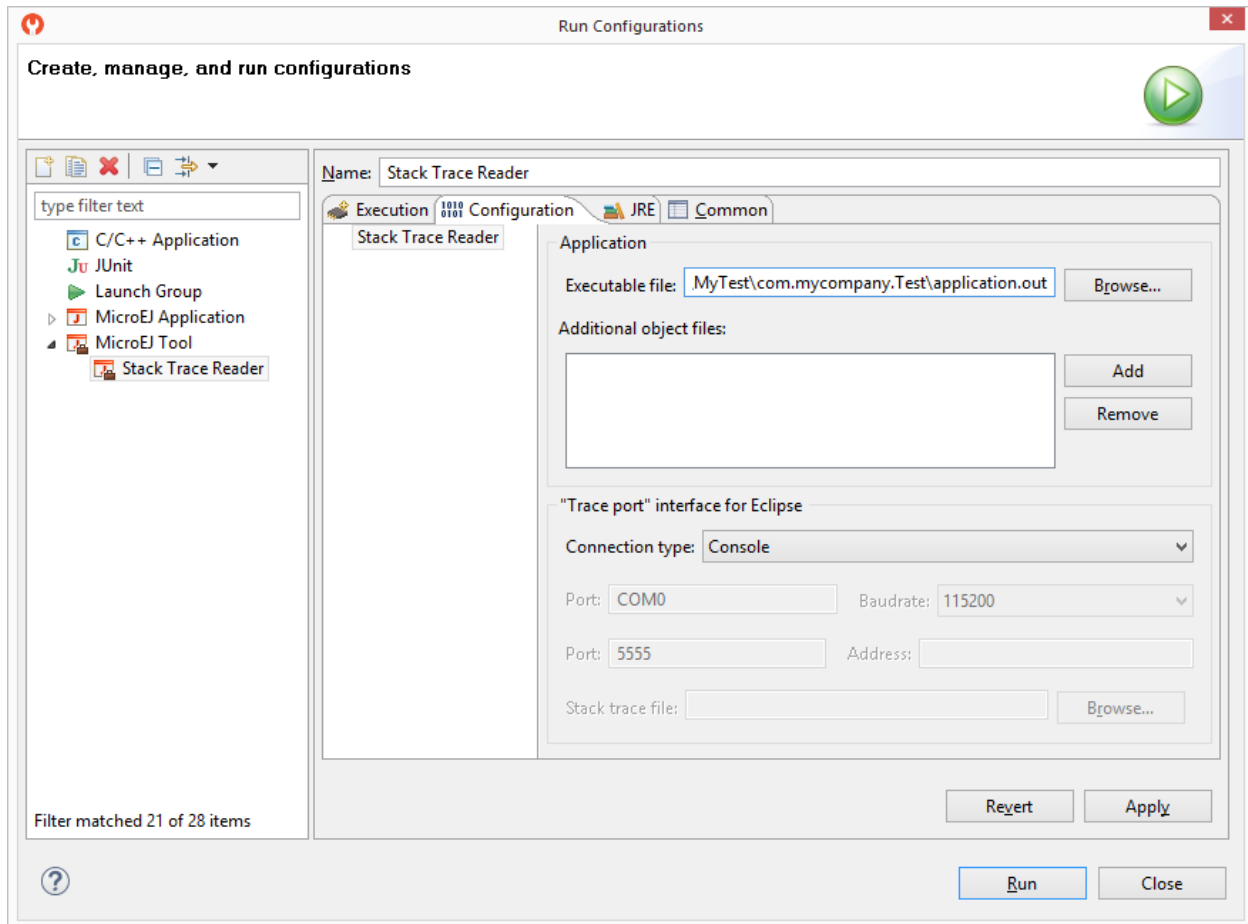


Fig. 41: Stack Trace Reader Tool Configuration (Standalone Application)

Click on **Run** button and copy/paste the trace into the Eclipse console. The decoded trace is dumped and the line corresponding to the application hook is now readable.

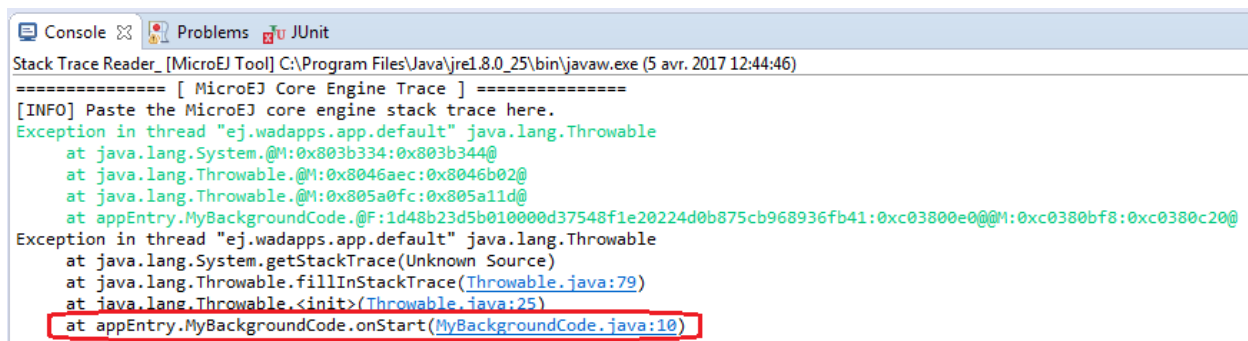


Fig. 42: Read the Stack Trace

The stack trace reader can simultaneously decode heterogeneous stack traces with lines owned by different applications and the firmware. Other debug information files can be appended using the **Additional object files** option. Lines owned by the firmware can be decoded with the firmware debug information file (optionally made available by your firmware provider).

The following section explains MicroEJ tool options.

### Category: Stack Trace Reader

#### Group: Application

##### Option(browse): Executable file

*Option Name:* `application.file`

*Default value:* `(empty)`

*Description:*

Specify the full path of a full linked elf file.

##### Option(list): Additional object files

*Option Name:* `additional.application.files`

*Default value:* `(empty)`

#### Group: “Trace port” interface for Eclipse

*Description:*

This group describes the hardware link between the device and the PC.



**Option(combo): Connection type**

*Option Name:* `proxy.connection.connection.type`

*Default value:* `Console`

*Available values:*

`Uart (COM)`

`Socket`

`File`

`Console`

*Description:*

Specify the connection type between the device and PC.

**Option(text): Port**

*Option Name:* `pcboardconnection.usart.pc.port`

*Default value:* `COM0`

*Description:*

*Format:* `port name`

Specifies the PC COM port:

Windows - `COM1` , `COM2` , ... , `COM*n*`

Linux - `/dev/ttyS0` , `/dev/ttyS1` , ... , `/dev/ttyS*n*`

**Option(combo): Baudrate**

*Option Name:* `pcboardconnection.usart.pc.baudrate`

*Default value:* `115200`

*Available values:*

`9600`

`38400`

`57600`

`115200`

*Description:*

Defines the COM baudrate for PC-Device communication.

**Option(text): Port**

*Option Name:* `pcboardconnection.socket.port`

*Default value:* `5555`

*Description:*

IP port.

**Option(text): Address**

*Option Name:* `pcboardconnection.socket.address`

*Default value:* `(empty)`

*Description:*

IP address, on the form A.B.C.D.

**Option(browse): Stack trace file**

*Option Name:* `pcboardconnection.file.path`

*Default value:* `(empty)`

### 3.10.4 Code Coverage Analyzer

**Principle**

The MicroEJ Simulator features an option to output .cc (Code Coverage) files that represent the use rate of functions of an application. It traces how the opcodes are really executed.

**Functional Description**

The Code Coverage Analyzer scans the output .cc files, and outputs an HTML report to ease the analysis of methods coverage. The HTML report is available in a folder named htmlReport in the same folder as the .cc files.

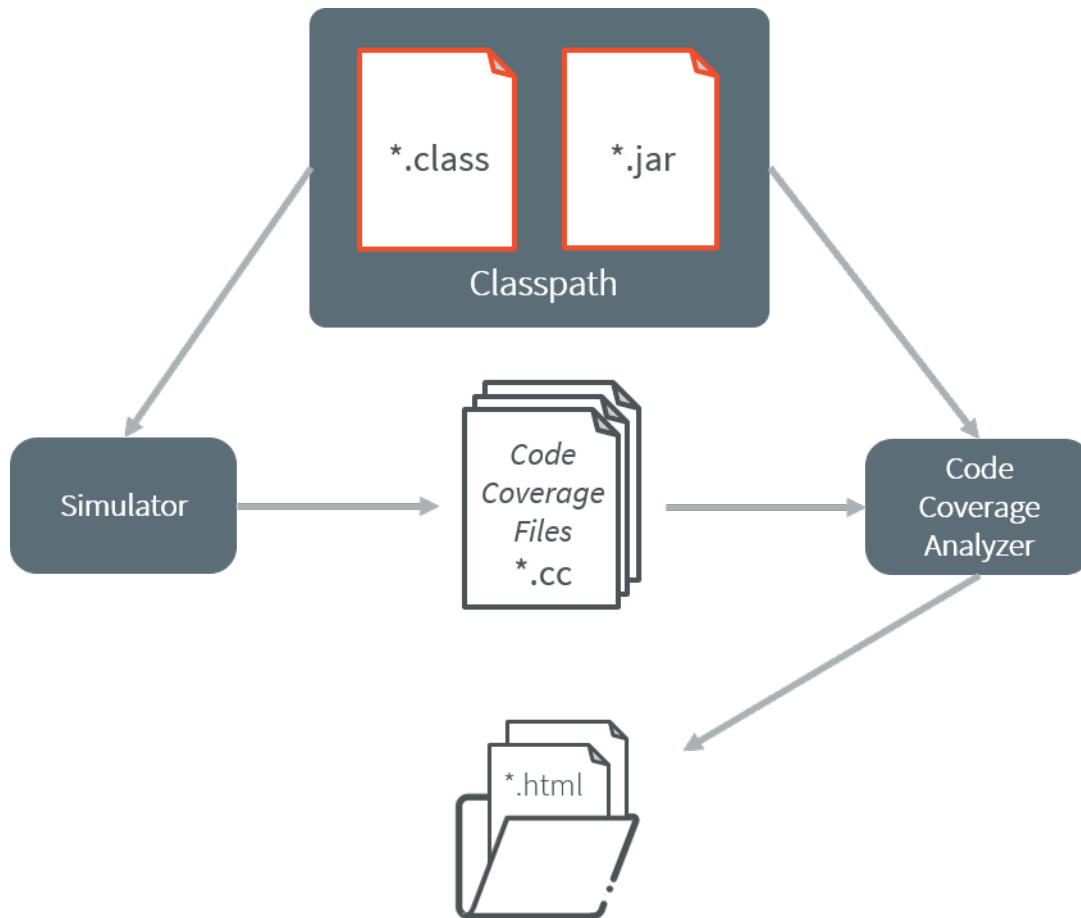


Fig. 43: Code Coverage Analyzer Process

### Dependencies

In order to work properly, the Code Coverage Analyzer should input the .cc files. The .cc files relay the classpath used during the execution of the Simulator to the Code Coverage Analyzer. Therefore the classpath is considered to be a dependency of the Code Coverage Analyzer.

### Installation

This tool is a built-in platform tool.

### Use

A MicroEJ tool is available to launch the Code Coverage Analyzer tool. The tool name is Code Coverage Analyzer.

Two levels of code analysis are provided, the Java level and the bytecode level. Also provided is a view of the fully or partially covered classes and methods. From the HTML report index, just use hyperlinks to navigate into the report and source / bytecode level code.

**Category: Code Coverage**

Code Coverage

\*.cc files folder:

Classes filter

Includes:

Excludes:

**Option(browse): \*.cc files folder***Option Name:* `cc.dir`*Default value:* `(empty)`*Description:*

Specify a folder which contains the cc files to process (\*.cc).

**Group: Classes filter****Option(list): Includes***Option Name:* `cc.includes`*Default value:* `(empty)`*Description:*

List packages and classes to include to code coverage report. If no package/class is specified, all classes found in the project classpath will be analyzed.

*Examples:*`packageA.packageB.*` : includes all classes which are in package `packageA.packageB``packageA.packageB.className` : includes the class `packageA.packageB.className`

**Option(list): Excludes**

*Option Name:* `cc.excludes`

*Default value:* `(empty)`

*Description:*

List packages and classes to exclude to code coverage report. If no package/class is specified, all classes found in the project classpath will be analyzed.

Examples:

`packageA.packageB.*` : excludes all classes which are in package `packageA.packageB`

`packageA.packageB.className` : excludes the class `packageA.packageB.className`

### 3.10.5 Heap Dumper & Heap Analyzer

**Introduction**

Heap Dumper is a tool that takes a snapshot of the heap. Generated files (with the `.heap` extension) are available on the application output folder. Note that it works only on simulations. It is a built-in platform tool and has no dependencies.

The Heap Analyzer is a set of tools to help developers understand the contents of the Java heap and find problems such as memory leaks. For its part, the Heap Analyzer plug-in is able to open dump files. It helps you analyze their contents thanks to the following features:

- memory leaks detection
- objects instances browse
- heap usage optimization (using immortal or immutable objects)

**The Heap**

The heap is a memory area used to hold Java objects created at runtime. Objects persist in the heap until they are garbage collected. An object becomes eligible for garbage collection when there are no longer any references to it from other objects.

**Heap Dump**

A heap dump is an XML file that provides a snapshot of the heap contents at the moment the file is created. It contains a list of all the instances of both class and array types that exist in the heap. For each instance it records:

- The time at which the instance was created
- The thread that created it
- The method that created it

For instances of class types, it also records:

- The class
- The values in the instance's non-static fields

For instances of array types, it also records:

- The type of the contents of the array
- The contents of the array

For each referenced class type it records the values in the static fields of the class.

### Heap Analyzer Tools

The Heap Analyzer is an Eclipse plugin that adds three tools to the MicroEJ environment.

Tool name	Number of input files	Purpose
Heap Viewer	1	Shows what instances are in the heap, when they were created, and attempts to identify problem areas
Progressive Heap Usage	1 or more	Shows how the number of instances in the heap has changed over time
Compare	2	Compares two heap dumps, showing which objects were created, or garbage collected, or have changed values

### Heap Dumper

When the Heap Dumper option is activated, the garbage collector process ends by performing a dump file that represent a snapshot of the heap at this moment. Thus, to generate such dump files, you must explicitly call the `System.gc()` method in your code, or wait long enough for garbage collector activation.

The heap dump file contains the list of all instances of both class and array types that exist in the heap. For each instance it records:

- the time at which the instance was created
- the thread that created it
- the method that created it

For instances of class types, it also records:

- the class
- the values in the instance's non-static fields

For instances of array types, it also records:

- the type of the contents of the array
- the contents of the array

For each referenced class type, it records the values in the static fields of the class.

**Category: Heap Dumper**

The screenshot shows the 'Heap Dumper' configuration window. On the left is a sidebar with a tab labeled 'Heap Dumper'. The main panel is divided into three sections:

- Application:** Contains an 'Executable file:' text box and a 'Browse...' button. Below it is a 'Resident application files:' list box with 'Add...' and 'Remove' buttons.
- Memory:** Contains a 'Heap memory file:' text box and a 'Browse...' button.
- Output:** Contains a 'Heap file name:' text box with the value 'application.heap'.

**Group: Application****Option(browse): Executable file**

*Option Name:* `application.filename`

*Default value:* `(empty)`

*Description:*

Specify the full path of a full linked ELF file.

**Option(list): Resident application files**

*Option Name:* `additional.application.fileNames`

*Default value:* `(empty)`

*Description:*

Specify the full path of resident applications `.out` files linked by the Firmware Linker.

**Group: Memory****Option(browse): Heap memory file**

*Option Name:* `heap.filename`

*Default value:* `(empty)`

*Description:*

Specify the full path of heap memory dump, in Intel Hex format.

**Group: Output****Option(text): Heap file name**

*Option Name:* `output.name`

*Default value:* `application.heap`

**Heap Viewer**

To open the Heap Viewer tool, select a heap dump XML file in the `Package Explorer`, right-click on it and select `Open With` > `Heap Viewer`

Alternatively, right-click on it and select `Heap Analyzer` > `Open heap viewer`

This will open a Heap Viewer tool window for the selected heap dump<sup>1</sup>.

The Heap Viewer works in conjunction with two views:

1. The Outline view
2. The Instance Browser view

These views are described below.

The Heap Viewer tool has three tabs, each described below.

**Outline View**

The Outline view shows a list of all the types in the heap dump, and for each type shows a list of the instances of that type. When an instance is selected it also shows a list of the instances that refer to that instance. The Outline view is opened automatically when an Heap Viewer is opened.

---

<sup>1</sup> Although this is an Eclipse 'editor', it is not possible to edit the contents of the heap dump.



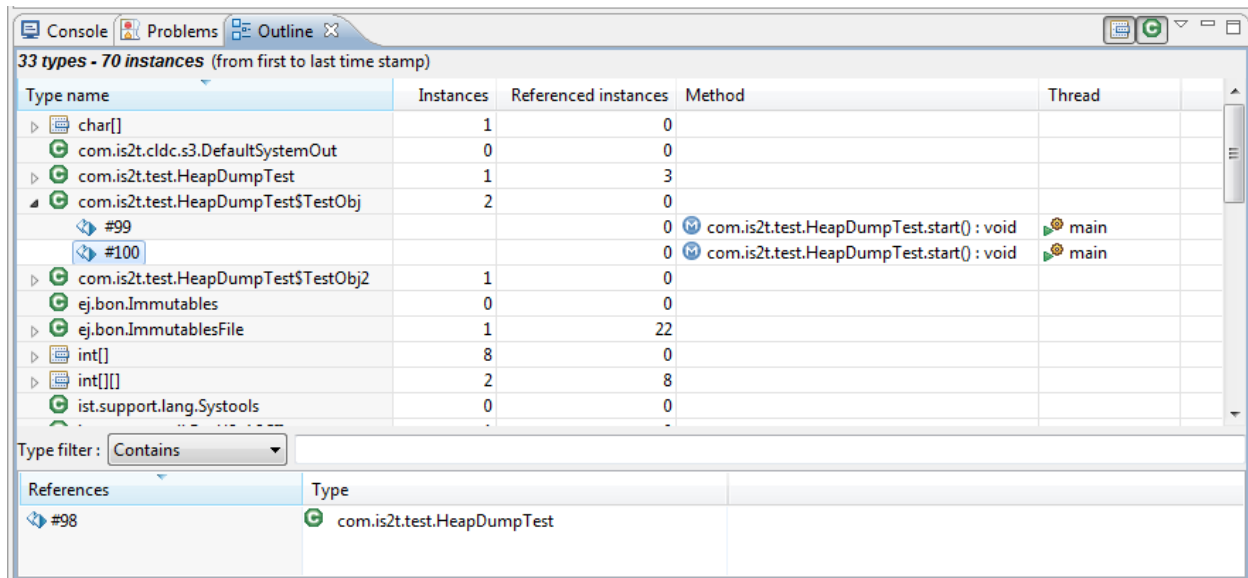


Fig. 44: Outline View

### Instance Browser View

The Instance Browser view opens automatically when a type or instance is selected in the Outline view. It has two modes, selected using the buttons in the top right corner of the view. In 'Fields' mode it shows the field values for the selected type or instance, and where those fields hold references it shows the fields of the referenced instance, and so on. In 'Reference' mode it shows the instances that refer to the selected instance, and the instances that refer to them, and so on.

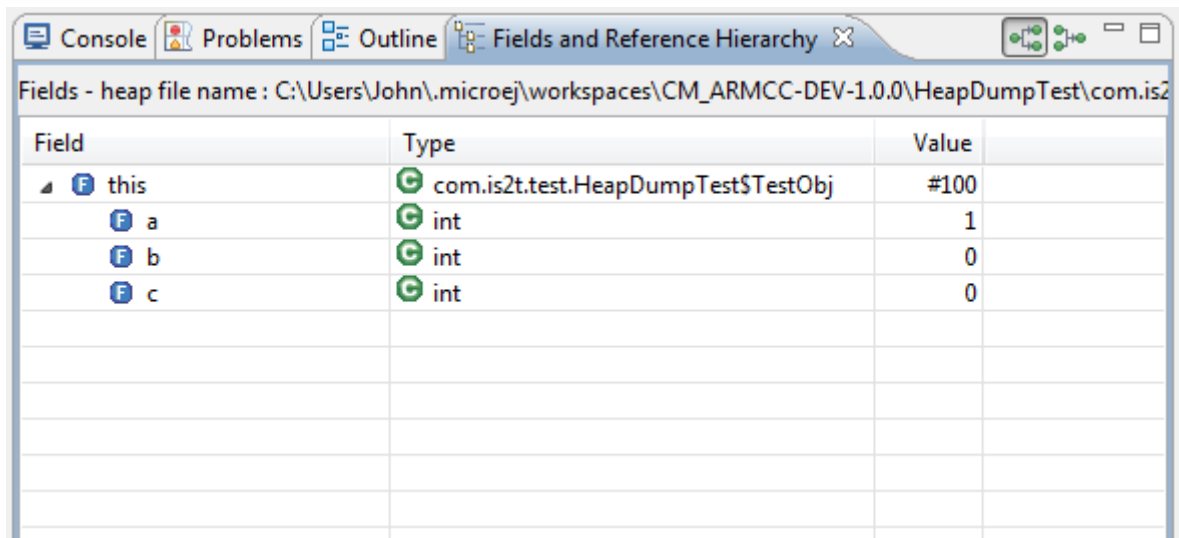
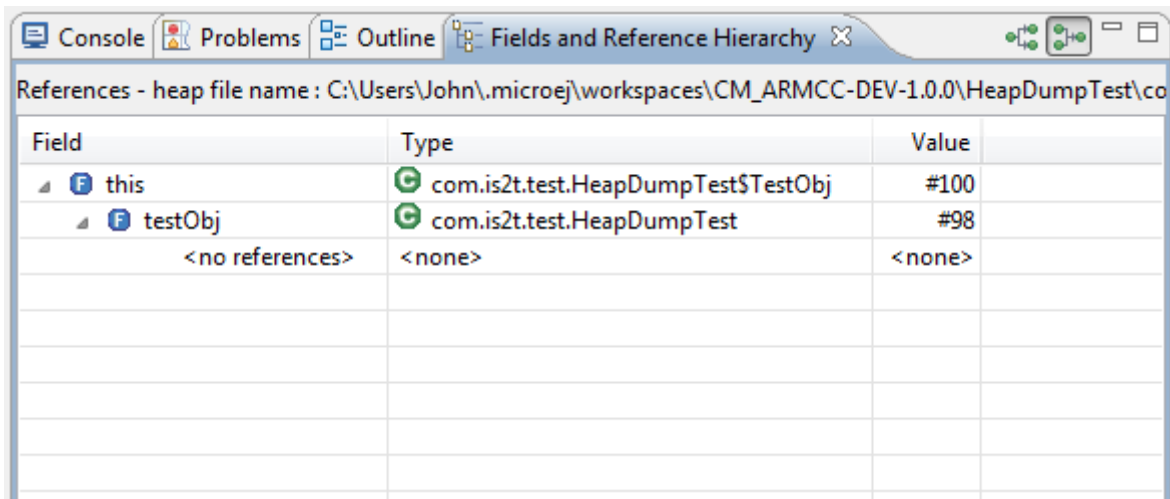


Fig. 45: Instance Browser View - Fields mode







Field	Type	Value
▲  this	 com.is2t.test.HeapDumpTest\$TestObj	#100
▲  testObj	 com.is2t.test.HeapDumpTest	#98
<no references>	<none>	<none>

Fig. 46: Instance Browser View - References mode

### Heap Usage Tab

The Heap usage page of the Heap Viewer displays four bar charts. Each chart divides the total time span of the heap dump (from the time stamp of the earliest instance creation to the time stamp of the latest instance creation) into a number of periods along the x axis, and shows, by means of a vertical bar, the number of instances created during the period.

- The top-left chart shows the total number of instances created in each period, and is the only chart displayed when the Heap Viewer is first opened.
- When a type or instance is selected in the Outline view the top-right chart is displayed. This chart shows the number of instances of the selected type created in each time period.
- When an instance is selected in the Outline view the bottom-left chart is displayed. This chart shows the number of instances created in each time period by the thread that created the selected instance.
- When an instance is selected in the Outline view the bottom-right chart is displayed. This chart shows the number of instances created in each time period by the method that created the selected instance.



Fig. 47: Heap Viewer - Heap Usage Tab

Clicking on the graph area in a chart restricts the Outline view to just the types and instances that were created during the selected time period. Clicking on a chart but outside of the graph area restores the Outline view to showing all types and instances<sup>2</sup>.

The button Generate graphViz file in the top-right corner of the Heap Usage page generates a file compatible with graphviz ([www.graphviz.org](http://www.graphviz.org)).

### Dominator Tree Tab

The Dominator tree page of the Heap Viewer allows the user to browse the instance reference tree which contains the greatest number of instances. This can be useful when investigating a memory leak because this tree is likely to contain the instances that should have been garbage collected.

The page contains two tree viewers. The top viewer shows the instances that make up the tree, starting with the root. The left column shows the ids of the instances – initially just the root instance is shown. The Shallow instances column shows the number of instances directly referenced by the instance, and the Referenced instances column shows the total number of instances below this point in the tree (all descendants).

<sup>2</sup> The Outline can also be restored by selecting the All types and instances option on the drop-down menu at the top of the Outline view.

The bottom viewer groups the instances that make up the tree either according to their type, the thread that created them, or the method that created them.

Double-clicking an instance in either viewer opens the Instance Browser view (if not already open) and shows details of the instance in that view.

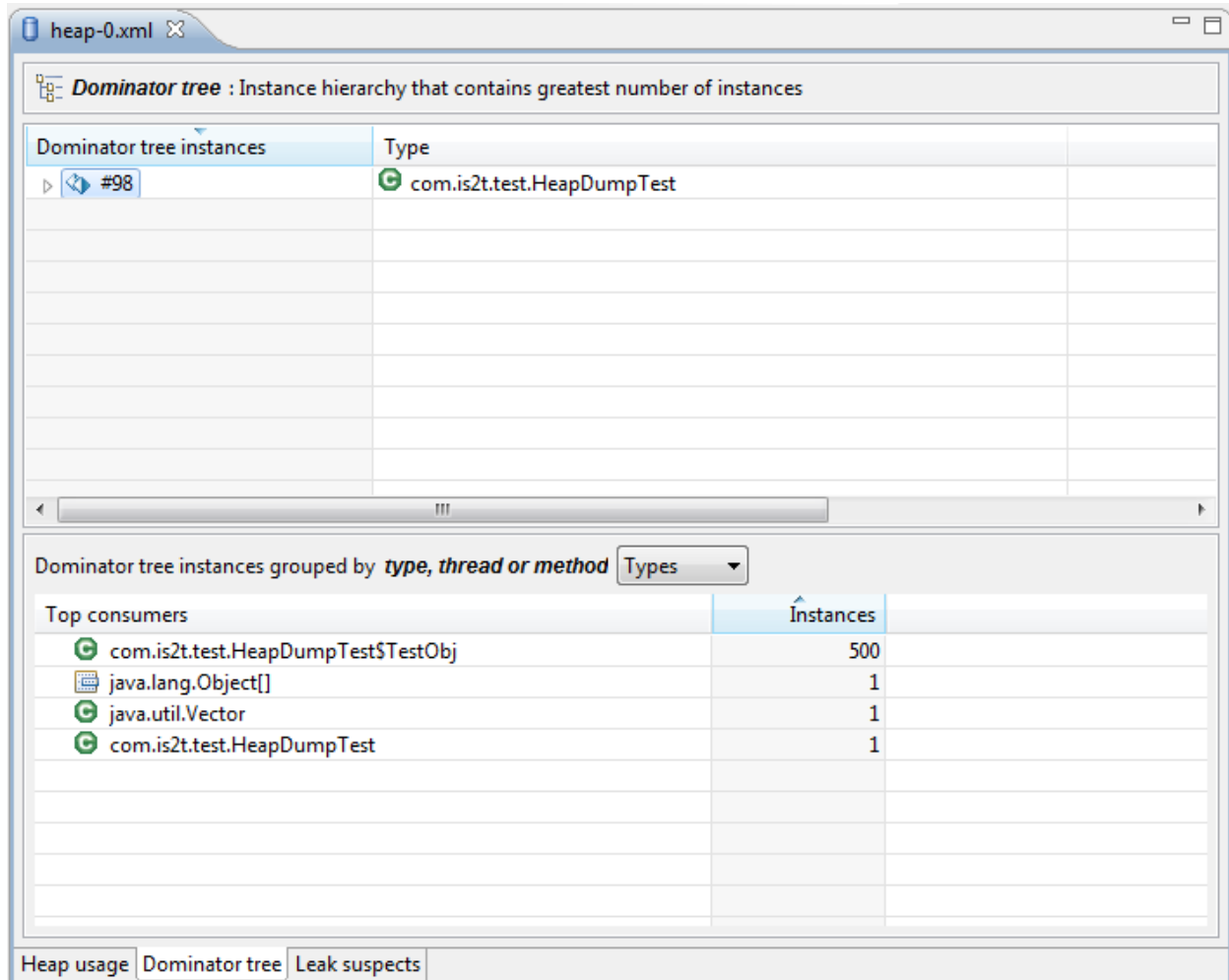


Fig. 48: Heap Viewer - Dominator Tree Tab

### Leak Suspects Tab

The Leak suspects page of the Heap Viewer shows the result of applying heuristics to the relationships between instances in the heap to identify possible memory leaks.

The page is in three parts.

- The top part lists the suspected types (classes). Suspected types are classes which, based on numbers of instances and instance creation frequency, may be implicated in a memory leak.
- The middle part lists accumulation points. An accumulation point is an instance that references a high number of instances of a type that may be implicated in a memory leak.
- The bottom part lists the instances accumulated at an accumulation point.

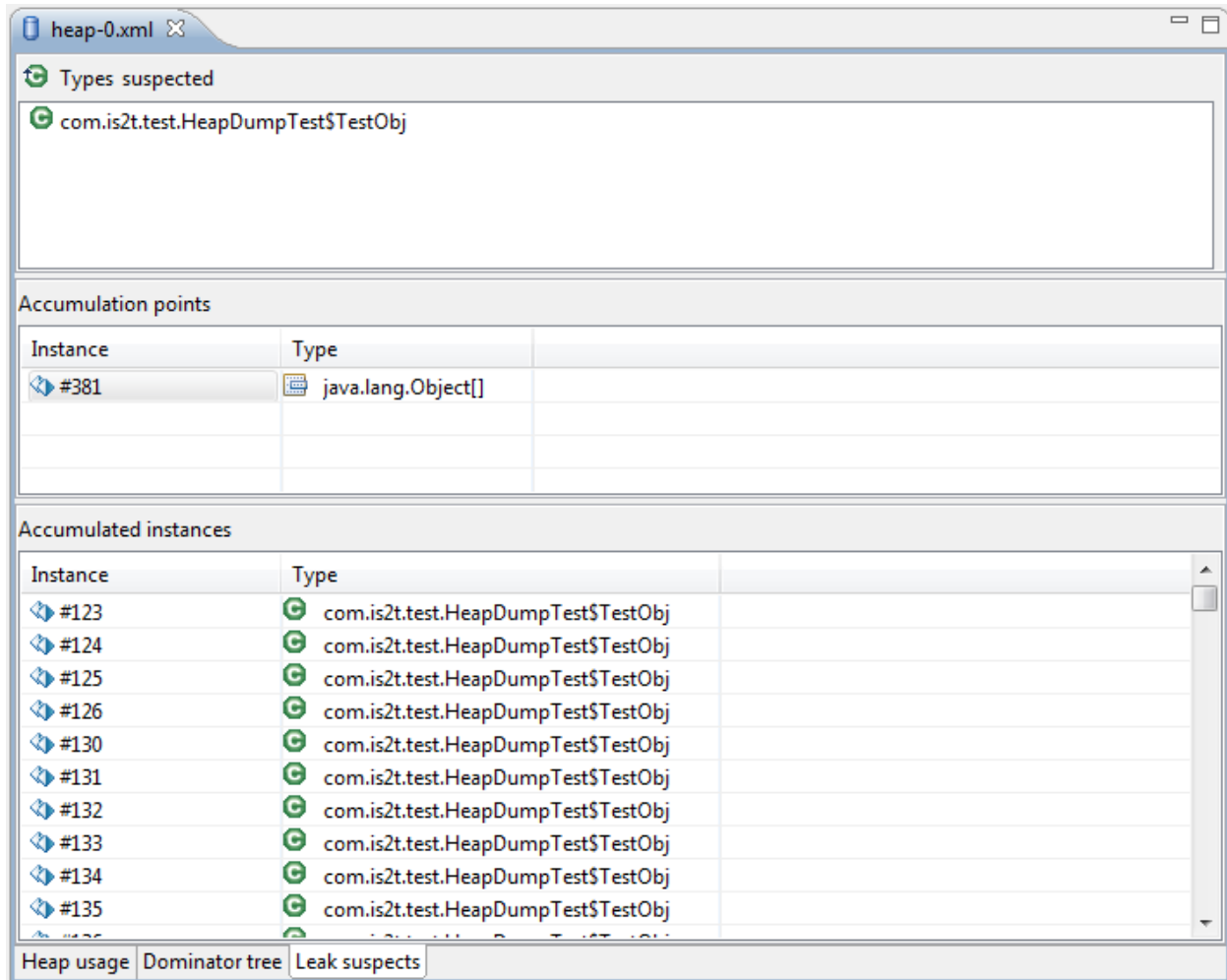


Fig. 49: Heap Viewer - Leak Suspects Tab

### Progressive Heap Usage

To open the Progressive Heap Usage tool, select one or more heap dump XML files in the **Package Explorer**, right-click and select **Heap Analyzer** > **Show progressive heap usage**

This tool is much simpler than the Heap Viewer described above. It comprises three parts.

- The top-right part is a line graph showing the total number of instances in the heap over time, based on the creation times of the instances found in the heap dumps.
- The left part is a pane with three tabs, one showing a list of types in the heap dump, another a list of threads that created instances in the heap dump, and the third a list of methods that created instances in the heap dump.
- The bottom-left is a line graph showing the number of instances in the heap over time restricted to those instances that match with the selection in the left pane. If a type is selected, the graph shows only instances of that type; if a thread is selected the graph shows only instances created by that thread; if a method is selected the graph shows only instances created by that method.

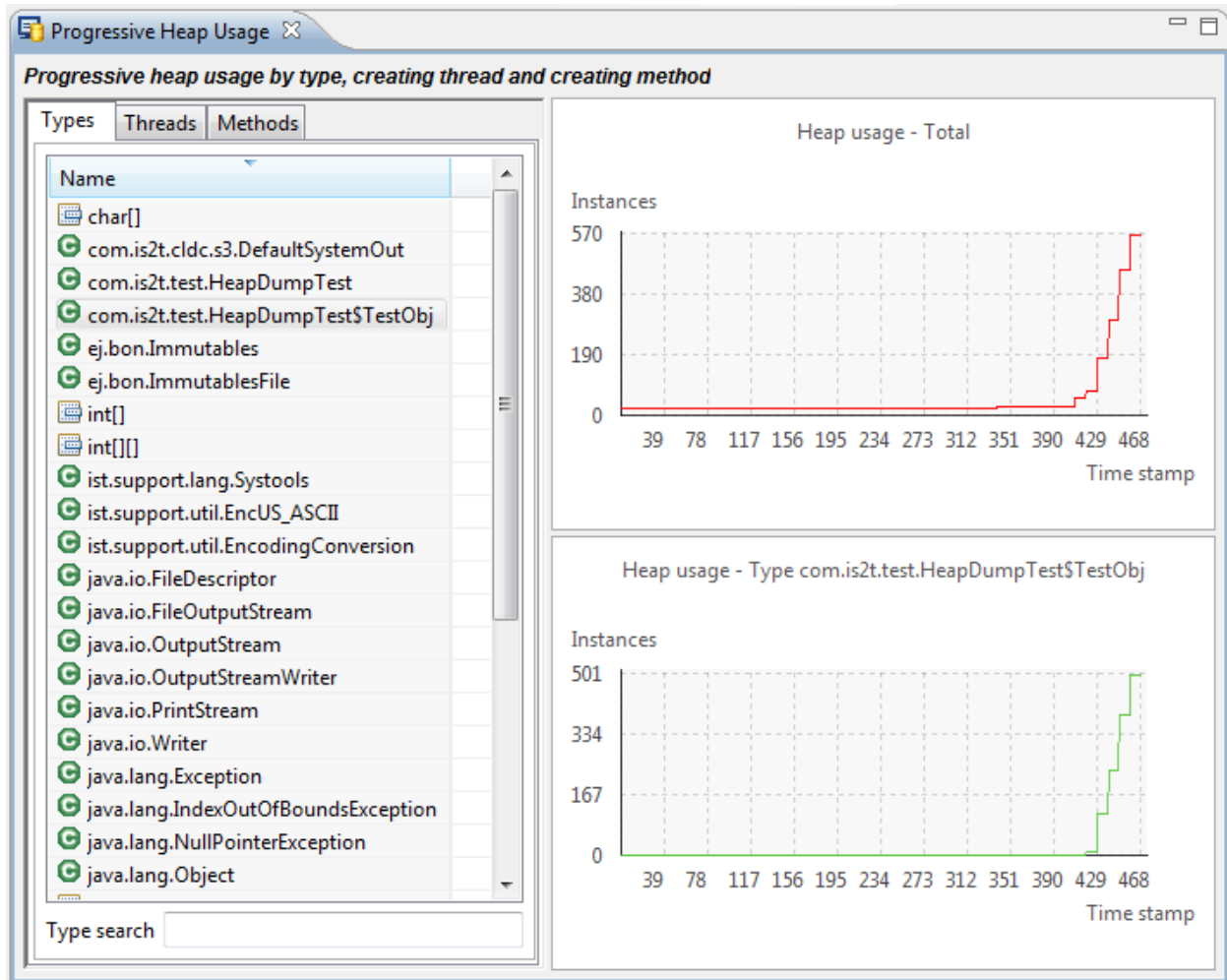


Fig. 50: Progressive Heap Usage

### Compare Heap Dumps

The Compare tool compares the contents of two heap dump files. To open the tool select two heap dump XML files in the Package Explorer, right-click and select **Heap Analyzer** > **Compare**

The Compare tool shows the types in the old heap on the left-hand side, and the types in the new heap on the right-hand side, and marks the differences between them using different colors.

Types in the old heap dump are colored red if there are one or more instances of this type which are in the old dump but not in the new dump. The missing instances have been garbage collected.

Types in the new heap dump are colored green if there are one or more instances of this type which are in the new dump but not in the old dump. These instances were created after the old heap dump was written.

Clicking to the right of the type name unfolds the list to show the instances of the selected type.

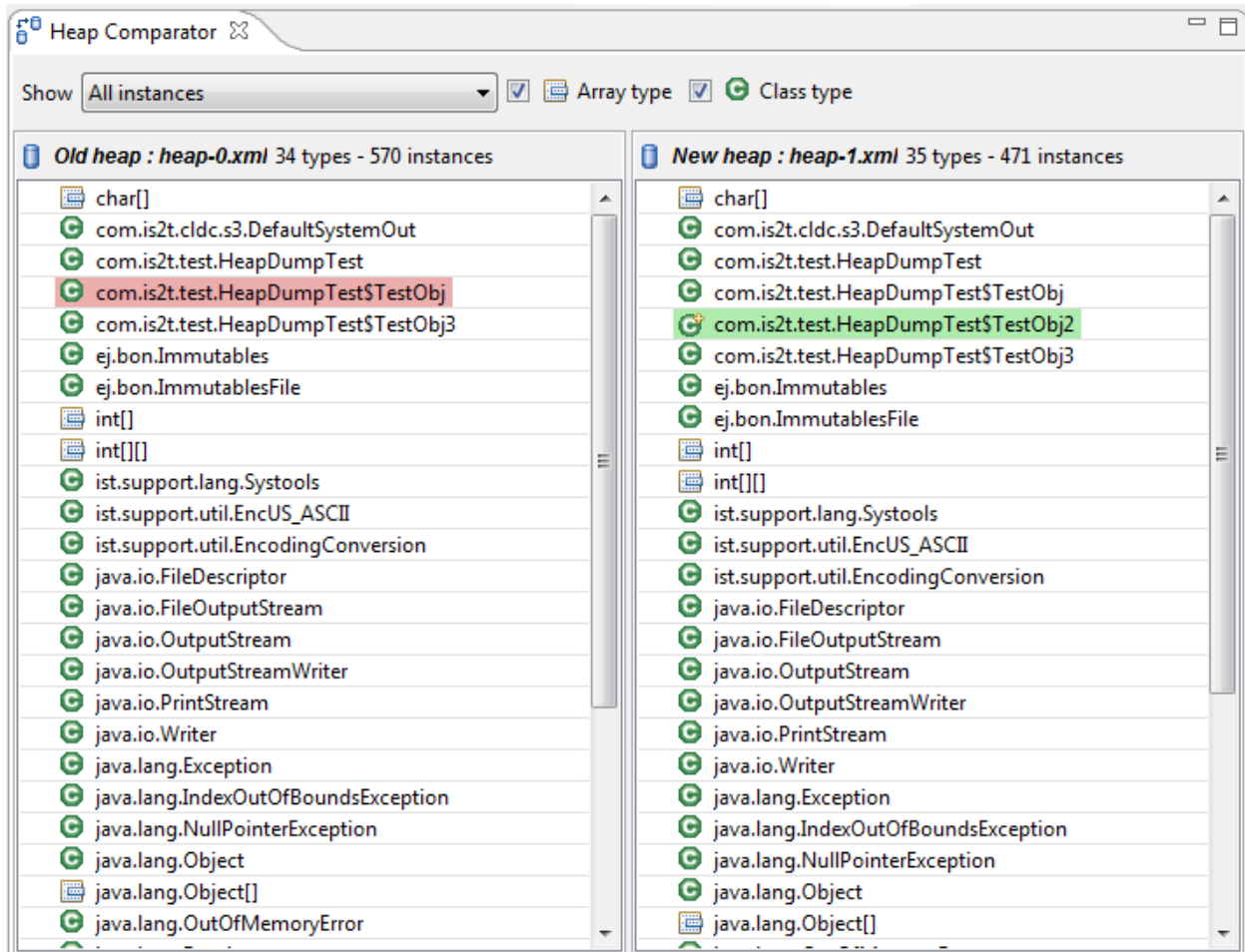


Fig. 51: Compare Heap Dumps

The combo box at the top of the tool allows the list to be restricted in various ways:

- All instances – no restriction.
- Garbage collected and new instances – show only the instances that exist in the old heap dump but not in the new dump, or which exist in the new heap dump but not in the old dump.
- Persistent instances – show only those instances that exist in both the old and new dumps.
- Persistent instances with value changed – show only those instances that exist in both the old and new dumps and have one or more differences in the values of their fields.

### Instance Fields Comparison View

The Compare tool works in conjunction with the Instance Fields Comparison view, which opens automatically when an instance is selected in the tool.

The view shows the values of the fields of the instance in both the old and new heap dumps, and highlights any differences between the values.

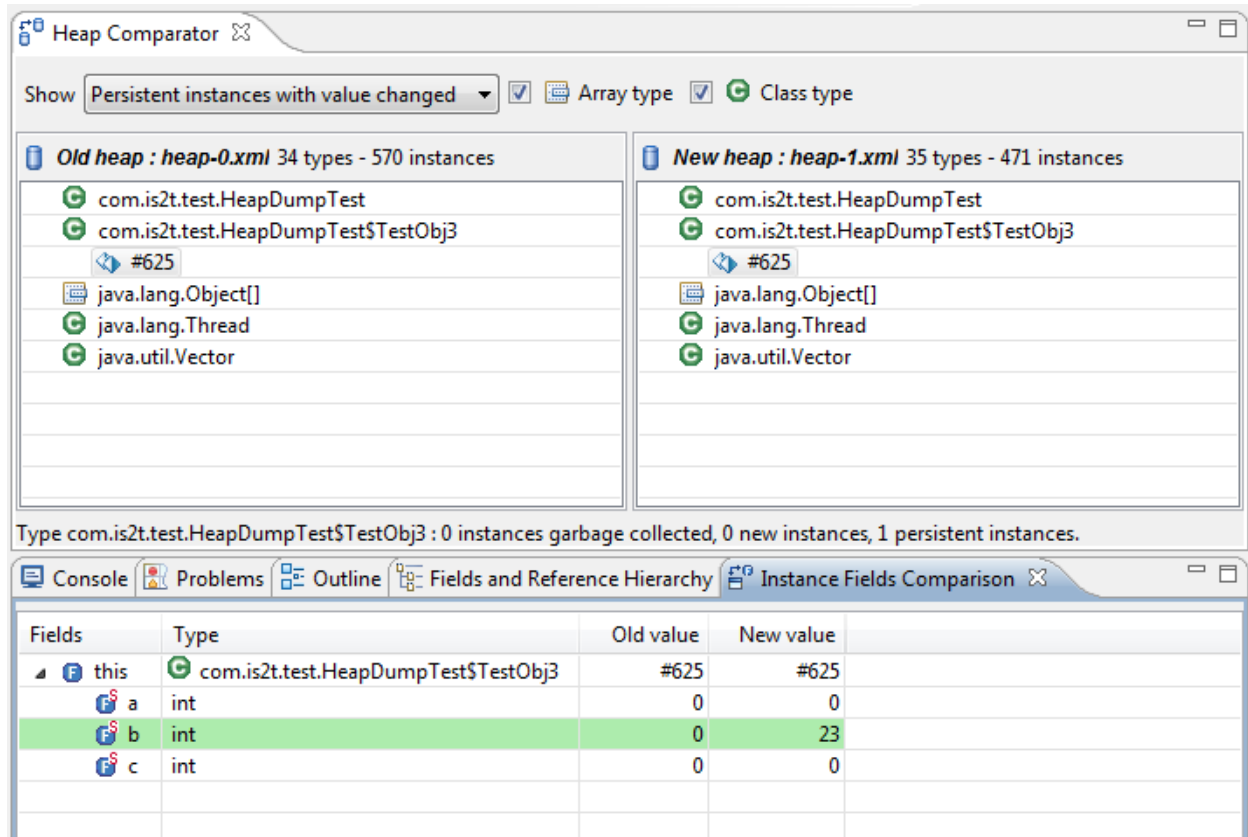


Fig. 52: Instance Fields Comparison view

### 3.10.6 ELF to Map File Generator

#### Principle

The ELF to Map generator takes an ELF executable file and generates a MicroEJ compliant `.map` file. Thus, any ELF executable file produced by third party linkers can be analyzed and interpreted using the *Memory Map Analyzer*.



## Functional Description

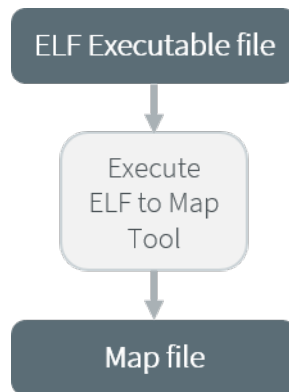


Fig. 53: ELF To Map Process

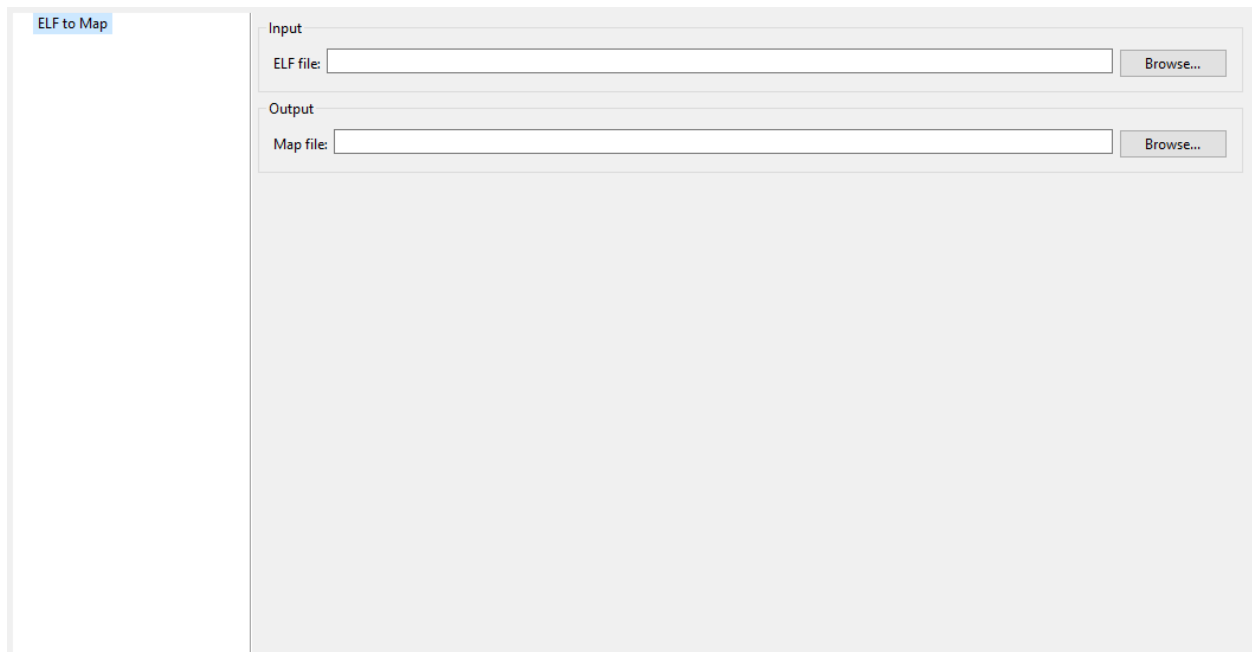
## Installation

This tool is a built-in platform tool.

## Use

This chapter explains MicroEJ tool options.

## Category: ELF to Map



**Group: Input****Option(browse): ELF file**

*Option Name:* `input.file`

*Default value:* `(empty)`

**Group: Output****Option(browse): Map file**

*Option Name:* `output.file`

*Default value:* `(empty)`

### 3.10.7 Serial to Socket Transmitter

**Principle**

The MicroEJ serialToSocketTransmitter is a piece of software which transfers all bytes from a serial port to a tcp client or tcp server.

**Installation**

This tool is a built-in platform tool.

**Use**

This chapter explains MicroEJ tool options.

**Category: Serial to Socket**

The screenshot shows a configuration window for 'Serial to Socket'. On the left is a sidebar with a tab labeled 'Serial to Socket'. The main panel is divided into two sections. The top section, 'Serial Options', contains a 'Port' text field with 'COM0' and a 'Baudrate' dropdown menu showing '115200'. The bottom section, 'Server Options', contains a 'Port' text field with '5555'.

**Group: Serial Options****Option(text): Port**

*Option Name:* `serail.to.socket.comm.port`

*Default value:* `COM0`

*Description:* Defines the COM port:

Windows - `COM1` , `COM2` , ... , `COM*n*`

Linux - `/dev/ttyS0` , `/dev/ttyUSB0` , ... , `/dev/ttyS*n*` , `/dev/ttyUSB*n*`

**Option(combo): Baudrate**

*Option Name:* `serail.to.socket.comm.baudrate`

*Default value:* `115200`

*Available values:*

`9600`

`38400`

`57600`

`115200`

*Description:* Defines the COM baudrate.

**Group: Server Options****Option(text): Port**

*Option Name:* `serail.to.socket.server.port`

*Default value:* `5555`

*Description:* Defines the server IP port.

**3.10.8 Memory Map Analyzer****Principle**

When a MicroEJ Application is linked with the MicroEJ Workbench, a Memory MAP file is generated. The Memory Map Analyzer (MMA) is an Eclipse plug-in made for exploring the map file. It displays the memory consumption of different features in the RAM and ROM.

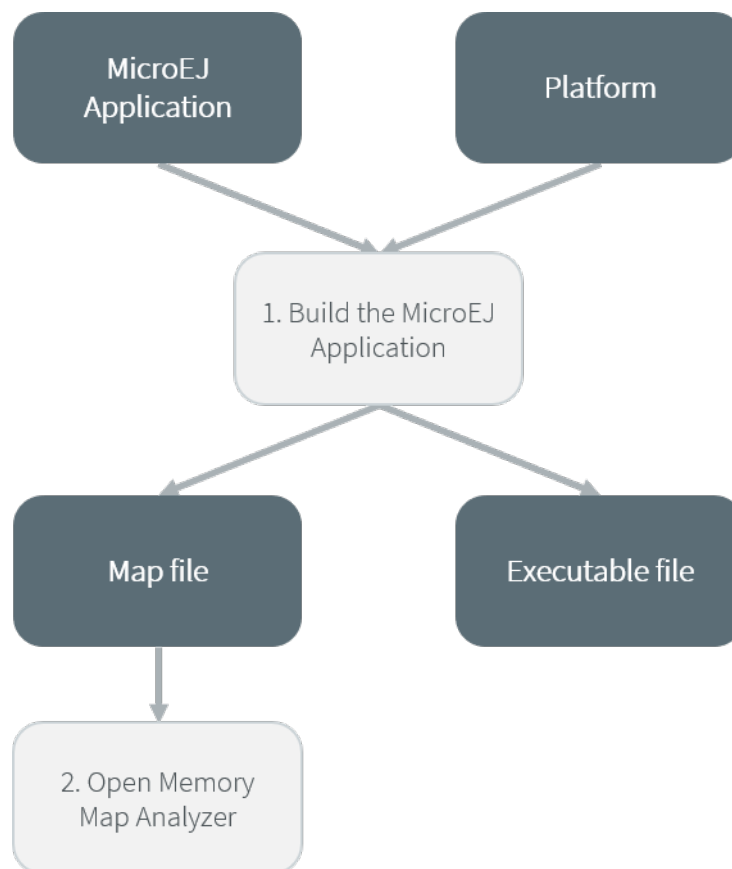
**Functional Description**

Fig. 54: Memory Map Analyzer Process

In addition to the executable file, the MicroEJ Platform generates a map file. Double click on this file to open the Memory Map Analyzer.

Dependencies

No dependency.

Installation

This tool is a built-in platform tool.

Use

The map file is available in the MicroEJ Application project output directory.

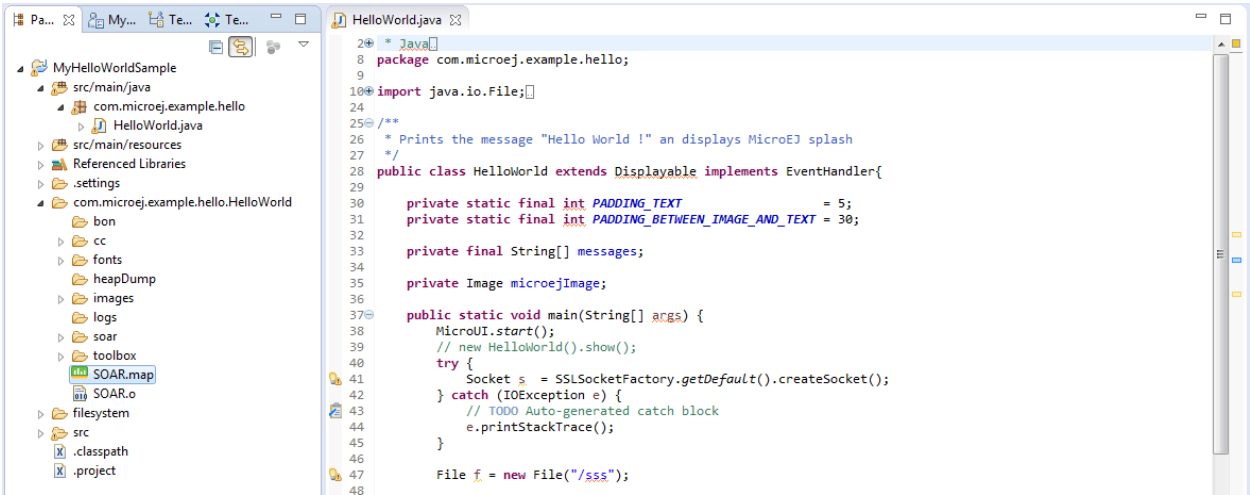


Fig. 55: Retrieve Map File

Select an item (or several) to show the memory used by this item(s) on the right. Select “All” to show the memory used by all items. This special item performs the same action as selecting all items in the list.

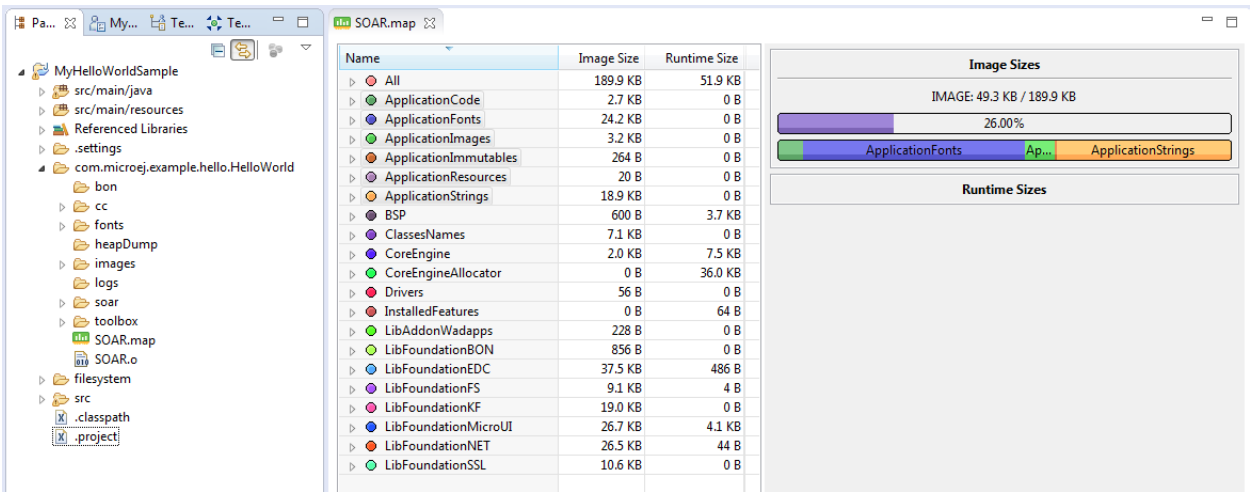


Fig. 56: Consult Full Memory

Select an item in the list, and expand it to see all symbols used by the item. This view is useful in understanding why a symbol is embedded.

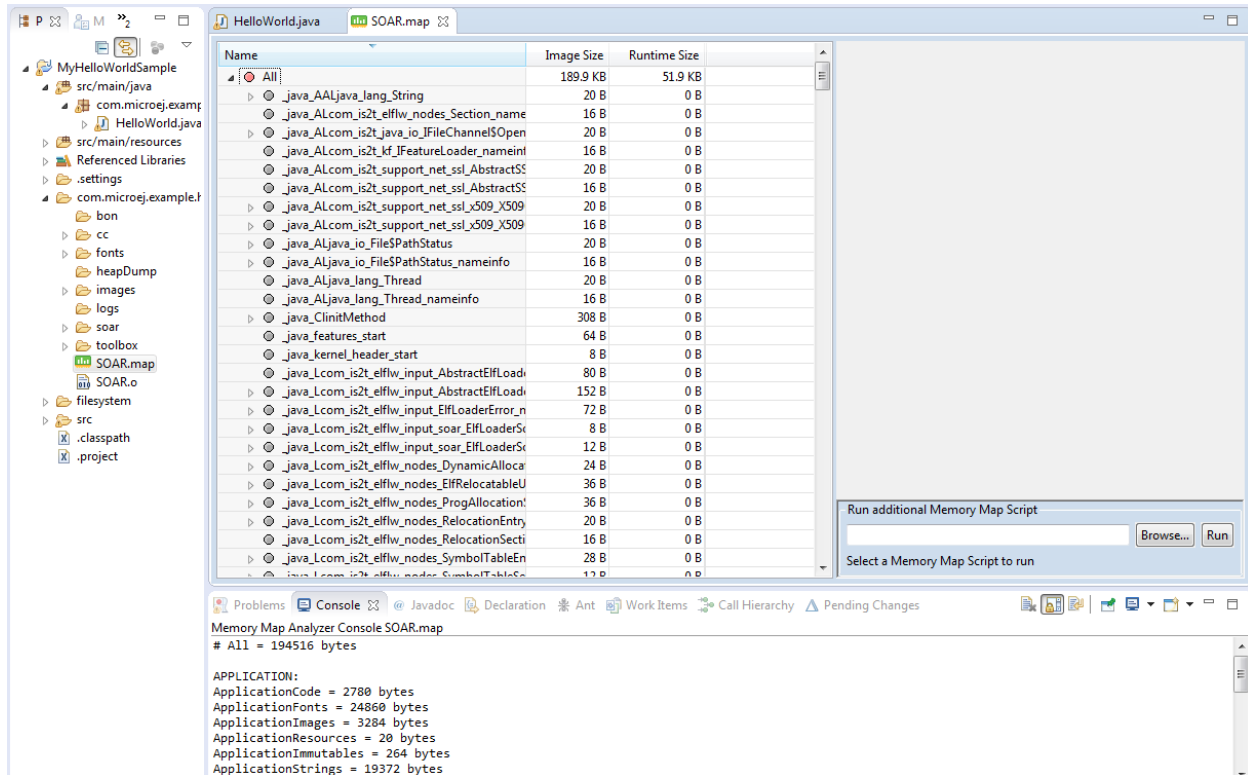


Fig. 57: Detailed View

### 3.10.9 Event Tracing

#### Description

Event Tracing allows to record integer based events for debugging and monitoring purposes without affecting execution performance too heavily. Basically, it gives access to **Tracer** objects that are named and can produce a limited number of different event types.

A record is an event type identified by an **eventID** and can have a list of values. It can be a single event or a period of time with a start and an end.

Event Tracing can be accessed from two APIs:

- A Java API, provided by the **Trace API module**. The following dependency must be added to the *module.ivy* of the MicroEJ Application project:

```
<dependency org="ej.api" name="trace" rev="1.1.0"/>
```

- A C API, provided by the Platform header file named **LLTRACE\_impl.h**.

Events are recorded if and only if:

- the MicroEJ Core Engine trace system is enabled,
- and trace recording is started.

To enable the MicroEJ Core Engine trace system, set the *Application Option* named `core.trace.enabled` to `true` (see also *launch configuration*).

Then, multiple ways are available to start and stop the trace recording:

- by setting the *Application Option* named `core.trace.autostart` to `true` to automatically start at startup (see also *launch configuration*),
- using the Java API methods `ej.trace.Tracer.startTrace()` and `ej.trace.Tracer.stopTrace()`,
- using the C API functions `LLTRACE_IMPL_start(void)` and `LLTRACE_IMPL_stop(void)`.

## Java API Usage

The detailed Trace API documentation is available [here](#).

First, you need to instantiate a `Tracer` object by calling its constructor with two parameters. The first parameter, `name`, is a String that will represent the `Tracer` object group's name. The second parameter, `nbEventTypes`, is an integer representing the maximum number of event types available for the group.

```
Tracer tracer = new Tracer("MyGroup", 10);
```

Then, you can record an event by calling the `recordEvent(int eventId)` method. The event ID needs to be in the range `0` to `nbEventTypes-1` with `nbEventTypes` the maximum number of event types set when initializing the `Tracer` object. Methods named `recordEvent(...)` always needs the event ID as the first parameter and can have up to ten integer parameters as custom values for the event.

To record the end of an event, call the method `recordEventEnd(int eventId)`. It will trace the duration of an event previously recorded with one of the `recordEvent(int)` methods. The `recordEventEnd(...)` method can also have another integer parameter for a custom value for the event end. One can use it to trace the returned value of a method.

The Trace API also provides a String constant `Tracer.TRACE_ENABLED_CONSTANT_PROPERTY` representing the *Constant* value of `core.trace.enabled` option. This constant can be used to *remove at build time* portions of code when the trace system is disabled. To do that, just surround tracer record calls with a if statement that checks the constant's state. When the constant is set to `false`, the code inside the if statement will not be embedded with the application and thus will not impact the performances.

```
if(Constants.getBoolean(Tracer.TRACE_ENABLED_CONSTANT_PROPERTY)) {
    // This code is not embedded if TRACE_ENABLED_CONSTANT_PROPERTY is set to false.
    tracer.recordEventEnd(0);
}
```

Examples:

- Trace a single event:

```
private static final Tracer tracer = new Tracer("Application", 100);

public static void main(String[] args) {
    Tracer.startTrace();
    tracer.recordEvent(0);
}
```

Standard Output:

```
VM START
[TRACE] [1] Declare group "Application"
[TRACE] [1] Event 0x0
```

- Trace a method with a start event showing the parameters of the method and an end event showing the result:

```
private static final Tracer tracer = new Tracer("Application", 100);

public static void main(String[] args) {
    Tracer.startTrace();
    int a = 14;
    int b = 54;
    add(a, b);
}

public static int add(int a, int b) {
    tracer.recordEvent(1, a, b);
    int result = a + b;
    tracer.recordEventEnd(1, result);
    return result;
}
```

Standard Output:

```
VM START
[TRACE] [1] Declare group "Application"
[TRACE] [1] Event 0x1 (14 [0xE],54 [0x36])
[TRACE] [1] Event End 0x1 (68 [0x44])
```

## Platform Implementation

By default, when enabled, the Trace API displays a message in the standard output for every `recordEvent(...)` and `recordEventEnd(...)` method calls.

It does not print a timestamp when displaying the trace message because it can drastically affect execution performances. It only prints the ID of the recorded event followed by the values given in parameters.

A Platform can connect its own implementation by overriding the functions defined in the `LLTRACE_impl.h` file.

MicroEJ provides an implementation for **SEGGER SystemView** tool. Please contact MicroEJ Support for more information about how to integrate this Platform module.

## 3.11 Advanced Tools

### 3.11.1 MicroEJ Linker

#### Overview

MicroEJ Linker is a standard linker that is compliant with the Executable and Linkable File format (ELF).

MicroEJ Linker takes one or several relocatable binary files and generates an image representation using a description file. The process of extracting binary code, positioning blocks and resolving symbols is called linking.

Relocatable object files are generated by SOAR and third-party compilers. An archive file is a container of Relocatable object files.

The description file is called a Linker Specific Configuration file (lsc). It describes what shall be embedded, and how those things shall be organized in the program image. The linker outputs :



- An ELF executable file that contains the image and potential debug sections. This file can be directly used by debuggers or programming tools. It may also be converted into another format (Intel\* hex, Motorola\* s19, rawBinary, etc.) using external tools, such as standard GNU binutils toolchain (objcopy, objdump, etc.).
- A map file, in XML format, which can be viewed as a database of what has been embedded and resolved by the linker. It can be easily processed to get a sort of all sizes, call graphs, statistics, etc.
- The linker is composed with one or more library loaders, according to the platform's configuration.

## ELF Overview

An ELF relocatable file is split into several sections:

- allocation sections representing a part of the program
- control sections describing the binary sections (relocation sections, symbol tables, debug sections, etc.)

An allocation section can hold some image binary bytes (assembler instructions and raw data) or can refer to an interval of memory which makes sense only at runtime (statics, main stack, heap, etc.). An allocation section is an atomic block and cannot be split. A section has a name that by convention, represents the kind of data it holds. For example, `.text` sections hold binary instructions, `.bss` sections hold read-write static data, `.rodata` hold read-only data, and `.data` holds read-write data (initialized static data). The name is used in the `.lsc` file to organize sections.

A symbol is an entity made of a name and a value. A symbol may be absolute (link-time constant) or relative to a section: Its value is unknown until MicroEJ Linker has assigned a definitive position to the target section. A symbol can be local to the relocatable file or global to the system. All global symbol names should be unique in the system (the name is the key that connects an unresolved symbol reference to a symbol definition). A section may need the value of symbols to be fully resolved: the address of a function called, address of a static variable, etc.

## Linking Process

The linking process can be divided into three main steps:

1. Symbols and sections resolution. Starting from root symbols and root sections, the linker embeds all sections targeted by symbols and all symbols referred by sections. This process is transitive while new symbols and/or sections are found. At the end of this step, the linker may stop and output errors (unresolved symbols, duplicate symbols, unknown or bad input libraries, etc.)
2. Memory positioning. Sections are laid out in memory ranges according to memory layout constraints described by the `.lsc` file. Relocations are performed (in other words, symbol values are resolved and section contents are modified). At the end of this step, the linker may stop and output errors (it could not resolve constraints, such as not enough memory, etc.)
3. An output ELF executable file and map file are generated.

A partial map file may be generated at the end of step 2. It provides useful information to understand why the link phase failed. Symbol resolution is the process of connecting a global symbol name to its definition, found in one of the linker input units. The order the units are passed to the linker may have an impact on symbol resolution. The rules are :

- Relocatable object files are loaded without order. Two global symbols defined with the same name result in an unrecoverable linker error.
- Archive files are loaded on demand. When a global symbol must be resolved, the linker inspects each archive unit in the order it was passed to the linker. When an archive contains a relocatable object file that declares the symbol, the object file is extracted and loaded. Then the first rule is applied. It is recommended that you group object files in archives as much as possible, in order to improve load performances. Moreover, archive files are the only way to tie with relocatable object files that share the same symbols definitions.

- A symbol name is resolved to a weak symbol if - and only if - no global symbol is found with the same name.

## Linker Specific Configuration File Specification

### Description

A Linker Specific Configuration (Lsc) file contains directives to link input library units. An lsc file is written in an XML dialect, and its contents can be divided into two principal categories:

- Symbols and sections definitions.
- Memory layout definitions.

Listing 5: Example of Relocation of Runtime Data from FLASH to RAM

```
<?xml version="1.0" encoding="UTF-8"?>
<!--
  An example of linker specific configuration file
-->
<lsc name="MyAppInFlash">
  <include name="subfile.lscf"/>
  <!--
    Define symbols with arithmetical and logical expressions
  -->
  <defSymbol name="FlashStart" value="0"/>
  <defSymbol name="FlashSize" value="0x10000"/>
  <defSymbol name="FlashEnd" value="FlashStart+FlashSize-1"/>
  <!--
    Define FLASH memory interval
  -->
  <defSection name="FLASH" start="FlashStart" size="FlashSize"/>

  <!--
    Some memory layout directives
  -->
  <memoryLayout ranges="FLASH">
    <sectionRef name="*.text"/>
    <sectionRef name="*.data"/>
  </memoryLayout>
</lsc>
```

### File Fragments

An lsc file can be physically divided into multiple lsc files, which are called lsc fragments. Lsc fragments may be loaded directly from the linker path option, or indirectly using the include tag in an lsc file.

Lsc fragments start with the root tag `lscFragment`. By convention the lsc fragments file extension is `.lscf`. From here to the end of the document, the expression “the lsc file” denotes the result of the union of all loaded (directly and indirectly loaded) lsc fragments files.

### Symbols and Sections

A new symbol is defined using `defSymbol` tag. A symbol has a name and an expression value. All symbols defined in the lsc file are global symbols.

A new section is defined using the `defSection` tag. A section may be used to define a memory interval, or define a chunk of the final image with the description of the contents of the section.

## Memory Layout

A memory layout contains an ordered set of statements describing what shall be embedded. Memory positioning can be viewed as moving a cursor into intervals, appending referenced sections in the order they appear. A symbol can be defined as a “floating” item: Its value is the value of the cursor when the symbol definition is encountered. In *the example below*, the memory layout sets the `FLASH` section. First, all sections named `.text` are embedded. The matching sections are appended in a undefined order. To reference a specific section, the section shall have a unique name (for example a reset vector is commonly called `.reset` or `.vector`, etc.). Then, the floating symbol `dataStart` is set to the absolute address of the virtual cursor right after embedded `.text` sections. Finally all sections named `.data` are embedded.

A memory layout can be relocated to a memory interval. The positioning works in parallel with the layout ranges, as if there were two cursors. The address of the section (used to resolve symbols) is the address in the relocated interval. Floating symbols can refer either to the layout cursor (by default), or to the relocated cursor, using the `relocation` attribute. A relocation layout is typically used to embed data in a program image that will be used at runtime in a read-write memory. Assuming the program image is programmed in a read only memory, one of the first jobs at runtime, before starting the main program, is to copy the data from read-only memory to `RAM`, because the symbols targeting the data have been resolved with the address of the sections in the relocated space. To perform the copy, the program needs both the start address in `FLASH` where the data has been put, and the start address in `RAM` where the data shall be copied.

Listing 6: Example of Relocation of Runtime Data from *FLASH* to *RAM*

```
<memoryLayout ranges="FLASH" relocation="RAM" image="true">
  <defSymbol name="DataFlashStart" value="." />
  <defSymbol name="DataRamStart" value="." relocation="true" />
  <sectionRef name=".data" />
  <defSymbol name="DataFlashLimit" value="." />
</memoryLayout>
```

**Note:** the symbol `DataRamStart` is defined to the start address where `.data` sections will be inserted in `RAM` memory.

## Tags Specification

Here is the complete syntactical and semantical description of all available tags of the `.lsc` file.

Table 5: Linker Specific Configuration Tags

Tags	Attributes	Description
<code>defSection</code>		Defines a new section. A floating section only holds a declared <code>size</code> attribute. A fixed section declares at least one of the <code>start</code> / <code>end</code> attributes. When this tag is empty, the section is a runtime section, and must define at least one of the <code>start</code> , <code>end</code> or <code>size</code> attributes. When this tag is not empty (when it holds a binary description), the section is an image section.

Continued on next page

Table 5 – continued from previous page

Tags	Attributes	Description
	<b>name</b>	Name of the section. The section name may not be unique. However, it is recommended that you define a unique name if the section must be referred separately for memory positioning.
	<b>start</b>	Optional. Expression defining the absolute start address of the section. Must be resolved to a constant after the full load of the lsc file.
	<b>end</b>	Optional. Expression defining the absolute end address of the section. Must be resolved to a constant after the full load of the lsc file.
	<b>size</b>	Optional. Expression defining the size in bytes of the section. Invariant: $(end - start) + 1 = size$ . Must be resolved to a constant after the full load of the lsc file.
	<b>align</b>	Optional. Expression defining the alignment in bytes of the section.
	<b>rootSection</b>	Optional. Boolean value. Sets this section as a root section to be embedded even if it is not targeted by any embedded symbol. See also <b>rootSection</b> tag.
	<b>symbolPrefix</b>	Optional. Used in collaboration with <b>symbolTags</b> . Prefix of symbols embedded in the auto-generated section. See <i>Auto-generated Sections</i> .
	<b>symbolTags</b>	Optional. Used in collaboration with <b>symbolPrefix</b> . Comma separated list of tags of symbols embedded in the auto-generated section. See <i>Auto-generated Sections</i> .
<b>defSymbol</b>		Defines a new global symbol. Symbol name must be unique in the linker context
	<b>name</b>	Name of the symbol.
	<b>type</b>	Optional. Type of symbol usage. This may be necessary to set the type of a symbol when using third party ELF tools. There are three types: - <b>none</b> : default. No special type of use. - <b>function</b> : symbol describes a function. - <b>data</b> : symbol describes some data.
	<b>value</b>	The value <b>"."</b> defines a floating symbol that holds the current cursor position in a memory layout. (This is the only form of this tag that can be used as a memoryLayout directive) Otherwise value is an expression. A symbol expression must be resolved to a constant after memory positioning.
	<b>relocation</b>	Optional. The only allowed value is <b>true</b> . Indicates that the value of the symbol takes the address of the current cursor in the memory layout relocation space. Only allowed on floating symbols.
	<b>rootSymbol</b>	Optional. Boolean value. Sets this symbol as a root symbol that must be resolved. See also <b>rootSymbol</b> tag.
	<b>weak</b>	Optional. Boolean value. Sets this symbol as a weak symbol.
<b>group</b>		memoryLayout directive. Defines a named group of sections. Group name may be used in expression macros <b>START</b> , <b>END</b> , <b>SIZE</b> . All memoryLayout directives are allowed within this tag (recursively).
	<b>name</b>	The name of the group.
<b>include</b>		Includes an lsc fragment file, semantically the same as if the fragment contents were defined in place of the <b>include</b> tag.
	<b>name</b>	Name of the file to include. When the name is relative, the file separator is <b>/</b> , and the file is relative to the directory where the current lsc file or fragment is loaded. When absolute, the name describes a platform-dependent filename.
<b>lsc</b>		Root tag for an .lsc file.
	<b>name</b>	Name of the lsc file. The ELF executable output will be <b>{name}.out</b> , and the map file will be <b>{name}.map</b>

Continued on next page

Table 5 – continued from previous page

Tags	Attributes	Description
<code>lscFragment</code>		Root tag for an lsc file fragment. Lsc fragments are loaded from the linker path option, or included from a master file using the <code>include</code> tag.
<code>memoryLayout</code>		Describes the organization of a set of memory intervals. The memory layouts are processed in the order in which they are declared in the file. The same interval may be organized in several layouts. Each layout starts at the value of the cursor the previous layout ended. The following tags are allowed within a <code>memoryLayout</code> directive: <code>defSymbol</code> (under certain conditions), <code>group</code> , <code>memoryLayoutRef</code> , <code>padding</code> , and <code>sectionRef</code> .
	<code>ranges</code>	Exclusive with default. Comma-separated ordered list of fixed sections to which the layout is applied. Sections represent memory segments.
	<code>image</code>	Optional. Boolean value. <code>false</code> if not set. If <code>true</code> , the layout describes a part of the binary image: Only image sections can be embedded. If <code>false</code> , only runtime sections can be embedded.
	<code>relocation</code>	Optional. Name of the section to which this layout is relocated.
	<code>name</code>	Exclusive with ranges. Defines a named <code>memoryLayout</code> directive instead of specifying a concrete memory location. May be included in a parent <code>memoryLayout</code> using <code>memoryLayoutRef</code> .
<code>memoryLayoutRef</code>		<code>memoryLayout</code> directive. Provides an extension-point mechanism to include <code>memoryLayout</code> directives defined outside the current one.
	<code>name</code>	All directives of <code>memoryLayout</code> defined with the same name are included in an undefined order.
<code>padding</code>		<code>memoryLayout</code> directive. Append padding bytes to the current cursor. Either size or align attributes should be provided.
	<code>size</code>	Optional. Expression must be resolved to a constant after the full load of the lsc file. Increment the cursor position with the given size.
	<code>align</code>	Optional. Expression must be resolved to a constant after the full load of the lsc file. Move the current cursor position to the next address that matches the given alignment. Warning: when used with relocation, the relocation cursor is also aligned. Keep in mind this may increase the cursor position with a different amount of bytes.
	<code>address</code>	Optional. Expression must be resolved to a constant after the full load of the lsc file. Move the current cursor position to the given absolute address.
	<code>fill</code>	Optional. Expression must be resolved to a constant after the full load of the lsc file. Fill padding with the given value (32 bits).
<code>rootSection</code>		References a section name that must be embedded. This tag is not a definition. It forces the linker to embed all loaded sections matching the given name.
	<code>name</code>	Name of the section to be embedded.
<code>rootSymbol</code>		References a symbol that must be resolved. This tag is not a definition. It forces the linker to resolve the value of the symbol.
	<code>name</code>	Name of the symbol to be resolved.
<code>sectionRef</code>		Memory layout statement. Embeds all sections matching the given name starting at the current cursor address.
	<code>file</code>	Select only sections defined in a linker unit matching the given file name. The file name is the simple name without any file separator, e.g. <code>bsp.o</code> or <code>mylink.lsc</code> . Link units may be object files within archive units.

Continued on next page

Table 5 – continued from previous page

Tags	Attributes	Description
	<b>name</b>	Name of the sections to embed. When the name ends with *, all sections starting with the given name are embedded (name completion), except sections that are embedded in another sectionRef using the exact name (without completion).
	<b>symbol</b>	Optional. Only embeds the section targeted by the given symbol. This is the only way at link level to embed a specific section whose name is not unique.
	<b>force</b>	Optional. Deprecated. Replaced by the <b>rootSection</b> tag. The only allowed value is <b>true</b> . By default, for compaction, the linker embeds only what is needed. Setting this attribute will force the linker to embed all sections that appear in all loaded relocatable files, even sections that are not targeted by a symbol.
	<b>sort</b>	Optional. Specifies that the sections must be sorted in memory. The value can be: - <b>order</b> : the sections will be in the same order as the input files - <b>name</b> : the sections are sorted by their file names - <b>unit</b> : the sections declared in an object file are grouped and sorted in the order they are declared in the object file
<b>u4</b>		Binary section statement. Describes the four next raw bytes of the section. Bytes are organized in the endianness of the target ELF executable.
	<b>value</b>	Expression must be resolved to a constant after the full load of the lsc file (32 bits value).
<b>file</b>		Binary section statement. Fills the section with the given expression. Bytes are organized in the endianness of the target ELF executable.
	<b>size</b>	Expression defining the number of bytes to be filled.
	<b>value</b>	Expression must be resolved to a constant after the full load of the lsc file (32 bits value).

## Expressions

An attribute expression is a value resulting from the computation of an arithmetical and logical expression. Supported operators are the same operators supported in the Java language, and follow Java semantics:

- Unary operators: **+** , **-** , **~** , **!**
- Binary operators: **+** , **-** , **\*** , **/** , **%** , **<<** , **>>>** , **>>** , **<** , **>** , **<=** , **>=** , **==** , **!=** , **&** , **|** , **^** , **&&** , **||**
- Ternary operator: **cond ? ifTrue : ifFalse**
- Built-in macros:
  - **START(name)** : Get the start address of a section or a group of sections
  - **END(name)** : Get the end address of a section or a group of sections
  - **SIZE(name)** : Get the size of a section or a group of sections. Equivalent to **END(name)-START(name)**
  - **TSTAMPH()** , **TSTAMPL()** : Get 32 bits linker time stamp (high/low part of system time in milliseconds)
  - **SUM(name, tag)** : Get the sum of an auto-generated section (*Auto-generated Sections*) column. The column is specified by its tag name.

An operand is either a sub expression, a constant, or a symbol name. Constants may be written in decimal (**127**) or hexadecimal form (**0x7F**). There are no boolean constants. Constant value **0** means **false**, and other constants' values mean **true**. Examples of use:

```
value="symbol+3"
value="(symbol1*4)-(symbol2*3)"
```

Note: Ternary expressions can be used to define selective linking because they are the only expressions that may remain partially unresolved without generating an error. Example:

```
<defSymbol name="myFunction" value="condition ? symb1 : symb2"/>
```

No error will be thrown if the condition is `true` and `symb1` is defined, or the condition is `false` and `symb2` is defined, even if the other symbol is undefined.

## Auto-generated Sections

The MicroEJ Linker allows you to define sections that are automatically generated with symbol values. This is commonly used to generate tables whose contents depends on the linked symbols. Symbols eligible to be embedded in an auto-generated section are of the form: `prefix_tag_suffix`. An auto-generated section is viewed as a table composed of lines and columns that organize symbols sharing the same prefix. On the same column appear symbols that share the same tag. On the same line appear symbols that share the same suffix. Lines are sorted in the lexical order of the symbol name. The next line defines a section which will embed symbols starting with `zeroinit`. The first column refers to symbols starting with `zeroinit_start_`; the second column refers to symbols starting with `zeroinit_end_`.

```
<defSection
    name=".zeroinit"
    symbolPrefix="zeroInit"
    symbolTags="start,end"
/>
```

Consider there are four defined symbols named `zeroinit_start_xxx`, `zeroinit_end_xxx`, `zeroinit_start_yyy` and `zeroinit_end_yyy`. The generated section is of the form:

```
0x00: zeroinit_start_xxx
0x04: zeroinit_end_xxx
0x08: zeroinit_start_yyy
0x0C: zeroinit_end_yyy
```

If there are missing symbols to fill a line of an auto-generated section, an error is thrown.

## Execution

MicroEJ Linker can be invoked through an ANT task. The task is installed by inserting the following code in an ANT script

```
<taskdef
    name="linker"
    classname="com.is2t.linker.GenericLinkerTask"
    classpath="[LINKER_CLASSPATH]"
/>
```

`[LINKER_CLASSPATH]` is a list of path-separated jar files, including the linker and all architecture-specific library loaders.

The following code shows a linker ANT task invocation and available options.

```
<linker
  doNotLoadAlreadyDefinedSymbol="[true|false]"
  endianness="[little|big|none]"
  generateMapFile="[true|false]"
  ignoreWrongPositioningForEmptySection="[true|false]"
  lsc="[filename]"
  linkPath="[path1:...pathN]"
  mergeSegmentSections="[true|false]"
  noWarning="[true|false]"
  outputArchitecture="[tag]"
  outputName="[name]"
  stripDebug="[true|false]"
  toDir="[outputDir]"
  verboseLevel="[0...9]"
>
  <!-- ELF object & archives files using ANT paths / filesets -->
  <fileset dir="xxx" includes="*.o">
  <fileset file="xxx.a">
  <fileset file="xxx.a">

  <!-- Properties that will be reported into .map file -->
  <property name="myProp" value="myValue"/>
</linker>
```



Table 6: Linker Options Details

Option	Description
<code>doNotLoadAlreadyDefinedSymbol</code>	Silently skip the load of a global symbol if it has already been loaded before. ( <code>false</code> by default. Only the first loaded symbol is taken into account (in the order input files are declared). This option only affects the load semantic for global symbols, and does not modify the semantic for loading weak symbols and local symbols.
<code>endianness</code>	Explicitly declare linker endianness [ <code>little</code> , <code>big</code> ] or [ <code>none</code> ] for auto-detection. All input files must declare the same endianness or an error is thrown.
<code>generateMapFile</code>	Generate the <code>.map</code> file ( <code>true</code> by default).
<code>ignoreWrongPositioningForEmptySection</code>	Silently ignore wrong section positioning for zero size sections. ( <code>false</code> by default).
<code>lsc</code>	Provide a master lsc file. This option is mandatory unless the <code>linkPath</code> option is set.
<code>linkPath</code>	Provide a set of directories into which to load link file fragments. Directories are separated with a platform-path separator. This option is mandatory unless the <code>lsc</code> option is set.
<code>noWarning</code>	Silently skip the output of warning messages.
<code>mergeSegmentSections</code>	( <i>experimental</i> ). Generate a single section per segment. This may speed up the load of the output executable file into debuggers or flasher tools. ( <code>false</code> by default).
<code>outputArchitecture</code>	Set the architecture tag for the output ELF file (ELF machine id).
<code>outputName</code>	Specify the output name of the generated files. By default, take the name provided in the lsc tag. The output ELF executable filename will be <code>name.out</code> . The map filename will be <code>name.map</code> .
<code>stripDebug</code>	Remove all debug information from the output ELF file. A stripped output ELF executable holds only the binary image (no remaining symbols, debug sections, etc.).
<code>toDir</code>	Specify the output directory in which to store generated files. Output filenames are in the form: <code>od + separator + value of the lsc name attribute + suffix</code> . By default, without this option, files are generated in the directory from which the linker was launched.
<code>verboseLevel</code>	Print additional messages on the standard output about linking process.

## Error Messages

This section lists MicroEJ Linker error messages.

Table 7: Linker-Specific Configuration Tags

Message ID	Description
0	The linker has encountered an unexpected internal error. Please contact the support hotline.

Continued on next page

Table 7 – continued from previous page

1	A library cannot be loaded with this linker. Try verbose to check installed loaders.
2	No lsc file provided to the linker.
3	A file could not be loaded. Check the existence of the file and file access rights.
4	Conflicting input libraries. A global symbol definition with the same name has already been loaded from a previous object file.
5	Completion (*) could not be used in association with the force attribute. Must be an exact name.
6	A required section refers to an unknown global symbol. Maybe input libraries are missing.
7	A library loader has encountered an unexpected internal error. Check input library file integrity.
8	Floating symbols can only be declared inside <code>memoryLayout</code> tags.
9	Invalid value format. For example, the attribute relocation in <code>defSymbol</code> must be a boolean value.
10	Missing one of the following attributes: <code>address</code> , <code>size</code> , <code>align</code> .
11	Too many attributes that cannot be used in association.
13	Negative padding. Memory layout cursor cannot decrease.
15	Not enough space in the memory layout intervals to append all sections that need to be embedded. Check the output map file to get more information about what is required as memory space.
16	A block is referenced but has already been embedded. Most likely a block has been especially embedded using the force attribute and the symbol attribute.
17	A block that must be embedded has no matching <code>sectionRef</code> statement.
19	An IO error occurred when trying to dump one of the output files. Check the output directory option and file access rights.
20	<code>size</code> attribute expected.
21	The computed size does not match the declared size.
22	Sections defined in the lsc file must be unique.
23	One of the memory layout intervals refers to an unknown lsc section.
24	Relocation must be done in one and only one contiguous interval.
25	<code>force</code> and <code>symbol</code> attributes are not allowed together.
26	XML char data not allowed at this position in the lsc file.
27	A section which is a part of the program image must be embedded in an image memory layout.
28	A section which is not a part of the program image must be embedded in a non-image memory layout.
29	Expression could not be resolved to a link-time constant. Some symbols are unresolved.
30	Sections used in memory layout ranges must be sections defined in the lsc file.
31	Invalid character encountered when scanning the lsc expression.
32	A recursive include cycle was detected.
33	An alignment inconsistency was detected in a relocation memory layout. Most likely one of the start addresses of the memory layout is not aligned on the current alignment.
34	An error occurs in a relocation resolution. In general, the relocation has a value that is out of range.
35	<code>symbol</code> and <code>sort</code> attributes are not allowed together.
36	Invalid sort attribute value is not one of <code>order</code> , <code>name</code> , or <code>no</code> .
37	Attribute <code>start</code> or <code>end</code> in <code>defSection</code> tag is not allowed when defining a floating section.
38	Autogenerated section can build tables according to symbol names (see <i>Auto-generated Sections</i> ). A symbol is needed to build this section but has not been loaded.
39	Deprecated feature warning. Remains for backward compatibility. It is recommended that you use the new indicated feature, because this feature may be removed in future linker releases.

Continued on next page

Table 7 – continued from previous page

40	Unknown output architecture. Either the architecture ID is invalid, or the library loader has not been loaded by the linker. Check loaded library loaders using verbose option.
41...43	Reserved.
44	Duplicate group definition. A group name is unique and cannot be defined twice.
45	Invalid endianness. The endianness mnemonic is not one of the expected mnemonics ( <code>little</code> , <code>big</code> , <code>none</code> ).
46	Multiple endiannesses detected within loaded input libraries.
47	Reserved.
48	Invalid type mnemonic passed to a <code>defSymbol</code> tag. Must be one of <code>none</code> , <code>function</code> , or <code>data</code> .
49	Warning. A directory of link path is invalid (skipped).
50	No linker-specific description file could be loaded from the link path. Check that the link path directories are valid, and that they contain <code>.lsc</code> or <code>.lscf</code> files.
51	Exclusive options (these options cannot be used simultaneously). For example, <code>-linkFilename</code> and <code>-linkPath</code> are exclusive; either select a master lsc file or a path from which to load <code>.lscf</code> files.
52	Name given to a <code>memoryLayoutRef</code> or a <code>memoryLayout</code> is invalid. It must not be empty.
53	A <code>memoryLayoutRef</code> with the same name has already been processed.
54	A <code>memoryLayout</code> must define <code>ranges</code> or the <code>name</code> attribute.
55	No memory layout found matching the name of the current <code>memoryLayoutRef</code> .
56	A named <code>memoryLayout</code> is declared with a relocation directive, but the relocation interval is incompatible with the relocation interval of the <code>memoryLayout</code> that referenced it.
57	A named <code>memoryLayout</code> has not been referenced. Every declared <code>memoryLayout</code> must be processed. A named <code>memoryLayout</code> must be referenced by a <code>memoryLayoutRef</code> statement.
58	<code>SUM</code> operator expects an auto-generated section.
59	<code>SUM</code> operator tag is unknown for the targetted auto-generated section.
60	<code>SUM</code> operator auto-generated section name is unknown.
61	An option is set for an unknown extension. Most likely the extension has not been set to the linker classpath.
62	Reserved.
63	ELF unit flags are inconsistent with flags set using the <code>-forceFlags</code> option.
64	Reserved.
65	Reserved.
66	Found an executable object file as input (expected a relocatable object file).
67	Reserved.
68	Reserved.
69	Reserved.
70	Not enough memory to achieve the linking process. Try to increase JVM heap that is running the linker (e.g. by adding option <code>-Xmx1024M</code> to the JRE command line).

## Map File Interpreter

The map file interpreter is a tool that allows you to read, classify and display memory information dumped by the linker map file. The map file interpreter is a graph-oriented tool. It supports graphs of symbols and allows standard operations on them (union, intersection, subtract, etc.). It can also dump graphs, compute graph total sizes, list graph paths, etc.

The map file interpreter uses the standard Java regular expression syntax.

It is used internally by the graphical *Memory Map Analyzer* tool.

Commands:

- `createGraph graphName symbolRegExp ... section=regexp`

```
createGraph all section=.*
```

Recursively create a graph of symbols from root symbols and sections described as regular expressions. For example, to extract the complete graph of the application:

- `createGraphNoRec symbolRegExp ... section=regexp`

The above line is similar to the previous statement, but embeds only declared symbols and sections (without recursive connections).

- `removeGraph graphName`

Removes the graph for memory.

- `listGraphs`

Lists all the created graphs in memory.

- `listSymbols graphName`

Lists all graph symbols.

- `listPadding`

Lists the padding of the application.

- `listSections graphName`

Lists all sections targeted by all symbols of the graph.

- `inter graphResult g1 ... gn`

Creates a graph which is the intersection of `g1/\ ... /\gn`.

- `union graphResult g1 ... gn`

Creates a graph which is the union of `g1\ / ... \ / gn`.

- `subtract graphResult g1 ... gn`

Creates a graph which is the subtract of `g1\ ... \ gn`.

- `reportConnections graphName`

Prints the graph connections.

- `totalImageSize graphName`

Prints the image size of the graph.

- `totalDynamicSize graphName`

Prints the dynamic size of the graph.

- `accessPath symbolName`

The above line prints one of the paths from a root symbol to this symbol. This is very useful in helping you understand why a symbol is embedded.

- `echo arguments`

Prints raw text.

- `exec commandFile`

Execute the given commandFile. The path may be absolute or relative from the current command file.

### 3.11.2 Testsuite Engine

#### Definition

The MicroEJ Testsuite is an engine made for validating any development project using automatic testing. The MicroEJ Testsuite engine allows the user to test any kind of projects within the configuration of a generic ant file.

#### Using the MicroEJ Testsuite Ant tasks

Multiple Ant tasks are available in the testsuite-engine provided jar:

- `testsuite` allows the user to run a given testsuite and to retrieve an XML report document in a JUnit format.
- `javaTestsuite` is a subtask of the `testsuite` task, used to run a specialized testsuite for Java (will only run Java classes).
- `htmlReport` is a task which will generate an HTML report from a list of JUnit report files.

#### The testsuite Task

This task have some mandatory attributes to fill:

- `outputDir` : the output folder of the testsuite. The final report will be generated at `[outputDir]/[label]/[reportName].xml` , see the `testsuiteReportFileProperty` and `testsuiteReportDirProperty` attributes.
- `harnessScript` : the harness script must be an Ant script and it is the script which will be called for each test by the testsuite engine. It is called with a `basedir` located at output location of the current test. The testsuite engine will provide to it some properties giving all the informations to start the test:
  - `testsuite.test.name` : The output name of the current test in the report. Default value is the relative path of the test. It can be manually set by the user. More details on the output name are available in the section *Specific Custom Properties*.
  - `testsuite.test.path` : The current test absolute path in the filesystem.
  - `testsuite.test.properties` : The absolute path to the custom properties of the current test (see the property `customPropertiesExtension` )
  - `testsuite.common.properties` : The absolute path to the common properties of all the tests (see the property `commonProperties` )
  - `testsuite.report.dir` : The absolute path to the directory of the final report.

Some attributes are optional, and if not set by the user, a default value will be attributed.

- `timeOut` : the time in seconds before any test is considered as unknown. Set it to 0 to disable the time-out. Will be defaulted as 60.
- `verboseLevel` : the required level to output messages from the testsuite. Can be one of those values: error, warning, info, verbose, debug. Will be defaulted as info.
- `reportName` : the final report name (without extension). Default value is `testsuite-report`.
- `customPropertiesExtension` : the extension of the custom properties for each test. For instance, if it is set to `.options`, a test named `xxx/Test1.class` will be associated with `xxx/Test1.options`. If a file exists for a test, the property `testsuite.test.properties` is set with its absolute path and given to the `harnessScript`. If the test path references a directory, then the custom properties path is the concatenation of the test path and the `customPropertiesExtension` value. By default, custom properties extension is `.properties`.
- `commonProperties` : the properties to apply to every test of the testsuite. Those options might be overridden by the custom properties of each test. If this option is set and the file exists, the property `testsuite.common.properties` is set to the absolute path of the `harnessScript` file. By default, there is not any common properties.
- `label` : the build label. Will be generated as a timestamp by the testsuite if not set.
- `productName` : the name of the current tested product. Default value is `TestSuite`.
- `jvm` : the location of your Java VM to start the testsuite (the `harnessScript` is called as is: `[jvm] [...] -buildfile [harnessScript]`). Will be defaulted as your `java.home` location if the property is set, or to `java`.
- `jvmargs` : the arguments to pass to the Java VM started for each test.
- `testsuiteReportFileProperty` : the name of the Ant property in which is stored the path of the final report. Default value is `testsuite.report.file` and path is `[outputDir]/[label]/[reportName].xml`
- `testsuiteReportDirProperty` : the name of the Ant property in which is store the path of the directory of the final report. Default value is `testsuite.report.dir` and path is `[outputDir]/[label]`
- `testsuiteResultProperty` : the name of the Ant property in which you want to have the result of the test-suite (true or false), depending if every tests successfully passed the testsuite or not. Ignored tests do not affect this result.

Finally, you have to give as nested element the path containing the tests.

- `testPath` : containing all the file of the tests which will be launched by the testsuite.
- `testIgnoredPath` (optional): Any test in the intersection between `testIgnoredPath` and `testPath` will be executed by the testsuite, but will not appear in the JUnit final report. It will still generate a JUnit report for each test, which will allow the HTML report to let them appears as “ignored” if it is generated. Mostly used for known bugs which are not considered as failure but still relevant enough to appears on the HTML report.

### The javaTestsuite Task

This task extends the `testsuite` task, specializing the testsuite to only start real Java class. This task will retrieve the classname of the tests from the classfile and will provide new properties to the harness script:

- `testsuite.test.class` : The classname of the current test. The value of the property `testsuite.test.name` is also set to the classname of the current test.
- `testsuite.test.classpath` : The classpath of the current test.

## The htmlReport Task

This task allow the user to transform a given path containing a sample of JUnit reports to an HTML detailed report. Here is the attributes to fill:

- A nested fileset containing all the JUnit reports of each test. Take care to exclude the final JUnit report generated by the testsuite.
- A nested element `report`
  - `format` : The format of the generated HTML report. Must be `noframes` or `frames` . When `noframes` format is choosen, a standalone HTML file is generated.
  - `todir` : The output folder of your HTML report.
  - The `report` tag accepts the nested tag `param` with `name` and `expression` attributes. These tags can pass XSL parameters to the stylesheet. The built-in stylesheets support the following parameters:
    - \* `PRODUCT` : the product name that is displayed in the title of the HTML report.
    - \* `TITLE` : the comment that is displayed in the title of the HTML report.

---

**Note: Tip :** It is advised to set the format to `noframes` if your test suite is not a Java testsuite. If the format is set to `frames` , with a non-Java MicroEJ Testsuite, the name of the links will not be relevant because of the non-existancy of packages.

---

## Using the Trace Analyzer

This section will shortly explains how to use the `Trace Analyzer` . The MicroEJ Testsuite comes with an archive containing the `Trace Analyzer` which can be used to analyze the output trace of an application. It can be used from different forms;

- The `FileTraceAnalyzer` will analyze a file and research for the given tags, failing if the success tag is not found.
- The `SerialTraceAnalyzer` will analyze the data from a serial connection.

## The TraceAnalyzer Tasks Options

Here is the common options to all TraceAnalyzer tasks:

- `successTag` : the regular expression which is synonym of success when found (by default `.*PASSED.*` ).
- `failureTag` : the regular expression which is synonym of failure when found (by default `.*FAILED.*` ).
- `verboseLevel` : int value between 0 and 9 to define the verbose level.
- `waitingTimeAfterSuccess` : waiting time (in s) after success before closing the stream (by default 5).
- `noActivityTimeout` : timeout (in s) with no activity on the stream before closing the stream. Set it to 0 to disable timeout (default value is 0).
- `stopEOFReached` : boolean value. Set to `true` to stop analyzing when input stream EOF is reached. If `false` , continue until timeout is reached (by default `false` ).
- `onlyPrintableCharacters` : boolean value. Set to `true` to only dump ASCII printable characters (by default `false` ).

## The FileTraceAnalyzer Task Options

Here is the specific options of the FileTraceAnalyzer task:

- `traceFile` : path to the file to analyze.

## The SerialTraceAnalyzer Task Options

Here is the specific options of the SerialTraceAnalyzer task:

- `port` : the comm port to open.
- `baudrate` : serial baudrate (by default 9600).
- `databits` : databits (5|6|7|8) (by default 8).
- `stopBits` : stopbits (0|1|3 for (1\_5)) (by default 1).
- `parity` : `none` | `odd` | `event` (by default `none`).

## Appendix

The goal of this section is to explain some tips and tricks that might be useful in your usage of the testsuite engine.

### Specific Custom Properties

Some custom properties are specifics and retrieved from the testsuite engine in the custom properties file of a test.

- The `testsuite.test.name` property is the output name of the current test. Here are the steps to compute the output name of a test:
  - If the custom properties are enabled and a property named `testsuite.test.name` is find on the corresponding file, then the output name of the current test will be set to it.
  - Otherwise, if the running MicroEJ Testsuite is a Java testsuite, the output name is set to the class name of the test.
  - Otherwise, from the path containing all the tests, a common prefix will be retrieved. The output name will be set to the relative path of the current test from this common prefix. If the common prefix equals the name of the test, then the output name will be set to the name of the test.
  - Finally, if multiples tests have the same output name, then the current name will be followed by `_XXX`, an underscore and an integer.
- The `testsuite.test.timeout` property allow the user to redefine the time out for each test. If it is negative or not an integer, then global timeout defined for the MicroEJ Testsuite is used.

### Dependencies

No dependency.

### Installation

This tool is a built-in platform tool.



## PLATFORM DEVELOPER GUIDE

### 4.1 Introduction

#### 4.1.1 Scope

This document explains how the core features of MicroEJ Architecture are accessed, configured and used by the MicroEJ Platform builder. It describes the process for creating and augmenting a MicroEJ Architecture. This document is concise, but attempts to be exact and complete. Semantics of implemented Foundation Libraries are described in their respective specifications. This document includes an outline of the required low level drivers (LLAPI) for porting the MicroEJ Architectures to different real-time operating systems (RTOS).

MicroEJ Architecture is state-of-the-art, with embedded MicroEJ runtimes for MCUs. They also provide simulated runtimes that execute on workstations to allow software development on “virtual hardware.”

#### 4.1.2 Intended Audience

The audience for this document is software engineers who need to understand how to create and configure a MicroEJ Platform using the MicroEJ Platform builder. This document also explains how a MicroEJ Application can interoperate with C code on the target, and the details of the MicroEJ Architecture modules, including their APIs, error codes and options.

#### 4.1.3 MicroEJ Architecture Modules Overview

MicroEJ Architecture features the MicroEJ Core Engine: a tiny and fast runtime associated with a Garbage Collector. It provides four built-in Foundation Libraries :

- *[BON]*
- EDC
- *[SNI]*
- *[SP]*

*The following figure* shows the components involved.

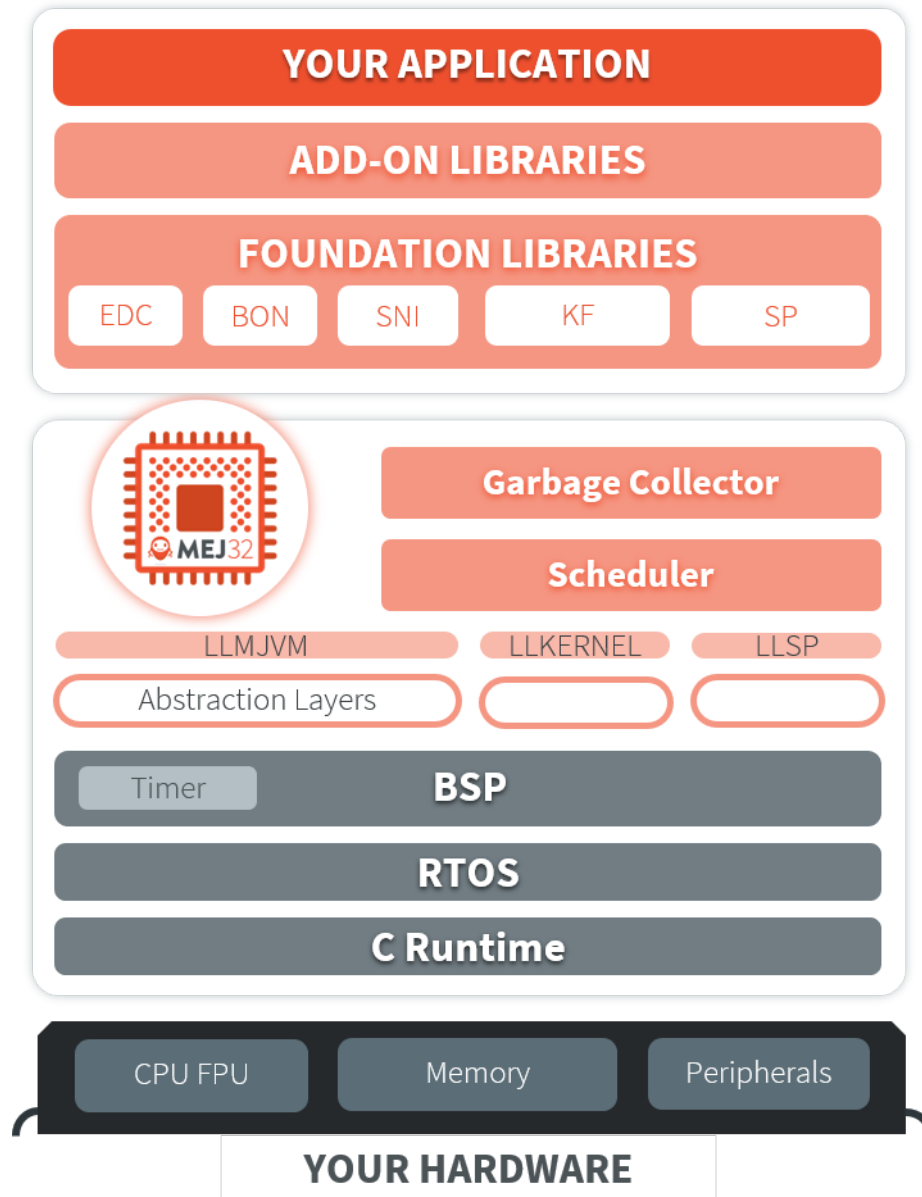


Fig. 1: MicroEJ Architecture Runtime Modules: Tools, Libraries and APIs

Three APIs allow the device architecture runtime to link with (and port to) external code, such as any kind of RTOS or legacy C libraries. These three APIs are

- Simple Native Interface (*[SNI]*)
- Low Level MicroEJ Core Engine (LLMJVM)
- Low Level Shielded Plug (LLSP)

MicroEJ Architecture features additional Foundation Libraries and modules to extend the kernel:

- serial communication,
- UI extension (User Interface)
- networking

- file system
- etc.

Each additional module is optional and selected on demand during the MicroEJ Platform configuration.

## 4.2 MicroEJ Platform

### 4.2.1 Process Overview

This section summarizes the steps required to build a MicroEJ Platform and obtain a binary file to deploy on a board.

*The following figure* shows the overall process. The first three steps are performed within the MicroEJ Platform builder. The remaining steps are performed within the C IDE.

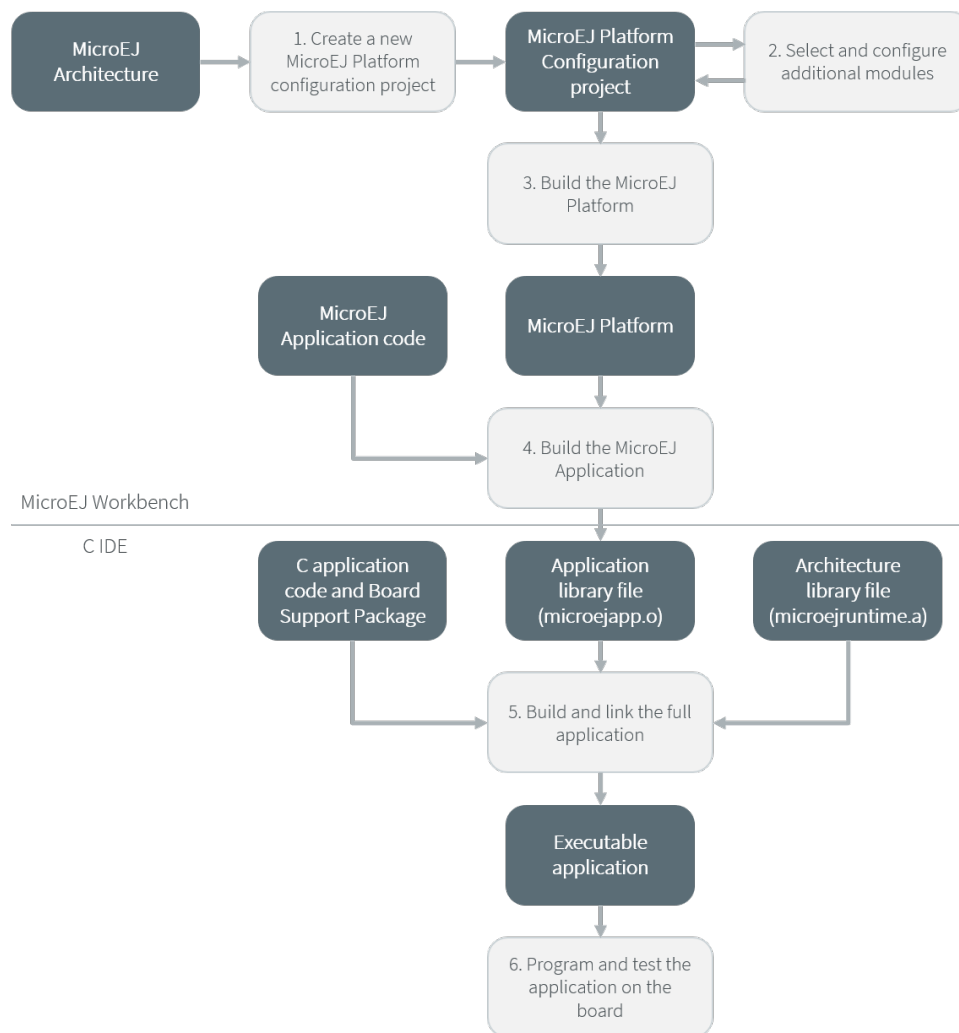


Fig. 2: Overall Process

1. Step 1 consists in creating a new MicroEJ Platform configuration project. This project describes the MicroEJ Platform (MicroEJ architecture, metadata, etc.).

2. Step 2 allows you to select which modules available in MicroEJ Architecture will be installed in the MicroEJ Platform.
3. Step 3 builds the MicroEJ Platform according to the choices made in steps 1 and 2.
4. Step 4 compiles a MicroEJ Application against the MicroEJ Platform in order to obtain an application file to link in the BSP.
5. Step 5 consists in compiling the BSP and linking it with the MicroEJ Application that was built previously, in step 4.
6. Step 6 is the final step: Deploy the binary application onto a board.

## 4.2.2 Concepts

### MicroEJ Platform

A MicroEJ Platform includes development tools and a runtime environment.

The runtime environment consists of:

- A MicroEJ Core Engine.
- Some Foundation Libraries.
- Some C libraries.

The development tools are composed of:

- Java APIs to compile MicroEJ Application code.
- Documentation: this guide, library specifications, etc.
- Tools for development and compilation.
- Launch scripts to run the simulation or build the binary file.
- Eclipse plugins.

### MicroEJ Platform Configuration

A MicroEJ Platform is described by a `.platform` file. This file is usually called `[name].platform`, and is stored at the root of a MicroEJ Platform configuration project called `[name]-configuration`.

The configuration file is recognized by the MicroEJ Platform builder. The MicroEJ Platform builder offers a visualization with two tabs:

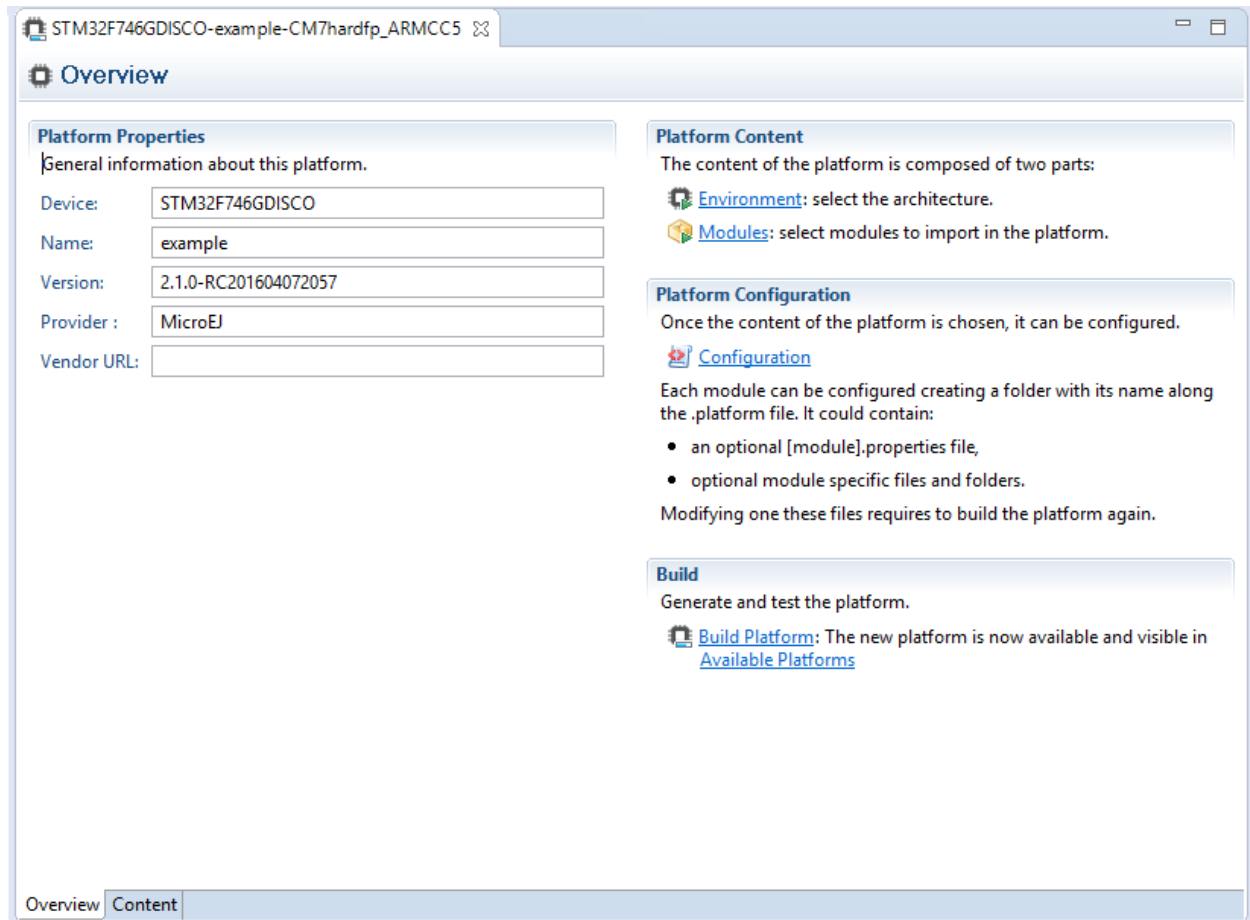


Fig. 3: MicroEJ Platform Configuration Overview Tab

This tab groups the basic platform information used to identify it: its name, its version, etc. These tags can be updated at any time.



Fig. 4: MicroEJ Platform Configuration Content Tab

This tab shows all additional modules (see [Modules](#)) which can be installed into the platform in order to augment its features. The modules are sorted by groups and by functionality. When a module is checked, it will be installed into the platform during the platform creation.

## Modules

The primary mechanism for augmenting the capabilities of a *MicroEJ Platform* is to add modules to it.

A MicroEJ module is a group of related files (Foundation Libraries, scripts, link files, C libraries, Simulator, tools, etc.) that together provide all or part of a platform capability. Generally, these files serve a common purpose. For example, providing an API, or providing a library implementation with its associated tools.

The list of modules is in the second tab of the platform configuration tab. A module may require a configuration step to be installed into the platform. The **Modules Detail** view indicates if a configuration file is required.

## Low Level API Pattern

### Principle

Each time the user must supply C code that connects a platform component to the target, a *Low Level API* is defined. There is a standard pattern for the implementation of these APIs. Each interface has a name and is specified by two

header files:

- `[INTERFACE_NAME].h` specifies the functions that make up the public API of the implementation. In some cases the user code will never act as a client of the API, and so will never use this file.
- `[INTERFACE_NAME].impl.h` specifies the functions that must be coded by the user in the implementation.

The user creates *implementations* of the interfaces, each captured in a separate C source file. In the simplest form of this pattern, only one implementation is permitted, as shown in the illustration below.



Fig. 5: Low Level API Pattern (single implementation)

The following figure shows a concrete example of an LLAPI. The C world (the board support package) has to implement a `send` function and must notify the library using a `receive` function.



Fig. 6: Low Level API Example

### Multiple Implementations and Instances

When a Low Level API allows multiple implementations, each implementation must have a unique name. At run-time there may be one or more instances of each implementation, and each instance is represented by a data structure that holds information about the instance. The address of this structure is the handle to the instance, and that address is passed as the first parameter of every call to the implementation.

The illustration below shows this form of the pattern, but with only a single instance of a single implementation.





Fig. 7: Low Level API Pattern (multiple implementations/instances)

The `#define` statement in `MYIMPL.c` specifies the name given to this implementation.

### 4.2.3 New MicroEJ Platform Creation

This section describes the steps to create a new MicroEJ Platform in MicroEJ SDK, and options to connect it to an external Board Support Package (BSP) as well as a third-party C toolchain.

MicroEJ SDK must be started on a new empty *workspace*.

#### MicroEJ Architecture Import

The first step is to choose and import a *MicroEJ Architecture*. MicroEJ Architectures for most common microcontroller instructions sets and compilers can be downloaded from <https://repository.microej.com/architectures/><sup>1</sup>.

MicroEJ Architecture files ends with the `.xpf` extension, and are classified using the following folder naming convention:

```
com/microej/architecture/[ISA]/[TOOLCHAIN]/[UID]/[VERSION]/[UID]-[VERSION]-[USAGE].xpf
```

- **ISA**: instruction set architecture (e.g. **CM4** for Arm® Cortex®-M4, **ESP32** for Espressif ESP32, ...).
- **TOOLCHAIN**: C compilation toolchain (e.g. **CM4hardfp\_GCC48**).

<sup>1</sup> MicroEJ Architectures for production can be retrieved from the [license server](#).

- **VERSION** : module version (e.g. `7.12.0`).
- **UID** : Architecture unique ID (e.g. `flopi4G25`).
- **USAGE** = `eval` for evaluation Architectures, `prod` for production Architectures.

For example, MicroEJ Architecture versions for Arm® Cortex®-M4 microcontrollers compiled with GNU CC toolchain is available at [https://repository.microej.com/architectures/com/microej/architecture/CM4/CM4hardfp\\_GCC48/flopi4G25/](https://repository.microej.com/architectures/com/microej/architecture/CM4/CM4hardfp_GCC48/flopi4G25/).

Once you downloaded a MicroEJ Architecture file, proceed with the following steps to import it in MicroEJ SDK:

- Select **File** > **Import** > **MicroEJ** > **Architectures**.
- Browse an `.xpf` file or a folder that contains one or more an `.xpf` files.
- Check the **I agree and accept the above terms and conditions...** box to accept the license.
- Click on **Finish** button.

**Note:** A MicroEJ Architecture can be imported using MicroEJ Module Manager, by adding the following line in a *module description file*:

```
<dependency org="com.microej.architecture.[ISA].[TOOLCHAIN]" name="[UID]" rev="[VERSION]" conf="default"
  ↪">
  <artifact name="[UID]" m:classifier="[USAGE]" ext="xpf"/>
</dependency>
```

## New MicroEJ Platform Configuration

The next step is to create a MicroEJ Platform configuration:

- Select **File** > **New** > **MicroEJ Platform Project...**.
- Click on **Next** button. The **Configure Target Architecture** page allows to select the MicroEJ Architecture that contains a minimal MicroEJ Platform and a set of compatible modules targeting a processor architecture and a compilation toolchain. This environment can be changed later.
  - Click on **Browse...** button to select one of the installed MicroEJ Architecture.
  - Check the **Create from a platform reference implementation** box to use one of the available implementation. Uncheck it if you want to provide your own implementation or if no reference implementation is available.
- Click on **Next** button. The **Configure platform properties** page contains the identification of the MicroEJ Platform to create. Most fields are mandatory, you should therefore set them. Note that their values can be modified later on.
- Click on **Finish** button. A new project `[device]-[name]-[toolchain]` is being created containing a `[name].platform` file. A Platform description editor shall then open.
- Install **Platform Configuration Additions**. Files within the `content` folder have to be copied to the configuration project folder, by following instructions described at <https://github.com/MicroEJ/PlatformQualificationTools/blob/master/framework/platform/README.rst>.

You should get a MicroEJ Platform configuration project that looks like:

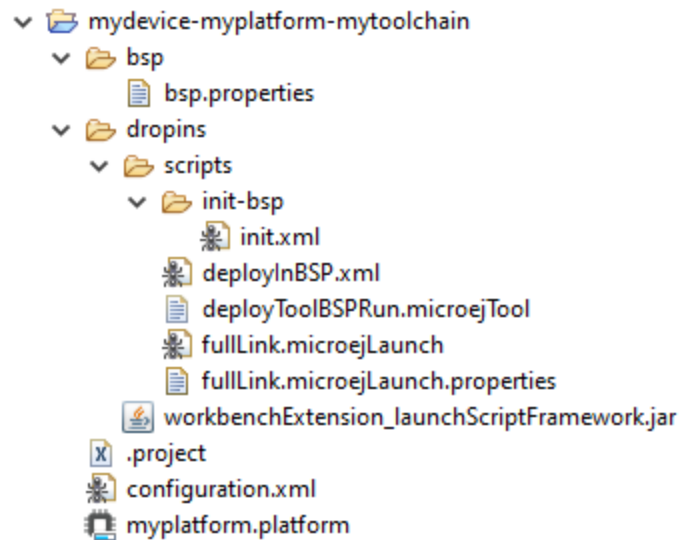


Fig. 8: MicroEJ Platform Configuration Project Skeleton

### Groups / Modules Selection

From the Platform description editor, select the Content tab to access the Platform modules selection. Modules can be selected/deselected from the Modules frame.

Modules are organized into groups. When a group is selected, by default, all its modules are selected. To view the modules making up a group, click on the Show/Hide modules icon on the top-right of the frame. This will let you select/deselect on a per module basis. Note that individual module selection is not recommended.

The description and contents of an item (group or module) are displayed beside the list on item selection.

All the checked modules will be installed in the Platform.



Fig. 9: MicroEJ Platform Configuration Modules Selection

## Modules Customization

Each selected module can be customized by creating a `[module]` folder named after the module beside the `[name].platform` definition. It may contain:

- An optional `[module].properties` file named after the module name. These properties will be injected in the execution context prefixed by the module name. Some properties might be needed for the configuration of some modules. Please refer to the modules documentation for more information.
- Optional module specific files and folders.

Modifying one of these files requires to build the Platform again.

## Platform Customization

Platform can be customized by creating a `configuration.xml` script beside the `[name].platform` file. This script can extend one or several of the extension points available. By default, you should not have to change the default configuration script.

Configuration project (the project which contains the `[name].platform` file) can contain an optional `dropins` folder. The contents of this folder will be copied integrally into the final Platform. This feature allows to add some additional libraries, tools etc. into the Platform.

The dropins folder organization should respect the final Platform files and folders organization. For instance, the tools are located in the sub-folder `tools`. Launch a Platform build without the dropins folder to see how the Platform files and folders organization is. Then fill the dropins folder with additional features and build again the Platform to obtain an advanced Platform.

The dropins folder files are kept in priority. If one file has the same path and name as another file already installed into the Platform, the dropins folder file will be kept.

Modifying one of these files requires to build the Platform again.

## BSP Connection

### Principle

Using a MicroEJ Platform, the user can compile a MicroEJ Application on that Platform. The result of this compilation is a `microejapp.o` file.

This file has to be linked with the MicroEJ Platform runtime file ( `microejruntime.a` ) and a third-party C project, called the Board Support Package (BSP), to obtain the final binary file (MicroEJ Firmware). For more information, please consult the *MicroEJ build process overview*.

The BSP connection can be configured by defining 4 folders where the following files are located:

- MicroEJ Application file ( `microejapp.o` ).
- MicroEJ Platform runtime file ( `microejruntime.a` , also available in the Platform `lib` folder).
- MicroEJ Platform header files ( `*.h` , also available in the Platform `include` folder).
- BSP project *build script* file ( `build.bat` or `build.sh` ).

Once the MicroEJ Application file ( `microejapp.o` ) is built, the files are then copied to these locations and the `build.bat` or `build.sh` file is executed to produce the final executable file ( `application.out` ).

---

**Note:** The final build stage to produce the executable file can be done outside of MicroEJ SDK, and thus the BSP connection configuration is optional.

BSP connection configuration is only required in the following cases:

- Use MicroEJ SDK to produce the final executable file of a Mono-Sandbox Firmware (recommended).
  - Use MicroEJ SDK to run a *MicroEJ Testsuite* on device.
  - Build a Multi-Sandbox Firmware.
- 

MicroEJ provides a flexible way to configure the BSP connection to target any kind of projects, teams organizations and company build flows. To achieve this, the BSP connection can be configured either at MicroEJ Platform level or at MicroEJ Application level (or a mix of both).

The 3 most common integration cases are:

- Case 1: No BSP connection

The MicroEJ Platform does not know the BSP at all.

BSP connection can be configured when building the MicroEJ Application (absolute locations).

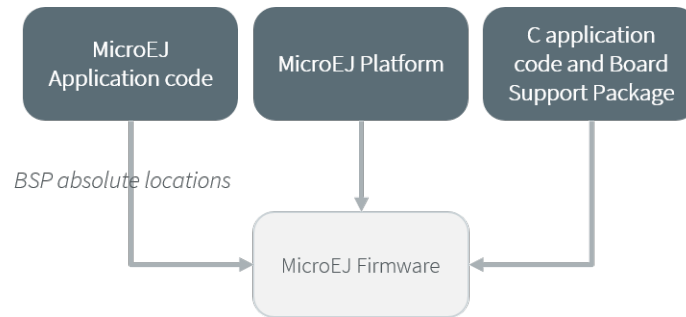


Fig. 10: MicroEJ Platform with no BSP connection

This case is recommended when:

- the MicroEJ Firmware is built outside MicroEJ SDK.
- the same MicroEJ Platform is intended to be reused on multiple BSP projects which do not share the same structure.

• Case 2: Partial BSP connection

The MicroEJ Platform knows how the BSP is structured.

BSP connection is configured when building the MicroEJ Platform (relative locations within the BSP), and the BSP root location is configured when building the MicroEJ Application (absolute directory).

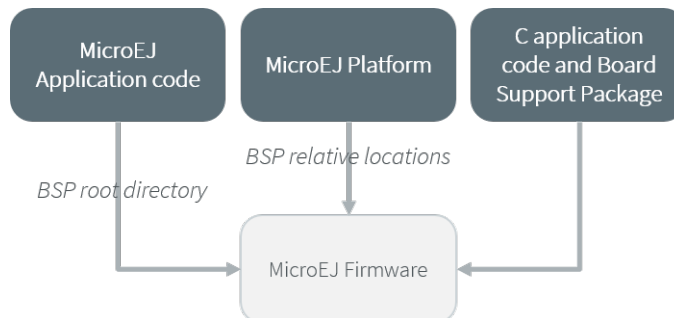


Fig. 11: MicroEJ Platform with partial BSP connection

This case is recommended when:

- the MicroEJ Platform is used to build one MicroEJ Application on top of one BSP.
- the Application and BSP are slightly coupled, thus making a change in the BSP just require to build the firmware again.

• Case 3: Full BSP connection

The MicroEJ Platform includes the BSP.

BSP connection is configured when building MicroEJ Platform (relative locations within the BSP), as well as the BSP root location (absolute directory). No BSP connection configuration is required when building the MicroEJ Application.

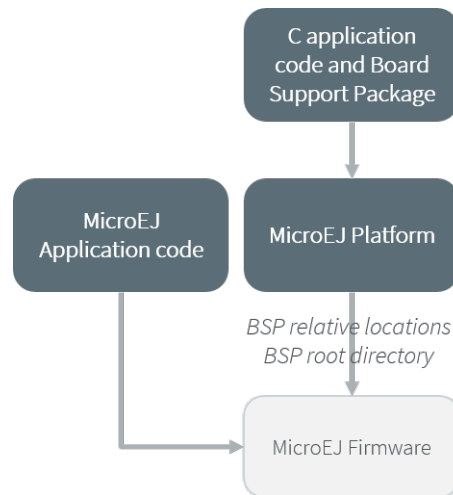


Fig. 12: MicroEJ Platform with full BSP connection

This case is recommended when:

- the MicroEJ Platform is used to build various MicroEJ Applications.
- the MicroEJ Platform is validated using MicroEJ testsuites.
- the MicroEJ Platform and BSP are delivered as a single standalone module (same versioning), perhaps subcontracted to a team or a company outside the application project(s).

### Options

BSP connection options can be specified as Platform options or as Application options or a mix of both.

The following table describes Platform options, configured in `bsp > bsp.properties` file of the Platform configuration project.

Table 1: MicroEJ Platform Options for BSP Connection

Option Name	Description	Example
<code>microejapp.relative.dir</code>	The path relative to BSP <code>root.dir</code> where to deploy the MicroEJ Application file ( <code>microejapp.o</code> ).	<code>MicroEJ/lib</code>
<code>microejlib.relative.dir</code>	The path relative to BSP <code>root.dir</code> where to deploy the MicroEJ Platform runtime file ( <code>microejruntime.a</code> ).	<code>MicroEJ/lib</code>
<code>microejinc.relative.dir</code>	The path relative to BSP <code>root.dir</code> where to deploy the MicroEJ Platform header files ( <code>*.h</code> ).	<code>MicroEJ/inc</code>
<code>microejscript.relative.dir</code>	The path relative to BSP <code>root.dir</code> where to execute the BSP build script file ( <code>build.bat</code> or <code>build.sh</code> ).	<code>Project/MicroEJ</code>
<code>root.dir</code>	The 3rd-party BSP project absolute directory, to be included to the Platform.	<code>c:\\Users\\user\\mybsp</code> on Windows systems or <code>/home/user/bsp</code> on Unix systems.

The following table describes Application options, configured as regular *MicroEJ Application Options*.

Table 2: MicroEJ Application Options for BSP Connection

Option Name	Description
<code>deploy.bsp.microejapp</code>	Deploy the MicroEJ Application file ( <code>microejapp.o</code> ) to the location defined by the Platform (defaults to <code>true</code> when Platform option <code>microejapp.relative.dir</code> is set).
<code>deploy.bsp.microejlib</code>	Deploy the MicroEJ Platform runtime file ( <code>microejruntime.a</code> ) to the location defined by the Platform (defaults to <code>true</code> when Platform option <code>microejlib.relative.dir</code> is set).
<code>deploy.bsp.microejinc</code>	Deploy the MicroEJ Platform header files ( <code>*.h</code> ) to the location defined by the Platform (defaults to <code>true</code> when Platform option <code>microejinc.relative.dir</code> is set).
<code>deploy.bsp.microejscript</code>	Execute the BSP build script file ( <code>build.bat</code> or <code>build.sh</code> ) present at the location defined by the Platform. (defaults to <code>false</code> and requires <code>microejscript.relative.dir</code> Platform option to be set).
<code>deploy.bsp.root.dir</code>	The 3rd-party BSP project absolute directory. This option is required if at least one the 4 options described above is set to <code>true</code> and the Platform does not includes the BSP.
<code>deploy.dir.microejapp</code>	Deploy the MicroEJ Application file ( <code>microejapp.o</code> ) to this absolute directory. An empty value means no deployment.
<code>deploy.dir.microejlib</code>	Deploy the MicroEJ Platform runtime file ( <code>microejruntime.a</code> ) to this absolute directory. An empty value means no deployment.
<code>deploy.dir.microejinc</code>	Deploy the MicroEJ Platform header files ( <code>*.h</code> ) to this absolute directory. An empty value means no deployment.
<code>deploy.bsp.microejscript</code>	Execute the BSP build script file ( <code>build.bat</code> or <code>build.sh</code> ) present in this absolute directory. An empty value means no deployment.



**Note:** It is also possible to configure the BSP root directory using the build option named `toolchain.dir`, instead of the application option `deploy.bsp.root.dir`. This allow to configure a MicroEJ Firmware by specifying both the Platform (using the `target.platform.dir` option) and the BSP at build level, without having to modify the application options files.

For each *Platform BSP connection case*, here is a summary of the options to set:

- No BSP connection, executable file built outside MicroEJ SDK

```
Platform Options:
[NONE]

Application Options:
[NONE]
```

- No BSP connection, executable file built using MicroEJ SDK

```
Platform Options:
[NONE]

Application Options:
deploy.dir.microejapp=[absolute_path]
deploy.dir.microejlib=[absolute_path]
deploy.dir.microejinc=[absolute_path]
deploy.bsp.microejscript=[absolute_path]
```

- Partial BSP connection, executable file built outside MicroEJ SDK

```
Platform Options:
microejapp.relative.dir=[relative_path]
microejlib.relative.dir=[relative_path]
microejinc.relative.dir=[relative_path]

Application Options:
deploy.bsp.root.dir=[absolute_path]
```

- Partial BSP connection, executable file built using MicroEJ SDK

```
Platform Options:
microejapp.relative.dir=[relative_path]
microejlib.relative.dir=[relative_path]
microejinc.relative.dir=[relative_path]
microejscript.relative.dir=[relative_path]

Application Options:
deploy.bsp.root.dir=[absolute_path]
deploy.bsp.microejscript=true
```

- Full BSP connection, executable file built using MicroEJ SDK

```
Platform Options:
microejapp.relative.dir=[relative_path]
microejlib.relative.dir=[relative_path]
microejinc.relative.dir=[relative_path]
microejscript.relative.dir=[relative_path]
root.dir=[absolute_path]
```

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```
Application Options:
  deploy.bsp.microejscript=true
```

## Build Script File

The BSP build script file is responsible to invoke the third-party C toolchain (compiler and linker) to produce the final executable file ( `application.out` ).

The build script must implement the following specification:

- On Windows operating system, it is a Windows batch file named `build.bat`.
- On Mac OS X or Linux operating systems, it is a shell script named `build.sh`, with execution permission enabled.
- On build error, the script must end with a non zero exit code.
- On success
  - The executable must be copied to the file `application.out` in the folder from where the script has been executed.
  - The script must end with zero exit code.

Many build script templates are available for most commonly used C toolchains in the [Platform Qualification Tools repository](#).

## Low Level APIs Implementation Files

Some MicroEJ Architecture modules require some additional information about the BSP implementation of Low Level APIs.

This information must be stored in each module's configuration folder, in a file named `bsp.xml`.

This file must start with the node `<bsp>`. It can contain several lines like this one: `<nativeName="A_LLAPI_NAME" nativeImplementation name="AN_IMPLEMENTATION_NAME"/>` where:

- `A_LLAPI_NAME` refers to a Low Level API native name. It is specific to the MicroEJ C library which provides the Low Level API.
- `AN_IMPLEMENTATION_NAME` refers to the implementation name of the Low Level API. It is specific to the BSP; and more specifically, to the C file which does the link between the MicroEJ C library and the C driver.

Example:

```
<bsp>
  <nativeImplementation name="COMM_DRIVER" nativeName="LLCOMM_BUFFERED_CONNECTION"/>
</bsp>
```

These files will be converted into an internal format during the MicroEJ Platform build.

## MicroEJ Platform Build

To build the MicroEJ Platform, click on the [Build Platform](#) link on the Platform configuration [Overview](#) tab.

It will create a MicroEJ Platform in the workspace available for the MicroEJ Application project to run on. The MicroEJ Platform will be available in: **Window** > **Preferences** > **MicroEJ** > **Platforms in workspace** .

## 4.3 MicroEJ Core Engine

The MicroEJ Core Engine (also called the platform engine) and its components represent the core of the platform. It is used to compile and execute at runtime the MicroEJ Application code.

### 4.3.1 Functional Description

*The following diagram* shows the overall process. The first two steps are performed within the MicroEJ Workbench. The remaining steps are performed within the C IDE.

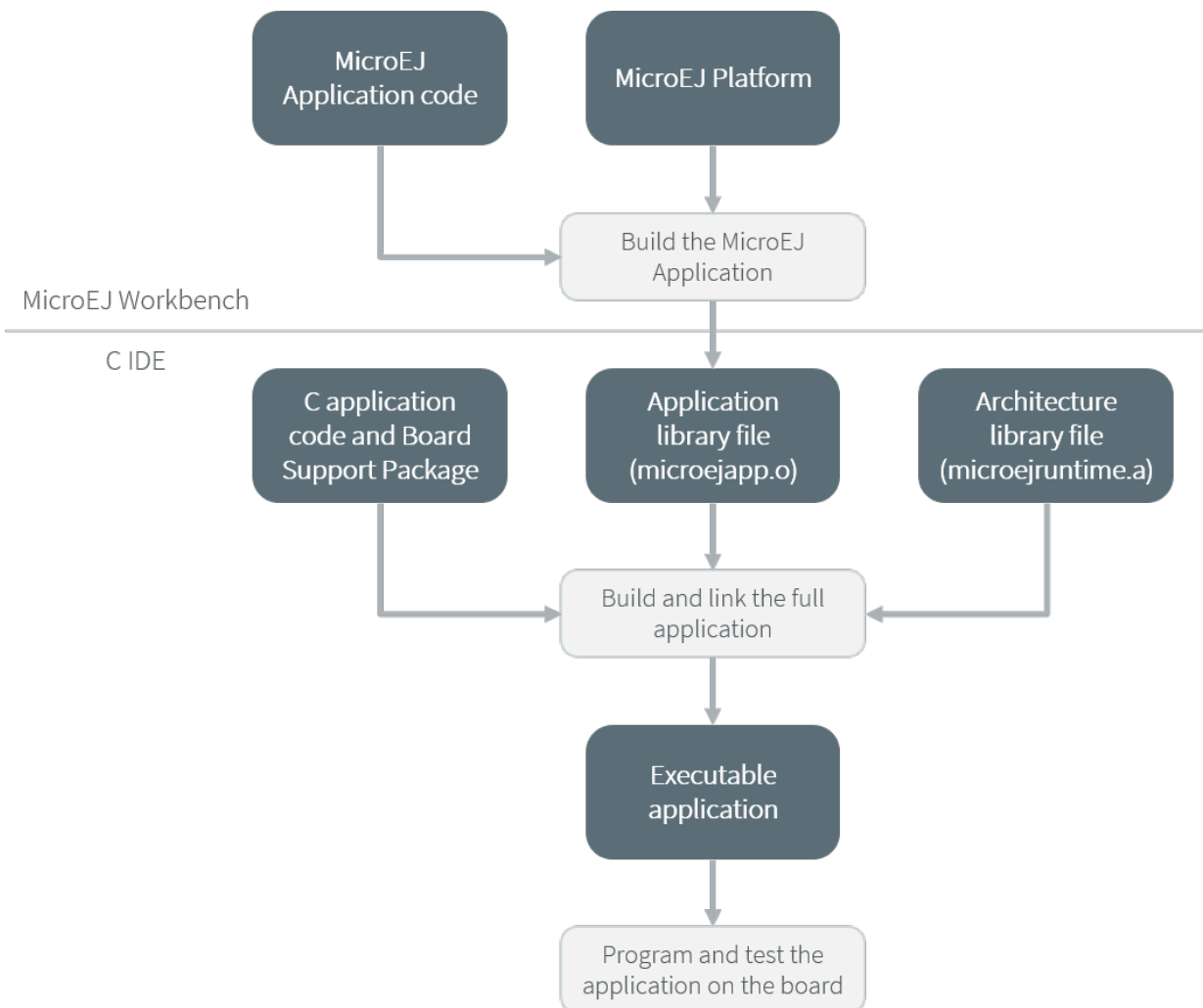


Fig. 13: MicroEJ Core Engine Flow

1. Step 1 consists in writing a MicroEJ Application against a set of Foundation Libraries available in the platform.

2. Step 2 consists in compiling the MicroEJ Application code and the required libraries in an ELF library, using the SOAR.
3. Step 3 consists in linking the previous ELF file with the MicroEJ Core Engine library and a third-party BSP (OS, drivers, etc.). This step may require a third-party linker provided by a C toolchain.

### 4.3.2 Architecture

The MicroEJ Core Engine and its components have been compiled for one specific CPU architecture and for use with a specific C compiler.

The architecture of the platform engine is called green thread architecture, it runs in a single RTOS task. Its behavior consists in scheduling MicroEJ threads. The scheduler implements a priority preemptive scheduling policy with round robin for the MicroEJ threads with the same priority. In the following explanations the term “RTOS task” refers to the tasks scheduled by the underlying OS; and the term “MicroEJ thread” refers to the Java threads scheduled by the MicroEJ Core Engine.

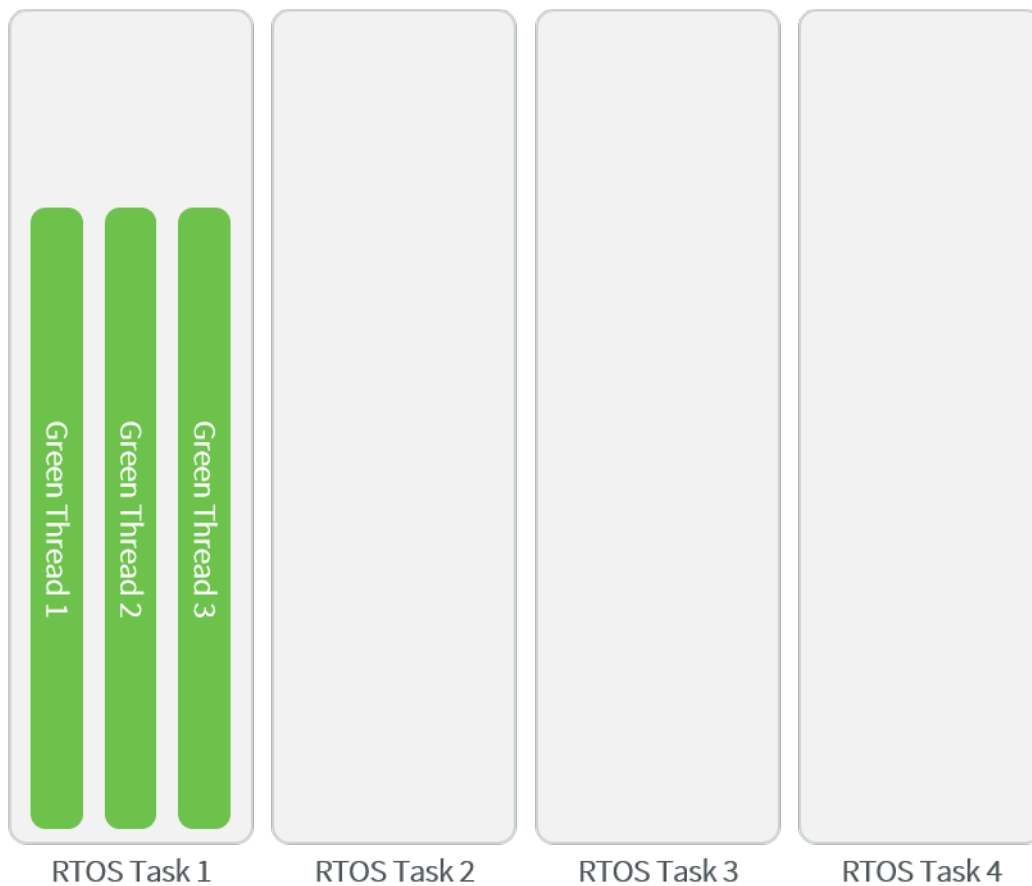


Fig. 14: A Green Threads Architecture Example

The activity of the platform is defined by the MicroEJ Application. When the MicroEJ Application is blocked (when all MicroEJ threads are sleeping), the platform sleeps entirely: The RTOS task that runs the platform sleeps.

The platform is responsible for providing the time to the MicroEJ world: the precision is 1 millisecond.

### 4.3.3 Capabilities

MicroEJ Core Engine defines 3 exclusive capabilities:

- Mono-sandbox : capability to produce a monolithic firmware (default one).
- Multi-Sandbox : capability to produce a extensible firmware on which new applications can be dynamically installed. See section *Multi-Sandbox*.
- Tiny application : capability to produce a compacted firmware (optimized for size). See section *Tiny application*.

All MicroEJ Core Engine capabilities may not be available on all architectures. Refer to section *Supported MicroEJ Core Engine Capabilities by Architecture Matrix* for more details.

### 4.3.4 Implementation

The platform implements the *[SNI] specification*. It is created and initialized with the C function `SNI_createVM`. Then it is started and executed in the current RTOS task by calling `SNI_startVM`. The function `SNI_startVM` returns when the MicroEJ Application exits. The function `SNI_destroyVM` handles the platform termination.

The file `LLMJVM_impl.h` that comes with the platform defines the API to be implemented. The file `LLMJVM.h` that comes with the platform defines platform-specific exit code constants. (See *LLMJVM: MicroEJ Core Engine*.)

#### Initialization

The Low Level MicroEJ Core Engine API deals with two objects: the structure that represents the platform, and the RTOS task that runs the platform. Two callbacks allow engineers to interact with the initialization of both objects:

- `LLMJVM_IMPL_initialize` : Called once the structure representing the platform is initialized.
- `LLMJVM_IMPL_vmTaskStarted` : Called when the platform starts its execution. This function is called within the RTOS task of the platform.

#### Scheduling

To support the green thread round-robin policy, the platform assumes there is an RTOS timer or some other mechanism that counts (down) and fires a call-back when it reaches a specified value. The platform initializes the timer using the `LLMJVM_IMPL_scheduleRequest` function with one argument: the absolute time at which the timer should fire. When the timer fires, it must call the `LLMJVM_schedule` function, which tells the platform to execute a green thread context switch (which gives another MicroEJ thread a chance to run).

#### Idle Mode

When the platform has no activity to execute, it calls the `LLMJVM_IMPL_idleVM` function, which is assumed to put the RTOS task of the platform into a sleep state. `LLMJVM_IMPL_wakeupVM` is called to wake up the platform task. When the platform task really starts to execute again, it calls the `LLMJVM_IMPL_ackWakeup` function to acknowledge the restart of its activity.

#### Time

The platform defines two times:

- the application time: The difference, measured in milliseconds, between the current time and midnight, January 1, 1970, UTC.
- the system time: The time since the start of the device. This time is independent of any user considerations, and cannot be set.

The platform relies on the following C functions to provide those times to the MicroEJ world:

- `LLMJVM_IMPL_getCurrentTime` : Depending on the parameter ( `true` / `false` ) must return the application time or the system time. This function is called by the MicroEJ method `System.currentTimeMillis()`. It is also used by the platform scheduler, and should be implemented efficiently.
- `LLMJVM_IMPL_getTimeNanos` : must return the system time in nanoseconds.
- `LLMJVM_IMPL_setApplicationTime` : must set the difference between the current time and midnight, January 1, 1970, UTC.

### Example

The following example shows how to create and launch the MicroEJ Core Engine from the C world. This function ( `mjvm_main` ) should be called from a dedicated RTOS task.

```
#include <stdio.h>
#include "mjvm_main.h"
#include "LLMJVM.h"
#include "sni.h"

void mjvm_main(void)
{
    void* vm;
    int32_t err;
    int32_t exitcode;

    // create VM
    vm = SNI_createVM();

    if(vm == NULL)
    {
        printf("VM initialization error.\n");
    }
    else
    {
        printf("VM START\n");
        err = SNI_startVM(vm, 0, NULL);

        if(err < 0)
        {
            // Error occurred
            if(err == LLMJVM_E_EVAL_LIMIT)
            {
                printf("Evaluation limits reached.\n");
            }
            else
            {
                printf("VM execution error (err = %d).\n", err);
            }
        }
        else
    }
}
```

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```

{
    // VM execution ends normally
    exitcode = SNI_getExitCode(vm);
    printf("VM END (exit code = %d)\n", exitcode);
}

// delete VM
SNI_destroyVM(vm);
}
}

```

## Debugging

The internal MicroEJ Core Engine function called `LLMJVM_dump` allows you to dump the state of all MicroEJ threads: name, priority, stack trace, etc. This function can be called at any time and from an interrupt routine (for instance from a button interrupt).

This is an example of a dump:

```

===== VM Dump =====
2 java threads
-----
Java Thread[3]
name="SYSINpmp" prio=5 state=WAITING

java/lang/Thread:
  at com/is2t/microbsp/microui/natives/NSystemInputPump.@134261800
  [0x0800AC32]
  at com/is2t/microbsp/microui/io/SystemInputPump.@134265968
  [0x0800BC80]
  at ej/microui/Pump.@134261696
  [0x0800ABCC]
  at ej/microui/Pump.@134265872
  [0x0800BC24]
  at java/lang/Thread.@134273964
  [0x0800DBC4]
  at java/lang/Thread.@134273784
  [0x0800DB04]
  at java/lang/Thread.@134273892
  [0x0800DB6F]
-----
Java Thread[2]
name="DISPLpmp" prio=5 state=WAITING

java/lang/Thread:
  at java/lang/Object.@134256392
  [0x08009719]
  at ej/microui/FIFOPump.@134259824
  [0x0800A48E]
  at ej/microui/io/DisplayPump.134263016
  [0x0800B0F8]
  at ej/microui/Pump.@134261696
  [0x0800ABCC]
  at ej/microui/Pump.@134265872
  [0x0800BC24]

```

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```

    at ej/microui/io/DisplayPump.@134262868
[0x0800B064]
    at java/lang/Thread.@134273964
[0x0800DBC4]
    at java/lang/Thread.@134273784
[0x0800DB04]
    at java/lang/Thread.@134273892
[0x0800DB6F]
=====

```

See [Stack Trace Reader](#) for additional info related to working with VM dumps.

### 4.3.5 Generic Output

The `System.err` stream is connected to the `System.out` print stream. See below for how to configure the destination of these streams.

### 4.3.6 Link

Several sections are defined by the MicroEJ Core Engine. Each section must be linked by the third-party linker.

Table 3: Linker Sections

Section name	Aim	Location	Alignment (in bytes)
<code>.bss.features.installed</code>	Resident applications statics	RW	4
<code>.bss.soar</code>	Application static	RW	8
<code>.bss.vm.stacks.java</code>	Application threads stack blocks	RW	8
<code>ICETEA_HEAP</code>	MicroEJ Core Engine internal heap	Internal RW	8
<code>_java_heap</code>	Application heap	RW	4
<code>_java_immortals</code>	Application immortal heap	RW	4
<code>.rodata.resources</code>	Application resources	RO	16
<code>.rodata.soar.features</code>	Resident applications code and resources	RO	4
<code>.shieldedplug</code>	Shielded Plug data	RO	4
<code>.text.soar</code>	Application and library code	RO	16

### 4.3.7 Dependencies

The MicroEJ Core Engine requires an implementation of its low level APIs in order to run. Refer to the chapter [Implementation](#) for more information.

### 4.3.8 Installation

The MicroEJ Core Engine and its components are mandatory. In the platform configuration file, check `Multi Applications` to install the MicroEJ Core Engine in “Multi-Sandbox” mode. Otherwise, the “Single appli-



cation” mode is installed.

#### 4.3.9 Use

A MicroEJ classpath variable named `EDC-1.2` is available, according to the selected foundation core library. This MicroEJ classpath variable is always required in the build path of a MicroEJ project; and all others libraries depend on it. This library provides a set of options. Refer to the chapter *Application Options* which lists all available options.

Another classpath variable named `BON-1.2` is available. This variable must be added to the build path of the MicroEJ Application project in order to access the *[BON] library*.

### 4.4 Multi-Sandbox

#### 4.4.1 Principle

The Multi-Sandbox capability of the MicroEJ Core Engine allows a main application (called Standalone Application) to install and execute at runtime additional applications (called sandboxed applications).

The MicroEJ Core Engine implements the *[KF] specification*. A Kernel is a Standalone Application generated on a Multi-Sandbox-enabled platform. A Feature is a sandboxed application generated against a Kernel.

A sandboxed application may be dynamically downloaded at runtime or integrated at build-time within the executable application.

Note that the Multi-Sandbox is a capability of the MicroEJ Core Engine. The MicroEJ Simulator always runs an application as a Standalone Application.

#### 4.4.2 Functional Description

The Multi-Sandbox process extends the overall process described in *the overview of the platform process*.

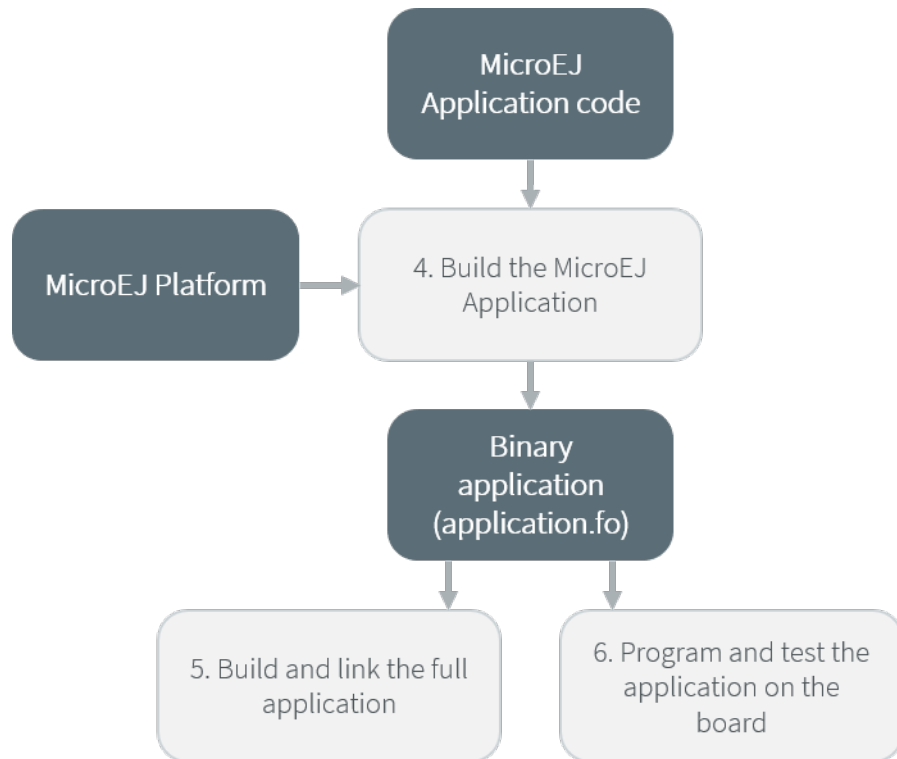


Fig. 15: Multi-Sandbox Process

Once a Kernel has been generated, additional MicroEJ Application code (Feature) can be built against the Kernel by :

- Creating one launch configuration per feature.
- Setting the **Settings** field in the **Execution** tab of each feature launch configuration to **Build Dynamic Feature** .
- Setting the **Kernel** field in the **Configuration** tab of each feature launch configuration to the **...** .

using the MicroEJ Application launch named Build Dynamic Feature. The binary application file produced ( **application.fo** ) is compatible only for the Kernel on which it was generated. Generating a new Kernel requires that you generate the Features again on this Kernel.

The Features built can be deployed in the following ways:

- Downloaded and installed at runtime by software. Refer to the *[KF] specification* for **ej.kf.Kernel** install APIs.
- Linked at build-time into the executable application. Features linked this way are then called Installed Features. The Kernel should have been generated with options for dimensioning the maximum size (code, data) for such Installed Features. Features are linked within the Kernel using the Firmware linker tool.

#### 4.4.3 Firmware Linker

A MicroEJ tool is available to link Features as Installed Features within the executable application. The tool name is Firmware Linker. It takes as input the executable application file and the Feature binary code into which to be

linked. It outputs a new executable application file, including the Installed Feature. This tool can be used to append multiple Features, by setting as the input file the output file of the previous pass.

#### 4.4.4 Memory Considerations

Multi-Sandbox memory overhead of MicroEJ Core Engine runtime elements are described in *the table below*.

Table 4: Multi-Sandbox Memory Overhead

Runtime element	Memory	Description
Object	RW	4 bytes
Thread	RW	24 bytes
Stack Frame	RW	8 bytes
Class Type	RO	4 bytes
Interface Type	RO	8 bytes

#### 4.4.5 Dependencies

- `LLKERNEL_impl.h` implementation (see *LLKERNEL: Multi-Sandbox*).

#### 4.4.6 Installation

Multi-Sandbox is an additional module, disabled by default.

To enable Multi-Sandbox of the MicroEJ Core Engine, in the platform configuration file, check **Multi Applications**.

#### 4.4.7 Use

A classpath variable named `KF-1.4` is available.

This library provides a set of options. Refer to the chapter *Application Options* which lists all available options.

### 4.5 Tiny application

#### 4.5.1 Principle

The Tiny application capability of the MicroEJ Core Engine allows to build a main application optimized for size. This capability is suitable for environments requiring a small memory footprint.

#### 4.5.2 Installation

Tiny application is an option disabled by default. To enable Tiny application of the MicroEJ Core Engine, set the property `mjvm.standalone.configuration` in `configuration.xml` file as follows:

```
<property name="mjvm.standalone.configuration" value="tiny"/>
```

See section *Platform Customization* for more info on the `configuration.xml` file.

### 4.5.3 Limitations

In addition to general *Limitations*:

- The maximum application code size (classes and methods) cannot exceed **256KB**. This does not include application resources, immutable objects and internal strings which are not limited.
- The option `SOAR > Debug > Embed all type names` has no effect. Only the fully qualified names of types marked as required types are embedded.

## 4.6 Native Interface Mechanisms

The MicroEJ Core Engine provides two ways to link MicroEJ Application code with native C code. The two ways are fully complementary, and can be used at the same time.

### 4.6.1 Simple Native Interface (SNI)

#### Principle

*[SNI]* provides a simple mechanism for implementing native Java methods in the C language.

*[SNI]* allows you to:

- Call a C function from a Java method.
- Access an Immortal array in a C function (see the *[BON] specification* to learn about immortal objects).

*[SNI]* does not allow you to:

- Access or create a Java object in a C function.
- Access Java static variables in a C function.
- Call Java methods from a C function.

*[SNI]* provides some Java APIs to manipulate some data arrays between Java and the native (C) world.

#### Functional Description

*[SNI]* defines how to cross the barrier between the Java world and the native world:

- Call a C function from Java.
- Pass parameters to the C function.
- Return a value from the C world to the Java world.
- Manipulate (read & write) shared memory both in Java and C : the immortal space.

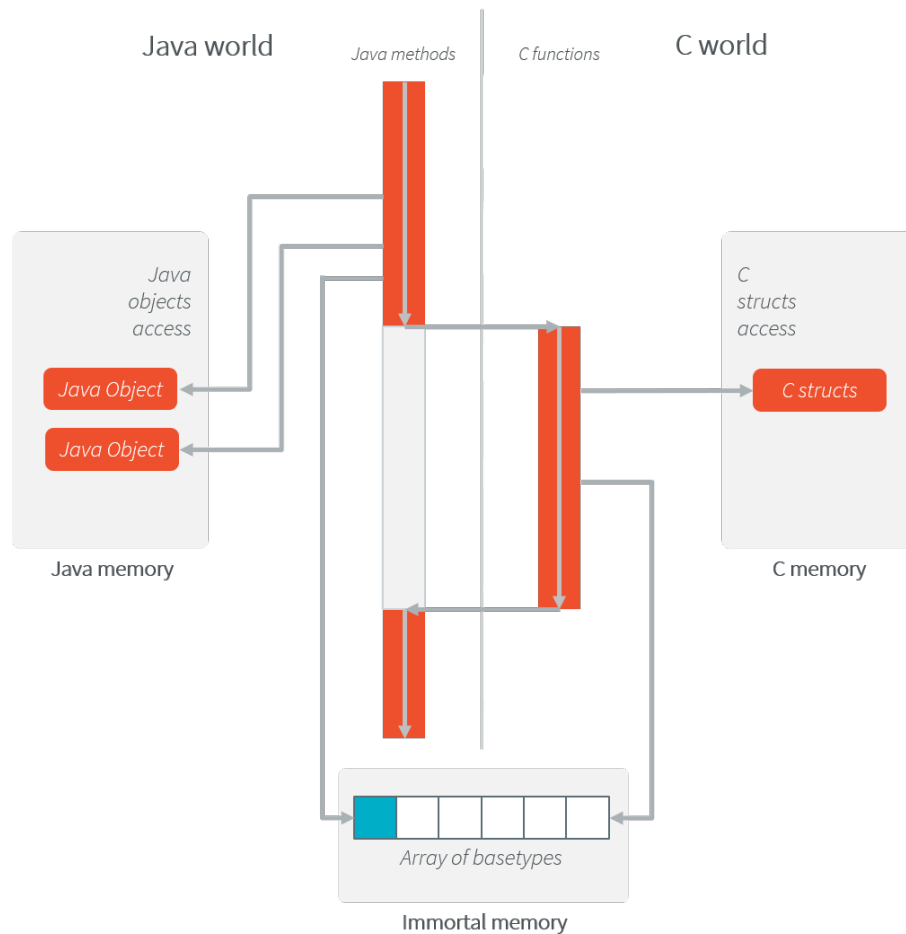


Fig. 16: [SNI] Processing

The above illustration shows both Java and C code accesses to shared objects in the immortal space, while also accessing their respective memory.

### Example

```
package example;

import java.io.IOException;

/**
 * Abstract class providing a native method to access sensor value.
 * This method will be executed out of virtual machine.
 */
public abstract class Sensor {

    public static final int ERROR = -1;

    public int getValue() throws IOException {
        int sensorID = getSensorID();
        int value = getSensorValue(sensorID);
    }
}
```

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```

        if (value == ERROR) {
            throw new IOException("Unsupported sensor");
        }
        return value;
    }

    protected abstract int getSensorID();

    public static native int getSensorValue(int sensorID);
}

class Potentiometer extends Sensor {

    protected int getSensorID() {
        return Constants.POTENTIOMETER_ID; // POTENTIOMETER_ID is a static final
    }
}

```

```

// File providing an implementation of native method using a C function
#include <sni.h>
#include <potentiometer.h>

#define SENSOR_ERROR (-1)
#define POTENTIOMETER_ID (3)

jint Java_example_Sensor_getSensorValue(jint sensor_id){

    if (sensor_id == POTENTIOMETER_ID)
    {
        return get_potentiometer_value();
    }
    return SENSOR_ERROR;
}

```

## Synchronization

A call to a native function uses the same RTOS task as the RTOS task used to run all Java green threads. So during this call, the MicroEJ Core Engine cannot schedule other Java threads.

[SNI] defines C functions that provide controls for the green threads' activities:

- `int32_t SNI_suspendCurrentJavaThread(int64_t timeout)` : Suspends the execution of the Java thread that initiated the current C call. This function does not block the C execution. The suspension is effective only at the end of the native method call (when the C call returns). The green thread is suspended until either an RTOS task calls `SNI_resumeJavaThread`, or the specified number of milliseconds has elapsed.
- `int32_t SNI_getCurrentJavaThreadID(void)` : Permits retrieval of the ID of the current Java thread within the C function (assuming it is a "native Java to C call"). This ID must be given to the `SNI_resumeJavaThread` function in order to resume execution of the green thread.
- `int32_t SNI_resumeJavaThread(int32_t id)` : Resumes the green thread with the given ID. If the thread is not suspended, the resume stays pending.

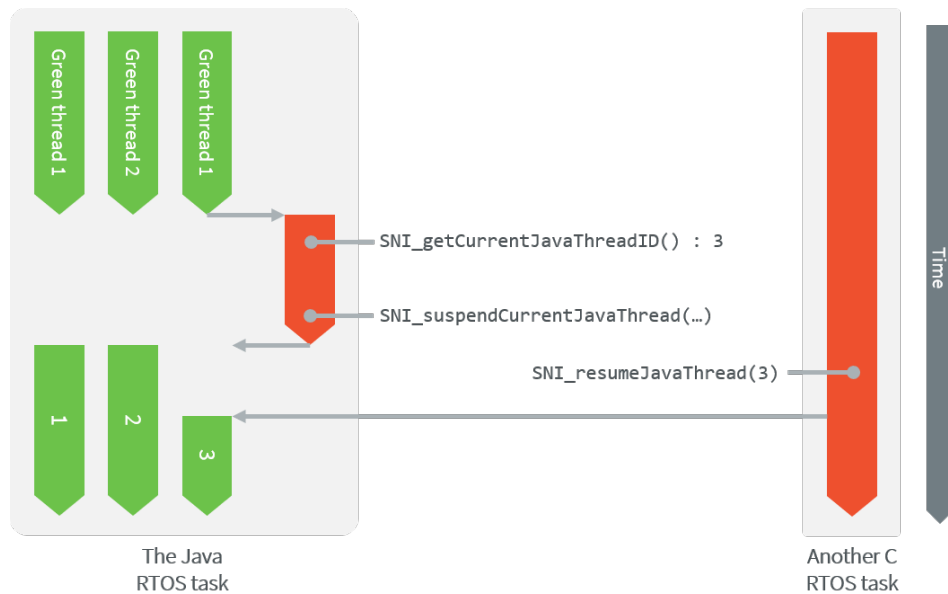


Fig. 17: Green Threads and RTOS Task Synchronization

*The above illustration* shows a green thread (GT3) which has called a native method that executes in C. The C code suspends the thread after having provisioned its ID (e.g. 3). Another RTOS task may later resume the Java green thread.

## Dependencies

No dependency.

## Installation

The `[SNI]` library is a built-in feature of the platform, so there is no additional dependency to call native code from Java. In the platform configuration file, check `Java to C Interface` > `SNI API` to install the additional Java APIs in order to manipulate the data arrays.

## Use

The `SNI API module` must be added to the `module.ivy` of the MicroEJ Application project, in order to allow access to the `[SNI]` library.

```
<dependency org="ej.api" name="sni" rev="1.3.1"/>
```

## 4.6.2 Shielded Plug (SP)

### Principle

The Shielded Plug `[SP]` provides data segregation with a clear publish-subscribe API. The data-sharing between modules uses the concept of shared memory blocks, with introspection. The database is made of blocks: chunks of RAM.

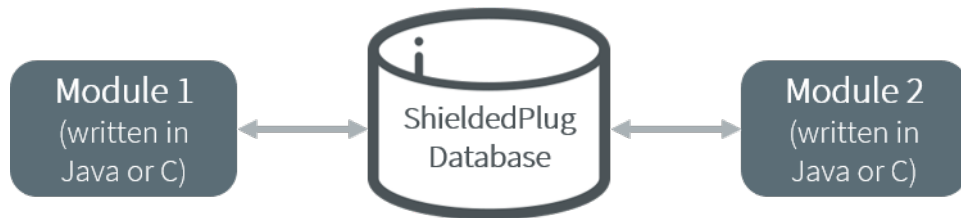


Fig. 18: A Shielded Plug Between Two Application (Java/C) Modules.

### Functional Description

The usage of the Shielded Plug (SP) starts with the definition of a database. The implementation of the [\[SP\]](#) for the MicroEJ Platform uses an XML file description to describe the database; the syntax follows the one proposed by the [\[SP\] specification](#).

Once this database is defined, it can be accessed within the MicroEJ Application or the C application. The [\[SP\]](#) Foundation Library is accessible from the classpath variable `SP-2.0`. This library contains the classes and methods to read and write data in the database. See also the Java documentation from the MicroEJ Workbench resources center (“Javadoc” menu). The C header file `sp.h` available in the MicroEJ Platform `source/MICROJVM/include` folder contains the C functions for accessing the database.

To embed the [\[SP\]](#) database in your binary file, the XML file description must be processed by the [\[SP\]](#) compiler. This compiler generates a binary file ( `.o` ) that will be linked to the overall application by the linker. It also generates two descriptions of the block ID constants, one in Java and one in C. These constants can be used by either the Java or the C application modules.

### Shielded Plug Compiler

A MicroEJ tool is available to launch the [\[SP\]](#) compiler tool. The tool name is Shielded Plug Compiler. It outputs:

- A description of the requested resources of the database as a binary file ( `.o` ) that will be linked to the overall application by the linker. It is an ELF format description that reserves both the necessary RAM and the necessary Flash memory for the Shielded Plug database.
- Two descriptions, one in Java and one in C, of the block ID constants to be used by either Java or C application modules.



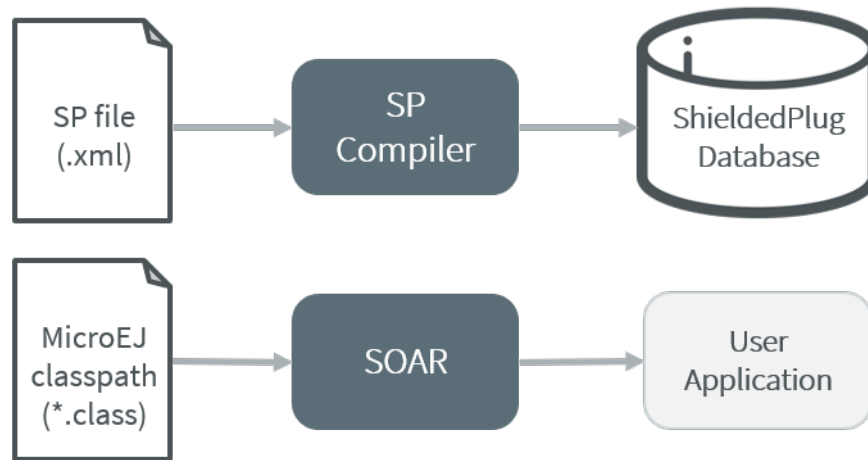


Fig. 19: Shielded Plug Compiler Process Overview

### Example

Below is an example of using a database [\[SP\]](#). The code that publishes the data is written in C, and the code that receives the data is written in Java. The data is transferred using two memory blocks. `TEMP` is a scalar value, `THERMOSTAT` is a boolean.

### Database Description

The database is described as follows:

```

<shieldedPlug>
  <database name="Forecast" id="0" immutable="true" version="1.0.0">
    <block id="1" name="TEMP" length="4" maxTasks="1"/>
    <block id="2" name="THERMOSTAT" length="4" maxTasks="1"/>
  </database>
</shieldedPlug>
  
```

### Java Code

From the database description we can create an interface.

```

public interface Forecast {
    public static final int ID = 0;
    public static final int TEMP = 1;
    public static final int THERMOSTAT = 2;
}
  
```

Below is the task that reads the published temperature and controls the thermostat.

```

public void run(){
    ShieldedPlug database = ShieldedPlug.getDatabase(Forecast.ID);
  
```

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```

while (isRunning) {
    //reading the temperature every 30 seconds
    //and update thermostat status
    try {
        int temp = database.readInt(Forecast.TEMP);
        print(temp);
        //update the thermostat status
        database.writeInt(Forecast.THERMOSTAT,temp>tempLimit ? 0 : 1);
    }
    catch(EmptyBlockException e){
        print("Temperature not available");
    }
    sleep(30000);
}
}

```

## C Code

Here is a C header that declares the constants defined in the XML description of the database.

```

#define Forecast_ID 0
#define Forecast_TEMP 1
#define Forecast_THERMOSTAT 2

```

Below, the code shows the publication of the temperature and thermostat controller task.

```

void temperaturePublication() {
    ShieldedPlug database = SP_getDatabase(Forecast_ID);
    int32_t temp = temperature();
    SP_write(database, Forecast_TEMP, &temp);
}

void thermostatTask(){
    int32_t thermostatOrder;
    ShieldedPlug database = SP_getDatabase(Forecast_ID);
    while(1){
        SP_waitFor(database, Forecast_THERMOSTAT);
        SP_read(database, Forecast_THERMOSTAT, &thermostatOrder);
        if(thermostatOrder == 0) {
            thermostatOFF();
        }
        else {
            thermostatON();
        }
    }
}

```

## Dependencies

- `LLSP_impl.h` implementation (see *LLSP: Shielded Plug*).

## Installation

The *[SP]* library and its relative tools are an optional feature of the platform. In the platform configuration file, check **Java to C Interface** > **Shielded Plug** to install the library and its relative tools.

## Use

A classpath variable named *SP-2.0* is available, which must be added to the build path of the MicroEJ Application project in order to access the *[SP]* library.

This library provides a set of options. Refer to the chapter *Application Options* which lists all available options.

### 4.6.3 MicroEJ Java H

#### Principle

This MicroEJ tool is useful for creating the skeleton of a C file, to which some Java native implementation functions will later be written. This tool helps prevent misses of some *#include* files, and helps ensure that function signatures are correct.

#### Functional Description

MicroEJ Java H tool takes as input one or several Java class files (\*.class) from directories and / or JAR files. It looks for Java native methods declared in these class files, and generates a skeleton(s) of the C file(s).

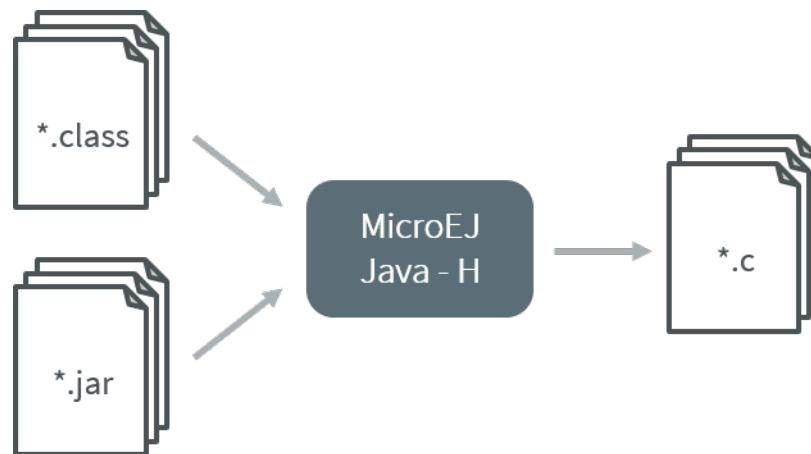


Fig. 20: MicroEJ Java H Process

#### Dependencies

No dependency.

## Installation

This is an additional tool. In the platform configuration file, check **Java to C Interface** > **MicroEJ Java H** to install the tool.

## Use

This chapter explains the MicroEJ tool options.

## 4.7 External Resources Loader

### 4.7.1 Principle

A *resource* is, for a MicroEJ Application, the contents of a file. This file is known by its path (its relative path from the MicroEJ Application classpath) and its name. The file may be stored in RAM, flash, or external flash; and it is the responsibility of the MicroEJ Core Engine and/or the BSP to retrieve and load it.

MicroEJ Platform makes the distinction between two kinds of resources:

- **Internal resource:** The resource is taken into consideration during the MicroEJ Application build. The SOAR step loads the resource and copies it into the same C library as the MicroEJ Application. Like the MicroEJ Application, the resource is linked into the CPU address space range (internal device memories, external parallel memories, etc.).

The available list of internal resources to embed must be specified in the MicroEJ Application launcher (MicroEJ launch). Under the “Resources” tab, select all internal resources to embed in the final binary file.

- **External resource:** The resource is not taken into consideration by MicroEJ. It is the responsibility of the BSP project to manage this kind of resource. The resource is often programmed outside the CPU address space range (storage media like SD card, serial NOR flash, EEPROM, etc.).

The BSP must implement some specific Low Level API (LLAPI) C functions: `LLEXT_RES_impl.h`. These functions allow the MicroEJ Application to load some external resources.

### 4.7.2 Functional Description

The External Resources Loader is an optional module. When not installed, only internal resources are available for the MicroEJ Application. When the External Resources Loader is installed, the MicroEJ Core Engine tries first to retrieve the expected resource from its available list of internal resources, before asking the BSP to load it (using `LLEXT_RES_impl.h` functions).

### 4.7.3 Implementations

External Resources Loader module provides some Low Level API (LLEXT\_RES) to let the BSP manage the external resources.

#### Open a Resource

The LLAPI to implement in the BSP are listed in the header file `LLEXT_RES_impl.h`. First, the framework tries to open an external resource using the `open` function. This function receives the resources path as a parameter. This path is the absolute path of the resource from the MicroEJ Application classpath (the MicroEJ Application source base directory). For example, when the resource is located here: `com.mycompany.myapplication.resource.MyResource.txt`, the given path is: `com/mycompany/myapplication/resource/MyResource.txt`.

### Resource Identifier

This `open` function has to return a unique ID (positive value) for the external resource, or returns an error code (negative value). This ID will be used by the framework to manipulate the resource (read, seek, close, etc.).

Several resources can be opened at the same time. The BSP does not have to return the same identifier for two resources living at the same time. However, it can return this ID for a new resource as soon as the old resource is closed.

### Resource Offset

The BSP must hold an offset for each opened resource. This offset must be updated after each call to `read` and `seek`.

### Resource Inside the CPU Address Space Range

An external resource can be programmed inside the CPU address space range. This memory (or a part of memory) is not managed by the SOAR and so the resources inside are considered as external.

Most of time the content of an external resource must be copied in a memory inside the CPU address space range in order to be accessible by the MicroEJ algorithms (draw an image etc.). However, when the resource is already inside the CPU address space range, this copy is useless. The function `LLEXTR_RES_getBaseAddress` must return a valid CPU memory address in order to avoid this copy. The MicroEJ algorithms are able to target the external resource bytes without using the other `LLEXTR_RES` APIs such as `read`, `mark` etc.

## 4.7.4 External Resources Folder

The External Resource Loader module provides an option (MicroEJ launcher option) to specify a folder for the external resources. This folder has two roles:

- It is the output folder used by some extra generators during the MicroEJ Application build. All output files generated by these tools will be copied into this folder. This makes it easier to retrieve the exhaustive list of resources to program on the board.
- This folder is taken into consideration by the Simulator in order to simulate the availability of these resources. When the resources are located in another computer folder, the Simulator is not able to load them.

If not specified, this folder is created (if it does not already exist) in the MicroEJ project specified in the MicroEJ launcher. Its name is `externalResources`.

## 4.7.5 Dependencies

- `LLEXTR_RES_impl.h` implementation (see *`LLEXTR_RES: External Resources Loader`*).

## 4.7.6 Installation

The External Resources Loader is an additional module. In the platform configuration file, check `External Resources Loader` to install this module.

### 4.7.7 Use

The External Resources Loader is automatically used when the MicroEJ Application tries to open an external resource.

## 4.8 Serial Communications

MicroEJ provides some Foundation Libraries to instantiate some communications with external devices. Each communication method has its own library. A global library called ECOM provides support for abstract communication streams (communication framework only), and a generic devices manager.

### 4.8.1 ECOM

#### Principle

The Embedded COMMunication Foundation Library (ECOM) is a generic communication library with abstract communication stream support (a communication framework only). It allows you to open and use streams on communication devices such as a COMM port.

This library also provides a device manager, including a generic device registry and a notification mechanism, which allows plug&play-based applications.

This library does not provide APIs to manipulate some specific options for each communication method, but it does provide some generic APIs which abstract the communication method. After the opening step, the MicroEJ Application can use every communications method (COMM, USB etc.) as generic communication in order to easily change the communication method if needed.

#### Functional Description

*The diagram below* shows the overall process to open a connection on a hardware device.

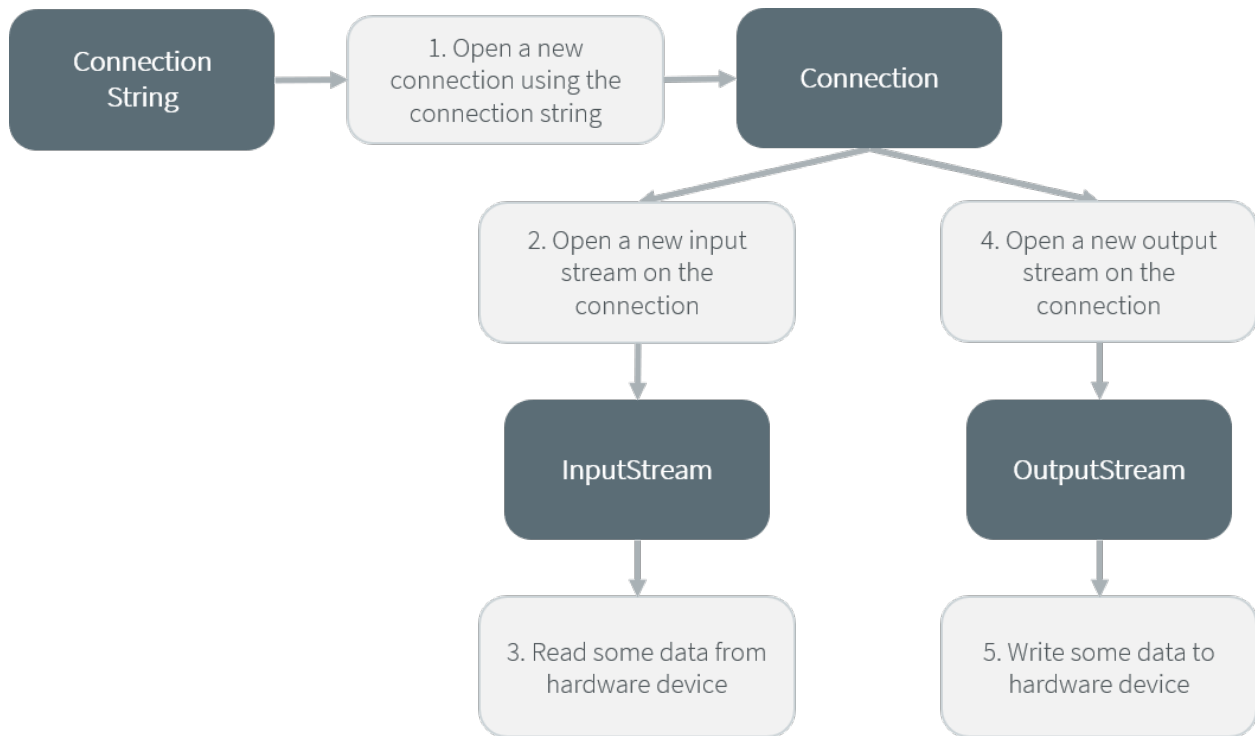


Fig. 21: ECOM Flow

1. Step 1 consists of opening a connection on a hardware device. The connection kind and its configuration are fixed by the parameter `String connectionString` of the method `Connection.open`.
2. Step 2 consists of opening an `InputStream` on the connection. This stream allows the MicroEJ Application to access the “RX” feature of the hardware device.
3. Step 3 consists of using the `InputStream` APIs to receive in the MicroEJ Application all hardware device data.
4. Step 4 consists of opening an `OutputStream` on the connection. This stream allows the MicroEJ Application to access the “TX” feature of the hardware device.
5. Step 5 consists of using the `OutputStream` APIs to transmit some data from the MicroEJ Application to the hardware device.

Note that steps 2 and 4 may be performed in parallel, and do not depend on each other.

### Device Management API

A device is defined by implementing `ej.ecom.Device`. It is identified by a name and a descriptor ( `ej.ecom.HardwareDescriptor` ), which is composed of a set of MicroEJ properties. A device can be registered/unregistered in the `ej.ecom.DeviceManager`.

A device registration listener is defined by implementing `ej.ecom.RegistrationListener`. When a device is registered to or unregistered from the device manager, listeners registered for the device type are notified. The notification mechanism is done in a dedicated Java thread. The mechanism can be enabled or disabled (see *Application Options*).

### Dependencies

No dependency.

## Installation

ECOM Foundation Library is an additional library. In the platform configuration file, check `Serial Communication` > `ECOM` to install the library.

## Use

A classpath variable named `ECOM-1.1` is available. This foundation library is always required when developing a MicroEJ Application which communicates with some external devices. It is automatically embedded as soon as a sub communication library is added in the classpath.

### 4.8.2 ECOM Comm

#### Principle

The ECOM Comm Java library provides support for serial communication. ECOM Comm extends ECOM to allow stream communication via serial communication ports (typically UARTs). In the MicroEJ Application, the connection is established using the `Connector.open()` method. The returned connection is a `ej.ecom.io.CommConnection`, and the input and output streams can be used for full duplex communication.

The use of ECOM Comm in a custom platform requires the implementation of an UART driver. There are two different modes of communication:

- In Buffered mode, ECOM Comm manages software FIFO buffers for transmission and reception of data. The driver copies data between the buffers and the UART device.
- In Custom mode, the buffering of characters is not managed by ECOM Comm. The driver has to manage its own buffers to make sure no data is lost in serial communications because of buffer overruns.

This ECOM Comm implementation also allows dynamic add or remove of a connection to the pool of available connections (typically hot-plug of a USB Comm port).

#### Functional Description

The ECOM Comm process respects the ECOM process. Please refer to the illustration *“ECOM flow”*.

#### Component Architecture

The ECOM Comm C module relies on a native driver to perform actual communication on the serial ports. Each port can be bound to a different driver implementation, but most of the time, it is possible to use the same implementation (i.e. same code) for multiple ports. Exceptions are the use of different hardware UART types, or the need for different behaviors.

Five C header files are provided:

- `LLCOMM_impl.h`  
Defines the set of functions that the driver must implement for the global ECOM comm stack, such as synchronization of accesses to the connections pool.
- `LLCOMM_BUFFERED_CONNECTION_impl.h`  
Defines the set of functions that the driver must implement to provide a Buffered connection



- `LLCOMM_BUFFERED_CONNECTION.h`

Defines the set of functions provided by ECOM Comm that can be called by the driver (or other C code) when using a Buffered connection

- `LLCOMM_CUSTOM_CONNECTION_impl.h`

Defines the set of functions that the driver must implement to provide a Custom connection

- `LLCOMM_CUSTOM_CONNECTION.h`

Defines the set of functions provided by ECOM Comm that can be called by the driver (or other C code) when using a Custom connection

The ECOM Comm drivers are implemented using standard LLAPI features. The diagram below shows an example of the objects (both Java and C) that exist to support a Buffered connection.

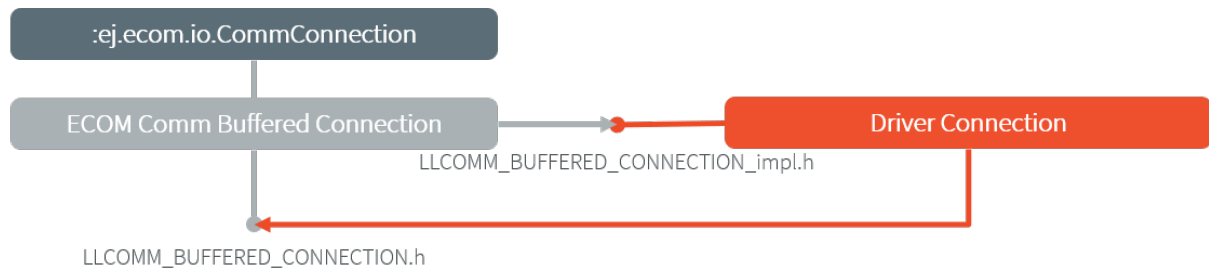


Fig. 22: ECOM Comm components

The connection is implemented with three objects<sup>1</sup>:

- The Java object used by the application; an instance of `ej.ecom.io.CommConnection`
- The connection object within the ECOM Comm C module
- The connection object within the driver

Each driver implementation provides one or more connections. Each connection typically corresponds to a physical UART.

### Comm Port Identifier

Each serial port available for use in ECOM Comm can be identified in three ways:

- An application port number. This identifier is specific to the application, and should be used to identify the data stream that the port will carry (for example, “debug traces” or “GPS data”).
- A platform port number. This is specific to the platform, and may directly identify an hardware device<sup>2</sup>.
- A platform port name. This is mostly used for dynamic connections or on platforms having a file-system based device mapping.

When the Comm Port is identified by a number, its string identifier is the concatenation of “com” and the number (e.g. com11).

<sup>1</sup> This is a conceptual description to aid understanding - the reality is somewhat different, although that is largely invisible to the implementor of the driver.

<sup>2</sup> Some drivers may reuse the same UART device for different ECOM ports with a hardware multiplexer. Drivers can even treat the platform port number as a logical id and map the ids to various I/O channels.

## Application Port Mapping

The mapping from application port numbers to platform ports is done in the application launch configuration. This way, the application can refer only to the application port number, and the data stream can be directed to the matching I/O port on different versions of the hardware.

Ultimately, the application port number is only visible to the application. The platform identifier will be sent to the driver.

## Opening Sequence

The following flow chart explains Comm Port opening sequence according to the given Comm Port identifier.

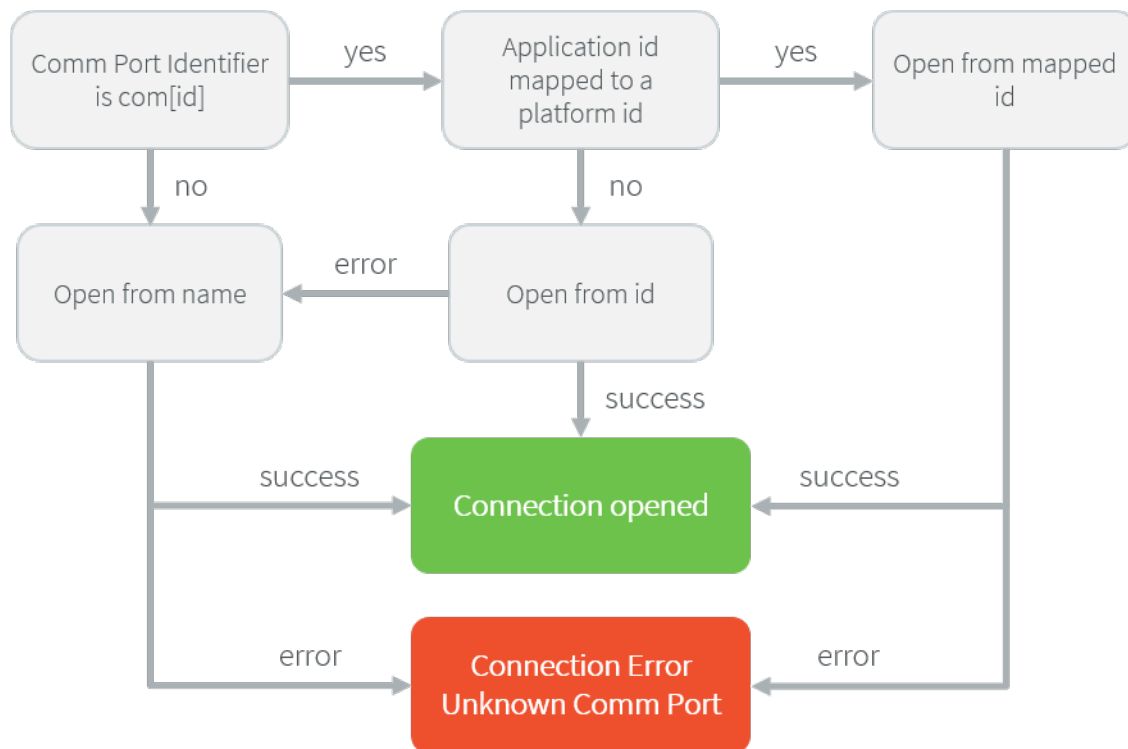


Fig. 23: Comm Port Open Sequence

## Dynamic Connections

The ECOM Comm stack allows to dynamically add and remove connections from the *Driver API*. When a connection is added, it can be immediately open by the application. When a connection is removed, the connection cannot be open anymore and `java.io.IOException` is thrown in threads that are using it.

In addition, a dynamic connection can be registered and unregistered in ECOM device manager (see *Device Management API*). The registration mechanism is done in dedicated thread. It can be enabled or disabled, see *Application Options*.

A removed connection is alive until it is closed by the application and, if enabled, unregistered from ECOM device manager. A connection is effectively uninstalled (and thus eligible to be reused) only when it is released by the stack.

The following sequence diagram shows the lifecycle of a dynamic connection with ECOM registration mechanism enabled.

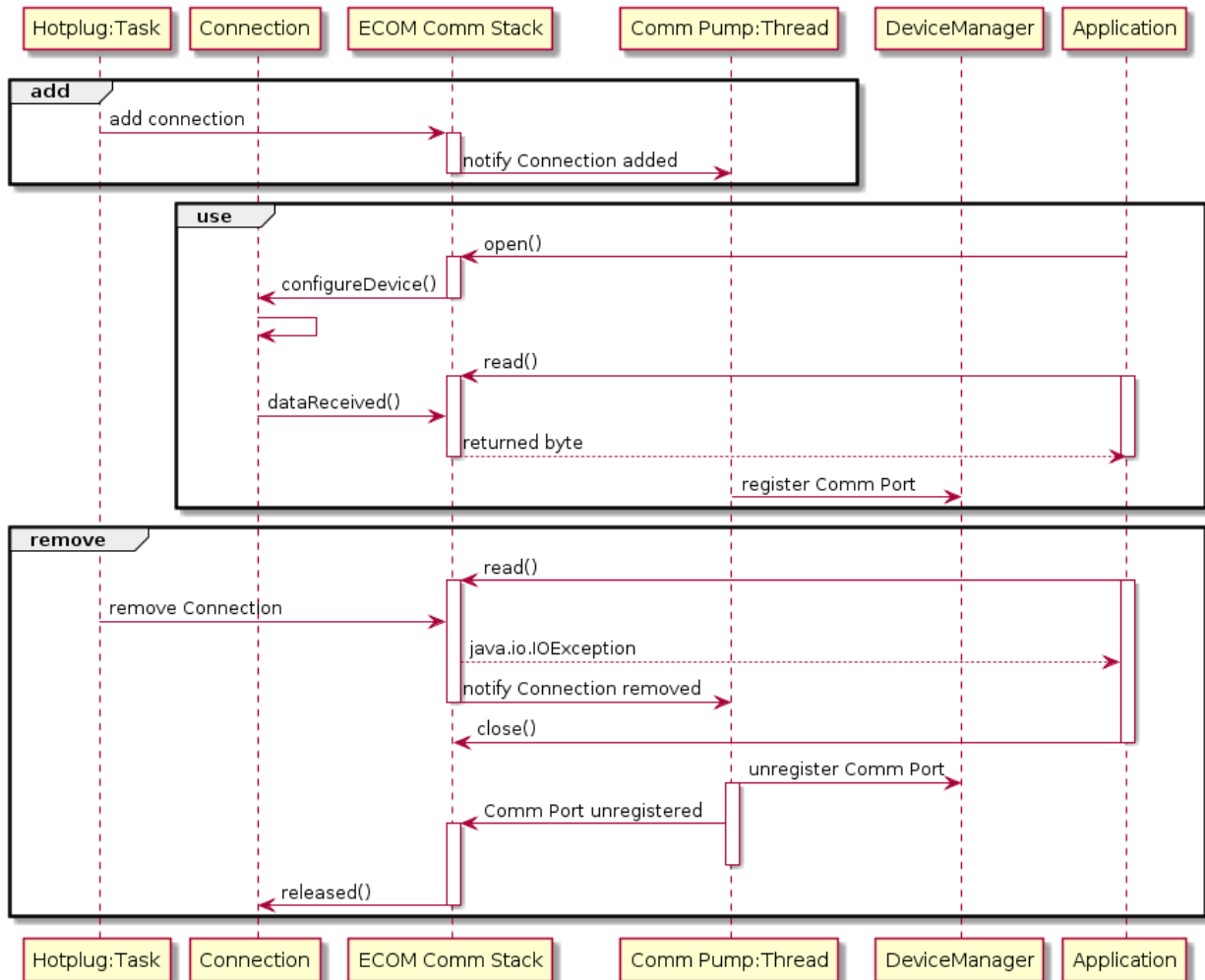


Fig. 24: Dynamic Connection Lifecycle

## Java API

Opening a connection is done using `ej.ecom.io.Connector.open(String name)`. The connection string (the `name` parameter) must start with "comm:", followed by the Comm port identifier, and a semicolon-separated list of options. Options are the baudrate, the parity, the number of bits per character, and the number of stop bits:

- baudrate=n (9600 by default)
- bitsperchar=n where n is in the range 5 to 9 (8 by default)
- stopbits=n where n is 1, 2, or 1.5 (1 by default)
- parity=x where x is odd, even or none (none by default)

All of these are optional. Illegal or unrecognized parameters cause an `IllegalArgumentException`.

## Driver API

The ECOM Comm Low Level API is designed to allow multiple implementations (e.g. drivers that support different UART hardware) and connection instances (see Low Level API Pattern chapter). Each ECOM Comm driver defines a data structure that holds information about a connection, and functions take an instance of this data structure as the first parameter.

The name of the implementation must be set at the top of the driver C file, for example<sup>3</sup>:

```
#define LLCOMM_BUFFERED_CONNECTION MY_LLCOMM
```

This defines the name of this implementation of the `LLCOMM_BUFFERED_CONNECTION` interface to be `MY_LLCOMM`.

The data structure managed by the implementation must look like this:

```
typedef struct MY_LLCOMM{
    struct LLCOMM_BUFFERED_CONNECTION header;
    // extra data goes here
} MY_LLCOMM;

void MY_LLCOMM_new(MY_LLCOMM* env);
```

In this example the structure contains only the default data, in the header field. Note that the header must be the first field in the structure. The name of this structure must be the same as the implementation name (`MY_LLCOMM` in this example).

The driver must also declare the “new” function used to initialize connection instances. The name of this function must be the implementation name with `_new` appended, and it takes as its sole argument a pointer to an instance of the connection data structure, as shown above.

The driver needs to implement the functions specified in the `LLCOMM_impl.h` file and for each kind of connection, the `LLCOMM_BUFFERED_CONNECTION_impl.h` (or `LLCOMM_CUSTOM_CONNECTION_impl.h`) file.

The driver defines the connections it provides by adding connection objects using `LLCOMM_addConnection`. Connections can be added to the stack as soon as the `LLCOMM_initialize` function is called. Connections added during the call of the `LLCOMM_impl_initialize` function are static connections. A static connection is registered to the ECOM registry and cannot be removed. When a connection is dynamically added outside the MicroJVM task context, a suitable reentrant synchronization mechanism must be implemented (see `LLCOMM_IMPL_syncConnectionsEnter` and `LLCOMM_IMPL_syncConnectionsExit`).

When opening a port from the MicroEJ Application, each connection declared in the connections pool will be asked about its platform port number (using the `getPlatformId` method) or its name (using the `getName` method) depending on the requested port identifier. The first matching connection is used.

The life of a connection starts with the call to `getPlatformId()` or `getName()` method. If the connection matches the port identifier, the connection will be initialized, configured and enabled. Notifications and interrupts are then used to keep the stream of data going. When the connection is closed by the application, interrupts are disabled and the driver will not receive any more notifications. It is important to remember that the transmit and receive sides of the connection are separate Java stream objects, thus, they may have a different life cycle and one side may be closed long before the other.

## The Buffered Comm Stream

In Buffered mode, two buffers are allocated by the driver for sending and receiving data. The ECOM Comm C module will fill the transmit buffer, and get bytes from the receive buffer. There is no flow control.

<sup>3</sup> The following examples use Buffered connections, but Custom connections follow the same pattern.

When the transmit buffer is full, an attempt to write more bytes from the MicroEJ Application will block the Java thread trying to write, until some characters are sent on the serial line and space in the buffer is available again.

When the receive buffer is full, characters coming from the serial line will be discarded. The driver must allocate a buffer big enough to avoid this, according to the UART baudrate, the expected amount of data to receive, and the speed at which the application can handle it.

The Buffered C module manages the characters sent by the application and stores them in the transmit buffer. On notification of available space in the hardware transmit buffer, it handles removing characters from this buffer and putting them in the hardware buffer. On the other side, the driver notifies the C module of data availability, and the C module will get the incoming character. This character is added to the receive buffer and stays there until the application reads it.

The driver should take care of the following:

- Setting up interrupt handlers on reception of a character, and availability of space in the transmit buffer. The C module may mask these interrupts when it needs exclusive access to the buffers. If no interrupt is available from the hardware or underlying software layers, it may be faked using a polling thread that will notify the C module.
- Initialization of the I/O pins, clocks, and other things needed to get the UART working.
- Configuration of the UART baudrate, character size, flow control and stop bits according to the settings given by the C module.
- Allocation of memory for the transmit and receive buffers.
- Getting the state of the hardware: is it running, is there space left in the TX and RX hardware buffers, is it busy sending or receiving bytes?

The driver is notified on the following events:

- Opening and closing a connection: the driver must activate the UART and enable interrupts for it.
- A new byte is waiting in the transmit buffer and should be copied immediately to the hardware transmit unit. The C module makes sure the transmit unit is not busy before sending the notification, so it is not needed to check for that again.

The driver must notify the C module on the following events:

- Data has arrived that should be added to the receive buffer (using the `LLCOMM_BUFFERED_CONNECTION_dataReceived` function)
- Space available in the transmit buffer (using the `LLCOMM_BUFFERED_CONNECTION_transmitBufferReady` function)

### The Custom Comm Stream

In custom mode, the ECOM Comm C module will not do any buffering. Read and write requests from the application are immediately forwarded to the driver.

Since there is no buffer on the C module side when using this mode, the driver has to define a strategy to store received bytes that were not handed to the C module yet. This could be a fixed or variable size FIFO, the older received but unread bytes may be dropped, or a more complex priority arbitration could be set up. On the transmit side, if the driver does not do any buffering, the Java thread waiting to send something will be blocked and wait for the UART to send all the data.

In Custom mode flow control (eg. RTS/CTS or XON/XOFF) can be used to notify the device connected to the serial line and so avoid losing characters.

## BSP File

The ECOM Comm C module needs to know, when the MicroEJ Application is built, the name of the implementation. This mapping is defined in a BSP definition file. The name of this file must be `bsp.xml` and must be written in the ECOM comm module configuration folder (near the `ecom-comm.xml` file). In previous example the `bsp.xml` file would contain:

Listing 1: ECOM Comm Driver Declaration (bsp.xml)

```
<bsp>
  <nativeImplementation
    name="MY_LLCOMM"
    nativeName="LLCOMM_BUFFERED_CONNECTION"
  />
</bsp>
```

where `nativeName` is the name of the interface, and `name` is the name of the implementation.

## XML File

The Java platform has to know the maximum number of Comm ports that can be managed by the ECOM Comm stack. It also has to know each Comm port that can be mapped from an application port number. Such Comm port is identified by its platform port number and by an optional nickname (The port and its nickname will be visible in the MicroEJ launcher options, see [Application Options](#) ).

A XML file is so required to configure the Java platform. The name of this file must be `ecom-comm.xml` . It has to be stored in the module configuration folder (see [Installation](#) ).

This file must start with the node `<ecom>` and the sub node `<comms>` . It can contain several time this kind of line: `<comm platformId="A_COMM_PORT_NUMBER" nickname="A_NICKNAME"/>` where:

- `A_COMM_PORT_NUMBER` refers the Comm port the Java platform user will be able to use (see [Application Port Mapping](#) ).
- `A_NICKNAME` is optional. It allows to fix a printable name of the Comm port.

The `maxConnections` attribute indicates the maximum number of connections allowed, including static and dynamic connections. This attribute is optional. By default, it is the number of declared Comm Ports.

Example:

Listing 2: ECOM Comm Module Configuration (ecom-comm.xml)

```
<ecom>
  <comms maxConnections="20">
    <comm platformId="2"/>
    <comm platformId="3" nickname="DB9"/>
    <comm platformId="5"/>
  </comms>
</ecom>
```

First Comm port holds the port 2, second "3" and last "5". Only the second Comm port holds a nickname "DB9".

## ECOM Comm Mock

In the simulation environment, no driver is required. The ECOM Comm mock handles communication for all the serial ports and can redirect each port to one of the following:

- An actual serial port on the host computer: any serial port identified by your operating system can be used. The baudrate and flow control settings are forwarded to the actual port.
- A TCP socket. You can connect to a socket on the local machine and use netcat or telnet to see the output, or you can forward the data to a remote device.
- Files. You can redirect the input and output each to a different file. This is useful for sending precomputed data and looking at the output later on for offline analysis.

When using the socket and file modes, there is no simulation of an UART baudrate or flow control. On a file, data will always be available for reading and will be written without any delay. On a socket, you can reach the maximal speed allowed by the network interface.

## Dependencies

- ECOM (see *Serial Communications*).
- `LLCOMM_impl.h` and `LLCOMM_xxx_CONNECTION_impl.h` implementations (see *LLCOMM: Serial Communications*).

## Installation

ECOM-Comm Java library is an additional library. In the platform configuration file, check `Serial Communication` > `ECOM-COMM` to install it. When checked, the xml file `ecom-comm` > `ecom-comm.xml` is required during platform creation to configure the module (see *XML File*).

## Use

A classpath variable named `ECOM-COMM-1.1` is available. This Foundation Library is always required when developing a MicroEJ Application which communicates with some external devices using the serial communication mode.

This library provides a set of options. Refer to the chapter *Application Options* which lists all available options.

## 4.9 Graphics User Interface

### 4.9.1 Principle

The User Interface Extension features one of the fastest graphical engines, associated with a unique int-based event management system. It provides *[MUI] library* implementation. The following diagram depicts the components involved in its design, along with the provided tools:

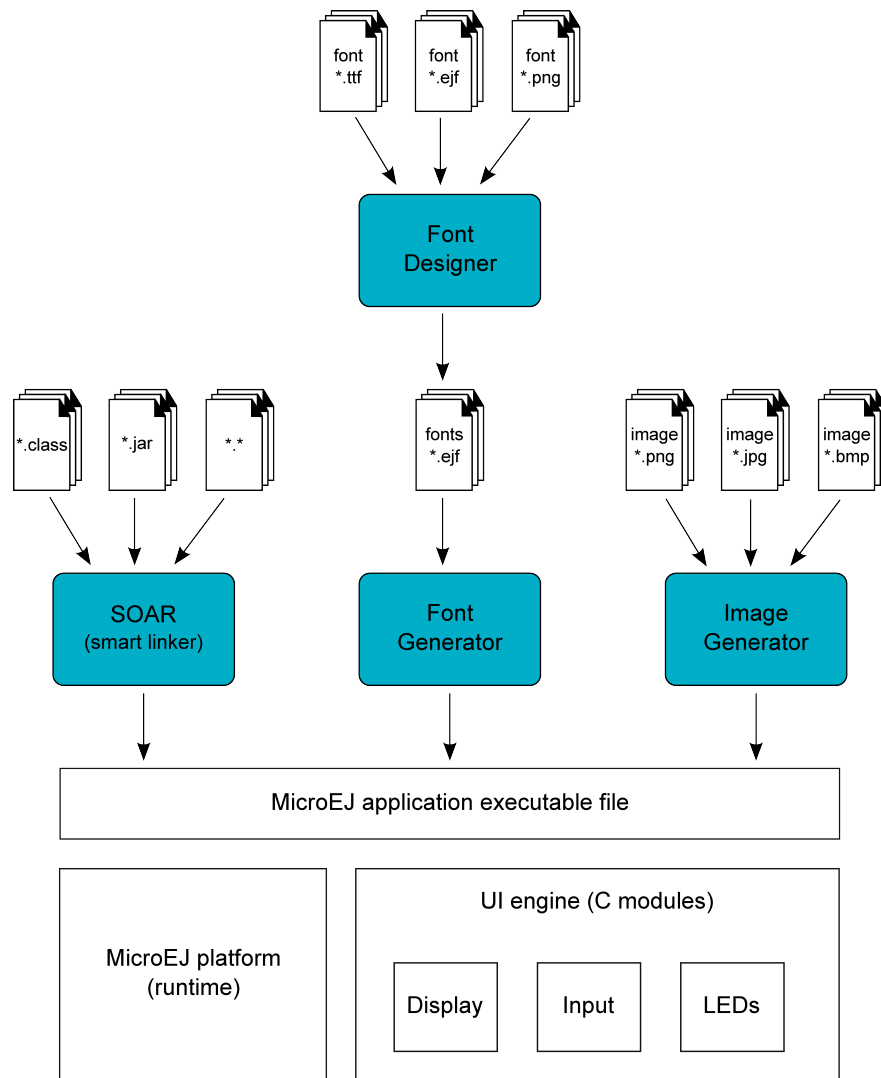


Fig. 25: The User Interface Extension Components along with a Platform

The diagram below shows a simplified view of the components involved in the provisioning of a Java user interface.



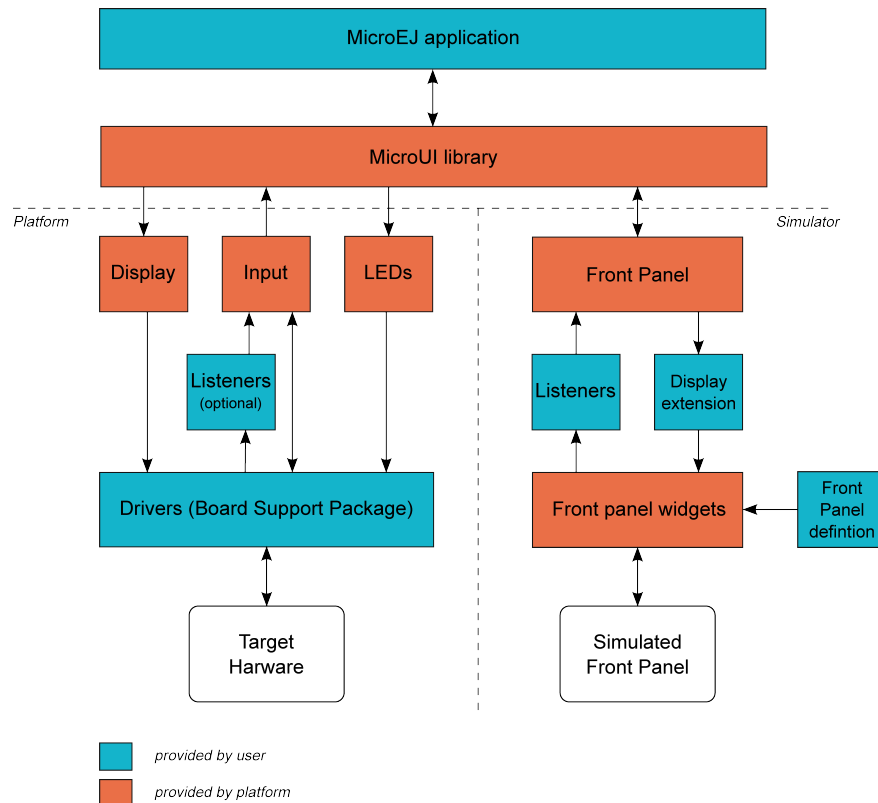


Fig. 26: Overview

Stacks are the native parts of MicroUI. They connect the MicroUI library to the user-supplied drivers code (coded in C).

Drivers for input devices must generate events that are sent, via a *MicroUI Event Generator*, to the MicroEJ Application. An event generator accepts notifications from devices, and generates an event in a standard format that can be handled by the application. Depending on the MicroUI configuration, there can be several different types of event generator in the system, and one or more instances of each type. Each instance has a unique id.

Drivers may either interface directly with event generators, or they can send their notifications to a *Listener*, also written in C, and the listener passes the notifications to the event generator. This decoupling has two major benefits:

- The drivers are isolated from the MicroEJ libraries – they can even be existing code.
- The listener can translate the notification; so, for example, a joystick could generate pointer events.

For the MicroEJ Simulator, the platform is supplied with a set of software widgets that generically support a range of input devices, such as buttons, joysticks and touchscreens, and output devices such as pixelated displays and LEDs. With the help of the Front Panel Designer tool that forms part of the MicroEJ Workbench the user must define a front panel mock-up using these widgets. The user must provide a set of listeners that connects the input widgets to event generators. The user may choose to simulate events that will ultimately come from a special-purpose input device using one of the standard input widgets; the listener will do the necessary translation. The user must also supply, in Java, a display extension that adapts the supplied display widget to the specifics of the hardware being simulated.

#### 4.9.2 MicroUI

## Principle

The MicroUI module defines a low-level UI framework for embedded devices. This module allows the creation of basic Human-Machine-Interfaces (HMI), with output on a pixelated screen. For more information, please consult the [\[MUI\] Specification](#).

## Architecture

MicroUI is not a standalone library. It requires a configuration step and several extensions to drive I/O devices (display, inputs, LEDs, etc.).

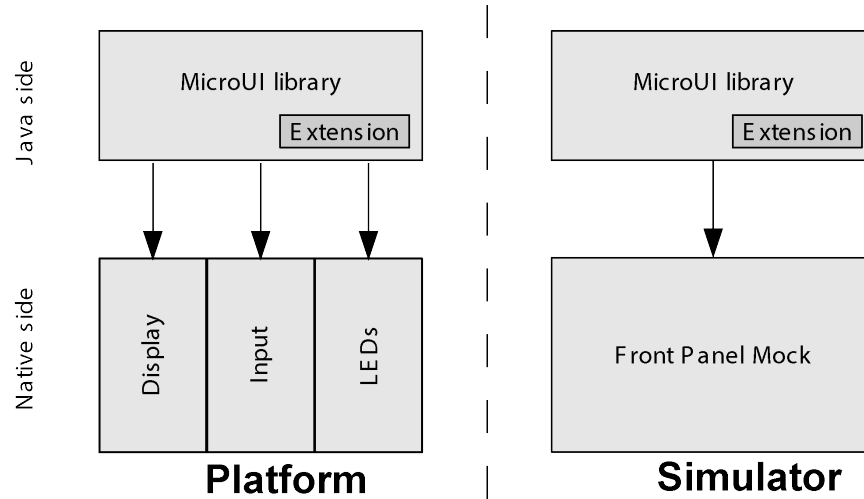


Fig. 27: MicroUI Elements

At MicroEJ Application startup all MicroUI objects relative to the I/O devices are created and accessible. The following MicroUI methods allow you to access these internal objects:

- `Display.getDefaultDisplay()` : returns the instance of the default display which drives the main LCD screen.
- `Leds.getNumberOfLeds()` : returns the numbers of available LEDs.

First, MicroUI requires a configuration step in order to create these internal objects before the call to the `main()` method. The chapter [Static Initialization](#) explains how to perform the configuration step.

---

**Note:** This configuration step is the same for both embedded and simulation platforms.

---

The embedded platform requires some additional C libraries to drive the I/O devices. Each C library is dedicated to a specific kind of I/O device. A specific chapter is available to explain each kind of I/O device.

Table 5: MicroUI C libraries

I/O devices	Extension Name	Chapter
Graphical / pixelated display (LCD screen)	Display	<a href="#">Display</a>
Inputs (buttons, joystick, touch, pointers etc.)	Input	<a href="#">Inputs</a>
LEDs	LEDs	<a href="#">LEDs</a>

The simulation platform uses a mock which simulates all I/O devices. Refer to the chapter [Simulation](#).

## Threads

### Principle

The MicroUI implementation for MicroEJ uses internal threads. These threads are created during the MicroUI initialization step, and are started by a call to `MicroUI.start()`. Refer to the *MicroUI specification* for more information about internal threads.

### List

- DisplayPump: This thread manages all display events (`repaint`, `show()`, etc. There is one thread per display.
- InputPump: This thread reads the I/O devices inputs and dispatches them into the display pump(s).

### Memory

The threads are always running. The user has to count them to determine the number of concurrent threads the MicroEJ Core Engine can run (see Memory options in *Application Options*).

### Exceptions

The threads cannot be stopped with a Java exception: The exceptions are always checked by the framework.

When an exception occurs in a user method called by an internal thread (for instance `paint()`), the current `UncaughtExceptionHandler` receives the exception. The behavior of the default handler is to print the stack trace.

### Transparency

MicroUI provides several policies to use the transparency. These policies depend on several factors, including the kind of drawing and the LCD pixel rendering format. The main concept is that MicroUI does not allow you to draw something with a transparency level different from 255 (fully opaque). There are two exceptions: the images and the fonts.

### Images

Drawing an image (a pre-generated image or an image decoded at runtime) which contains some transparency levels does not depend on the LCD pixel rendering format. During the image drawing, each pixel is converted into 32 bits by pixel format.

This pixel format contains 8 bits to store the transparency level (alpha). This byte is used to merge the foreground pixel (image transparent pixel) with the background pixel (LCD buffer opaque pixel). The formula to obtain the pixel is:

$$\alpha_{Mult} = (\alpha_{FG} * \alpha_{BG}) / 255$$

$$\alpha_{Out} = \alpha_{FG} + \alpha_{BG} - \alpha_{Mult}$$

$$C_{Out} = (C_{FG} * \alpha_{FG} + C_{BG} * \alpha_{BG} - C_{BG} * \alpha_{Mult}) / \alpha_{Out}$$

where:

- $\alpha_{FG}$  is the alpha level of the foreground pixel (layer pixel)

- $\alpha BG$  is the alpha level of the background pixel (working buffer pixel)
- $\alpha xx$  is a color component of a pixel (Red, Green or Blue).
- $\alpha Out$  is the alpha level of the final pixel

## Fonts

A font holds only a transparency level (alpha). This fixed alpha level is defined during the pre-generation of a font (see [Fonts](#)).

- 1 means 2 levels are managed: fully opaque and fully transparent.
- 2 means 4 levels are managed: fully opaque, fully transparent and 2 intermediate levels.
- 4 means 16 levels are managed: fully opaque, fully transparent and 14 intermediate levels.
- 8 means 256 levels are managed: fully opaque, fully transparent and 254 intermediate levels.

## Dependencies

- MicroUI initialization step (see [Static Initialization](#)).
- MicroUI C libraries (see [Architecture](#)).

## Installation

The MicroUI library is an additional module. In the platform configuration file, check `UI > MicroUI` to install the library. When checked, the XML file `microui > microui.xml` is required during platform creation in order to configure the module. This configuration step is used to extend the MicroUI library. Refer to the chapter [Static Initialization](#) for more information about the MicroUI Initialization step.

## Use

The [MicroUI API module](#) must be added to the `module.ivy` of the MicroEJ Application project:

```
<dependency org="ej.api" name="microui" rev="2.4.0"/>
```

This library provides a set of options. Refer to the chapter [Application Options](#) which lists all available options.

### 4.9.3 Static Initialization

#### Principle

MicroUI requires a configuration step (also called extension step) to customize itself before MicroEJ Application startup (see [Architecture](#)). This configuration step uses an XML file. In order to save both runtime execution time and flash memory, the file is processed by the Static MicroUI Initializer tool, avoiding the need to process the XML configuration file at runtime. The tool generates appropriate initialized objects directly within the MicroUI library, as well as Java and C constants files for sharing MicroUI event generator IDs.

This XML file (also called the initialization file) defines:

- The MicroUI event generators that will exist in the application in relation to low level drivers that provide data to these event generators (see [Inputs](#)).

- Whether the application has a display; and if so, it provides its logical name.
- Which fonts will be provided to the application.

### Functional Description

The Static MicroUI Initializer tool takes as entry point the initialization file which describes the MicroUI library extension. This tool is automatically launched during the MicroEJ platform build (see [Installation](#) ).

The Static MicroUI Initializer tool is able to output two files:

- A Java library which extends MicroUI library. This library is automatically added to the MicroEJ Application classpath when MicroUI API library is fetched. This library is used at MicroUI startup to create all instances of I/O devices ([Display](#) , [EventGenerator](#) etc.) and contains the fonts described into the configuration file (these fonts are also called “system fonts”).

**Warning:** This MicroUI extension library is always generated and MicroUI library cannot run without this extension.

- A C header file ( \*.h ) file. This H file contains some IDs which are used to make a link between an input device (buttons, touch) and its MicroUI event generator (see [Inputs](#)).

**Note:** The front panel project does not need a configuration file (like C header file for embedded platform).

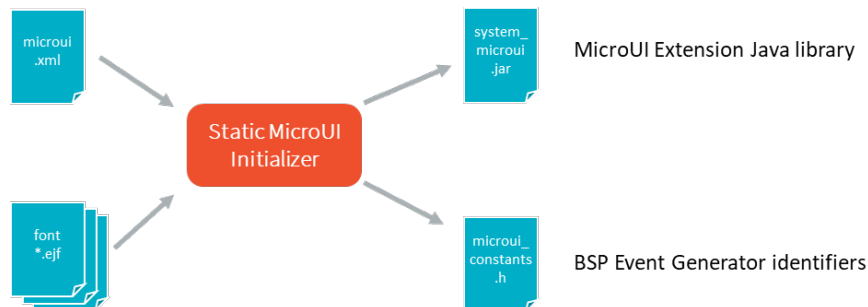


Fig. 28: MicroUI Process

### Root Element

The initialization file root element is `<microui>` and contains component-specific elements.

```
<microui>
  [ component specific elements ]
</microui>
```

### Display Element

The display component augments the initialization file with:

- The configuration of the display.

- Fonts that are implicitly embedded within the application (also called system fonts). Applications can also embed their own fonts.

```
<display name="DISPLAY"/>

<fonts>
  <font file="resources\fonts\myfont.ejf">
    <range name="LATIN" sections="0-2"/>
    <customrange start="0x21" end="0x3f"/>
  </font>
  <font file="C:\data\myfont.ejf"/>
</fonts>
```

## Event Generators Element

The event generators component augments the initialization file with:

- the configuration of the predefined MicroUI **Event Generator** : **Command** , **Buttons** , **States** , **Pointer** , **Touch**
- the configuration of the generic MicroUI **Event Generator**

```
<eventgenerators>
  <!-- Generic Event Generators -->
  <eventgenerator name="GENERIC" class="foo.bar.Zork">
    <property name="PROP1" value="3"/>
    <property name="PROP2" value="aaa"/>
  </eventgenerator>

  <!-- Predefined Event Generators -->
  <command name="COMMANDS"/>
  <buttons name="BUTTONS" extended="3"/>
  <buttons name="JOYSTICK" extended="5"/>
  <pointer name="POINTER" width="1200" height="1200"/>
  <touch name="TOUCH" display="DISPLAY"/>
  <states name="STATES" numbers="NUMBERS" values="VALUES"/>

</eventgenerators>

<array name="NUMBERS">
  <elem value="3"/>
  <elem value="2"/>
  <elem value="5"/>
</array>

<array name="VALUES">
  <elem value="2"/>
  <elem value="0"/>
  <elem value="1"/>
</array>
```

## Example

This common MicroUI initialization file initializes MicroUI with:

- a display

- a **Command** event generator
- a **Buttons** event generator which targets  $n$  buttons (3 first buttons having extended features)
- a **Buttons** event generator which targets the buttons of a joystick
- a **Pointer** event generator which targets a touch panel
- a **DisplayFont** whose path is relative to this file

```
<microui>

  <display name="DISPLAY" />

  <eventgenerators>
    <command name="COMMANDS" />
    <buttons name="BUTTONS" extended="3" />
    <buttons name="JOYSTICK" extended="5" />
    <touch name="TOUCH" display="DISPLAY" />
  </eventgenerators>

  <fonts>
    <font file="resources\fonts\myfont.ejf" />
  </font>

</microui>
```

## Dependencies

No dependency.

## Installation

The Static Initialization tool is part of the MicroUI module (see *MicroUI*). Install the MicroUI module to install the Static Initialization tool and fill all properties in MicroUI module configuration file (which must specify the name of the initialization file).

## Use

The Static MicroUI Initializer tool is automatically launched during the MicroUI module installation.

### 4.9.4 LEDs

#### Principle

The LEDs module contains the C part of the MicroUI implementation which manages LED devices. This module is composed of two elements:

- the C part of the MicroUI LEDs API (a built-in C archive),
- an implementation of a low level API for the LEDs (LLEDS) which must be provided by the BSP (see *LLEDS: LEDs*).

## Implementations

The LEDs module provides only one implementation which exposes some low level API (LLEDS) that allow the BSP to manage the LEDs. This implementation of the MicroUI `Leds` API provides some low level API. The BSP has to implement these LLAPI, making the link between the MicroUI C library `leds` and the BSP LEDs drivers.

The LLAPI to implement are listed in the header file `LLEDS_impl.h`. First, in the initialization function, the BSP must return the available number of LEDs the board provides. The others functions are used to turn the LEDs on and off.

The LLAPI are the same for the LED which is connected to a `GPIO` ( `0` or `1` ) or via a `PWM`. The BSP has the responsibility of interpreting the MicroEJ Application parameter `intensity`.

Typically, when the LED is connected to a `GPIO`, the `intensity` “0” means “OFF,” and all others values “ON.” When the LED is connected via a `PWM`, the `intensity` “0” means “OFF,” and all others values must configure the `PWM` signal.

The BSP should be able to return the state of an LED. If it is not able to do so (for example `GPIO` is not accessible in read mode), the returned value may be wrong. The MicroEJ Application may not be able to know the LEDs states.

When there is no LED on the board, a *stub* implementation of C library is available. This C library must be linked by the third-party C IDE when the MicroUI module is installed in the MicroEJ Platform.

## Dependencies

- MicroUI module (see *MicroUI*)
- `LLEDS_impl.h` implementation if standard implementation is chosen (see *Implementations* and *LLEDS: LEDs*).

## Installation

LEDs is a sub-part of MicroUI library. When the MicroUI module is installed, the LEDs module must be installed in order to be able to connect physical LEDs with MicroEJ Platform. If not installed, the *stub* module will be used.

In the platform configuration file, check `UI > LEDs` to install LEDs.

## Use

The MicroUI LEDs APIs are available in the class `ej.microui.led.Leds`.

## 4.9.5 Inputs

### Principle

The Inputs module contains the C part of the MicroUI implementation which manages input devices. This module is composed of two elements:

- the C part of MicroUI input API (a built-in C archive)
- an implementation of a low level API for the input devices (LLINPUT) that must be provided by the BSP (see *LLINPUT: Inputs*)



## Functional Description

The Inputs module implements the MicroUI **int** -based event generators' framework. **LLINPUT** specifies the low level API that send events to the Java world.

Each MicroUI **Event Generator** represents one side of a pair of collaborative components that communicate using a shared buffer:

- The producer: the C driver connected to the hardware. As a producer, it sends its data into the communication buffer.
- The consumer: the MicroUI **Event Generator** . As a consumer, it reads (and removes) the data from the communication buffer.

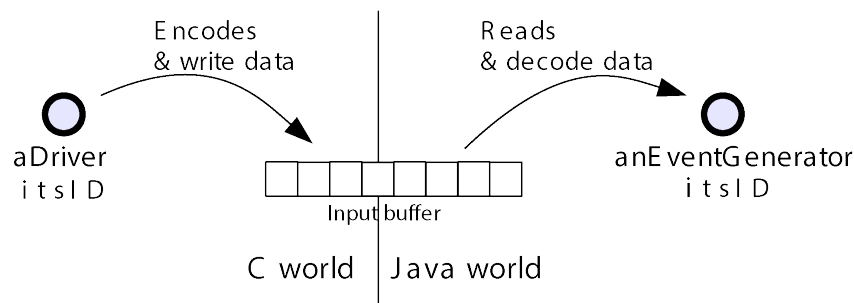


Fig. 29: Drivers and MicroUI Event Generators Communication

The **LLINPUT** API allows multiple pairs of **<driver - event generator>** to use the same buffer, and associates drivers and event generators using an **int** ID. The ID used is the event generator ID held within the MicroUI global registry **[MUI]**. Apart from sharing the ID used to “connect” one driver’s data to its respective event generator, both entities are completely decoupled.

A Java green thread, called the **InputPump** thread, waits for data to be published by drivers into the “input buffer,” and dispatches to the correct (according to the ID) event generator to read the received data. This “driver-specific-data” is then transformed into MicroUI events by event generators and sent to objects that listen for input activity.

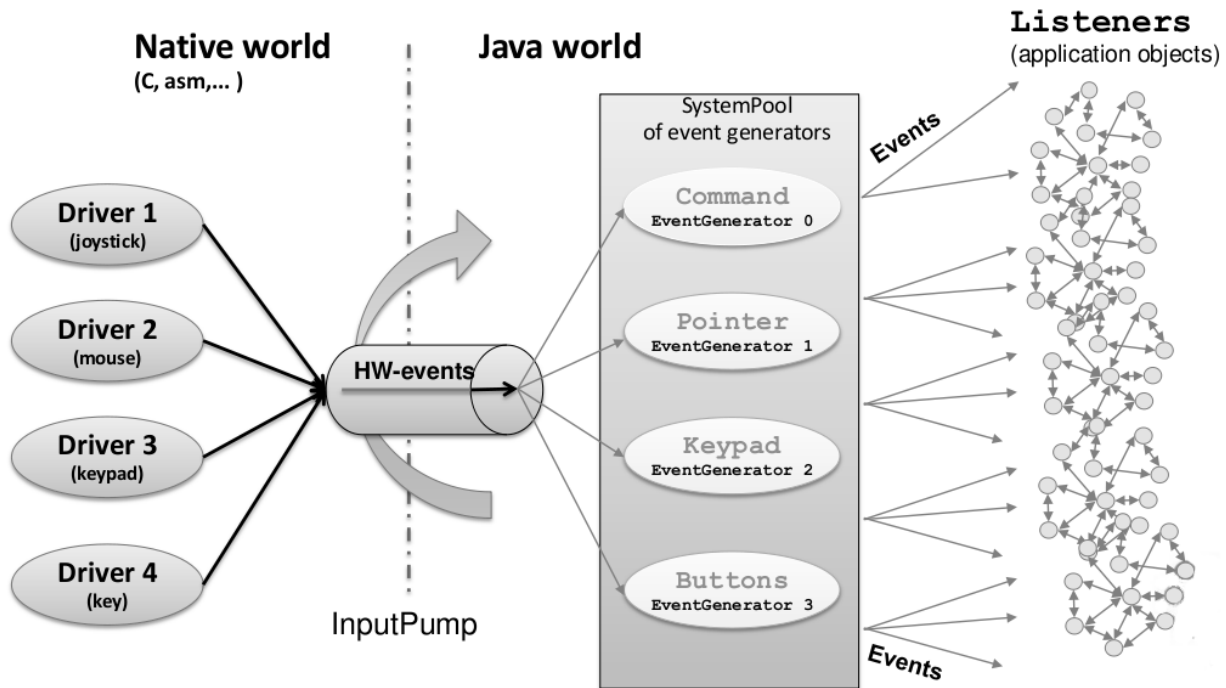


Fig. 30: MicroUI Events Framework

## Implementation

The implementation of the MicroUI **Event Generator** APIs provides some low level APIs. The BSP has to implement these LLAPI, making the link between the MicroUI C library **inputs** and the BSP input devices drivers.

The LLAPI to implement are listed in the header file **LLINPUT\_impl.h**. It allows events to be sent to the MicroUI implementation. The input drivers are allowed to add events directly using the event generator's unique ID (see **Static Initialization**). The drivers are fully dependent on the MicroEJ framework (a driver cannot be developed without MicroEJ because it uses the header file generated during the MicroUI initialization step).

When there is no input device on the board, a *stub* implementation of C library is available. This C library must be linked by the third-party C IDE when the MicroUI module is installed in the MicroEJ Platform.

## Generic Event Generators

On the application side, the UI extension provides an abstract class **GenericEventGenerator** (package **ej.microui.event**) that must be implemented by clients who want to define their own event generators. Two abstract methods must be implemented by subclasses:

- **eventReceived**: The event generator received an event from a C driver through the low level API **sendEvent** function.
- **eventsReceived**: The event generator received an event made of several **int** s.
- **setProperty**: Handle a generic property (key/value pair) set from the static initialization file (see **MicroUI Static Initializer**)

The event generator is responsible for converting incoming data into a MicroUI event and sending the event to its listener.

## Dependencies

- MicroUI module (see *MicroUI*)
- Static MicroUI initialization step (see *section\_static\_init*). This step generates a header file which contains some unique event generator IDs. These IDs must be used in the BSP to make the link between the input devices drivers and the MicroUI *Event Generator* s.
- *LLINPUT\_impl.h* implementation (see *LLINPUT: Inputs*).

## Installation

Inputs is a sub-part of the MicroUI library. When the MicroUI module is installed, the Inputs module must be installed in order to be able to connect physical input devices with MicroEJ Platform. If not installed, the *stub* module will be used. In the platform configuration file, check `UI > Inputs` to install Inputs.

## Use

The MicroUI Input APIs are available in the class `ej.microui.EventGenerator`.

## 4.9.6 Display

### Principle

The Display module contains the C part of the MicroUI implementation which manages graphical displays. This module is composed of two elements:

- the C part of MicroUI Display API (a built-in C archive)
- an implementation of a low level API for the displays (LLDISPLAY) that the BSP must provide (see *LLDISPLAY: Display*)

### Display Configurations

The Display modules provides a number of different configurations. The appropriate configuration should be selected depending on the capabilities of the screen and other related hardware, such as LCD controllers.

The modes can vary in three ways:

- the buffer mode: double-buffer, simple buffer (also known as “direct”)
- the memory layout of the pixels
- pixel format or depth

The supplied configurations offer a limited range of combinations of the options.

### Buffer Modes

#### Overview

When using the double buffering technique, the memory into which the application draws (called graphics buffer or back buffer) is not the memory used by the screen to refresh it (called frame buffer or display buffer). When

everything has been drawn consistently from the application point of view, the back buffer contents are synchronized with the display buffer. Double buffering avoids flickering and inconsistent rendering: it is well suited to high quality animations.

For more static display-based applications, and/or to save memory, an alternative configuration is to use only one buffer, shared by both the application and the screen.

Displays addressed by one of the standard configurations are called *generic displays*. For these generic displays, there are three buffer modes: switch, copy and direct. The following flow chart provides a handy guide to selecting the appropriate buffer mode according to the hardware configuration.

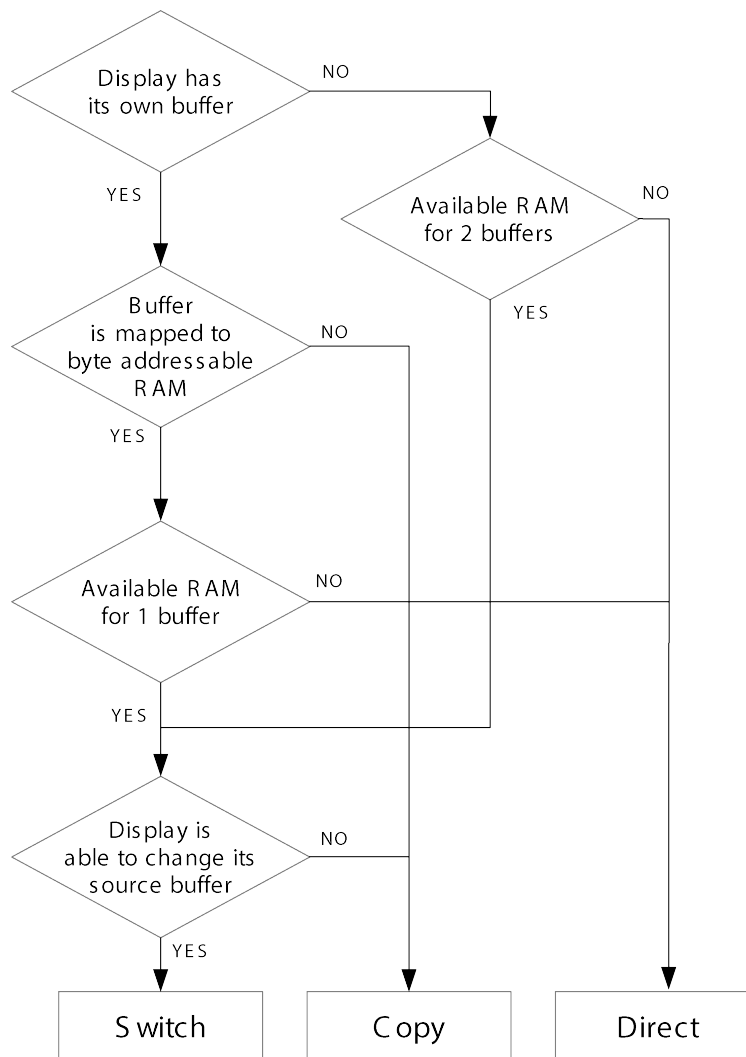


Fig. 31: Buffer Modes

## Implementation

The display module (or stack) does not depend on type of buffer mode. At the end of a drawing, the display stack calls the LLAPI `LLDISPLAY_IMPL_flush` to let the implementation to update the LCD data. This function should be atomic and the implementation has to return the new graphics buffer address (back buffer address). In **direct** and **copy** modes, this address never changes and the implementation has always to return the back buffer address. In **switch** mode, the implementation has to return the old LCD frame buffer address.

The next sections describe the work to do for each mode.

## Switch

The switch mode is a double-buffered mode where two buffers in RAM alternately play the role of the back buffer and the display buffer. The display source is alternatively changed from one buffer to the other.

Switching the source address may be done asynchronously. The synchronize function is called before starting the next set of draw operations, and must wait until the driver has switched to the new buffer.

Synchronization steps are described *below*.

### Switch Mode Synchronization Steps

- *Step 1: Drawing*

MicroUI is drawing in buffer 0 (back buffer) and the display is reading its contents from buffer 1 (display buffer).

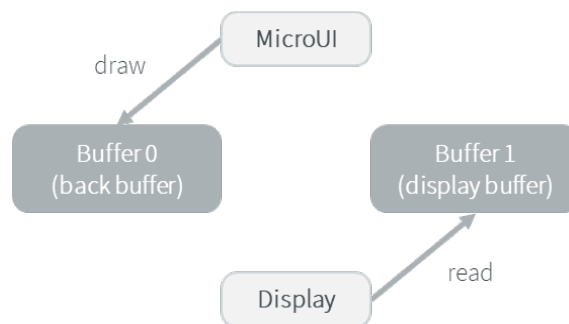


Fig. 32: Step 1 : Drawing

- *Step 2: Switch*

The drawing is done. Set that the next read will be done from buffer 0.

Note that the display “hardware component” asynchronously continues to read data from buffer 1.

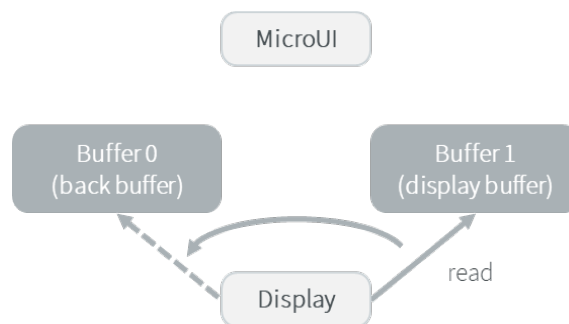


Fig. 33: Step 2 : Switch

- *Step 3: Copy*

A copy from the buffer 0 (new display buffer) to the buffer 1 (new back buffer) must be done to keep the contents of the current drawing. The copy routine must wait until the display has finished the switch, and start asynchronously by comparison with the MicroUI drawing routine (see next step).

This copy routine can be done in a dedicated RTOS task or in an interrupt routine. The copy should start after the display “hardware component” has finished a full buffer read to avoid flickering.

Usually a tearing signal from the LCD at the end of the read of the previous buffer (buffer 1) or at the beginning of the read of the new buffer (buffer 0) throws an interrupt. The interrupt routine starts the copy using a DMA.

If it is not possible to start an asynchronous copy, the copy must be performed in the MicroUI drawing routine, at the beginning of the next step.

Note that the copy is partial: only the parts that have changed need to be copied, lowering the CPU load.

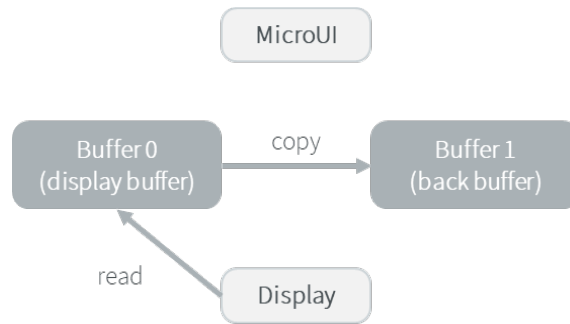


Fig. 34: Step 3 : Copy

- **Step 4: Synchronisation**

Waits until the copy routine has finished the full copy.

If the copy has not been done asynchronously, the copy must start after the display has finished the switch. It is a blocking copy because the next drawing operation has to wait until this copy is done.

- **Step 5: Next draw operation**

Same behavior as step 1 with buffers reversed.

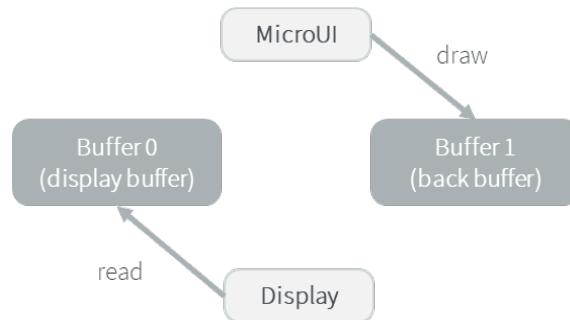


Fig. 35: Step 5 : Next draw operation

## Copy

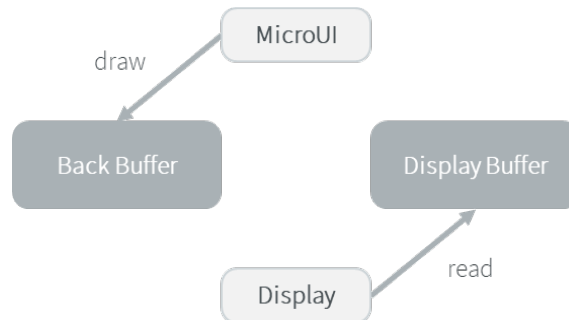
The copy mode is a double-buffered mode where the back buffer is in RAM and has a fixed address. To update the display, data is sent to the display buffer. This can be done either by a memory copy or by sending bytes using a bus, such as SPI or I2C.

Synchronization steps are described *below*.

## Display Copy Mode

- *Step 1: Drawing*

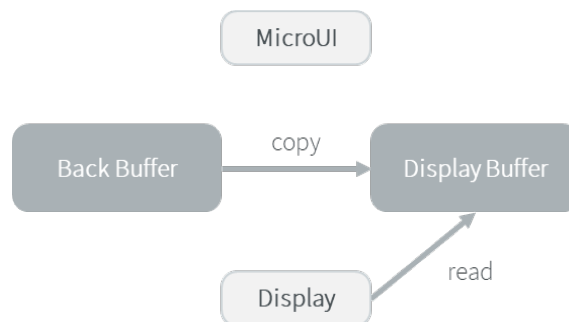
MicroUI is drawing in the back buffer and the display is reading its content from the display buffer.



- *Step 2: Copy*

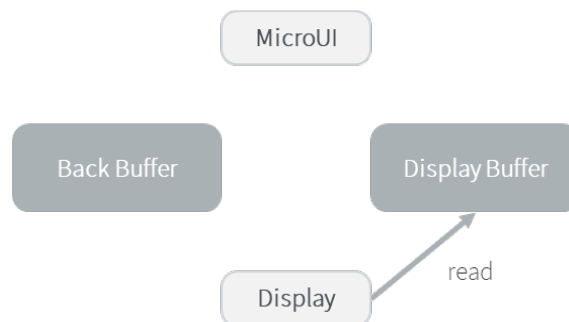
The drawing is done. A copy from the back buffer to the display buffer is triggered.

Note that the implementation of the copy operation may be done asynchronously – it is recommended to wait until the display “hardware component” has finished a full buffer read to avoid flickering. At the implementation level, the copy may be done by a DMA, a dedicated RTOS task, interrupt, etc.



- *Step 3: Synchronization*

The next drawing operation waits until the copy is complete.



## Direct

The direct mode is a single-buffered mode where the same memory area is used for the back buffer and the display buffer (*See illustration below*). Use of the direct mode is likely to result in “noisy” rendering and flickering, but saves one buffer in runtime memory.

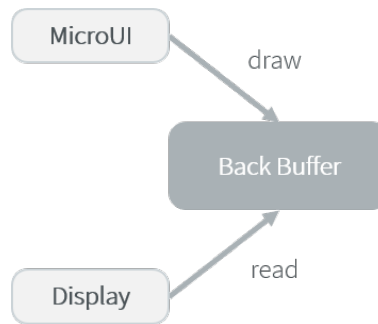


Fig. 36: Display Direct Mode

## Byte Layout

This chapter concerns only LCD with a number of bits-per-pixel (BPP) smaller than 8. For this kind of LCD, a byte contains several pixels and the display module allows to customize how to organize the pixels in a byte.

Two layouts are available:

- **line**: The byte contains several consecutive pixels on same line. When the end of line is reached, a padding is added in order to start a new line with a new byte.
- **column**: The byte contains several consecutive pixels on same column. When the end of column is reached, a padding is added in order to start a new column with a new byte.

When installing the display module, a property `byteLayout` is required to specify the kind of pixels representation (see [Installation](#)).

Table 6: Byte Layout: line

BPP	MSB							LSB
4	pixel 1				pixel 0			
2	pixel 3		pixel 2		pixel 1		pixel 0	
1	pixel 7	pixel 6	pixel 5	pixel 4	pixel 3	pixel 2	pixel 1	pixel 0

Table 7: Byte Layout: column

BPP	4	2	1
MSB	pixel 1	pixel 3	pixel 7
			pixel 6
			pixel 5
			pixel 4
	pixel 0	pixel 1	pixel 3
			pixel 2
			pixel 1
LSB			pixel 0

## Memory Layout

For the LCD with a number of bits-per-pixel (BPP) higher or equal to 8, the display module supports the line-by-line memory organization: pixels are laid out from left to right within a line, starting with the top line. For a display with 16 bits-per-pixel, the pixel at (0,0) is stored at memory address 0, the pixel at (1,0) is stored at address 2, the pixel at (2,0) is stored at address 4, and so on.



Table 8: Memory Layout for BPP &gt;= 8

BPP	@ + 0	@ + 1	@ + 2	@ + 3	@ + 4
32	pixel 0 [7:0]	pixel 0 [15:8]	pixel 0 [23:16]	pixel 0 [31:24]	pixel 1 [7:0]
24	pixel 0 [7:0]	pixel 0 [15:8]	pixel 0 [23:16]	pixel 1 [7:0]	pixel 1 [15:8]
16	pixel 0 [7:0]	pixel 0 [15:8]	pixel 1 [7:0]	pixel 1 [15:8]	pixel 2 [7:0]
8	pixel 0 [7:0]	pixel 1 [7:0]	pixel 2 [7:0]	pixel 3 [7:0]	pixel 4 [7:0]

For the LCD with a number of bits-per-pixel (BPP) lower than 8, the display module supports the both memory organizations: line by line (pixels are laid out from left to right within a line, starting with the top line) and column by column (pixels are laid out from top to bottom within a line, starting with the left line). These byte organizations concern until 8 consecutive pixels (see [Byte Layout](#)). When installing the display module, a property `memoryLayout` is required to specify the kind of pixels representation (see [Installation](#)).

Table 9: Memory Layout 'line' for BPP &lt; 8 and byte layout 'line'

BPP	@ + 0	@ + 1	@ + 2	@ + 3	@ + 4
4	(0,0) to (1,0)	(2,0) to (3,0)	(4,0) to (5,0)	(6,0) to (7,0)	(8,0) to (9,0)
2	(0,0) to (3,0)	(4,0) to (7,0)	(8,0) to (11,0)	(12,0) to (15,0)	(16,0) to (19,0)
1	(0,0) to (7,0)	(8,0) to (15,0)	(16,0) to (23,0)	(24,0) to (31,0)	(32,0) to (39,0)

Table 10: Memory Layout 'line' for BPP &lt; 8 and byte layout 'column'

BPP	@ + 0	@ + 1	@ + 2	@ + 3	@ + 4
4	(0,0) to (0,1)	(1,0) to (1,1)	(2,0) to (2,1)	(3,0) to (3,1)	(4,0) to (4,1)
2	(0,0) to (0,3)	(1,0) to (1,3)	(2,0) to (2,3)	(3,0) to (3,3)	(4,0) to (4,3)
1	(0,0) to (0,7)	(1,0) to (1,7)	(2,0) to (2,7)	(3,0) to (3,7)	(4,0) to (4,7)

Table 11: Memory Layout 'column' for BPP &lt; 8 and byte layout 'line'

BPP	@ + 0	@ + 1	@ + 2	@ + 3	@ + 4
4	(0,0) to (1,0)	(0,1) to (1,1)	(0,2) to (1,2)	(0,3) to (1,3)	(0,4) to (1,4)
2	(0,0) to (3,0)	(0,1) to (3,1)	(0,2) to (3,2)	(0,3) to (3,3)	(0,4) to (3,4)
1	(0,0) to (7,0)	(0,1) to (7,1)	(0,2) to (7,2)	(0,3) to (7,3)	(0,4) to (7,4)

Table 12: Memory Layout 'column' for BPP &lt; 8 and byte layout 'column'

BPP	@ + 0	@ + 1	@ + 2	@ + 3	@ + 4
4	(0,0) to (0,1)	(0,2) to (0,3)	(0,4) to (0,5)	(0,6) to (0,7)	(0,8) to (0,9)
2	(0,0) to (0,3)	(0,4) to (0,7)	(0,8) to (0,11)	(0,12) to (0,15)	(0,16) to (0,19)
1	(0,0) to (0,7)	(0,8) to (0,15)	(0,16) to (0,23)	(0,24) to (0,31)	(0,32) to (0,39)

## Pixel Structure

The Display module provides pre-built display configurations with standard pixel memory layout. The layout of the bits within the pixel may be standard (see MicroUI GraphicsContext pixel formats) or driver-specific. When installing the display module, a property `bpp` is required to specify the kind of pixel representation (see [Installation](#)).

When the value is one among this list: `ARGB8888` | `RGB888` | `RGB565` | `ARGB1555` | `ARGB4444` | `C4` | `C2` | `C1`, the display module considers the LCD pixels representation as standard. According to the chosen format, some color data can be lost or cropped.

- `ARGB8888`: the pixel uses 32 bits-per-pixel (alpha[8], red[8], green[8] and blue[8]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return c;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return c;
}

```

- RGB888: the pixel uses 24 bits-per-pixel (alpha[0], red[8], green[8] and blue[8]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return c & 0xffffff;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return 0
        | 0xff000000
        | c
        ;
}

```

- RGB565: the pixel uses 16 bits-per-pixel (alpha[0], red[5], green[6] and blue[5]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return 0
        | ((c & 0xf80000) >> 8)
        | ((c & 0x00fc00) >> 5)
        | ((c & 0x0000f8) >> 3)
        ;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return 0
        | 0xff000000
        | ((c & 0xf800) << 8)
        | ((c & 0x07e0) << 5)
        | ((c & 0x001f) << 3)
        ;
}

```

- ARGB1555: the pixel uses 16 bits-per-pixel (alpha[1], red[5], green[5] and blue[5]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return 0
        | (((c & 0xff000000) == 0xff000000) ? 0x8000 : 0)
        | ((c & 0xf80000) >> 9)
        | ((c & 0x00f800) >> 6)
        | ((c & 0x0000f8) >> 3)
        ;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return 0
        | ((c & 0x8000) == 0x8000 ? 0xff000000 : 0x00000000)
        | ((c & 0x7c00) << 9)
        | ((c & 0x03e0) << 6)
        | ((c & 0x001f) << 3)
}

```

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```

        ;
    }

```

- ARGB4444: the pixel uses 16 bits-per-pixel (alpha[4], red[4], green[4] and blue[4]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return 0
        | ((c & 0xf0000000) >> 16)
        | ((c & 0x0f000000) >> 12)
        | ((c & 0x0000f000) >> 8)
        | ((c & 0x00000f00) >> 4)
        ;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return 0
        | ((c & 0xf000) << 16)
        | ((c & 0xf000) << 12)
        | ((c & 0x0f00) << 12)
        | ((c & 0x0f00) << 8)
        | ((c & 0x00f0) << 8)
        | ((c & 0x00f0) << 4)
        | ((c & 0x000f) << 4)
        | ((c & 0x000f) << 0)
        ;
}

```

- C4: the pixel uses 4 bits-per-pixel (grayscale[4]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return (toGrayscale(c) & 0xff) / 0x11;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return 0xff000000 | (c * 0x111111);
}

```

- C2: the pixel uses 2 bits-per-pixel (grayscale[2]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return (toGrayscale(c) & 0xff) / 0x55;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return 0xff000000 | (c * 0x555555);
}

```

- C1: the pixel uses 1 bit-per-pixel (grayscale[1]).

```

u32 convertARGB8888toLCDPixel(u32 c){
    return (toGrayscale(c) & 0xff) / 0xff;
}

u32 convertLCDPixeltoARGB8888(u32 c){
    return 0xff000000 | (c * 0xffffffff);
}

```

When the value is one among this list: `1 | 2 | 4 | 8 | 16 | 24 | 32`, the display module considers the LCD pixel representation as generic but not standard. In this case, the driver must implement functions that convert MicroUI's standard 32 bits ARGB colors to LCD color representation (see [LLDISPLAY: Display](#)). This mode is often used when the pixel representation is not `ARGB` or `RGB` but `BGRA` or `BGR` instead. This mode can also be used when the number of bits for a color component (alpha, red, green or blue) is not standard or when the value does not represent a color but an index in an LUT.

## Antialiasing

### Fonts

The antialiasing mode for the fonts concerns only the fonts with more than 1 bit per pixel (see [Font Generator](#)).

### Background Color

For each pixel to draw, the antialiasing process blends the foreground color with a background color. This background color is static or dynamic:

- static: The background color is fixed by the MicroEJ Application (`GraphicsContext.setBackgroundColor()`).
- dynamic: The background color is the original color of the destination pixel (a “read pixel” operation is performed for each pixel).

Note that the dynamic mode is slower than the static mode.

### LUT

The display module allows to target LCD which uses a pixel indirection table (LUT). This kind of LCD are considered as generic but not standard (see [Pixel Structure](#)). By consequence, the driver must implement functions that convert MicroUI's standard 32 bits ARGB colors (see [LLDISPLAY: Display](#)) to LCD color representation. For each application ARGB8888 color, the display driver has to find the corresponding color in the table. The display module will store the index of the color in the table instead of using the color itself.

When an application color is not available in the display driver table (LUT), the display driver can try to find the nearest color or return a default color. First solution is often quite difficult to write and can cost a lot of time at runtime. That's why the second solution is preferred. However, a consequence is that the application has only to use a range of colors provided by the display driver.

MicroUI and the display module uses blending when drawing some texts or anti-aliased shapes. For each pixel to draw, the display stack blends the current application foreground color with the targeted pixel current color or with the current application background color (when enabled). This blending *creates* some intermediate colors which are managed by the display driver. Most of time the default color will be returned and so the rendering will be wrong. To prevent this use case, the display module offers a specific LLAPI `LLDISPLAY_EXTRA_IMPL_prepareBlendingOfIndexedColors(void* foreground, void* background)`. This API is only used when a blending is required and when the background color is enabled. Display module calls the API just before the blending and gives as parameter the pointers on the both ARGB colors. The display driver should replace the ARGB colors by the LUT indexes. Then the display module will only use the indexes between the both indexes. For instance, when the returned indexes are `20` and `27`, the display stack will use the indexes `20` to `27`, where all indexes between `20` and `27` target some intermediate colors between the both original ARGB colors.

This solution requires several conditions:

- Background color is enabled and it is an available color in the LUT.

- Application can only use foreground colors provided by the LUT. The platform designer should give to the application developer the available list of colors the LUT manages.
- The LUT must provide a set blending ranges the application can use. Each range can have its own size (different number of colors between two colors). Each range is independent. For instance if the foreground color **RED** ( `0xFFFF0000` ) can be blended with two background colors **WHITE** ( `0xFFFFFFFF` ) and **BLACK** ( `0xFF000000` ), two ranges must be provided. The both ranges have to contain the same index for the color **RED** .
- Application can only use blending ranges provided by the LUT. Otherwise the display driver is not able to find the range and the default color will be used to perform the blending.
- Rendering of dynamic images (images decoded at runtime) may be wrong because the ARGB colors may be out of LUT range.

## Hardware Accelerator

### Overview

The display module allows to use an hardware accelerator to perform some drawings: fill a rectangle, draw an image, rotate an image etc. Some optional functions are available in `LLDISPLAY_EXTRA.h` file (see *LLDISPLAY\_EXTRA: Display Extra Features*). These functions are not automatically call by the display module. The display module must be configured during the MicroEJ Platform construction specifying which hardware accelerator to use. It uses the property `hardwareAccelerator` in `display/display.properties` file to select a hardware accelerator (see *Installation*).

The following table lists the available hardware accelerators supported by MicroEJ, their full names, short names (used in the next tables) and the `hardwareAccelerator` property value (see *Installation*).

Table 13: Hardware Accelerators

	Short name	Property
Renesas Graphics Library RGA <sup>1</sup>	RGA	rga
Renesas TES Dave/2d	Dave2D	dave2d
STMicroelectronics Chrom-ART Graphics Accelerator	DMA2D	dma2d
Custom Hardware Accelerator	Custom	custom <sup>2</sup>

**Note:** It is possible to target an hardware accelerator which is not supported by MicroEJ yet. Set the property `hardwareAccelerator` to `custom` to force display module to call all drawing functions which can be accelerated. The LLDISPLAY implementation is able or not to implement a function. If not, the software algorithm will be used.

The available list of supported hardware accelerators is MicroEJ Architecture dependent. For instance, the STMicroelectronics Chrom-ART Graphics Accelerator is only available for the MicroEJ Architecture for Cortex-M4 and Cortex-M7. The Renesas Graphics Library RGA is only available for the MicroEJ Architecture for Cortex-A9. The following table shows in which MicroEJ Architecture an hardware accelerator is available.

<sup>1</sup> hardware or software implementation

<sup>2</sup> see next note

Table 14: Hardware Accelerators according MicroEJ Architectures

	RGA	Dave2D	DMA2D	Custom
ARM Cortex-M0+ IAR				•
ARM Cortex-M4 ARMCC			•	•
ARM Cortex-M4 GCC		•	•	•
ARM Cortex-M4 IAR			•	•
ARM Cortex-M7 ARMCC			•	•

**Note:** Some hardware accelerators may not be available in off-the-self architectures . However they are available on some specific architectures. Please consult the engineering services page on MicroEJ website.

All hardware accelerators are not available for each number of bits-per-pixel configuration. The following table illustrates in which display stack according **bpp** , an hardware accelerator can be used.

Table 15: Hardware Accelerators according BPP

	RGA	Dave2D	DMA2D	Custom
1 BPP				
C1				
2 BPP				
C2				
4 BPP				
C4				
8 BPP				
16 BPP				•
RGB565	•	•	•	•
ARGB1555	•	•	•	•
ARGB4444	•	•	•	•
24 BPP				•
RGB888			•	•
32 BPP				•
ARGB8888	•	•	•	•

## Features and Limits

Each hardware accelerator has a list of features (list of drawings the hardware accelerator can perform) and some constraints. When the display module is configured to use an hardware accelerator, it takes in consideration these features and limits. If a drawing is detected by the display module as a drawing to be hardware accelerated, the LLDISPLAY implementation *must* configure and use the hardware accelerator to perform the full drawing (not just a part of drawing).

---

**Note:** The *custom* hardware generator does not have any limit by default. This is the LLDISPLAY implementation which fixes the limits.

---

The following table lists the algorithms accelerated by each hardware accelerator.

Table 16: Hardware Accelerators Algorithms

	RGA	Dave2D	DMA2D
Fill a rectangle	.	.	.
Draw an image	.	.	.
Scale an image	.		
Rotate an image	.		

## Images

The available list of supported image formats is not the same for all hardware accelerators. Furthermore some hardware accelerators require a custom header before the RAW pixel data, require a padding between each line etc.. MicroEJ manages these constraints for supported hardware accelerators. For *custom* hardware accelerator, no image header can be added and no padding can be set.

The following table illustrates the RAW image formats supported by each hardware accelerator.

Table 17: Hardware Accelerators RAW Image Formats

	RGA	Dave2D	DMA2D
A1	• <sup>3</sup>		
A2			
A4	• <sup>4</sup>		•
A8	• <sup>5</sup>		•
C1			
C2			
C4			
AC11			
AC22			
AC44			
RGB565	•	•	•
ARGB1555	•	•	•
ARGB4444	•	•	•
RGB888			•
ARGB8888	•	•	•

The RAW image given as parameter (in input and/or in output) respects the hardware accelerator specification. For instance a RAW image with 4BPP must be often aligned on 8 bits, even if its size is odd. The RAW image size given as parameter is the *software* size. That means it is the size of the original image.

Example for a A4 image with required alignment on 8 bits:

- Original image width in pixels (== width in MicroEJ Application): 47
- Hardware image width in pixels (== line width in pixels in RAW image data): 48
- Width in pixels available in `LLDISPLAY ( ((LLDISPLAY_SImage*)src)->width )`: 48
- Hardware width in bytes (== line width in bytes in RAW image data):  $48 / 2 = 24$

The hardware size may be higher than the software size (like in the example). However the number of pixels to draw ( `((LLDISPLAY_SDrawImage*)drawing)->src_width` ) is *always* smaller or equal to the software area size. That means the display module never asks to draw the pixels which are outside the software area. The hardware size is only useful to be compatible with the hardware accelerator restrictions about memory alignment.

<sup>3</sup> maximum size <= display width

<sup>4</sup> maximum size <= display width

<sup>5</sup> maximum size <= display width



## Implementations

The implementation of the MicroUI `Display` API targets a generic display (see [Display Configurations](#)): Switch, Copy and Direct. It provides some low level API. The BSP has to implement these LLAPI, making the link between the MicroUI C library `display` and the BSP display driver. The LLAPI to implement are listed in the header file `LLDISPLAY_impl.h`.

When there is no display on the board, a *stub* implementation of C library is available. This C library must be linked by the third-party C IDE when MicroUI module is installed in the MicroEJ Platform.

## Dependencies

- MicroUI module (see [MicroUI](#))
- `LLDISPLAY_impl.h` implementation if standard or custom implementation is chosen (see [Implementations](#) and [LLDISPLAY: Display](#)).

## Installation

Display is a sub-part of the MicroUI library. When the MicroUI module is installed, the Display module must be installed in order to be able to connect the physical display with the MicroEJ Platform. If not installed, the *stub* module will be used.

In the platform configuration file, check `UI > Display` to install the Display module. When checked, the properties file `display > display.properties` is required during platform creation to configure the module. This configuration step is used to choose the kind of implementation (see [Implementations](#)).

The properties file must / can contain the following properties:

- `bpp` [mandatory]: Defines the number of bits per pixels the display device is using to render a pixel. Expected value is one among these both list:

Standard formats:

- `ARGB8888` : Alpha 8 bits; Red 8 bits; Green 8 bits; Blue 8 bits
- `RGB888` : Alpha 0 bit; Red 8 bits; Green 8 bits; Blue 8 bits (fully opaque)
- `RGB565` : Alpha 0 bit; Red 5 bits; Green 6 bits; Blue 5 bits (fully opaque)
- `ARGB1555` : Alpha 1 bit; Red 5 bits; Green 5 bits; Blue 5 bits (fully opaque or fully transparent)
- `ARGB4444` : Alpha 4 bits; Red 4 bits; Green 4 bits; Blue 4 bits
- `C4` : 4 bits to encode linear grayscale colors between 0xff000000 and 0xffffffff (fully opaque)
- `C2` : 2 bits to encode linear grayscale colors between 0xff000000 and 0xffffffff (fully opaque)
- `C1` : 1 bit to encode grayscale colors 0xff000000 and 0xffffffff (fully opaque)

Custom formats:

- `32` : until 32 bits to encode Alpha, Red, Green and/or Blue
- `24` : until 24 bits to encode Alpha, Red, Green and/or Blue
- `16` : until 16 bits to encode Alpha, Red, Green and/or Blue
- `8` : until 8 bits to encode Alpha, Red, Green and/or Blue
- `4` : until 4 bits to encode Alpha, Red, Green and/or Blue

- **2** : until 2 bits to encode Alpha, Red, Green and/or Blue
- **1** : 1 bit to encode Alpha, Red, Green or Blue

All others values are forbidden (throw a generation error).

- **byteLayout** [optional, default value is “line”]: Defines the pixels data order in a byte the display device is using. A byte can contain several pixels when the number of bits-per-pixels (see ‘bpp’ property) is lower than 8. Otherwise this property is useless. Two modes are available: the next bit(s) on same byte can target the next pixel on same line or on same column. In first case, when the end of line is reached, the next byte contains the first pixels of next line. In second case, when the end of column is reached, the next byte contains the first pixels of next column. In both cases, a new line or a new column restarts with a new byte, even if it remains some free bits in previous byte.

- **line** : the next bit(s) on current byte contains the next pixel on same line (x increment)
- **column** : the next bit(s) on current byte contains the next pixel on same column (y increment)

---

**Note:**

- Default value is ‘line’.
  - All others modes are forbidden (throw a generation error).
  - When the number of bits-per-pixels (see ‘bpp’ property) is higher or equal than 8, this property is useless and ignored.
- 

- **memoryLayout** [optional, default value is “line”]: Defines the pixels data order in memory the display device is using. This option concerns only the LCD with a bpp lower than 8 (see ‘bpp’ property). Two modes are available: when the byte memory address is incremented, the next targeted group of pixels is the next group on the same line or the next group on same column. In first case, when the end of line is reached, the next group of pixels is the first group of next line. In second case, when the end of column is reached, the next group of pixels is the first group of next column.

- **line** : the next memory address targets the next group of pixels on same line (x increment)
- **column** : the next memory address targets the next group of pixels on same column (y increment)

---

**Note:**

- Default value is ‘line’.
  - All others modes are forbidden (throw a generation error).
  - When the number of bits-per-pixels (see ‘bpp’ property) is higher or equal than 8, this property is useless and ignored.
- 

## Use

The MicroUI Display APIs are available in the class `ej.microui.display.Display`.

### 4.9.7 Images

The Image Engine is composed of:

- The “Image Engine Core” module which is able to load and drawing simultaneously some pre-generated images and some dynamic images.

- An “Image Generator” module, for converting standard image formats into the display image format before runtime (pre-generated images).
- A set of “Image Decoder” modules, for converting standard image formats into the display image format at runtime. Each Image Decoder is an additional module of the main module “Image Engine”.

## Image Engine Core

### Principle

The Image Engine Core module is a built-in module of the MicroUI module (see *MicroUI*) for the application side, and a built-in module of the Display module (see *Display*) for the C side.

### Functional Description

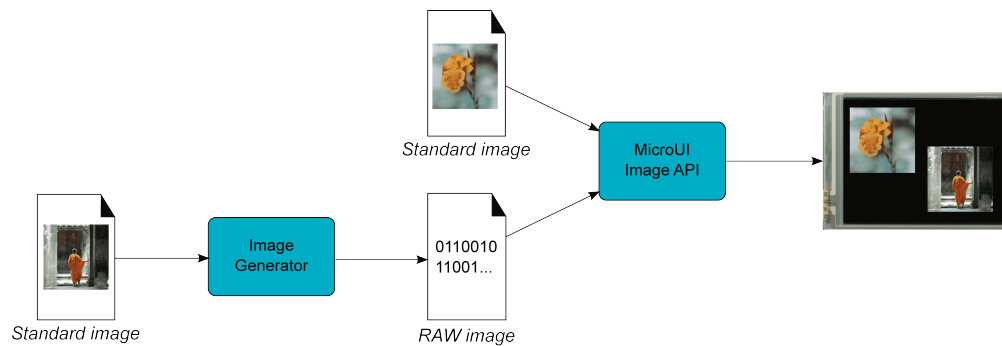


Fig. 37: Image Engine Core Principle

Process overview:

1. The user specifies the pre-generated images to embed (see *Image Generator*) and / or the images to embed as regular resources (see *Image Decoder*)
2. The files are embedded as resources with the MicroEJ Application. The files' data are linked into the FLASH memory.
3. When the MicroEJ Application creates a MicroUI Image object, the Image Engine Core loads the image, calling the right sub Image Engine module (see *Image Generator* and *Image Decoder*) to decode the specified image.
4. When the MicroEJ Application draws this MicroUI Image on the display (or on another image), the decoded image data is used, and no more decoding is required, so the decoding is done only once.
5. When the MicroUI Image is no longer needed, it is garbage-collected by the platform; and the Image Engine Core asks the right sub Image Engine module (see *Image Generator* and *Image Decoder*) to free the image working area.

### External Resources

The Image Engine Core is able to load some images located outside the CPU addresses' space range. It uses the External Resource Loader.

When an image is located in such memory, the Image Engine Core copies it into RAM (into the CPU address space range). Then it calls the right sub Image Engine module (see *Image Generator* and *Image Decoder*) to decode the specified image.

The RAM section used to load the external image is automatically freed when the Image Engine Core and its modules do not need it again.

## Dependencies

- MicroUI module (see *MicroUI*)
- Display module (see *Display*)

## Installation

Image Engine Core modules are part of the MicroUI module and Display module. Install them in order to be able to use some images.

## Use

The MicroUI image APIs are available in the class `ej.microui.display.Image`.

## Image Generator

### Principle

The Image Generator module is an off-board tool that generates image data that is ready to be displayed without needing additional runtime memory. The two main advantages of this module are:

- A pre-generated image is already encoded in the format known by the display stack. The image loading is very fast and does not require any RAM.
- No extra support is needed (no runtime decoder).

### Functional Description

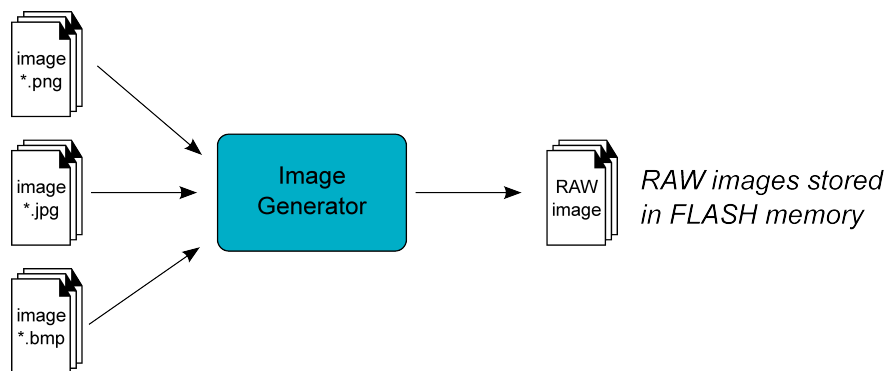


Fig. 38: Image Generator Principle

Process overview (see too [Functional Description](#))

1. The user defines, in a text file, the images to load.
2. The Image Generator outputs a raw file for each image to convert (the raw format is display device-dependent).
3. The raw files are embedded as (hidden) resources within the MicroEJ Application. The raw files' data are linked into the FLASH memory.
4. When the MicroEJ Application creates a MicroUI Image object which targets a pre-generated image, the Image Engine Core has only to create a link from the MicroUI image object to the data in the FLASH memory. Therefore, the loading is very fast; only the image data from the FLASH memory is used: no copy of the image data is sent to the RAM first.
5. When the MicroUI Image is no longer needed, it is garbage-collected by the platform, which just deletes the useless link to the FLASH memory.

### Extensions Purpose

The output representation of the images in the same format as the LCD (same pixel representation, see [Display Output Format](#)) is dependent on the drivers that run the underlying screen. Indeed, the output raw format is specific to each display device. The Image Generator tool provided is expandable by extensions, each extension implementing a dedicated display device layout.

### Standard Extension

When the LCD pixels representation is standard ( [ARGB8888](#) or [RGB565](#) etc., see [Pixel Structure](#)) the image generator does not need an extension. The formulas of conversions [ARGB8888](#) to RAW formats are the same as described in the chapter [Pixel Structure](#).

### Generic Extension

When the LCD pixel representation is generic ( [1](#) | [2](#) | [4](#) | [8](#) | [16](#) | [24](#) | [32](#) , see [Pixel Structure](#)) the image generator requires an extension in order to understand how to convert ARGB pixels into LCD pixel representations.

The Display module provides generic display implementation according the number of bits-per-pixels (1, 2, 4, 8, 16, 24 and 32). The Image Generator tool provides a simple extension to implement in order to target these kinds of displays: [GenericDisplayExtension](#).<sup>1</sup>

A method must be implemented in relation to the way the driver has built the layout of the display buffers in memory: The [convertARGBColorToDisplayColor](#) method is used to convert a 32-bits ARGB color into the display pixel memory representation.

---

**Note:** The Image Generator automatically uses the right number of bits to represent a pixel (BPP) and respect the memory buffer layout using the result of the installation of the Display module.

---

### Create an Extension

Follow the steps below to create an Image Generator extension:

---

<sup>1</sup> Package `com.is2t.microej.microui.image`

1. First, create a new J2SE project, called (for example) `imageGeneratorExtension`.
2. In the project's Java build path (project's property window, select `Java Build Path > Libraries` tab), add the variable `IMAGE-GENERATOR-x.y`.
3. Create the package `com.is2t.microui.generators.extension`.
4. Create a class in the package whose name must be: `MicroUIGeneratorExtension`.
5. The Java class must implement the extension interface available in the library `IMAGE-GENERATOR-x.y` (see previous chapters). Fill the required methods.

The Java project should now look like this:

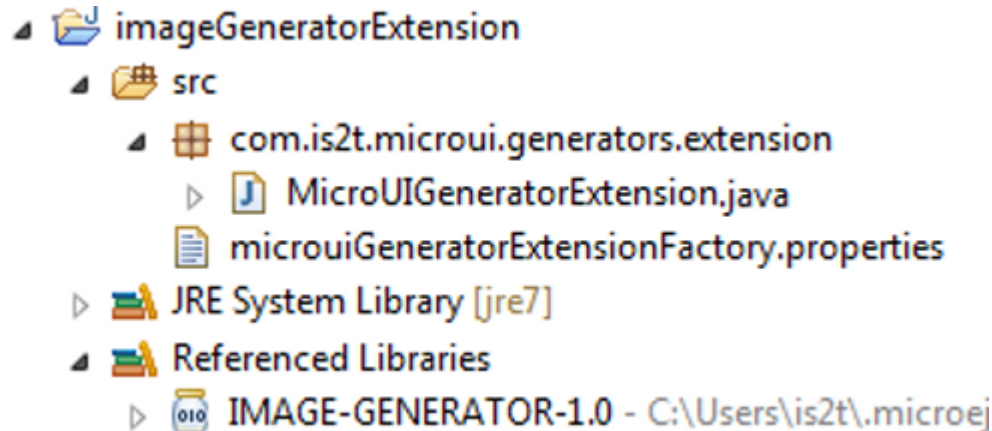


Fig. 39: Image Generator Extension Project

With a Java class like this:

Listing 3: Image Generator Extension Implementation Example

```
package com.is2t.microui.generators.extension;

import com.is2t.microej.microui.image.GenericDisplayExtension;

public class MicroUIGeneratorExtensionMyLCD implements GenericDisplayExtension{

    public int convertARGBColorToDisplayColor(int color) {
        return (char)
            ((color & 0xf80000) >>> 8) |
            ((color & 0x00fc00) >>> 5) |
            ((color & 0x0000f8) >>> 3);
    }
}
```

## Configuration File

The Image Generator uses a configuration file (also called the “list file”) for describing images that need to be processed. The list file is a text file in which each line describes an image to convert. The image is described as a resource path, and should be available from the application classpath.

---

**Note:** The list file must be specified in the MicroEJ Application launcher (see [Application Options](#)). However, all files in application classpath with suffix `.images.list` are automatically parsed by the Image Generator tool.

---

Each line can add optional parameters (separated by a ':') which define and/or describe the output file format (raw format). When no option is specified, the image is converted into the default format.

---

**Note:** See [Image Generator](#) to understand the list file grammar.

---

Below is an example of a list file for the Image Generator:

Listing 4: Image Generator Configuration File Example

```
image1
image2:RGB565
```

The next chapters describe the available output formats.

## Generic Output Formats

Several generic output formats are available. Some formats may be directly managed by the display driver. Refers to the platform specification to retrieve the list of better formats.

Advantages:

- The pixels layout and bits format are standard, so it is easy to manipulate these images on the C-side.
- Drawing an image is very fast when the display driver recognizes the format (with or without transparency).
- Supports or not the alpha encoding: select the better format according to the image to encode.

Disadvantages:

- No compression: the image size in bytes is proportional to the number of pixels, the transparency, and the bits-per-pixel.

Select one the following format to use a generic format:

- ARGB8888: 32 bits format, 8 bits for transparency, 8 per color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return c;
}
```

- RGB888: 24 bits format, 8 per color. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return c & 0xffffff;
}
```

- ARGB4444: 16 bits format, 4 bits for transparency, 4 per color.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((c & 0xf0000000) >> 16)
        | ((c & 0x00f00000) >> 12)
        | ((c & 0x0000f000) >> 8)
```

(continues on next page)

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```

        | ((c & 0x000000f0) >> 4)
        ;
    }

```

- ARGB1555: 16 bits format, 1 bit for transparency, 5 per color.

```

u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | (((c & 0xff000000) == 0xff000000) ? 0x8000 : 0)
        | ((c & 0xf80000) >> 9)
        | ((c & 0x00f800) >> 6)
        | ((c & 0x0000f8) >> 3)
        ;
}

```

- RGB565: 16 bits format, 5 or 6 per color. Image is always fully opaque.

```

u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((c & 0xf80000) >> 8)
        | ((c & 0x00fc00) >> 5)
        | ((c & 0x0000f8) >> 3)
        ;
}

```

- A8: 8 bits format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```

u32 convertARGB8888toRAWFormat(u32 c){
    return 0xff - (toGrayscale(c) & 0xff);
}

```

- A4: 4 bits format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```

u32 convertARGB8888toRAWFormat(u32 c){
    return (0xff - (toGrayscale(c) & 0xff)) / 0x11;
}

```

- A2: 2 bits format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```

u32 convertARGB8888toRAWFormat(u32 c){
    return (0xff - (toGrayscale(c) & 0xff)) / 0x55;
}

```

- A1: 1 bit format, only transparency is encoded. The color to apply when drawing the image, is the current GraphicsContext color.

```

u32 convertARGB8888toRAWFormat(u32 c){
    return (0xff - (toGrayscale(c) & 0xff)) / 0xff;
}

```

- C4: 4 bits format with grayscale conversion. Image is always fully opaque.



```
u32 convertARGB8888toRAWFormat(u32 c){
    return (toGrayscale(c) & 0xff) / 0x11;
}
```

- C2: 2 bits format with grayscale conversion. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (toGrayscale(c) & 0xff) / 0x55;
}
```

- C1: 1 bit format with grayscale conversion. Image is always fully opaque.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return (toGrayscale(c) & 0xff) / 0xff;
}
```

- AC44: 4 bits for transparency, 4 bits with grayscale conversion.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((color >> 24) & 0xf0)
        | ((toGrayscale(color) & 0xff) / 0x11)
        ;
}
```

- AC22: 2 bits for transparency, 2 bits with grayscale conversion.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((color >> 28) & 0xc0)
        | ((toGrayscale(color) & 0xff) / 0x55)
        ;
}
```

- AC11: 1 bit for transparency, 1 bit with grayscale conversion.

```
u32 convertARGB8888toRAWFormat(u32 c){
    return 0
        | ((c & 0xff000000) == 0xff000000 ? 0x2 : 0x0)
        | ((toGrayscale(color) & 0xff) / 0xff)
        ;
}
```

Listing 5: Generic Output Format Examples

```
image1:ARGB8888
image2:RGB565
image3:A4
```

## Display Output Format

The default embedded image data format provided by the Image Generator tool when using a generic extension is to encode the image into the exact display memory representation. If the image to encode contains some transparent pixels, the output file will embed the transparency according to the display's implementation capacity. When all pixels are fully opaque, no extra information will be stored in the output file in order to free up some memory space.

**Advantages:**

- Drawing an image is very fast.
- Supports alpha encoding.

**Disadvantages:**

- No compression: the image size in bytes is proportional to the number of pixels.

Listing 6: Display Output Format Example

```
image1:display
```

**RLE1 Output Format**

The image engine can display embedded images that are encoded into a compressed format which encodes several consecutive pixels into one or more 16-bits words. This encoding manages a maximum alpha level of 2 (alpha level is always assumed to be 2, even if the image is not transparent).

- Several consecutive pixels have the same color (2 words).
  - First 16-bit word specifies how many consecutive pixels have the same color.
  - Second 16-bit word is the pixels' color.
- Several consecutive pixels have their own color (1 + n words).
  - First 16-bit word specifies how many consecutive pixels have their own color.
  - Next 16-bit word is the next pixel color.
- Several consecutive pixels are transparent (1 word).
  - 16-bit word specifies how many consecutive pixels are transparent.

**Advantages:**

- Supports 0 & 2 alpha encoding.
- Good compression when several consecutive pixels respect one of the three previous rules.

**Disadvantages:**

- Drawing an image is slightly slower than when using Display format.

Listing 7: RLE1 Output Format Example

```
image1:RLE1
```

**No Compression**

When no output format is set in the images list file, the image is embedded without any conversion / compression. This allows you to embed the resource as well, in order to keep the source image characteristics (compression, bpp etc.). This option produces the same result as specifying an image as a resource in the MicroEJ launcher.

**Advantages:**

- Conserves the image characteristics.

**Disadvantages:**

- Requires an image runtime decoder.
- Requires some RAM in which to store the decoded image

Listing 8: Unchanged Image Example

```
image1
```

## External Resources

The Image Generator manages two configuration files when the External Resources Loader is enabled. The first configuration file lists the images which will be stored as internal resources with the MicroEJ Application. The second file lists the images the Image Generator must convert and store in the External Resource Loader output directory. It is the BSP's responsibility to load the converted images into an external memory.

## Dependencies

- Image Engine Core module (see *Image Engine Core*).
- Display module (see *Display*): This module gives the characteristics of the graphical display that are useful in configuring the Image Generator.

## Installation

The Image Generator is an additional module for the MicroUI library. When the MicroUI module is installed, also install this module in order to be able to target pre-generated images.

In the platform configuration file, check **UI** > **Image Generator** to install the Image Generator module. When checked, the properties file `imageGenerator > imageGenerator.properties` is required during platform creation to configure the module, only when the LCD pixel representation is not standard (see *Pixel Structure*). This configuration step is used to identify the extension class name (see *Create an Extension*).

## Use

The MicroUI Image APIs are available in the class `ej.microui.display.Image`. There are no specific APIs that use a pre-generated image. When an image has been pre-processed, the MicroUI Image APIs `createImage*` will load the image.

Refer to the chapter *Application Options* ( **Libraries** > **MicroUI** > **Image** ) for more information about specifying the image configuration file.

## Image Decoder

### Principle

The Image Engine provides runtime decoders which allow the dynamic loading of images without using the Image Generator (see *Image Generator*). The two main advantages are:

- The original image is embedded as a resource with the MicroEJ Application.
- The original image size in bytes is often smaller than a pre-generated image (especially in PNG mode).

## Functional Description

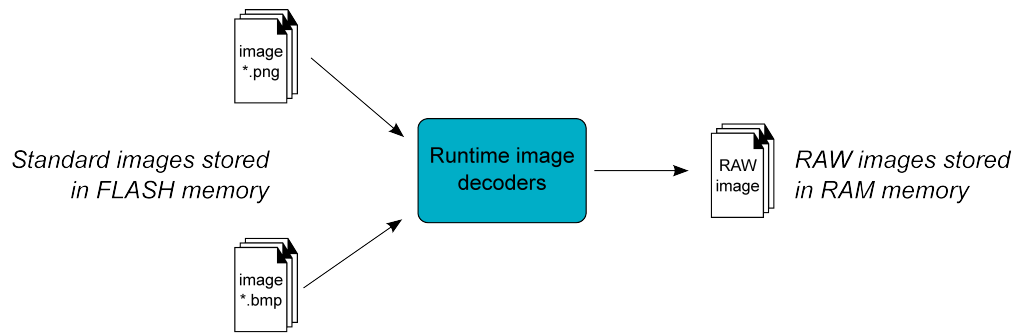


Fig. 40: Image Decoder Principle

Process overview (see too [Functional Description](#))

1. The user specifies the images to embed as regular resources.
2. The original files are embedded as resources with the MicroEJ Application. The original files' data are linked into the FLASH memory.
3. When the Image Engine Core calls the decoder to load an image, it transforms the image into a raw format that is compatible with the display format. It may need some additional RAM to store some working buffers. At the end of the decoding step, the working buffers are freed: Only the decoded image memory needs to be retained.
4. When the Image Engine Core calls the decoder to free the image resources, the decoder frees the decoded image buffer area.

## Internal Decoders

The UI extension provides two internal Image Decoders modules:

- PNG Decoder: a full PNG decoder that implements the PNG format ( <https://www.w3.org/Graphics/PNG> ). Regular, interlaced, indexed (palette) compressions are handled. The RAM used by the decoder is allocated outside the Java heap.
- BMP Monochrome Decoder: .bmp format files that embed only 1 bit per pixel can be decoded by this decoder. The RAM used by the decoder to store the decoded image is outside the Java heap.

## External Decoders

Some additional decoders can be added. Implement the function `LLDISPLAY_EXTRA_IMPL_decodeImage` to add a new decoder (see [LLDISPLAY\\_EXTRA: Display Extra Features](#)).

The implementation must respect the following rules:

- Fills the `LLDISPLAY_SImage` structure with the image characteristics: width, height and format.

---

**Note:** The output image format might be different than the expected format (given as argument). In this way, the display module will perform a conversion after the decoding step. During this conversion, an out of memory error can occur because the final RAW image cannot be allocated.

---

- Allocates the RAW image data calling the function `LLDISPLAY_UTILS_allocateRawImage`. This function will allocate the RAW image data space in the display working buffer according the RAW image format and size.
- Decodes the image in the allocated buffer.
- Waiting the end of decoding step before returning.

## Dependencies

- Image Engine Core module (see *Image Engine Core*)

## Installation

The Image Decoders modules are some additional modules to the Display module. The decoders belong to distinct modules, and either or several may be installed.

In the platform configuration file, check `UI > Image PNG Decoder` to install the runtime PNG decoder. Check `UI > Image BMP Monochrome Decoder` to install the runtime BMP monochrom decoder.

## Use

The MicroUI Image APIs are available in the class `ej.microui.display.Image`. There is no specific API that uses a runtime image. When an image has not been pre-processed (see *Image Generator*), the MicroUI Image APIs `createImage*` will load this image.

### 4.9.8 Fonts

The Font Engine is composed of:

- The “Font Engine Core” module which decodes and prints at application runtime the platform-dependent fonts files generated by the “Font Generator.”
- A “Font Designer” module: a graphical tool which runs within the MicroEJ Workbench used to build and edit MicroUI fonts; it stores fonts in a platform-independent format.
- A “Font Generator” module, for converting fonts from the platform-independent format into a platform-dependent format.

The three modules are complementary: a MicroUI font must be created and edited with the Font Designer before being integrated as a resource by the Font Generator. Finally the Font Engine Core uses the generated fonts at runtime.

The Font Designer module and Font Generator module options are the direct consequence of the Font Engine Core capacities. You must understand the Font Engine Core capacities in order to correctly use the modules.

## Font Engine Core

### Principle

The Font Engine Core module is a built-in module of the MicroUI module (see *MicroUI*) for the application side; and is a built-in module of the Display module (see *Display*) for the C side.

## Functional Description

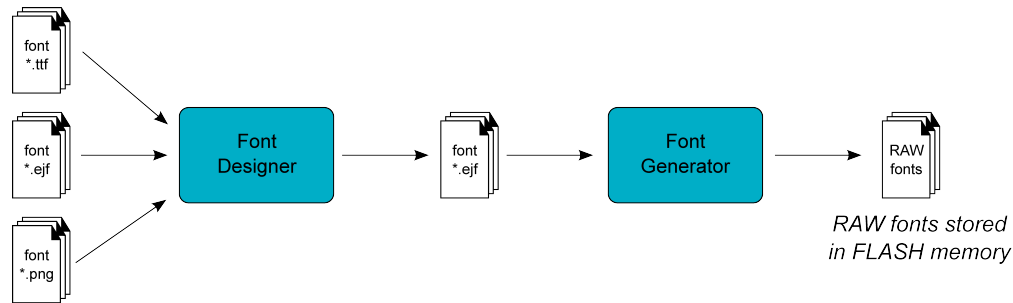


Fig. 41: Font Generation

Process overview:

1. User uses the Font Designer module to create a new font, and imports characters from system fonts ( `*.tff` files) and / or user images ( `*.png` , `*.jpg` , `*.bmp` , etc.).
2. Font Designer module saves the font as a MicroEJ Font ( `*.ejf` file).
3. The user defines, in a text file, the fonts to load.
4. The Font Generator outputs a raw file for each font to convert (the raw format is display device-dependent).
5. The raw files are embedded as (hidden) resources within the MicroEJ Application. The raw files' data are linked into the FLASH memory.
6. When the MicroEJ Application creates a MicroUI DisplayFont object which targets a pre-generated image, the Font Engine Core only has to link from the MicroUI DisplayFont object to the data in the FLASH memory. Therefore, the loading is very fast; only the font data from the FLASH memory is used: no copy of the image data is sent to RAM memory first.
7. When the MicroUI DisplayFont is no longer needed, it is garbage-collected by the platform, which just deletes the useless link to the FLASH memory.

## Font Engine

### Font Format

The font engine module provides fonts that conform to the **Unicode Standard**. The `.ejf` files hold font properties:

- Identifiers: Fonts hold at least one identifier that can be one of the **predefined Unicode scripts** or a user-specified identifier. The intention is that an identifier indicates that the font contains a specific set of character codes, but this is not enforced.
- Font height and width, in pixels. A font has a fixed height. This height includes the white pixels at the top and bottom of each character, simulating line spacing in paragraphs. A monospace font is a font where all characters have the same width; for example, a '!' representation has the same width as a 'w'. In a proportional font, 'w' will be wider than a '!'. No width is specified for a proportional font.

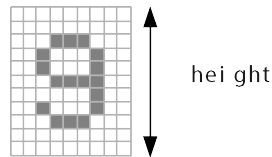


Fig. 42: Font Height

- Baseline, in pixels. All characters have the same baseline, which is an imaginary line on top of which the characters seem to stand. Characters can be partly under the line, for example 'g' or 'j'. The number of pixels specified is the number of pixels above the baseline.



Fig. 43: Font baseline

- Space character size, in pixels. For proportional fonts, the Space character ( `0x20` ) is a specific character because it has no filled pixels, and so its width must be specified. For monospace, the space size is equal to the font width (and hence the same as all other characters).
- Styles: A font holds either a combination of these styles: BOLD, ITALIC, UNDERLINED, or is said to be PLAIN.
- Runtime filters: Some fonts may allow the font engine to apply a transformation (in other words, a filter) on characters before they are displayed in order to provide some visual effect on characters (BOLD, ITALIC, UNDERLINED). Unless specified, a font allows the font engine to apply any of its filters.
- When the selected font does not have a graphical representation of the required character, a rectangle is displayed instead. For proportional fonts, the width is one third of the height of the font.

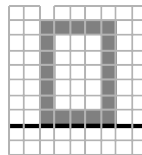


Fig. 44: Default Character

## Font Selection

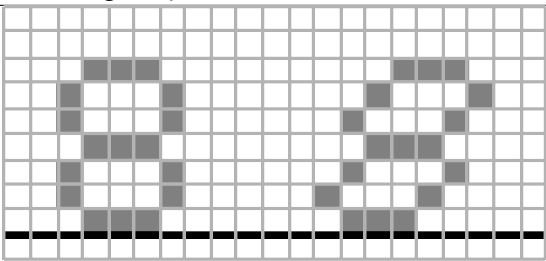
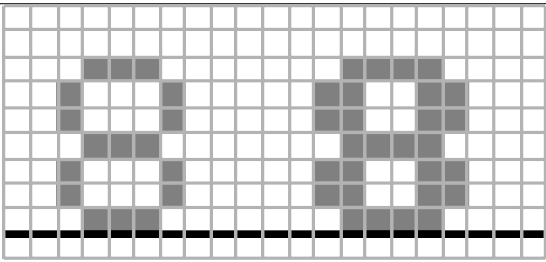
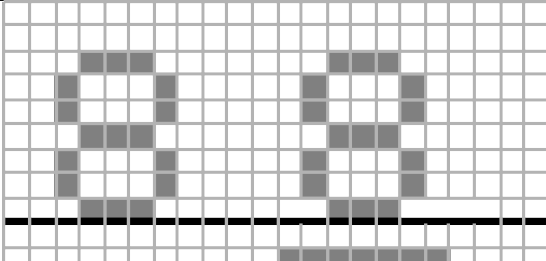
The font engine implements the *[MUI] selection semantics*, and also tries to select fonts for which styles are built in, instead of applying a runtime filter. The font is selected based on the following process:

1. Select fonts that define the specified identifier.
2. Select within the step1 fonts, those whose height is the closest to the specified height.
3. Select within the step2 fonts, those with built-in styles that match the specified styles.
4. If more than one font is selected by the steps above, select those fonts that have the most built-in styles. If there is still more than one font, one is selected arbitrarily.

## Runtime Transformation: Filters

The user interface extension font engine provides three runtime filters that may apply if the (currently selected) font allows it. The filters are:

Table 18: The Three Font Runtime Style Transformations (filters).

Name	Description	Rendering sample
ITALIC	Pixels on upper rows are shifted right. The higher a pixel is relative to the base line, the more it is right-shifted.	
BOLD	1 pixel is added to the right of each original pixel.	
UN- DER- LINED	A line is displayed two pixels below the baseline position.	

Multiple filters may apply at the same time, combining their transformations on the displayed characters.

## Pixel Transparency

The font engine renders the font according to the value stored for each pixel. If the value is 0, the pixel is not rendered. If the value is the maximum value (for example the value 3 for 2 bits-per-pixel), the pixel is rendered using the current foreground color, completely overwriting the current value of the destination pixel. For other values, the pixel is rendered by blending the selected foreground color with the current color of the destination.

If  $n$  is the number of bits-per-pixel, then the maximum value of a pixel ( $p_{max}$ ) is  $2^n - 1$ . The value of each color component of the final pixel is equal to:

$$\text{foreground} \times \text{pixelValue} / p_{max} + \text{background} \times (p_{max} - \text{pixelValue}) / p_{max} + \text{adjustment}$$

where adjustment is an adjustment factor specified in the board support package of the platform.



## Arabic Support

The font engine manages the ARABIC font specificities: the diacritics and contextual letters. Contrary to the LATIN fonts, some ARABIC characters can overlap another character. When a character must overlap the previous character in the text, the font engine repositions the X coordinate before rendering the new character (instead of placing the next character just after the previous one).

To render an Arabic text, the font engine requires several points:

- To determinate if a character has to overlap the previous character, the font engine uses a specific range of ARABIC characters: from `0xfe70` to `0xfefc`. All others characters (ARABIC or not) outside this range are considered *classic* and no overlap is performed. Note that several ARABIC characters are available outside this range, but the same characters (same representation) are available inside this range.
- The application strings must use the UTF-8 encoding. Furthermore, in order to force the use of characters in the range `0xfe70` to `0xfefc`, the string must be filled with the following syntax: '`\ufee2\ufedc\ufe91\u0020\ufe8e\ufe92\ufea3\ufeae\ufee3`'; where `\uxxxx` is the UTF-8 character encoding.
- The application string and its rendering are always performed from left to right. However the string contents are managed by the application itself, and so can be filled from right to left. To write the text:

مرحبا بكم

the string characters must be: '`\ufee2\ufedc\ufe91\u0020\ufe8e\ufe92\ufea3\ufeae\ufee3`'. The font engine will first render the character '`\ufee2`', then '`\ufedc`', and so on.

- Each character in the font (in the `ejf` file) must have a rendering compatible with the character position. The character will be rendered by the font engine as-is. No support is performed by the font engine to obtain a *linear* text.

## External Resources

The Font Engine Core is able to load some fonts located outside the CPU addresses' space range. It uses the External Resource Loader.

When a font is located in such memory, the Font Engine Core copies a very short part of the resource (the font file) into a RAM memory (into CPU addresses space range): the font header. This header stays located in RAM during the full MicroEJ Application time. Then, on MicroEJ Application demand, the Font Engine Core loads some extra information from the font into the RAM memory (the font meta data, the font pixels, etc.). This extra information is automatically unloaded from RAM when the Font Engine Core no longer needs them.

## Dependencies

- MicroUI module (see [MicroUI](#))
- Display module (see [Display](#))

## Installation

The Font Engine Core modules are part of the MicroUI module and Display module. You must install them in order to be able to use some fonts.

## Use

The MicroUI font APIs are available in the class `ej.microui.display.Font`.

## Font Generator

### Principle

The Font Generator module is an off-board tool that generates fonts ready to be displayed without the need for additional runtime memory. It outputs a raw file for each converted font.

### Functional Description

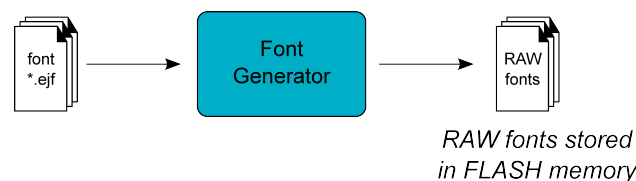


Fig. 45: Font Generator Principle

Process overview:

1. The user defines, in a text file, the fonts to load.
2. The Font Generator outputs a raw file for each font to convert.
3. The raw files are embedded as (hidden) resources within the MicroEJ Application. The raw file's data is linked into the FLASH memory.
4. When the MicroEJ Application draws text on the display (or on an image), the font data comes directly from the FLASH memory (the font data is not copied to the RAM memory first).

### Pixel Transparency

As mentioned above, each pixel of each character in an `.ejf` file has one of 256 different gray-scale values. However RAW files can have 1, 2, 4 or 8 bits-per-pixel (respectively 2, 4, 16 or 256 gray-scale values). The required pixel depth is defined in the configuration file (see next chapter). The Font Generator compresses the input pixels to the required depth.

The following tables illustrates the conversion “grayscale to transparency level”. The grayscale value ‘0x00’ is black whereas value ‘0xff’ is white. The transparency level ‘0x0’ is fully transparent whereas level ‘0x1’ (bpp == 1), ‘0x3’ (bpp == 2) or ‘0xf’ (bpp == 4) is fully opaque.

Table 19: Font 1-BPP RAW Conversion

Grayscale Ranges	Transparency Levels
0x00 to 0x7f	0x1
0x80 to 0xff	0x0

Table 20: Font 2-BPP RAW Conversion

Grayscale Ranges	Transparency Levels
0x00 to 0x1f	0x3
0x20 to 0x7f	0x2
0x80 to 0xdf	0x1
0xe0 to 0xff	0x0

Table 21: Font 4-BPP RAW Conversion

Grayscale Ranges	Transparency Levels
0x00 to 0x07	0xf
0x08 to 0x18	0xe
0x19 to 0x29	0xd
0x2a to 0x3a	0xc
0x3b to 0x4b	0xb
0x4c to 0x5c	0xa
0x5d to 0x6d	0x9
0x6e to 0x7e	0x8
0x7f to 0x8f	0x7
0x90 to 0xa0	0x6
0xa1 to 0xb1	0x5
0xb2 to 0xc2	0x4
0xc3 to 0xd3	0x3
0xd4 to 0xe4	0x2
0xe5 to 0xf5	0x1
0xf6 to 0xff	0x0

For 8-BPP RAW font, a transparency level is equal to  $255 - \text{grayscale value}$ .

## Configuration File

The Font Generator uses a configuration file (called the “list file”) for describing fonts that must be processed. The list file is a basic text file where each line describes a font to convert. The font file is described as a resource path, and should be available from the application classpath.

---

**Note:** The list file must be specified in the MicroEJ Application launcher (see [Application Options](#)). However, all files in application classpath with suffix `.fonts.list` are automatically parsed by the Font Generator tool.

---

Each line can have optional parameters (separated by a ‘:’) which define some ranges of characters to embed in the final raw file, and the required pixel depth. By default, all characters available in the input font file are embedded, and the pixel depth is 1 (i.e 1 bit-per-pixel).

---

**Note:** See [Font Generator](#) to understand the list file grammar.

---

Selecting only a specific set of characters to embed reduces the memory footprint. There are two ways to specify a character range: the custom range and the known range. Several ranges can be specified, separated by “;”.

Below is an example of a list file for the Font Generator:

Listing 9: Fonts Configuration File Example

```
myfont
myfont1:latin
myfont2:latin:8
myfont3::4
```

## External Resources

The Font Generator manages two configuration files when the External Resources Loader is enabled. The first configuration file lists the fonts which will be stored as internal resources with the MicroEJ Application. The second file lists the fonts the Font Generator must convert and store in the External Resource Loader output directory. It is the BSP's responsibility to load the converted fonts into an external memory.

## Dependencies

- Font Engine Core module (see *Font Engine Core*)

## Installation

The Font Generator module is an additional tool for MicroUI library. When the MicroUI module is installed, install this module in order to be able to embed some additional fonts with the MicroEJ Application.

If the module is not installed, the platform user will not be able to embed a new font with his/her MicroEJ Application. He/she will be only able to use the system fonts specified during the MicroUI initialization step (see *Static Initialization*).

In the platform configuration file, check **UI** > **Font Generator** to install the Font Generator module.

## Use

In order to be able to embed ready-to-be-displayed fonts, you must activate the fonts conversion feature and specify the fonts configuration file.

Refer to the chapter *Application Options* ( **Libraries** > **MicroUI** > **Font** ) for more information about specifying the fonts configuration file.

## 4.9.9 Simulation

### Principle

The graphical user interface uses the Front Panel mock (see *Front Panel Mock*) and some extensions (widgets) to simulate the user interactions. It is the equivalent of the three embedded modules (Display, Inputs and LED) of the MicroEJ Platform (see *MicroUI*).

The Front Panel enhances the development environment by allowing User Interface applications to be designed and tested on the computer rather than on the target device (which may not yet be built). The mock interacts with the user's computer in two ways:

- output: LEDs, graphical displays

- input: buttons, joystick, touch, haptic sensors

---

**Note:** This chapter completes the notions described in *Front Panel Mock* chapter.

---

## Module Dependencies

The Front Panel project requires the dependency `ej.tool.frontpanel#widget`. This library provides some widgets which have been designed to be compatible with the graphical engine: the MicroUI natives are implemented in these widgets and the widgets behavior matches with MicroUI implementation.

```
<ivy-module version="2.0" xmlns:ea="http://www.easyant.org" xmlns:ej="https://developer.microej.com" _
  ↪ej:version="2.0.0">
<info organisation="com.mycompany" module="examplePanel" status="integration" revision="1.0.0"/>

  <configurations defaultconfmapping="default->default;provided->provided">
    <conf name="default" visibility="public" description="Runtime dependencies to other artifacts"/>
    <conf name="provided" visibility="public" description="Compile-time dependencies to APIs provided_
  ↪by the platform"/>
  </configurations>

  <dependencies>
    <dependency org="ej.tool.frontpanel" name="widget" rev="1.0.0"/>
  </dependencies>
</ivy-module>
```

## Widget Display

By default, a display area is rectangular. Some displays can have another appearance (for instance: circular). The front panel is able to simulate that using a filter (see *Widget*). This filter defines the pixels inside and outside the real display area. The filter image must have the same size than display rectangular area. A display pixel at a given position will be not rendered if the pixel at the same position in mask is fully transparent.

## Inputs Extensions

The input device widgets (button, joystick, touch etc.) require a listener to know how to react on input events (press, release, move etc.). The aim of this listener is to generate an event compatible with MicroUI *EventGenerator*. Thereby, a button press action can become a MicroUI *Buttons* press event or a *Command* event or anything else.

A MicroUI *EventGenerator* is known by its name. This name is fixed during the MicroUI static initialization (see *Static Initialization*). To generate an event to a specific event generator, the widget has to use the event generator name as identifier.

A front panel widget can:

- Force the behavior of an input action: the associated MicroUI *EventGenerator* type is hardcoded (*Buttons*, *Pointer* etc.), the event is hardcoded (for instance: widget button press action may be hardcoded on event generator *Buttons* and on the event *pressed*). Only the event generator name (identifier) should be editable by the front panel extension project.
- Propose a default behavior of an input action: contrary to first point, the front panel extension project is able to change the default behavior. For instance a joystick can simulate a MicroUI *Pointer*.

- Do nothing: the widget requires the front panel extension project to give a listener. This listener will receive all widgets action (press, release, etc.) and will have to react on it. The action should be converted on a MicroUI [EventGenerator](#) event or might be dropped.

This choice of behavior is widget dependant. Please refer to the widget documentation to have more information about the chosen behavior.

## Heap Simulation

Graphical engine is using two dedicated heaps: for the images and the external fonts. Front panel simulates partly simulates the heaps usage.

- Images heap: Front Panel simulates the heap usage when the application is creating a [BufferedImage](#) , when it loads and decodes an image (PNG, BMP etc.), when it converts an image in MicroEJ format in another MicroEJ format. However it does not simulate the external image copy in heap.
- External fonts heap: Front Panel does not simulate this heap.

## Image Decoders

Front Panel uses its own internal image decoders when the internal image decoders related modules have been selected (see [Internal Decoders](#)).

Front Panel can add some additional decoders like the C-side for the embedded platform (see [External Decoders](#)). However, the exhaustive list of additional decoders is limited (Front Panel is using the Java AWT [ImageIO](#) API). To add an additional decoder, specify the property [hardwareImageDecoders.list](#) in front panel configuration properties file (see [Installation](#)) with one or several property values:

Table 22: Front Panel Additional Image Decoders

Type	Property value
Graphics Interchange Format (GIF)	gif
Joint Photographic Experts Group (JPEG)	jpeg   jpg
Portable Network Graphics (PNG)	png
Windows bitmap (BMP)	bmp

The decoders list is comma (,) separated. Example:

```
hardwareImageDecoders.list=jpg,bmp
```

## Dependencies

- MicroUI module (see [MicroUI](#)).
- Display module (see [Display](#)): This module gives the characteristics of the graphical display that are useful for configuring the Front Panel.

## Installation

Front Panel is an additional module for MicroUI library. When the MicroUI module is installed, install this module in order to be able to simulate UI drawings on the Simulator. See [Installation](#) to install the module.

The properties file can additional properties:

- `hardwareImageDecoders.list` [optional, default value is "" (*empty*)]: Defines the available list of additional image decoders provided by the hardware. Use comma (',') to specify several decoders among this list: bmp, jpg, jpeg, gif, png. If empty or unspecified, no image decoder is added.

## Use

Launch a MicroUI application on the Simulator to run the Front Panel.

## 4.10 Networking

### 4.10.1 Principle

MicroEJ provides some Foundation Libraries to initiate raw TCP/IP protocol-oriented communications and secure this communication by using Secure Socket Layer (SSL) or Transport Layer Security (TLS) cryptographic protocols.

The diagram below shows a simplified view of the components involved in the provisioning of a Java network interface.

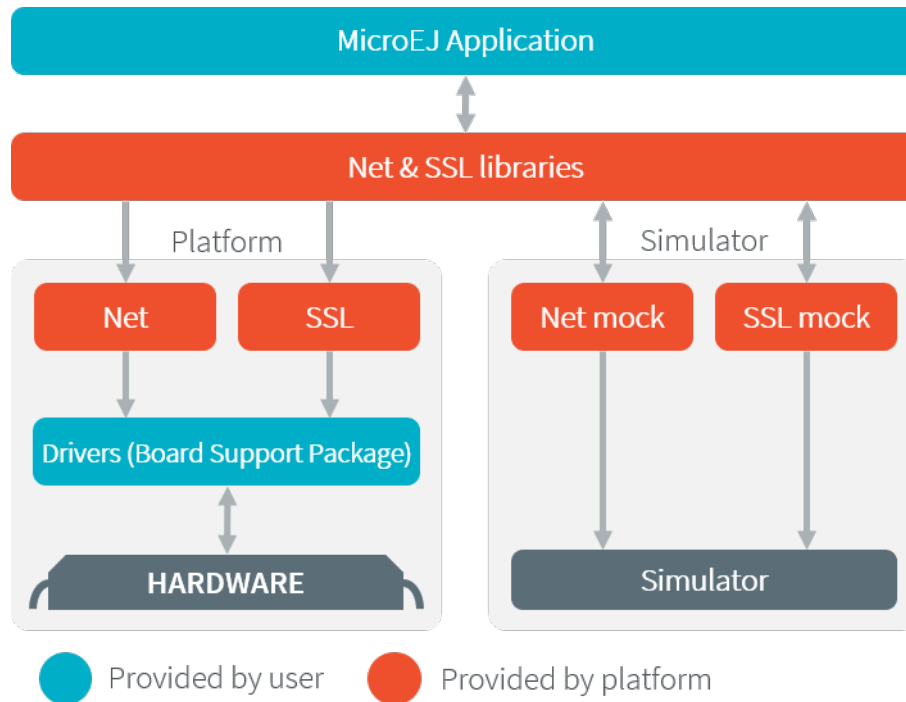


Fig. 46: Overview

Net and SSL low level parts connects the Net and SSL libraries to the user-supplied drivers code (coded in C).

The MicroEJ Simulator provides all features of Net and SSL libraries. This one takes part of the network settings stored in the operating system on which the Simulator will be launched.

### 4.10.2 Network Core Engine

## Principle

The Net module defines a low-level network framework for embedded devices. This module allows you to manage connection (TCP)- or connectionless (UDP)-oriented protocols for client/server networking applications.

## Functional Description

The Net library includes two sub-protocols:

- UDP: a connectionless-oriented protocol that allows communication with the server or client side in a non-reliable way. No handshake mechanisms, no guarantee on delivery, and no order in packet sending.
- TCP: a connection-oriented protocol that allows communication with the server or client side in a reliable way. Handshakes mechanism used, bytes ordered, and error checking performed upon delivery.

## Dependencies

- `LLNET_CHANNEL_impl.h` , `LLNET_SOCKETCHANNEL_impl.h` , `LLNET_STREAMSOCKETCHANNEL_impl.h` , `LLNET_DATAGRAMSOCKETCHANNEL_impl.h` , `LLNET_DNS_impl.h` , `LLNET_NETWORKADDRESS_impl.h` , `LLNET_NETWORKINTERFACE_impl.h` (see *LLNET: Network*).

## Installation

Network is an additional module. In the platform configuration file, check `NET` to install this module. When checked, the properties file `net > net.properties` is required during platform creation to configure the module. This configuration step is used to customize the kind of TCP/IP native stack used and the Domain Name System (DNS) implementation.

The properties file must / can contain the following properties:

- `stack` [optional, default value is “custom”]: Defines the kind of TCP/IP interface used in the C project.
  - `custom`: Select this configuration to make a “from scratch” implementation glue between the C Network Core Engine and the C project TCP/IP interface.
  - `bsd`: Select this configuration to use a BSD-like library helper to implement the glue between the C Network Core Engine and the C project TCP/IP interface. This property requires that the C project provides a TCP/IP native stack with a Berkeley Sockets API and a `select` mechanism.
- `dns` [optional, default value is “native”]: Defines the kind of Domain Name System implementation used.
  - `native`: Select this configuration to implement the glue between the C Network Core Engine DNS part and the C project TCP/IP interface.
  - `soft`: Select this configuration if you want a software implementation of the DNS part. Only the IPs list of the DNS server must be provided by the C Network Core Engine glue.

## Use

A classpath variable named `NET-1.1` is available.

This library provides a set of options. Refer to the chapter *Application Options* which lists all available options.



### 4.10.3 SSL

#### Principle

SSL (Secure Sockets Layer) library provides APIs to create and establish an encrypted connection between a server and a client. It implements the standard SSL/TLS (Transport Layer Security) protocol that manages client or server authentication and encrypted communication. Mutual authentication is supported since [SSL API 2.1.0](#).

#### Functional Description

The SSL/TLS process includes two sub-protocols :

- Handshake protocol : consists that a server presents its digital certificate to the client to authenticate the server's identity. The authentication process uses public-key encryption to validate the digital certificate and confirm that a server is in fact the server it claims to be.
- Record protocol : after the server authentication, the client and the server establish cipher settings to encrypt the information they exchange. This provides data confidentiality and integrity.

#### Dependencies

- Network core module (see [Network Core Engine](#)).
- `LLNET_SSL_CONTEXT_impl.h` and `LLNET_SSL_SOCKET_impl.h` implementations (see [LLNET\\_SSL: SSL](#)).

#### Installation

SSL is an additional module. In the platform configuration file, check [SSL](#) to install the module.

#### Use

The [SSL API module](#) must be added to the `module.ivy` of the MicroEJ Application project, in order to allow access to the SSL library.

```
<dependency org="ej.api" name="ssl" rev="2.2.0"/>
```

## 4.11 File System

### 4.11.1 Principle

The FS module defines a low-level File System framework for embedded devices. It allows you to manage abstract files and directories without worrying about the native underlying File System kind.

### 4.11.2 Functional Description

The MicroEJ Application manages File System elements using File/Directory abstraction. The FS implementation made for each MicroEJ Platform is responsible for surfacing the native File System specific behavior.

### 4.11.3 Dependencies

- `LLFS_impl.h` and `LLFS_File_impl.h` implementations (see *LLFS: File System*).

### 4.11.4 Installation

FS is an additional module. In the platform configuration file, check `FS` to install it. When checked, the properties file `fs > fs.properties` are required during platform creation in order to configure the module.

The properties file must / can contain the following properties:

- `fs` [optional, default value is “Custom”]: Defines the kind of File System native stack used in the C project.
  - `Custom`: select this configuration to make a specific File System portage.
  - `FatFS`: select this configuration to use FatFS native File System-compliant settings.
- `root.dir` [optional, for a FatFS File System. Mandatory, for a Custom File System.]: Defines the native File System root volume (default value is “/” for FatFS).
- `user.dir` [optional, for a FatFS File System. Mandatory, for a Custom File System.]: Defines the native File System user directory (default value is “/usr” for FatFS).
- `tmp.dir` [optional, for a FatFS File System. Mandatory, for a Custom File System.]: Defines the native File System temporary directory (default value is “/tmp” for FatFS).
- `file.separator` [optional, for a FatFS File System. Mandatory, for a Custom File System.]: Defines the native File System file separator (default value is “/” for FatFS).
- `path.separator` [optional, for a FatFS File System. Mandatory, for a Custom File System.]: Defines the native File System path separator (default value is “:” for FatFS).

### 4.11.5 Use

A classpath variable named `FS-2.0` is available.

## 4.12 Hardware Abstraction Layer

### 4.12.1 Principle

The Hardware Abstraction Layer (HAL) library features API that target IO devices, such as GPIOs, analog to/from digital converters (ADC / DAC), etc. The API are very basic in order to be as similar as possible to the BSP drivers.

### 4.12.2 Functional Description

The MicroEJ Application configures and uses some physical GPIOs, using one unique identifier per GPIO. The HAL implementation made for each MicroEJ Platform has the responsibility of verifying the veracity of the GPIO identifier and the valid GPIO configuration.

Theoretically, a GPIO can be reconfigured at any time. For example a GPIO is configured in OUTPUT first, and later in ADC entry. However the HAL implementation can forbid the MicroEJ Application from performing this kind of operation.

### 4.12.3 Identifier

#### Basic Rule

MicroEJ Application manipulates anonymous identifiers used to identify a specific GPIO (port and pin). The identifiers are fixed by the HAL implementation made for each MicroEJ Platform, and so this implementation is able to make the link between the MicroEJ Application identifiers and the physical GPIOs.

- A **port** is a value between **0** and **n - 1**, where **n** is the available number of ports.
- A **pin** is a value between **0** and **m - 1**, where **m** is the maximum number of pins per port.

#### Generic Rules

Most of time the basic implementation makes the link between the port / pin and the physical GPIO following these rules:

- The port **0** targets all MCU pins. The first pin of the first MCU port has the ID **0**, the second pin has **1**; the first pin of the next MCU port has the ID **m** (where **m** is the maximum number of pins per port), etc. Examples:

```
/* m = 16 (16 pins max per MCU port) */
mcu_pin = application_pin & 0xf;
mcu_port = (application_pin >> 4) + 1;
```

```
/* m = 32 (32 pins max per MCU port) */
mcu_pin = application_pin & 0x1f;
mcu_port = (application_pin >> 5) + 1;
```

- The port from **1** to **n** (where **n** is the available number of MCU ports) targets the MCU ports. The first MCU port has the ID **1**, the second has the ID **2**, and the last port has the ID **n**.
- The pin from **0** to **m - 1** (where **m** is the maximum number of pins per port) targets the port pins. The first port pin has the ID **0**, the second has the ID **1**, and the last pin has the ID **m - 1**.

The implementation can also normalize virtual and physical board connectors. A physical connector is a connector available on the board, and which groups several GPIOs. The physical connector is usually called **JPn** or **CNn**, where **n** is the connector ID. A virtual connector represents one or several physical connectors, and has a *name*; for example **ARDUINO\_DIGITAL**.

Using a unique ID to target a virtual connector allows you to make an abstraction between the MicroEJ Application and the HAL implementation. For example, on a board A, the pin **D5** of **ARDUINO\_DIGITAL** port will be connected to the MCU **portA**, **pin12** (GPIO ID = **1**, **12**). And on board B, it will be connected to the MCU **port5**, **pin0** (GPIO ID = **5**, **0**). From the MicroEJ Application point of view, this GPIO has the ID **30**, **5**.

Standard virtual connector IDs are:

```
ARDUINO_DIGITAL = 30;
ARDUINO_ANALOG = 31;
```

Finally, the available physical connectors can have a number from **64** to **64 + i - 1**, where **i** is the available number of connectors on the board. This allows the application to easily target a GPIO that is available on a physical connector, without knowing the corresponding MCU port and pin.

```
JP3 = 64;
JP6 = 65;
JP11 = 66;
```

#### 4.12.4 Configuration

A GPIO can be configured in any of five modes:

- Digital input: The MicroEJ Application can read the GPIO state (for example a button state).
- Digital input pull-up: The MicroEJ Application can read the GPIO state (for example a button state); the default GPIO state is driven by a pull-up resistor.
- Digital output: The MicroEJ Application can set the GPIO state (for example to drive an LED).
- Analog input: The MicroEJ Application can convert some incoming analog data into digital data (ADC). The returned values are values between 0 and  $n - 1$ , where  $n$  is the ADC precision.
- Analog output: The MicroEJ Application can convert some outgoing digital data into analog data (DAC). The digital value is a percentage (0 to 100%) of the duty cycle generated on selected GPIO.

#### 4.12.5 Dependencies

- `LLHAL_impl.h` implementation (see *LLHAL: Hardware Abstraction Layer*).

#### 4.12.6 Installation

HAL is an additional module. In the platform configuration file, check `HAL` to install the module.

#### 4.12.7 Use

A classpath variable named `HAL-1.0` is available.

### 4.13 Device Information

#### 4.13.1 Principle

The Device library provides access to the device information. This includes the architecture name and a unique identifier of the device for this architecture.

#### 4.13.2 Dependencies

- `LLDEVICE_impl.h` implementation (see *LLDEVICE: Device Information*).

#### 4.13.3 Installation

Device Information is an additional module. In the platform configuration file, check `Device Information` to install it. When checked, the property file `device > device.properties` may be defined during platform creation to customize the module.

The properties file must / can contain the following properties:

- `architecture` [optional, default value is “Virtual Device”]: Defines the value returned by the `ej.util.Device.getArchitecture()` method on the Simulator.

- `id.length` [optional]: Defines the size of the ID returned by the `ej.util.Device.getId()` method on the Simulator.

#### 4.13.4 Use

A classpath variable named `DEVICE-1.0` is available.

### 4.14 Simulation

#### 4.14.1 Principle

The MicroEJ Platform provides an accurate MicroEJ Simulator that runs on workstations. Applications execute in an almost identical manner on both the workstation and on target devices. The MicroEJ Simulator features IO simulation, JDWP debug coupled with Eclipse, accurate Java heap dump, and an accurate Java scheduling policy (the same as the embedded one).<sup>1</sup>

#### 4.14.2 Functional Description

In order to simulate external stimuli that come from the native world (that is, “the C world”), the MicroEJ Simulator has a Hardware In the Loop interface, HIL, which performs the simulation of Java-to-C calls. All Java-to-C calls are rerouted to an HIL engine. Indeed HIL is a replacement for the `[SNI]` interface.

---

<sup>1</sup> Only the execution speed is not accurate. The Simulator speed can be set to match the average MicroEJ Platform speed in order to adapt the Simulator speed to the desktop speed.



Fig. 47: The HIL Connects the MicroEJ Simulator to the Workstation.

The “simulated C world” is made of Mocks that simulate native code (such as drivers and any other kind of C libraries), so that the MicroEJ Application can behave the same as the device using the MicroEJ Platform.

The MicroEJ Simulator and the HIL are two processes that run in parallel: the communication between them is through a socket connection. Mocks run inside the process that runs the HIL engine.

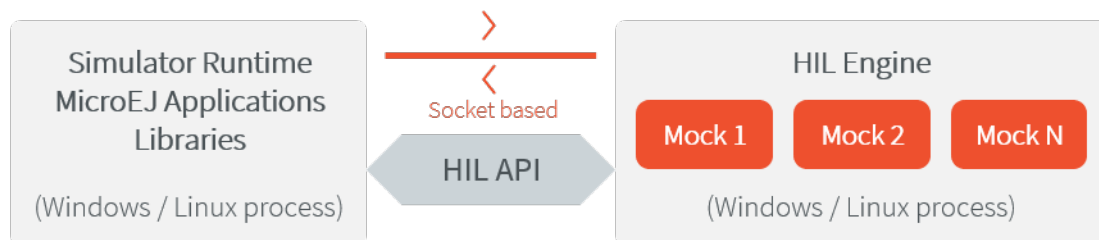


Fig. 48: A MicroEJ Simulator connected to its HIL Engine via a socket.

### 4.14.3 Dependencies

No dependency.

#### 4.14.4 Installation

The Simulator is a built-in feature of MicroEJ Platform architecture.

#### 4.14.5 Use

To run an application in the Simulator, create a MicroEJ launch configuration by right-clicking on the main class of the application, and selecting **Run As** > **MicroEJ Application** .

This will create a launch configuration configured for the Simulator, and will run it.

#### 4.14.6 Mock

##### Principle

The HIL engine is a Java standard-based engine that runs Mocks. A Mock is a jar file containing some Java classes that simulate natives for the Simulator. Mocks allow applications to be run unchanged in the Simulator while still (apparently) interacting with native code.

##### Functional Description

As with [\[SNI\]](#), HIL is responsible for finding the method to execute as a replacement for the native Java method that the MicroEJ Simulator tries to run. Following the [\[SNI\]](#) philosophy, the matching algorithm uses a naming convention. When a native method is called in the MicroEJ Simulator, it requests that the HIL engine execute it. The corresponding Mock executes the method and provides the result back to the MicroEJ Simulator.

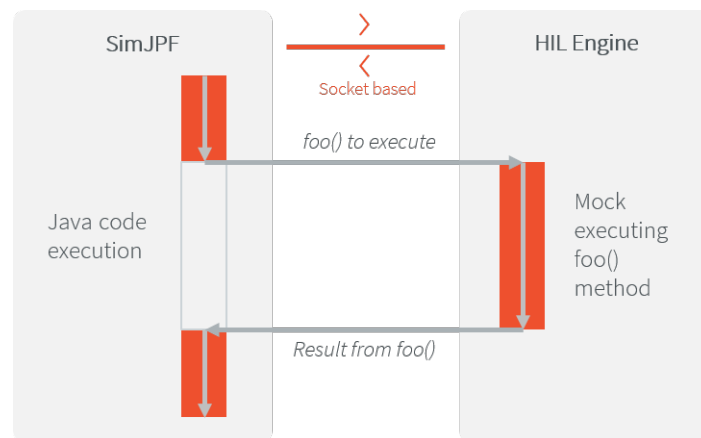


Fig. 49: The MicroEJ Simulator Executes a Native Java Method `foo()` .

##### Example

```
package example;

import java.io.IOException;

/**
```

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```

* Abstract class providing a native method to access sensor value.
* This method will be executed out of virtual machine.
*/
public abstract class Sensor {

    public static final int ERROR = -1;

    public int getValue() throws IOException {
        int sensorID = getSensorID();
        int value = getSensorValue(sensorID);
        if (value == ERROR) {
            throw new IOException("Unsupported sensor");
        }
        return value;
    }

    protected abstract int getSensorID();

    public static native int getSensorValue(int sensorID);
}

class Potentiometer extends Sensor {

    protected int getSensorID() {
        return Constants.POTENTIOMETER_ID; // POTENTIOMETER_ID is a static final
    }
}

```

To implement the native method `getSensorValue(int sensorID)`, you need to create a MicroEJ standard project containing the same `Sensor` class on the same `example` package. To do so, open the Eclipse menu `File > New > Project... > Java > Java Project` in order to create a MicroEJ standard project.

The following code is the required `Sensor` class of the created Mock project:

```

package example;

import java.util.Random;

/**
 * Java standard class included in a Mock jar file.
 * It implements the native method using a Java method.
 */
public class Sensor {

    /**
     * Constants
     */
    private static final int SENSOR_ERROR = -1;
    private static final int POTENTIOMETER_ID = 3;

    private static final Random RANDOM = new Random();

    /**
     * Implementation of native method "getSensorValue()"
     *
     * @param sensorID Sensor ID
     * @return Simulated sensor value
     */
}

```

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```

    */
    public static int getSensorValue(int sensorID) {
        if( sensorID == POTENTIOMETER_ID ) {
            // For the simulation, Mock returns a random value
            return RANDOM.nextInt();
        }
        return SENSOR_ERROR;
    }
}

```

## Mocks Design Support

### Interface

The MicroEJ Simulator interface is defined by static methods on the Java class `com.is2t.hil.NativeInterface`.

### Array Type Arguments

Both [\[SNI\]](#) and HIL allow arguments that are arrays of base types. By default the contents of an array are NOT sent over to the Mock. An “empty copy” is sent by the HIL engine, and the contents of the array must be explicitly fetched by the Mock. The array within the Mock can be modified using a regular assignment. Then to apply these changes in the MicroEJ Simulator, the modifications must be flushed back. There are two methods provided to support fetch and flush between the MicroEJ Simulator and the HIL:

- **refreshContent** : initializes the array argument from the contents of its MicroEJ Simulator counterpart.
- **flushContent** : propagates (to the MicroEJ Simulator) the contents of the array that is used within the HIL engine.

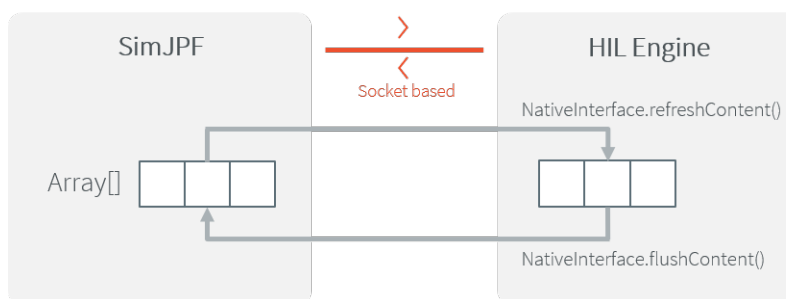


Fig. 50: An Array and Its Counterpart in the HIL Engine.

Below is a typical usage.

```

public static void foo(char[] chars, int offset, int length){
    NativeInterface ni = HIL.getInstance();
    //inside the Mock
    ni.refreshContent(chars, offset, length);
    chars[offset] = 'A';
    ni.flushContent(chars, offset, 1);
}

```

## Blocking Native Methods

Some native methods block until an event has arrived *[SNI]*. Such behavior is implemented in native using the following three functions:

- `int32_t SNI_suspendCurrentJavaThread(int64_t timeout)`
- `int32_t SNI_getCurrentJavaThreadID(void)`
- `int32_t SNI_resumeJavaThread(int32_t id)`

This behavior is implemented in a Mock using the following methods on a `lock` object:

- `Object.wait(long timeout)` : Causes the current thread to wait until another thread invokes the `notify()` method or the `notifyAll()` method for this object.
- `Object.notifyAll()` : Wakes up all the threads that are waiting on this object's monitor.

```
public static byte[] data = new byte[BUFFER_SIZE];
public static int dataLength = 0;
private static Object lock = new Object();

//Mock native method
public static void waitForData(){
    //inside the Mock
    //wait until the data is received
    synchronized (lock) {
        while(dataLength == 0) {
            try {
                lock.wait(); // equivalent to lock.wait(0)
            } catch (InterruptedException e) {
                Thread.currentThread().interrupt();
                // Use the error code specific to your library
                throw new NativeException(-1, "InterruptedException", e);
            }
        }
    }
}

//Mock data reader thread
public static void notifyDataReception() {
    synchronized (lock) {
        dataLength = readFromInputStream(data);
        lock.notifyAll();
    }
}
```

## Resource Management

In Java, every class can play the role of a small read-only file system root: The stored files are called “Java resources” and are accessible using a path as a String.

The MicroEJ Simulator interface allows the retrieval of any resource from the original Java world, using the `getResourceContent` method.

```
public static void bar(byte[] path, int offset, int length) {
    NativeInterface ni = HIL.getInstance();
    ni.refreshContent(path, offset, length);
}
```

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```
String pathStr = new String(path, offset, length);
byte[] data = ni.getResourceContent(pathStr);
...
}
```

## Synchronous Terminations

To terminate the whole simulation (MicroEJ Simulator and HIL), use the stop() method.

```
public static void windowClosed() {
    HIL.getInstance().stop();
}
```

## Dependencies

The MicroEJ Platform architecture provides some APIs (HIL APIs) to develop a Mock that will be ready to be used against the Simulator. The classpath variable that allows you to access to the HIL Engine API is [HILENGINE-2.0.1](#). MicroEJ projects that build Mocks should put that library on their build path.

## Installation

The Mock creator is responsible for building the Mock jar file using his/her own method (Eclipse build, [javac](#), etc.). Once built, the jar file must be put in this specific platform configuration project folder in order to be included during the platform creation : [dropins/mocks/dropins/](#).

## Use

Once installed, a Mock is used automatically by the Simulator when the MicroEJ Application calls a native method which is implemented into the Mock.

### 4.14.7 Shielded Plug Mock

#### General Architecture

The Shielded Plug Mock simulates a Shielded Plug [\[SP\]](#) on desktop computer. This mock can be accessed from the MicroEJ Simulator, the hardware platform or a Java J2SE application.

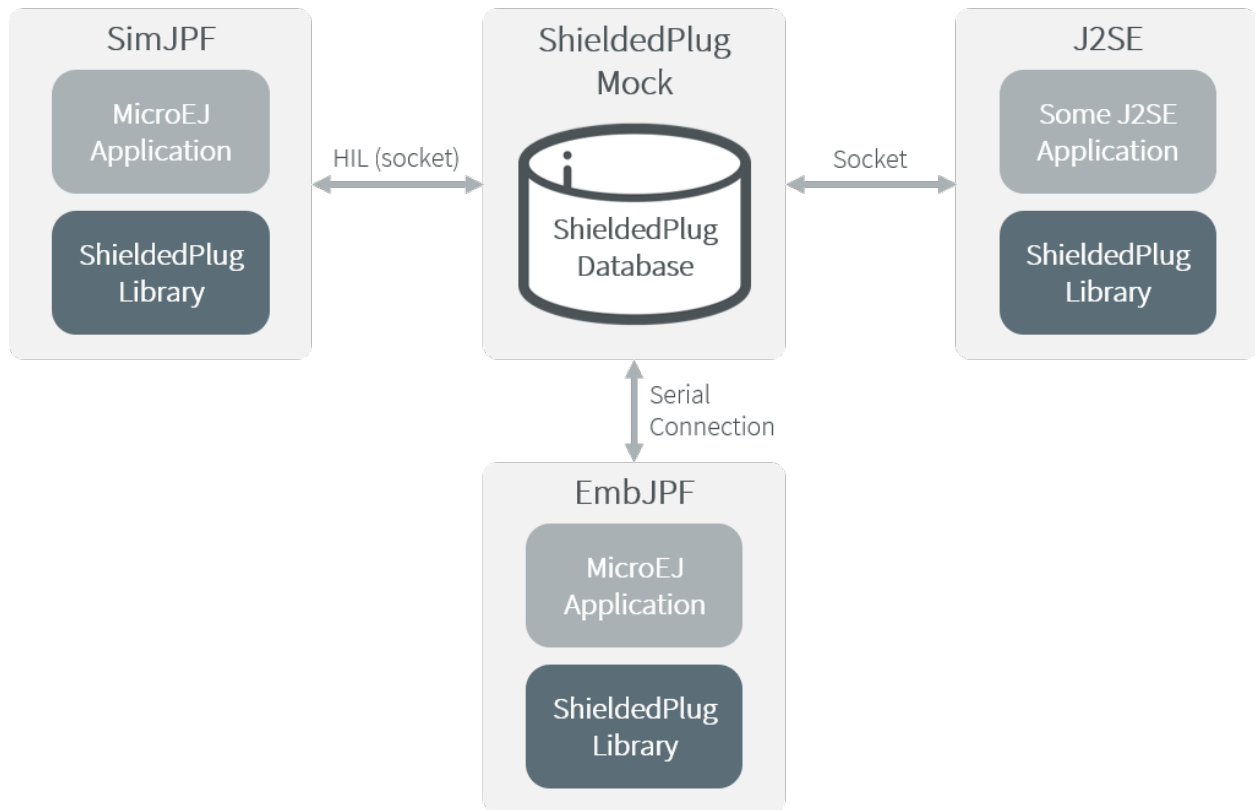


Fig. 51: Shielded Plug Mock General Architecture

### Configuration

The mock socket port can be customized for J2SE clients, even though several Shielded Plug mocks with the same socket port cannot run at the same time. The default socket port is 10082.

The Shielded Plug mock is a standard MicroEJ Application. It can be configured using Java properties:

- `sp.connection.address`
- `sp.connection.port`

### 4.14.8 Front Panel Mock

#### Principle

A major strength of the MicroEJ environment is that it allows applications to be developed and tested in a Simulator rather than on the target device, which might not yet be built. To make this possible for devices that controls operated by the user, the Simulator must connect to a “mock” of the control panel (the “Front Panel”) of the device. The Front Panel generates a graphical representation of the device, and is displayed in a window on the user’s development machine when the application is executed in the Simulator.

The Front Panel has been designed to be an implementation of MicroUI library (see [Simulation](#)). However it can be use to show a hardware device, blink a LED, interact with user without using MicroUI library.

## Functional Description

1. Creates a new Front Panel project.
2. Creates an image of the required Front Panel. This could be a photograph or a drawing.
3. Defines the contents and layout of the Front Panel by editing an XML file (called an fp file). Full details about the structure and contents of fp files can be found in chapter *Front Panel*.
4. Creates images to animate the operation of the controls (for example button down image).
5. Creates *Widgets* that make the link between the application and the user interactions.
6. Previews the Front Panel to check the layout of controls and the events they create, etc.
7. Exports the Front Panel project into a MicroEJ Platform project.

## The Front Panel Project

### Creating a Front Panel Project

A Front Panel project is created using the New Front Panel Project wizard. Select:

New > Project... > MicroEJ > Front Panel Project

The wizard will appear:

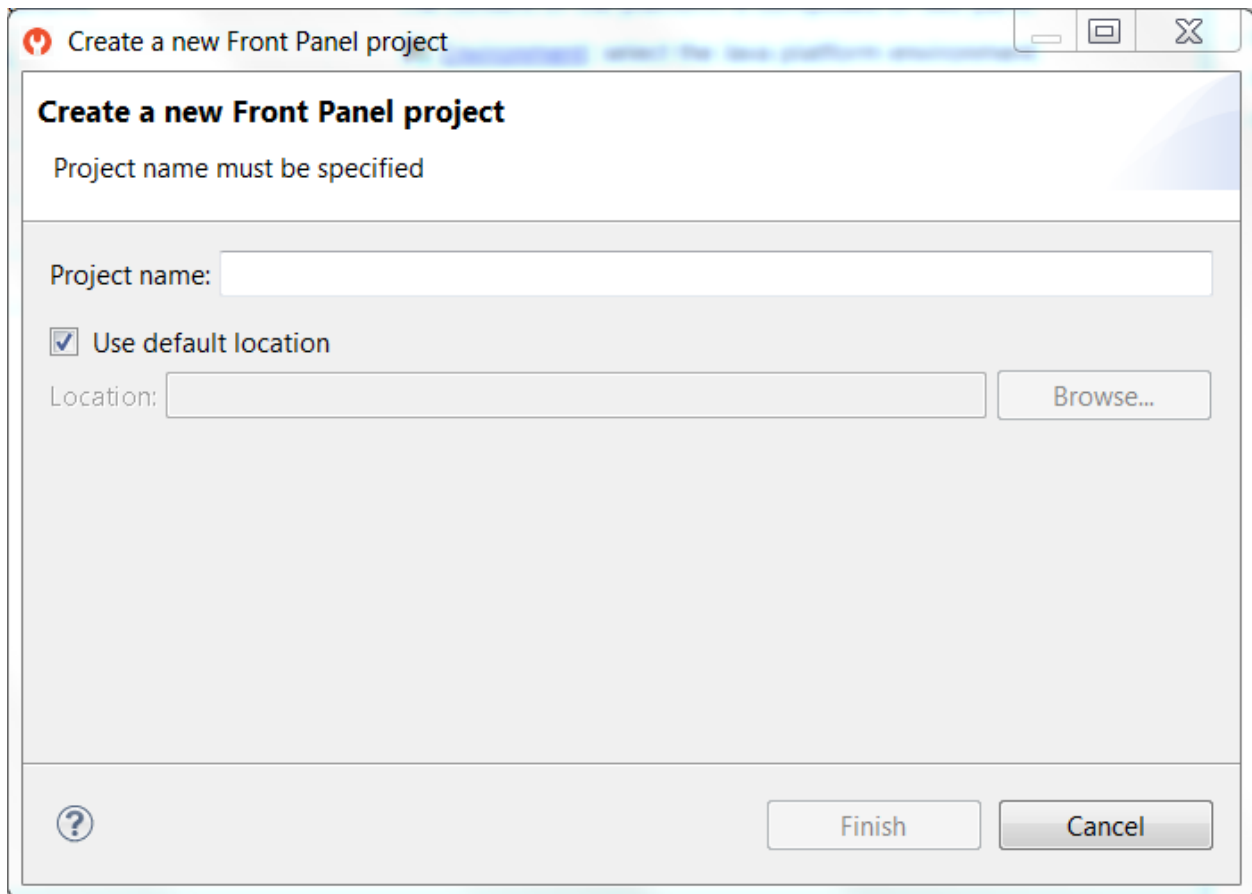


Fig. 52: New Front Panel Project Wizard

Enter the name for the new project.

### Project Contents

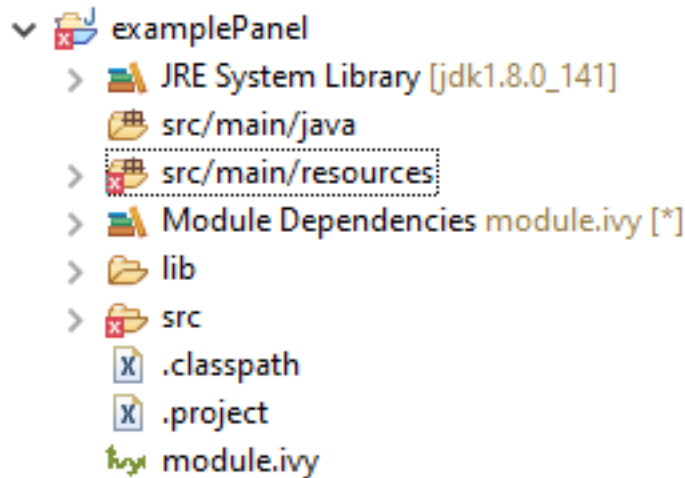


Fig. 53: Project Contents

A Front Panel project has the following structure and contents:

- The `src/main/java` folder is provided for the definition of `Widgets`. It is initially empty. The creation of these classes will be explained later.
- The `src/main/resources` folder holds the file or files that define the contents and layout of the Front Panel, with a `.fp` extension (the fp file or files), plus images used to create the Front Panel. A newly created project will have a single fp file with the same name as the project, as shown above. The contents of fp files are detailed later in this document.
- The `JRE System Library` is referenced, because a Front Panel project needs to support the writing of Java for the `Listeners` (and `DisplayExtensions`).
- The `Modules Dependencies` contains the libraries for the Front Panel simulation, the widgets it supports and the types needed to implement `Listeners` (and `DisplayExtensions`).
- The `lib` contains a local copy of `Modules Dependencies`.

### Module Dependencies

The Front Panel project is a regular MicroEJ Module project. Its `module.ivy` file should look like this example:

```
<ivy-module version="2.0" xmlns:ea="http://www.easyant.org" xmlns:ej="https://developer.microej.com" _
  ↪ej:version="2.0.0">
  <info organisation="com.mycompany" module="examplePanel" status="integration" revision="1.0.0"/>

  <configurations defaultconfmapping="default->default;provided->provided">
    <conf name="default" visibility="public" description="Runtime dependencies to other artifacts"/>
    <conf name="provided" visibility="public" description="Compile-time dependencies to APIs provided_
  ↪by the Platform"/>
  </configurations>
```

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```
<dependencies>
  <dependency org="ej.tool.frontpanel" name="widget" rev="1.0.0"/>
</dependencies>
</ivy-module>
```

The dependency `ej.tool.frontpanel#widget` is only useful for MicroUI application (see [Simulation](#)). The dependencies block must be manually updated to depend only on the Front Panel framework. This framework contains the Front Panel core classes:

```
<dependencies>
  <dependency org="ej.tool.frontpanel" name="framework" rev="1.0.0"/>
</dependencies>
```

The Front Panel framework does not provide any widgets. Widgets have to be added to simulate user interactions.

## Front Panel File

### File Content

The Front Panel engine takes an XML file (the `.fp` file) as input. It describes the panel using widgets: they simulate the drivers, sensors and actuators of the real device. The Front Panel engine generates the graphical representation of the real device, and is displayed in a window on the user's development machine when the application is executed in the Simulator.

The following example file describes a simple board with one LED:

```
<?xml version="1.0"?>
<frontpanel
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns="https://developer.microej.com"
  xsi:schemaLocation="https://developer.microej.com .widget.xsd">

  <device name="MyBoard" skin="myboard.png">
    <ej.fp.widget.LED x="131" y="127" skin="box_led.png"/>
  </device>
</frontpanel>
```

The `device skin` must refer to a `png` file in the `src/main/resources` folder. This image is used to render the background of the Front Panel. The widgets are drawn on top of this background.

The `device` contains the elements that define the widgets that make up the Front Panel. The name of the widget element defines the type of widget. The set of valid types is determined by the Front Panel Designer. Every widget element defines a `label`, which must be unique for widgets of this type (optional or not), and the `x` and `y` coordinates of the position of the widget within the Front Panel (0,0 is top left). There may be other attributes depending on the type of the widget.

The file and tags specifications are available in chapter [Front Panel](#).

---

**Note:** The `.fp` file grammar has changed since the UI Pack version `12.0.0` (Front Panel core has been moved to MicroEJ Architecture `7.11.0`). A quick migration guide is available here: open Platform configuration file `.Platform`, go to `Content` tab, click on module `Front Panel`. The migration guide is available in `Details` box.

---

## Editing Front Panel Files

To edit a `.fp` file, open it using the Eclipse XML editor (right-click on the `.fp` file, select **Open With > XML Editor**). This editor features syntax highlighting and checking, and content-assist based on the schema (XSD file) referenced in the `fp` file. This schema is a hidden file within the project's definitions folder. An incremental builder checks the contents of the `fp` file each time it is saved and highlights problems in the Eclipse Problems view, and with markers on the `fp` file itself.

A preview of the Front Panel can be obtained by opening the Front Panel Preview (**Window > Show View > Other... > MicroEJ > Front Panel Preview**).

The preview is updated each time the `.fp` file is saved.

A typical working layout is shown below.

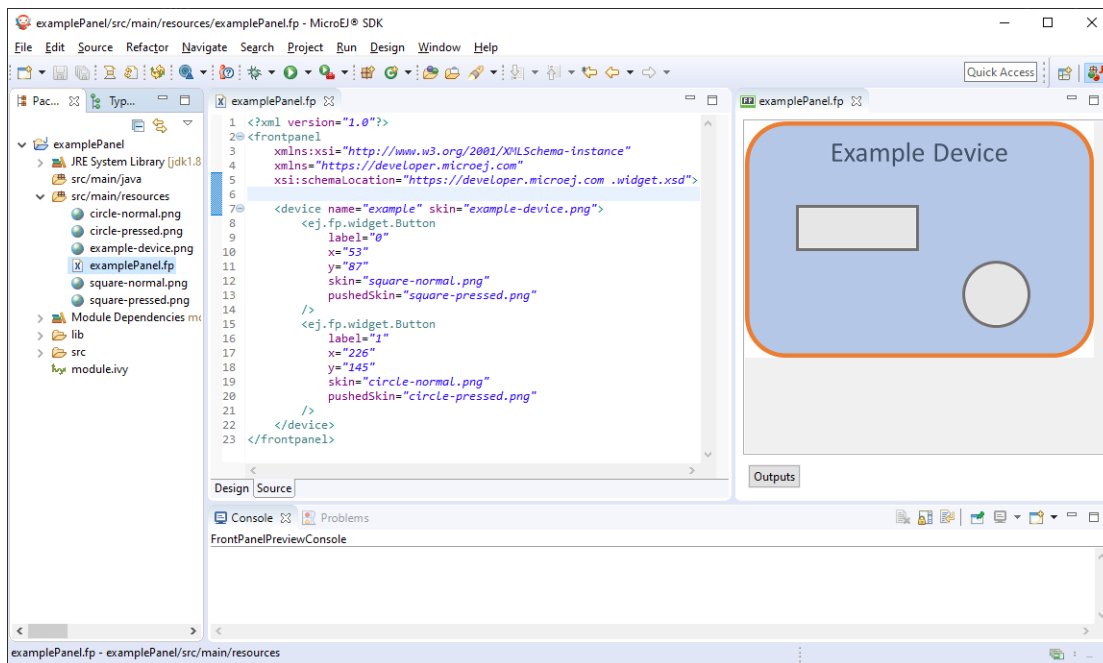


Fig. 54: Working Layout Example

Within the XML editor, content-assist is obtained by pressing **CTRL + SPACE** keys. The editor will list all the elements valid at the cursor position, and insert a template for the selected element.

## Multiple Front Panel Files

A Front Panel project can contain multiple `.fp` files. All `fp` files are compiled when exporting the Front Panel project in a Platform (or during Platform build). It is useful to have two or more representation of a board (size, devices layout, display size etc.). By default the Simulator will chooses the default `.fp` file declared by the Platform, or will defaults to a random one. To choose a specific one, set the *Application Option* `frontpanel.file` to a Front Panel simple file name included in the Platform (e.g. `mycompany.fp`).

## Widget



## Description

A widget is a subclass of Front Panel framework class `ej.fp.Widget`. The library `ej.tool.frontpanel#widget` provides a set of widgets which are graphical engine compatible (see *Simulation*). To create a new widget (or a subclass of an existing widget), have a look on available widgets in this library.

A widget is recognized by the `fp` file as soon as its class contains a `@WidgetDescription` annotation. The annotation contains several `@WidgetAttribute`. An attribute has got a name and tells if it is an optional attribute of widget (by default an attribute is mandatory).

This is the description of the widget `LED`:

```
@WidgetDescription(attributes = { @WidgetAttribute(name = "x"),
    @WidgetAttribute(name = "y"), @WidgetAttribute(name = "skin")})
```

As soon as a widget is created (with its description) in Front Panel project, the `fp` file can use it. Close and reopen `fp` file after creating a new widget. In `device` group, press `CTRL + SPACE` keys to visualize the available widgets: the new widget can be added.

```
<ej.fp.widget.LED x="170" y="753" skin="box_led.png" />
```

Each attribute requires the `set` methods in the widget source code. For instance, the widget `LED` (or its hierarchy) contains the following methods for sure:

- `setX(int)`,
- `setY(int)`,
- `setskin(Image)`.

The `set` method parameter's type fixes the expected value in `fp` file. If the attribute cannot match the expected type, an error is throw when editing `fp` file. Widget master class already provides a set of standard attributes:

- `setFilter(Image)`: apply a filtering image which allows to crop input area (*Input Device Filters*).
- `setWidth(int)` and `setHeight(int)`: limits the widget size.
- `setLabel(String)`: specifies an identifier to the widget.
- `setOverlay(boolean)`: draws widget skin with transparency or not.
- `setSkin(Image)`: specifies the widget skin.
- `setX(int)` and `setY(int)`: specifies widget position.

Notes:

- Widget class does not specify if an attribute is optional or not. It is the responsibility to the subclass.
- The label is often used as identifier. It also allows to retrieve a widget calling `Device.getDevice().getWidget(Class<T>, String)`. Some widgets are using this identifier as an integer label. It is the responsibility to the widget to fix the signification of the label.
- The widget size is often fixed by the its skin (which is an image). See `Widget.finalizeConfiguration()`: it sets the widget size according the skin if the skin has been set; even if methods `setWidth()` and `setHeight()` have been called before.

## Runtime

The Front Panel engine parsing the `fp` file at application runtime. The widget methods are called in two times. First, engine creates widget by widget:

1. widget's constructor: Widget should initialize its own fields which not depend on widget attributes (not valorized yet).
2. `setXXX()` : Widget should check if given attribute value matches the expected behavior (the type has been already checked by caller). For instance if a width is not negative. On error, implementation can throw an `IllegalArgumentException` . These checks must not depend on other attributes because they may have not already valorized.
3. `finalizeConfiguration()` : Widget should check the coherence between all attributes: they are now valorized.

During these three calls, all widgets are not created yet. And so, by definition, the main device (which is a widget) not more. By consequence, the implementation must not try to get the instance of device by calling `Device.getDevice()` . Furthermore, a widget cannot try to get another widget by calling `Device.getDevice().getWidget(s)` . If a widget depend on another widget for any reason, the last checks can be performed in `start()` method. This method is called when all widgets and main device are created. Call to `Device.getDevice()` is allowed.

The method `showYourself()` is only useful when visualizing the `fp` file during its editing (use Eclipse view `Front Panel Preview` ). This method is called when clicking on button `Outputs` .

## Example

The following code is a simple widget LED. MicroEJ Application can interact with it using native methods `on()` and `off()` of class `ej.fp.widget.LED` :

```
package ej.fp.widget;

import ej.fp.Device;
import ej.fp.Image;
import ej.fp.Widget;
import ej.fp.Widget.WidgetAttribute;
import ej.fp.Widget.WidgetDescription;

/**
 * Widget LED declaration. This class must have the same package than
 * <code>LED</code> in MicroEJ application. This is required by the simulator to
 * retrieve the implementation of native methods.
 */
@WidgetDescription(attributes = { @WidgetAttribute(name = "x"), @WidgetAttribute(name = "y"),
    @WidgetAttribute(name = "skin") })
public class LED extends Widget {

    boolean on; // false init

    /**
     * Called by the plugin when clicking on <code>Outputs</code> button from Front
     * Panel Preview.
     */
    @Override
    public void showYourself(boolean appearSwitchedOn) {
        update(appearSwitchedOn);
    }

    /**
     * Called by framework to render the LED.
     */
}
```

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```

@Override
public Image getCurrentSkin() {
    // when LED is off, hide its skin returning null
    return on ? getSkin() : null;
}

/**
 * MicroEJ application native
 */
public static void on() {
    update(true);
}

/**
 * MicroEJ application native
 */
public static void off() {
    update(false);
}

private static void update(boolean on) {

    // retrieve the LED (there is only one LED on device)
    LED led = Device.getDevice().getWidget(LED.class);

    // update its state
    led.on = on;

    // ask to repaint it
    led.repaint();
}
}

```

## Empty Widget

By definition a widget may not contain an attribute. This kind of widget is useful to perform something at Front Panel startup, for instance to start a thread to pick up data somewhere.

The widget description is `@WidgetDescription(attributes = { })`. In `start()` method, a custom behavior can be performed. In `fp` file, the widget declaration is `<com.mycompany.Init/>` (where `Init` is an example of widget name).

## Input Device Filters

The widgets which simulate the input devices use images (or “skins”) to show their current states (pressed and released). The user can change the state of the widget by clicking anywhere on the skin: it is the active area. This active area is, by default, rectangular.

These skins can be associated with an additional image called a `filter`. This image defines the widget’s active area. It is useful when the widget is not rectangular.

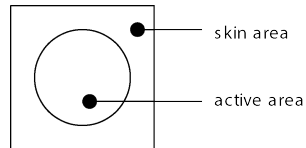


Fig. 55: Active Area

The filter image must have the same size as the skin image. The active area is delimited by the fully opaque pixels. Every pixel in the filter image which is not fully opaque is considered not part of the active area.

## Installation

In the *platform configuration* file, check **Front Panel** to install the Front Panel module. When checked, the properties file `frontpanel > frontpanel.properties` is required during platform creation to configure the module. This configuration step is used to identify and configure the Front Panel.

The properties file must / can contain the following properties:

- `project.name` [mandatory]: Defines the name of the Front Panel project (same workspace as the platform configuration project). If the project name does not exist, a new project will be created.
- `fpFile.name` [optional, default value is "" (empty)]: Defines the Front Panel file (\*.fp) the application has to use by default when several `fp` files are available in project.

To test a Front Panel project without rebuilding the platform or without exporting manually the project, add the *Application Option* `ej.fp.project` to a Front Panel Project absolute path (e.g. `c:\mycompany\myfrontpanel.fp`). The Simulator will use the specified Front Panel project prior to the one included by the Platform.

---

**Note:** This feature works only if the Platform has been built with the Front Panel module enabled.

---

**Warning:** This feature is useful to test locally some changes in Front Panel project. The Platform does not contain the changes until a new Platform is built.

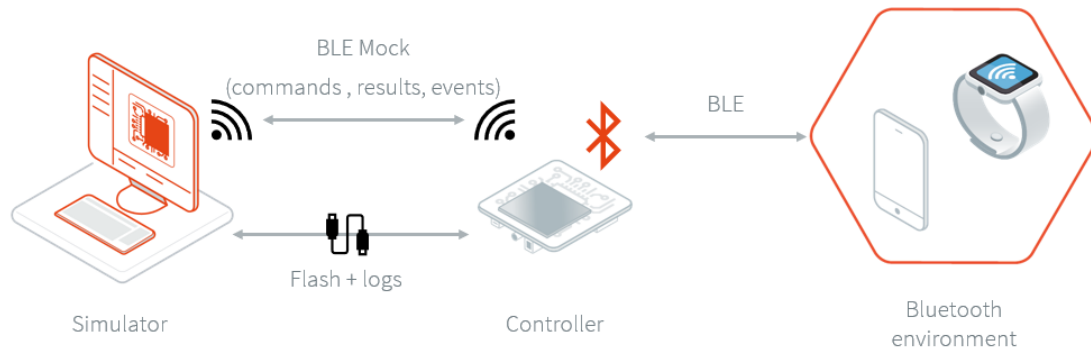
## Use

Launch an application on the Simulator to run the Front Panel.

### 4.14.9 Bluetooth LE Mock

#### Overview

To run a MicroEJ Application that uses the Bluetooth LE Foundation Library (`ej.api.bluetooth`) on MicroEJ Simulator, a Bluetooth LE mock controller must be set up first:



The Bluetooth LE mock controller is a hardware mock of the Bluetooth LE library. It means the Simulator uses a real Bluetooth LE device to scan other devices, advertise, discover services, connect, pair, etc... This design enables testing of apps in a real-world environment.

The Bluetooth LE mock controller implementation is provided for the [ESP32-DevKitC board reference](#). Other implementations or sources can be provided on request.

### Requirements

- A ESP32-DevKitC board.
- A Bluetooth LE mock controller [firmware](#).
- A tool to flash the firmware like <https://www.espressif.com/en/tools-type/flash-download-tools>.

### Usage

To simulate a Bluetooth LE application, follow these three steps:

- Set up the controller
- Set up the network configuration
- Run the application on the Simulator

If you are facing any issues, check the [Troubleshooting](#) section.

### Controller Setup

To set up the controller, follow these steps:

- Plug-in the ESP32-DevKitC board to your computer,
- Find the associated COM port,
- In the flash tool:
  - select the chip “ESP32 DownloadTool”
  - browse for the firmware file
  - set the offset to 0x000000
  - set the COM port
  - set the baudrate to 921 600

- start the flash download

With the flash download tool from Espressif, you should end with something similar to this :

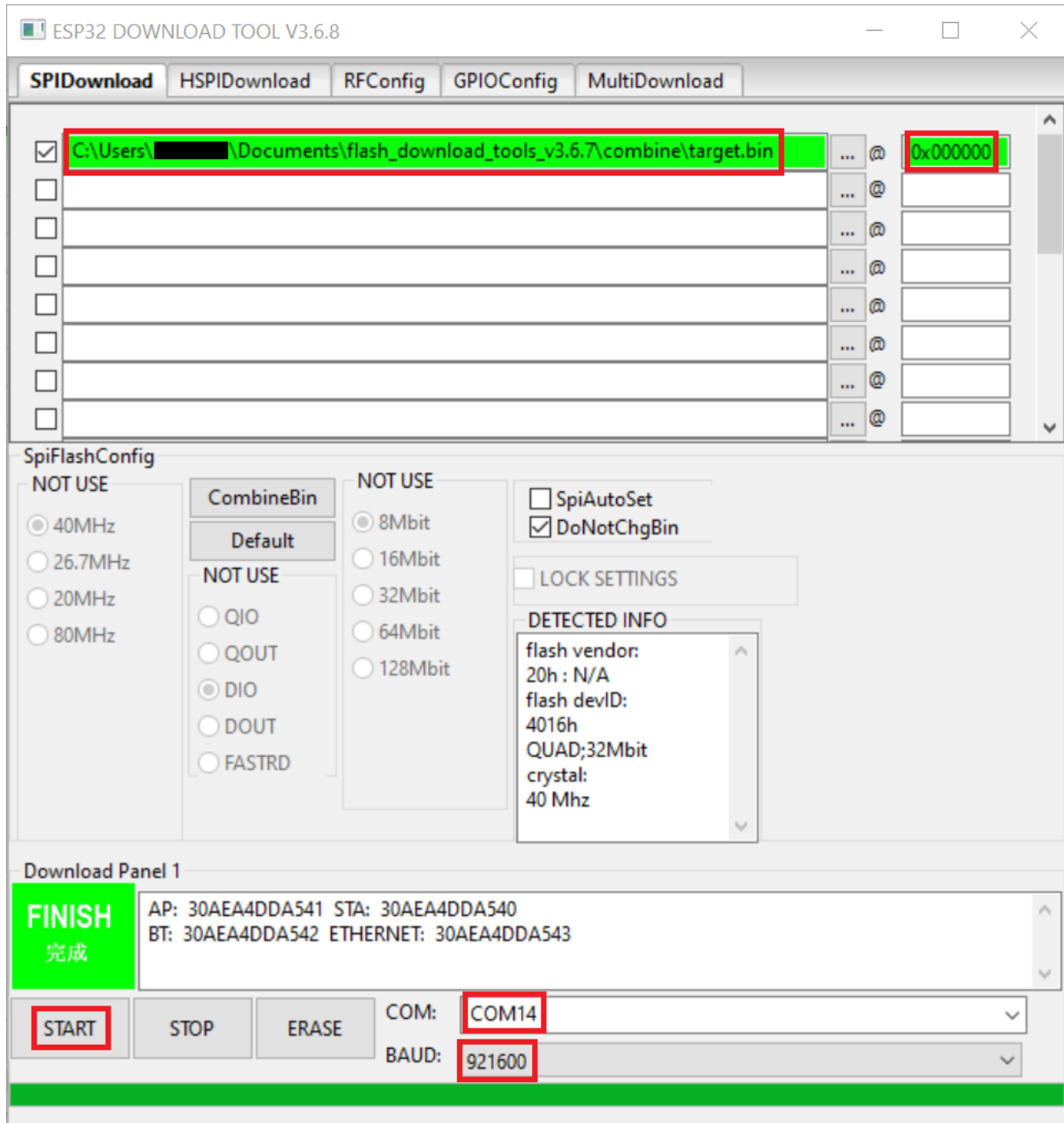


Fig. 56: Bluetooth LE Flash Download Tool Configuration

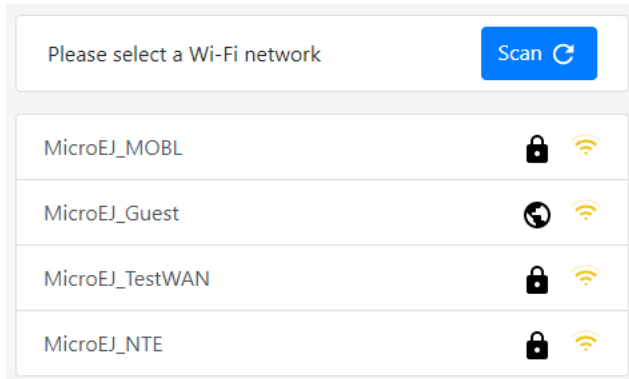
## Network Setup

To configure the network:

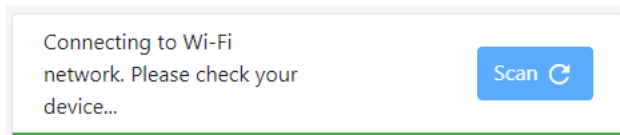
1. Connect your computer to the Wi-Fi network “BLE-Mock-Controller-[hexa device id]” mounted by the con-

troller.

2. Open a browser and connect to <http://192.168.4.1/> to access the Wi-Fi setup interface :



3. Select the desired network and provide the required information if asked. If an error occurs during the connection, retry this step.
4. In case the device is successfully connected to the desired network, the web page should look like this:



Additionally, the serial output of the device shows connection status.

5. Connect your computer back to this network : your computer and the controller must be in the same network.

## Simulation

It is possible to run the Simulator as many times as necessary using the same setup. Also, rebooting the controller will automatically set up the network with the saved configuration.

The IP address of the controller is available in the logs :

Termite 3.4 (by CompuPhase)

COM6 115200 bps, 8N1, no handshake

```

Hoka:F=7 5138 /192.168.4.2
Hoka:I=1
Hoka:F=4 5139 /192.168.4.2
Hoka:F=7 5139 /192.168.4.2
Hoka:I=1
Hoka:F=4 5140 /192.168.4.2
Hoka:I=5 5140 /192.168.4.2 202 Accepted /join
Hoka:F=7 5140 /192.168.4.2
Hoka:I=3
I(117372) wifi: station: 50:eb:71:25:96:71 leave, AID = 1
I(117372) wifi: n:1 0, o:1 1, ap:1 1, sta:255 255, prof:1
[ESP32 Wifi Driver][WARNING] Event 16 received, not treated
I(117402) wifi: flush txq
I(117402) wifi: stop sw txq
I(117402) wifi: lmac stop hw txq
I(117402) wifi: mode : sta (30:ae:a4:dd:91:10)
I(119822) wifi: n:11 0, o:1 0, ap:255 255, sta:11 0, prof:1
I(120372) wifi: state: init -> auth (b0)
I(120382) wifi: state: auth -> assoc (0)
I(120392) wifi: state: assoc -> run (10)
I(120412) wifi: connected with MicroEJ_TestWAN, channel 11
I(120412) wifi: pm start, type: 1

[1B][0:32ml (121772) event: sta ip: 192.168.80.33, mask: 255.255.255.0, gw: 192.168.80.1[1B][0m
ej.bluetooth.bluetoothwificontroller INFO: Succesfully joined the wifi network
ej.bluetooth.bluetoothwificontroller INFO: Saving credentials...
ej.bluetooth.bluetoothwificontroller INFO: Credentials saved
ej.bluetooth.bluetoothwificontroller INFO: Starting server at 192.168.80.33 on port 80
remotecommandserver INFO: Server listening on port 80

```

Before running your Bluetooth LE application on the Simulator, in the *Run configuration* panel, set the simulation mode to “Controller (over net)” and configure the Bluetooth LE mock settings.





Fig. 57: Bluetooth LE Mock Configuration

Launching the application on the Simulator will restore the controller to its initial state (the BLE adapter is disabled).

## Troubleshooting

### Network Setup Errors

#### I can't find the "BLE-Mock-Controller-[hexa device id]" access point

The signal of this Wi-Fi access point may be weaker than the surrounding access points. Try to reduce the distance between the controller and your computer; and rescan. If it's not possible, try using a smartphone instead (only a browser will be required to set up the network configuration).

#### I want to override the network configuration

If the Wi-Fi credentials are not valid anymore, the controller restarts the network setup phase. Yet, in case the credentials are valid but you want to change them, erase the flash and reflash the firmware.

### Simulation Errors

## Error during the simulation : mock could not connect to controller

This error means the mock process (Simulator) could not initialize the connection with the controller. Please check that the device is connected to the network (see logs in the serial port output) and that your computer is in the same network.

## 4.15 Limitations

Table 23: Platform Limitations

Item		EVAL	DEV
Number of Classes		4000	4000
Number of methods per class		3000	65000
Total number of methods		4000	unlimited
Class / Interface hierarchy depth		127 max	127 max
Number of monitors <sup>1</sup> per thread		8 max	8 max
Numbers of exception handlers per method		63 max	63 max
Number of fields	Base type	65000	65000
	References	65000	65000
Number of statics	boolean + byte	limited	65000
	short + char	limited	65000
	int + float	limited	65000
	long + double	limited	65000
	References	limited	65000
Method size		65000	65000
Time limit		60 minutes	unlimited
Number of threads		62	62

## 4.16 Appendices

### 4.16.1 Appendix A: Low Level API

This chapter describes succinctly the available Low Level API, module by module. The exhaustive documentation of each LLAPI function is available in the LLAPI header files themselves. The required header files to implement are automatically copied in the folder `include` of MicroEJ Platform at platform build time.

#### LLMJVM: MicroEJ Core Engine

##### Naming Convention

The Low Level MicroEJ Core Engine API, the `LLMJVM` API, relies on functions that need to be implemented. The naming convention for such functions is that their names match the `LLMJVM_IMPL_*` pattern.

##### Header Files

Three C header files are provided:

<sup>1</sup> No more than n different monitors can be held by one thread at any time.

- LLMJVM\_impl.h  
Defines the set of functions that the BSP must implement to launch and schedule the virtual machine
- LLMJVM.h  
Defines the set of functions provided by virtual machine that can be called by the BSP when using the virtual machine
- LLBSP\_impl.h  
Defines the set of extra functions that the BSP must implement.

## LLKERNEL: Multi-Sandbox

### Naming Convention

The Low Level Kernel API, the **LLKERNEL** API, relies on functions that need to be implemented. The naming convention for such functions is that their names match the **LLKERNEL\_IMPL\_\*** pattern.

### Header Files

One C header file is provided:

- LLKERNEL\_impl.h  
Defines the set of functions that the BSP must implement to manage memory allocation of dynamically installed applications.

## LLSP: Shielded Plug

### Naming Convention

The Low Level Shielded Plug API, the **LLSP** API, relies on functions that need to be implemented. The naming convention for such functions is that their names match the **LLSP\_IMPL\_\*** pattern.

### Header Files

The implementation of the **[SP]** for the MicroEJ Platform assumes some support from the underlying RTOS. It is mainly related to provide some synchronization when reading / writing into Shielded Plug blocks.

- **LLSP\_IMPL\_syncWriteBlockEnter** and **LLSP\_IMPL\_syncWriteBlockExit** are used as a semaphore by RTOS tasks. When a task wants to write to a block, it “locks” this block until it has finished to write in it.
- **LLSP\_IMPL\_syncReadBlockEnter** and **LLSP\_IMPL\_syncReadBlockExit** are used as a semaphore by RTOS tasks. When a task wants to read a block, it “locks” this block until it is ready to release it.

The **[SP] specification** provides a mechanism to force a task to wait until new data has been provided to a block. The implementation relies on functions **LLSP\_IMPL\_wait** and **LLSP\_IMPL\_wakeup** to block the current task and to reschedule it.

## LLEXTR\_RES: External Resources Loader

### Principle

This LLAPI allows to use the External Resource Loader. When installed, the External Resource Loader is notified when the MicroEJ Core Engine is not able to find a resource (an image, a file etc.) in the resources area linked with the MicroEJ Core Engine.

When a resource is not available, the MicroEJ Core Engine invokes the External Resource Loader in order to load an unknown resource. The External Resource Loader uses the LLAPI EXT\_RES to let the BSP loads or not the expected resource. The implementation has to be able to load several files in parallel.

### Naming Convention

The Low Level API, the **LLEXTR\_RES** API, relies on functions that need to be implemented. The naming convention for such functions is that their names match the **LLEXTR\_RES\_IMPL\_\*** pattern.

### Header Files

One header file is provided:

- **LLEXTR\_RES\_impl.h**

Defines the set of functions that the BSP must implement to load some external resources.

## LLCOMM: Serial Communications

### Naming Convention

The Low Level Comm API (LLCOMM), relies on functions that need to be implemented by engineers in a driver. The names of these functions match the **LLCOM\_BUFFERED\_CONNECTION\_IMPL\_\*** or the **LLCOM\_CUSTOM\_CONNECTION\_IMPL\_\*** pattern.

### Header Files

Four C header files are provided:

- **LLCOMM\_BUFFERED\_CONNECTION\_impl.h**

Defines the set of functions that the driver must implement to provide a Buffered connection

- **LLCOMM\_BUFFERED\_CONNECTION.h**

Defines the set of functions provided by ECOM Comm that can be called by the driver (or other C code) when using a Buffered connection

- **LLCOMM\_CUSTOM\_CONNECTION\_impl.h**

Defines the set of functions that the driver must implement to provide a Custom connection

- **LLCOMM\_CUSTOM\_CONNECTION.h**

Defines the set of functions provided by ECOM Comm that can be called by the driver (or other C code) when using a Custom connection

## LLINPUT: Inputs

LLINPUT API is composed of the following files:

- the file `LLINPUT_impl.h` that defines the functions to be implemented
- the file `LLINPUT.h` that provides the functions for sending events

## Implementation

`LLINPUT_IMPL_initialize` is the first function called by the input stack, and it may be used to initialize the underlying devices and bind them to event generator IDs.

`LLINPUT_IMPL_enterCriticalSection` and `LLINPUT_IMPL_exitCriticalSection` need to provide the stack with a critical section mechanism for synchronizing devices when sending events to the internal event queue. The mechanism used to implement the synchronization will depend on the platform configuration (with or without RTOS), and whether or not events are sent from an interrupt context.

`LLINPUT_IMPL_getInitialStateValue` allows the input stack to get the current state for devices connected to the MicroUI States event generator, such as switch selector, coding wheels, etc.

## Sending Events

The `LLINPUT` API provides two generic functions for a C driver to send data to its associated event generator:

- `LLINPUT_sendEvent` : Sends a 32-bit encoded event to a specific event generator, specified by its ID. If the input buffer is full, the event is not added, and the function returns 0; otherwise it returns 1.
- `LLINPUT_sendEvents` : Sends event data to a specific event generator, specified by its ID. If the input buffer cannot receive the whole data, the event is not added, and the function returns 0; otherwise it returns 1.

Events will be dispatched to the associated event generator that will be responsible for decoding them (see *Generic Event Generators*).

The UI extension provides an implementation for each of MicroUI's built-in event generators. Each one has dedicated functions that allows a driver to send them structured data without needing to understand the underlying protocol to encode/decode the data. *The following table* shows the functions provided to send structured events to the predefined event generators:

Table 24: LLINPUT API for predefined event generators

Function name	Default event generator kind <sup>1</sup>	Comments
<code>LLINPUT_sendCommandEvent</code>	Command	Constants are provided that define all standard MicroUI commands [MUI].
<code>LLINPUT_sendButtonPressedEvent</code> <code>LLINPUT_sendButtonReleasedEvent</code> <code>LLINPUT_sendButtonRepeatedEvent</code>	Buttons	In the case of chronological sequences (for example, a RELEASE that may occur only after a PRESSED), it is the responsibility of the driver to ensure the integrity of such sequences.
<code>LLINPUT_sendPointerPressedEvent</code> <code>LLINPUT_sendPointerReleasedEvent</code>  <code>LLINPUT_sendPointerMovedEvent</code>	Pointer	In the case of chronological sequences (for example, a RELEASE that may occur only after a PRESSED), it is the responsibility of the driver to ensure the integrity of such sequences. Depending on whether a button of the pointer is pressed while moving, a DRAG and/or a MOVE MicroUI event is generated.
<code>LLINPUT_sendStateEvent</code>	States	The initial value of each state machine (of a States) is retrieved by a call to <code>LLINPUT_IMPL_getInitialStateValue</code> that must be implemented by the device. Alternatively, the initial value can be specified in the XML static configuration.
<code>LLINPUT_sendTouchPressedEvent</code> <code>LLINPUT_sendTouchReleasedEvent</code> <code>LLINPUT_sendTouchMovedEvent</code>	Pointer	In the case of chronological sequences (for example, a RELEASE that may only occur after a PRESSED), it is the responsibility of the driver to ensure the integrity of such sequences. These APIs will generate a DRAG MicroUI event instead of a MOVE while they represent a touch pad over a display.

## Event Buffer

The maximum usage of the internal event buffer may be retrieved at runtime using the `LLINPUT_getMaxEventsBufferUsage` function. This is useful for tuning the size of the buffer.

## LLDISPLAY

### LLDISPLAY: Display

#### Principle & Naming Convention

Each display stack provides a low level API in order to connect a display driver. The file `LLDISPLAY_impl.h` defines the API headers to be implemented. For the APIs themselves, the naming convention is that their names match the `*_IMPL_*` pattern when the functions need to be implemented.

<sup>1</sup> The implementation class is a subclass of the MicroUI class of the column.

## Initialization

Each display stack gets initialized the same way:

- First, the function `LLDISPLAY_IMPL_initialize` is called: It asks its display driver to initialize itself.
- Second, the functions `LLDISPLAY_IMPL_getWidth` and `LLDISPLAY_IMPL_getHeight` are called to retrieve the size of the physical screen.

## Working Buffer

The display driver must allocate a runtime memory buffer for creating dynamic images when using MicroUI `Image.createImage()` methods that explicitly create mutable images.

The display driver may choose to return an empty buffer. Thus, calling MicroUI `Image.createImage()` methods will result in a `java.lang.OutOfMemoryError` exception.

`LLDISPLAY_getWorkingBufferStartAddress` returns the buffer start address.  
`LLDISPLAY_getWorkingBufferEndAddress` returns the next address after the buffer (end-start is the buffer length).

## Flush and Synchronization

Function `LLDISPLAY_getGraphicsBufferAddress` returns the address of the graphics buffer (back buffer) for the very first drawing. The content of this buffer is flushed to the external display memory by the function `LLDISPLAY_flush`. The parameters define the rectangular area of the content which has changed during the last drawing action, and which must be flushed to the display buffer (dirty area).

`LLDISPLAY_synchronize` is called before the next drawing after a call to the flush function, in order to avoid flickering on the display device.

## LLDISPLAY\_EXTRA: Display Extra Features

### Principle

An additional low level API allows you to connect display extra features. The files `LLDISPLAY_EXTRA_impl.h` define the API headers to be implemented. For the APIs themselves, the naming convention is that their names match the `*_IMPL*` pattern when the functions must be implemented. These LLAPIs are not required. When they are not implemented, a default implementation is used (weak function).

### Display Characteristics

Function `LLDISPLAY_EXTRA_IMPL_isColor` directly implements the method from the MicroUI `Display` class of the same name. The default implementation always returns `LLDISPLAY_EXTRA_OK`.

Function `LLDISPLAY_EXTRA_IMPL_getNumberOfColors` directly implements the method from the MicroUI `Display` class of the same name. The default implementation returns a value according to the number of bits by pixels, without taking into consideration the alpha bit(s).

Function `LLDISPLAY_EXTRA_IMPL_isDoubleBuffered` directly implements the method from the MicroUI `Display` class of the same name. The default implementation returns `LLDISPLAY_EXTRA_OK`. When LLAPI implementation targets a LCD in `direct` mode, this function must be implemented and return `LLDISPLAY_EXTRA_NOT_SUPPORTED`.

## Contrast

`LLDISPLAY_EXTRA_IMPL_setContrast` and `DISPLAY_EXTRA_IMPL_getContrast` are called to set/get the current display contrast intensity. The default implementations don't manage the contrast.

## BackLight

`LLDISPLAY_EXTRA_IMPL_hasBackLight` indicates whether the display has backlight capabilities.

`LLDISPLAY_EXTRA_IMPL_setBackLight` and `DISPLAY_EXTRA_IIMPL_getBackLight` are called to set/get the current display backlight intensity.

`LLDISPLAY_EXTRA_IMPL_backlightOn` and `LLDISPLAY_EXTRA_IMPL_backlightOff` enable/disable the backlight. The default implementations don't manage the backlight.

## Color Conversions

`LLDISPLAY_EXTRA_IMPL_convertARGBColorToDisplayColor` is called to convert a 32-bit ARGB MicroUI color in `0xAARRGGBB` format into the "driver" display color.

`LLDISPLAY_EXTRA_IMPL_convertDisplayColorToARGBColor` is called to convert a display color to a 32-bit ARGB MicroUI color.

## Drawings

### Synchronization

The display stack calls the functions `LLDISPLAY_EXTRA_IMPL_enterDrawingMode` and `LLDISPLAY_EXTRA_IMPL_exitDrawingMode` to enter / leave a critical section. This is useful when some drawings are performed in C-side using the `LLDISPLAY_UTILS` API. This function implementation can stay empty when there is no call from C-side, or when the calls from C-side are performed in the same OS task, rather than in the MicroEJ Core Engine task. By default these functions do nothing.

### LUT

The function `LLDISPLAY_EXTRA_IMPL_prepareBlendingOfIndexedColors` is called when drawing an image with indexed color. See [LUT](#) to have more information about indexed images.

### Hardware Accelerator

Some functions allow you to use an hardware accelerator to perform some drawings: `LLDISPLAY_EXTRA_IMPL_fillRect`, `LLDISPLAY_EXTRA_IMPL_drawImage`, `LLDISPLAY_EXTRA_IMPL_scaleImage` and `LLDISPLAY_EXTRA_IMPL_rotateImage`. When called, the LLDISPLAY *must* perform the drawing (see *Hardware Accelerator*). Otherwise a call to `LLDISPLAY_EXTRA_IMPL_error` will be performed with an error code as parameter (see `LLDISPLAY_EXTRA`). Furthermore, the drawing will be not performed by software.

A drawing may be executed directly during the call of the relative function (synchronous execution), may be executed by a hardware peripheral like a DMA (asynchronous execution), or may be executed by a dedicated OS task (asynchronous execution). When the drawing is synchronous, the function must return



`LLDISPLAY_EXTRA_DRAWING_COMPLETE` , which indicates the drawing is complete. When the drawing is asynchronous, the function must return `LLDISPLAY_EXTRA_DRAWING_RUNNING` , which indicates that the drawing is running. In this case, the very next drawing (with or without hardware acceleration) will be preceded by a specific call in order to synchronize the display stack work with the end of hardware drawing. The function used to wait for the end of drawing is `LLDISPLAY_EXTRA_IMPL_waitPreviousDrawing` .

The default implementations call the error function.

## Structures

The drawing functions are using some `struct` to specify the drawing to perform. These structures are listed in `LLDISPLAY_EXTRA_drawing.h` . Refer to this h file have the exhaustive list of structures and structures elements.

- `int32_t LLDISPLAY_EXTRA_IMPL_fillRect(LLDISPLAY_SImage* dest, int32_t destAddr, LLDISPLAY_SRectangle* rect, int32_t color)`
- `int32_t LLDISPLAY_EXTRA_IMPL_drawImage(LLDISPLAY_SImage* src, int32_t srcAddr, LLDISPLAY_SImage* dest, int32_t destAddr, LLDISPLAY_SDrawImage* drawing)`
- `int32_t LLDISPLAY_EXTRA_IMPL_scaleImage(LLDISPLAY_SImage* src, int32_t srcAddr, LLDISPLAY_SImage* dest, int32_t destAddr, LLDISPLAY_SScaleImage* drawing)`
- `int32_t LLDISPLAY_EXTRA_IMPL_rotateImage(LLDISPLAY_SImage* src, int32_t srcAddr, LLDISPLAY_SImage* dest, int32_t destAddr, LLDISPLAY_SRotateImage* drawing)`

## Image Decoders

The API `LLDISPLAY_EXTRA_IMPL_decodeImage` allows to add some additional image decoders (see *External Decoders*). This LLAPI uses some structures as parameter:

```
int32_t LLDISPLAY_EXTRA_IMPL_decodeImage(int32_t address, int32_t length, int32_t expected_format, LLDISPLAY_SImage* image, LLDISPLAY_SRawImageData* image_data)
```

## LLDISPLAY\_UTILS: Display Utils

### Principle

This header file lets some APIs in C-side perform some drawings in the same buffers used by the display stack. This is very useful for reusing legacy code, performing a specific drawing, etc.

### Synchronization

Every drawing performed in C-side must be synchronized with the display stack drawings. The idea is to force the display stack to wait the end of previous asynchronous drawings before drawing anything else. Use the functions `enterDrawingMode` and `exitDrawingMode` to enter / leave a critical section.

### Buffer Characteristics

A set of functions allow retrieval of several characteristics of an image (or the display buffer itself). These functions use a parameter to identify the image: the image Java object hash code ( `myImage.hashCode()` or `myGraphicsContext.hashCode()` ).

The function `getBufferAddress` returns the address of the image data buffer. This buffer can be located in runtime memory (RAM, SRAM, SDRAM, etc.) or in read-only memory (internal flash, NOR, etc.).

The functions `getWidth` and `getHeight` return the size of the image / graphics context.

The function `getFormat` returns the format of the image / graphics context. The formats list is available in `MicroUI.GraphicsContext` class.

The functions `getClipX1`, `getClipX2`, `getClipY1` and `getClipY2` return the current clip of the image / graphics context. The C-side drawing can use the clip limits (this is optional).

## Drawings

A set of functions allows you to use internal display stack functions to draw something on an image (or in the display buffer itself). These functions use a parameter to identify the image: the image Java object hash code ( `myImage.hashCode()` or `myGraphicsContext.hashCode()` ).

The basic functions `drawPixel` and `readPixel` are useful for drawing or reading a pixel. The function `blend` allows you to blend two colors and a global alpha.

The C-side can change the current clip of an image / graphics context only in the display stack. The clip is not updated in MicroUI. Use the function `setClip` to do this.

A C-side drawing has to update the drawing limits (before or after the drawing itself), using the function `setDrawingLimits` when the drawing is made in the display back buffer. This allows you to update the size of the dirty area the display stack has to flush. If it is not updated, the C-side drawing (available in back buffer) may never be flushed to the display graphical memory.

## Allocation

When decoding an image with an external image decoder (see *External Decoders*), the C-side has to allocate a RAW image in the working buffer. The function `LLDISPLAY_UTILS_allocateRawImage` takes as parameter a structure which describes the image (size and format) and an output structure where it stores the image allocation data:

```
int32_t LLDISPLAY_UTILS_allocateRawImage(LLDISPLAY_SImage* image, LLDISPLAY_SRawImageData* image_data)
```

This function can also be used by C-side to allocate a RAW image in the working buffer. This image will not be known by MicroUI but this image can be used in C-side.

## LLLEDS: LEDs

### Principle

The LEDs stack provides a Low Level API for connecting LED drivers. The file `LLLEDS_impl.h`, which comes with the LEDs stack, defines the API headers to be implemented.

### Naming Convention

The Low Level API relies on functions that must be implemented. The naming convention for such functions is that their names match the `*_IMPL_*` pattern.

## Initialization

The first function called is `LLLEDS_IMPL_initialize`, which allows the driver to initialize all LED devices. This method must return the number of LEDs available.

Each LED has a unique identifier. The first LED has the ID 0, and the last has the ID `NbLEDs - 1`.

This UI extension provides support to efficiently implement the set of methods that interact with the LEDs provided by a device. Below are the relevant C functions:

- `LLLEDS_IMPL_getIntensity`: Get the intensity of a specific LED using its ID.
- `LLLEDS_IMPL_setIntensity`: Set the intensity of an LED using its ID.

## LLNET: Network

### Naming Convention

The Low Level API, the `LLNET` API, relies on functions that need to be implemented. The naming convention for such functions is that their names match the `LLNET_IMPL_*` pattern.

### Header Files

Several header files are provided:

- `LLNET_CHANNEL_impl.h`  
Defines a set of functions that the BSP must implement to initialize the Net native component. It also defines some configuration operations to setup a network connection.
- `LLNET_SOCKETCHANNEL_impl.h`  
Defines a set of functions that the BSP must implement to create, connect and retrieve information on a network connection.
- `LLNET_STREAMSOCKETCHANNEL_impl.h`  
Defines a set of functions that the BSP must implement to do some I/O operations on connection oriented socket (TCP). It also defines function to put a server connection in accepting mode (waiting for a new client connection).
- `LLNET_DATAGRAMSOCKETCHANNEL_impl.h`  
Defines a set of functions that the BSP must implement to do some I/O operations on connectionless oriented socket (UDP).
- `LLNET_DNS_impl.h`  
Defines a set of functions that the BSP must implement to request host IP address associated to a host name or to request Domain Name Service (DNS) host IP addresses setup in the underlying system.
- `LLNET_NETWORKADDRESS_impl.h`  
Defines a set of functions that the BSP must implement to convert string IP address or retrieve specific IP addresses (lookup, localhost or loopback IP address).
- `LLNET_NETWORKINTERFACE_impl.h`  
Defines a set of functions that the BSP must implement to retrieve information on a network interface (MAC address, interface link status, etc.).

## LLNET\_SSL: SSL

### Naming Convention

The Low Level API, the `LLNET_SSL` API, relies on functions that need to be implemented. The naming convention for such functions is that their names match the `LLNET_SSL_*` pattern.

### Header Files

Three header files are provided:

- `LLNET_SSL_CONTEXT_impl.h`  
Defines a set of functions that the BSP must implement to create a SSL Context and to load CA (Certificate Authority) certificates as trusted certificates.
- `LLNET_SSL_SOCKET_impl.h`  
Defines a set of functions that the BSP must implement to initialize the SSL native components, to create an underlying SSL Socket and to initiate a SSL session handshake. It also defines some I/O operations such as `LLNET_SSL_SOCKET_IMPL_write` or `LLNET_SSL_SOCKET_IMPL_read` used for encrypted data exchange between the client and the server.
- `LLNET_SSL_X509_CERT_impl.h`  
Defines a function named `LLNET_SSL_X509_CERT_IMPL_parse` for certificate parsing. This function checks if a given certificate is an X.509 digital certificate and returns its encoded format type : Distinguished Encoding Rules (DER) or Privacy-Enhanced Mail (PEM).

## LLFS: File System

### Naming Convention

The Low Level File System API (LLFS), relies on functions that need to be implemented by engineers in a driver. The names of these functions match the `LLFS_IMPL_*` and the `LLFS_File_IMPL_*` pattern.

### Header Files

Two C header files are provided:

- `LLFS_impl.h`  
Defines a set of functions that the BSP must implement to initialize the FS native component. It also defines some functions to manage files, directories and retrieve information about the underlying File System (free space, total space, etc.).
- `LLFS_File_impl.h`  
Defines a set of functions that the BSP must implement to do some I/O operations on files (open, read, write, close, etc.).

## LLHAL: Hardware Abstraction Layer

### Naming Convention

The Low Level API, the **LLHAL** API, relies on functions that need to be implemented. The naming convention for such functions is that their names match the **LLHAL\_IMPL\_\*** pattern.

### Header Files

One header file is provided:

- **LLHAL\_impl.h**

Defines the set of functions that the BSP must implement to configure and drive some MCU GPIO.

## LLDEVICE: Device Information

### Naming Convention

The Low Level Device API (LLDEVICE), relies on functions that need to be implemented by engineers in a driver. The names of these functions match the **LLDEVICE\_IMPL\_\*** pattern.

### Header Files

One C header file is provided:

- **LLDEVICE\_impl.h**

Defines a set of functions that the BSP must implement to get the platform architecture name and unique device identifier.

## 4.16.2 Appendix B: MicroEJ Foundation Libraries

### EDC

#### Error Messages

When an exception is thrown by the runtime, the error message

**Generic:E=<messageId>**

is issued, where **<messageId>** meaning is defined in the next table:

Table 25: Generic Error Messages

Message ID	Description
1	Negative offset.
2	Negative length.
3	Offset + length > object length.

When an exception is thrown by the implementation of the EDC API, the error message

**EDC-1.2:E=<messageId>**

is issued, where `<messageId>` meaning is defined in the next table:

Table 26: EDC Error Messages

Message ID	Description
-4	No native stack found to execute the Java native method.
-3	Maximum stack size for a thread has been reached. Increase the maximum size of the thread stack parameter.
-2	No Java stack block could be allocated with the given size. Increase the Java stack block size.
-1	The Java stack space is full. Increase the Java stack size or the number of Java stack blocks.
1	A closed stream is being written/read.
2	The operation <code>Reader.mark()</code> is not supported.
3	<code>lock</code> is <code>null</code> in <code>Reader(Object lock)</code> .
4	String index is out of range.
5	Argument must be a positive number.
6	Invalid radix used. Must be from <code>Character.MIN_RADIX</code> to <code>Character.MAX_RADIX</code> .

## Exit Codes

The RTOS task that runs the MicroEJ runtime may end, especially when the MicroEJ Application calls `System.exit` method. By convention, a negative value indicates abnormal termination.

Table 27: MicroEJ Platform exit codes

Message ID	Meaning
0	The MicroEJ Application ended normally.
-1	The SOAR and the MicroEJ Platform are not compatible.
-2	Incompatible link configuration ( <code>lsc</code> file) with either the SOAR or the MicroEJ Platform.
-3	Evaluation version limitations reached: termination of the application.
-5	Not enough resources to start the very first MicroEJ thread that executes <code>main</code> method.
-12	Maximum number of threads reached.
-13	Fail to start the MicroEJ Platform because the specified MicroEJ heap is too large.
-14	Invalid stack space due to a link placement error.
-15	The application has too many static (the requested static head is too large).
-16	The MicroEJ Core Engine cannot be restarted.

## SNI

### Error Messages

The following error messages are issued at runtime.

Table 28: [SNI] Run Time Error Messages.

Message ID	Description
-1	Not enough blocks.
-2	Reserved.
-3	Max stack blocks per thread reached.

**KF****Definitions****Feature Definition Files**

A Feature is a group of types, resources and *[BON]* immutable objects defined using two files that shall be in application classpath:

- *[featureName].kf* , a Java properties file. Keys are described in *the “Feature definition file properties” table below*.
- *[featureName].cert* , an X509 certificate file that uniquely identifies the Feature

Table 29: Feature definition file properties

Key	Usage	Description
entryPoint	Mandatory	The fully qualified name of the class that implements <code>ej.kf.FeatureEntryPoint</code>
immutables	Optional	Semicolon separated list of paths to <i>[BON]</i> immutable files owned by the Feature. <i>[BON]</i> immutable file is defined by a / separated path relative to application classpath
resources	Optional	Semicolon separated list of resource names owned by the Feature. Resource name is defined by <code>Class.getResourceAsStream(String)</code>
requiredTypes	Optional	Comma separated list of fully qualified names of required types. (Types that may be dynamically loaded using <code>Class.forName()</code> ).
types	Optional	Comma separated list of fully qualified names of types owned by the Feature. A wildcard is allowed as terminal character to embed all types starting with the given qualified name ( <code>a.b.C,x.y.*</code> )
version	Mandatory	String version, that can retrieved using <code>ej.kf.Module.getVersion()</code>

**Kernel Definition Files**

Kernel definition files are mandatory if one or more Feature definition file is loaded and are named `kernel.kf` and `kernel.cert` . `kernel.kf` must only define the `version` key. All types, resources and immutables are automatically owned by the Kernel if not explicitly set to be owned by a Feature.

**Kernel API Definition**

Kernel types, methods and static fields allowed to be accessed by Features must be declared in `kernel.api` file. Kernel API file is an XML file (see *example “Kernel API XML Schema”* and *table “XML elements specification”*).

Listing 10: Kernel API XML Schema

```
<xs:schema xmlns:xs='http://www.w3.org/2001/XMLSchema'>
  <xs:element name='require'>
    <xs:complexType>
      <xs:choice minOccurs='0' maxOccurs='unbounded'>
        <xs:element ref='type' />
        <xs:element ref='field' />
        <xs:element ref='method' />
      </xs:choice>
    </xs:complexType>
  </xs:element>
</xs:schema>
```

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```

</xs:element>

<xs:element name='type'>
  <xs:complexType>
    <xs:attribute name='name' type='xs:string' use='required' />
  </xs:complexType>
</xs:element>

<xs:element name='field'>
  <xs:complexType>
    <xs:attribute name='name' type='xs:string' use='required' />
  </xs:complexType>
</xs:element>

<xs:element name='method'>
  <xs:complexType>
    <xs:attribute name='name' type='xs:string' use='required' />
  </xs:complexType>
</xs:element>
</xs:schema>

```

Table 30: XML elements specification

Tag	Attributes	Description
require		The root element
field		Static field declaration. Declaring a field as a Kernel API automatically sets the declaring type as a Kernel API
	name	Fully qualified name on the form <code>[type].[fieldName]</code>
method		Method or constructor declaration. Declaring a method or a constructor as a Kernel API automatically sets the declaring type as a Kernel API
	name	Fully qualified name on the form <code>[type].[methodName]([typeArg1,...,typeArgN])typeReturned</code> . Types are fully qualified names or one of a base type as described by the Java language ( <code>boolean</code> , <code>byte</code> , <code>char</code> , <code>short</code> , <code>int</code> , <code>long</code> , <code>float</code> , <code>double</code> ) When declaring a constructor, <code>methodName</code> is the single type name. When declaring a void method or a constructor, <code>typeReturned</code> is <code>void</code>
type		Type declaration, allowed to be loaded from a Feature using <code>Class.forName()</code>
	name	Fully qualified name on the form <code>[package].[package].[typeName]</code>

## Access Error Codes

When an instruction is executed that will break a *[KF]* insulation semantic rule, a `java.lang.IllegalAccessError` is thrown, with an error code composed of two parts: `[source][errorKind]`.

- **source** : a single character indicating the kind of Java element on which the access error occurred (*Table “Error codes: source”*)
- **errorKind** : an error number indicating the action on which the access error occurred (*Table “Error codes: kind”*)



Table 31: Error codes: source

Character	Description
A	Error thrown when accessing an array
I	Error thrown when calling a method
F	Error thrown when accessing an instance field
M	Error thrown when entering a synchronized block or method
P	Error thrown when passing a parameter to a method call
R	Error thrown when returning from a method call
S	Error thrown when accessing a static field

Table 32: Error codes: kind

Id	Description
1	An object owned by a Feature is being assigned to an object owned by the Kernel, but the current context is not owned by the Kernel
2	An object owned by a Feature is being assigned to an object owned by another Feature
3	An object owned by a Feature is being accessed from a context owned by another Feature
4	A synchronize on an object owned by the Kernel is executed in a method owned by a Feature
5	A call to a feature code occurs while owning a Kernel monitor

## Loading Features Dynamically

Features may be statically embedded with the Kernel or dynamically built against a Kernel. To build a Feature binary file, select **Build Dynamic Feature** MicroEJ Platform **Execution** tab. The generated file can be dynamically loaded by the Kernel runtime using `ej.kf.Kernel.load(InputStream)`.

## ECOM

### Error Messages

When an exception is thrown by the implementation of the ECOM API, the error message

`ECOM-1.1:E=<messageId>`

is issued, where `<messageId>` meaning is defined in the next table:

Table 33: ECOM Error Messages

Message ID	Description
1	The connection has been closed. No more action can be done on this connection.
2	The connection has already been closed.
3	The connection description is invalid. The connection cannot be opened.
4	The connection stream has already been opened. Only one stream per kind of stream (input or output stream) can be opened at the same time.
5	Too many connections have been opened at the same time. The platform is not able to open a new one. Try to close useless connections before trying to open the new connection.

### ECOM Comm

## Error Messages

When an exception is thrown by the implementation of the ECOM-COMM API, the error message

`ECOM-COMM:E=<messageId>`

is issued, where `<messageId>` meaning is defined in the next table:

Table 34: ECOM-COMM error messages

Message ID	Description
1	The connection descriptor must start with <code>"comm: "</code>
2	Reserved.
3	The Comm port is unknown.
4	The connection descriptor is invalid.
5	The Comm port is already open.
6	The baudrate is unsupported.
7	The number of bits per character is unsupported.
8	The number of stop bits is unsupported.
9	The parity is unsupported.
10	The input stream cannot be opened because native driver is not able to create a RX buffer to store the incoming data.
11	The output stream cannot be opened because native driver is not able to create a TX buffer to store the outgoing data.
12	The given connection descriptor option cannot be parsed.

## MicroUI

### Error Messages

When an exception is thrown by the implementation of the MicroUI API, the exception `MicroUIException` with the error message

`MicroUI:E=<messageId>`

is issued, where the meaning of `<messageId>` is defined in *Table "MicroUI Error Messages"*.

Table 35: MicroUI Error Messages

Message ID	Description
1	Deadlock. Cannot wait for an event in the same thread that runs events. <b>Display.waitForEvent()</b> must not be called in the display pump thread (for example in <b>paint</b> methods).
3	Out of memory. Not enough memory to allocate the <b>Image</b> 's buffer. Try to remove references on useless images and retry opening the new image, or increase the size of the MicroUI working buffer.
4	A polygon cannot have more than 16 sides.
5	The platform cannot allocate memory to create a dynamic image.
6	<b>Image</b> 's path is limited to 100 characters.
7	The platform cannot decode this kind of image, because the required runtime image decoder is not available in the platform.
8	Another <b>EventGenerator</b> cannot be added into the system pool (max 254).
9	Font's path is limited to 100 characters.
10	Invalid font path: cannot load this font.
11	MicroUI is not started; call MicroUI.start() before using a MicroUI API.
15	<b>FIFOPump</b> size must be positive
16	<b>FlyingImage</b> feature is disabled in MicroEJ launch options; cannot use this feature in application.
17	Out of memory. There is not enough memory to open a new <b>FlyingImage</b> Try to increase the number of concurrent flying images in the MicroEJ launcher.
19	Font's path must be relative to the classpath.
20	Unknown event generator class name.
21	The font data cannot be loaded for an unknown reason (font is stored outside the CPU address space range).

## Exceptions

Some other exceptions can be thrown by the MicroUI framework in addition to the generic **MicroUIException** (see previous chapter).

Table 36: MicroUI Exceptions

Message ID	Description
OutOfEventsException	<p>This exception is thrown when the pump of the internal thread <b>DisplayPump</b> is full. In this case, no more event (such as <b>repaint</b> , input events etc.) can be added into it.</p> <p>Most of time this error occurs when:</p> <ul style="list-style-type: none"> <li>• There is a user thread which performs too many calls to the method <b>paint</b> without waiting for the end of the previous drawing.</li> <li>• Too many input events are pushed from an input driver to the display pump (for example some touch events).</li> </ul>

## FS

## Error Messages

When an exception is thrown by the implementation of the FS API, the error message

`FS:E=<messageId>`

is issued, where `<messageId>` meaning is defined in the next table:

Table 37: File System Error Messages

Message ID	Description
-1	End of File (EOF).
-2	An error occurred during a File System operation.
-3	File System not initialized.

## Net

### Error Messages

When an exception is thrown by the implementation of the Net API, the error message

`NET-1.1:E=<messageId>`

is issued, where `<messageId>` meaning is defined in the next table:

Table 38: Net Error Messages

Message ID	Description
-2	Permission denied.
-3	Bad socket file descriptor.
-4	Host is down.
-5	Network is down.
-6	Network is unreachable.
-7	Address already in use.
-8	Connection abort.
-9	Invalid argument.
-10	Socket option not available.
-11	Socket not connected.
-12	Unsupported network address family.
-13	Connection refused.
-14	Socket already connected.
-15	Connection reset by peer.
-16	Message size to be sent is too long.
-17	Broken pipe.
-18	Connection timed out.
-19	Not enough free memory.
-20	No route to host.
-21	Unknown host.
-23	Native method not implemented.
-24	The blocking request queue is full, and a new request cannot be added now.
-25	Network not initialized.
-255	Unknown error.

## SSL

### Error Messages

When an exception is thrown by the implementation of the SSL API, the error message

`SSL-2.0:E=<messageId>`

is issued, where `<messageId>` meaning is defined in the next table:

Table 39: SSL Error Messages

Message ID	Description
-2	Connection reset by the peer.
-3	Connection timed out.
-5	Dispatch blocking request queue is full, and a new request cannot be added now.
-6	Certificate parsing error.
-7	The certificate data size bigger than the immortal buffer used to process certificate.
-8	No trusted certificate found.
-9	Basic constraints check failed: Intermediate certificate is not a CA certificate.
-10	Subject/issuer name chaining error.
-21	Wrong block type for RSA function.
-22	RSA buffer error: Output is too small, or input is too large.
-23	Output buffer is too small, or input is too large.
-24	Certificate AlogID setting error.
-25	Certificate public-key setting error.
-26	Certificate date validity setting error.
-27	Certificate subject name setting error.
-28	Certificate issuer name setting error.
-29	CA basic constraint setting error.
-30	Extensions setting error.
-31	Invalid ASN version number.
-32	ASN get int error: invalid data.
-33	ASN key init error: invalid input.
-34	Invalid ASN object id.
-35	Not null ASN tag.
-36	ASN parsing error: zero expected.
-37	ASN bit string error: wrong id.
-38	ASN OID error: unknown sum id.
-39	ASN date error: bad size.
-40	ASN date error: current date before.
-41	ASN date error: current date after.
-42	ASN signature error: mismatched OID.
-43	ASN time error: unknown time type.
-44	ASN input error: not enough data.
-45	ASN signature error: confirm failure.
-46	ASN signature error: unsupported hash type.
-47	ASN signature error: unsupported key type.
-48	ASN key init error: invalid input.
-49	ASN NTRU key decode error: invalid input.
-50	X.509 critical extension ignored.
-51	ASN no signer to confirm failure (no CA found).
-52	ASN CRL signature-confirm failure.

Continued on next page

Table 39 – continued from previous page

Message ID	Description
-53	ASN CRL: no signer to confirm failure.
-54	ASN OCSP signature-confirm failure.
-60	ECC input argument is wrong type.
-61	ECC ASN1 bad key data: invalid input.
-62	ECC curve sum OID unsupported: invalid input.
-63	Bad function argument provided.
-64	Feature not compiled in.
-65	Unicode password too big.
-66	No password provided by user.
-67	AltNames extensions too big.
-70	AES-GCM Authentication check fail.
-71	AES-CCM Authentication check fail.
-80	Cavium Init type error.
-81	Bad alignment error, no alloc help.
-82	Bad ECC encrypt state operation.
-83	Bad padding: message wrong length.
-84	Certificate request attributes setting error.
-85	PKCS#7 error: mismatched OID value.
-86	PKCS#7 error: no matching recipient found.
-87	FIPS mode not allowed error.
-88	Name constraint error.
-89	Random Number Generator failed.
-90	FIPS Mode HMAC minimum key length error.
-91	RSA Padding error.
-92	Export public ECC key in ANSI format error: Output length only set.
-93	In Core Integrity check FIPS error.
-94	AES Known Answer Test check FIPS error.
-95	DES3 Known Answer Test check FIPS error.
-96	HMAC Known Answer Test check FIPS error.
-97	RSA Known Answer Test check FIPS error.
-98	DRBG Known Answer Test check FIPS error.
-99	DRBG Continuous Test FIPS error.
-100	AESGCM Known Answer Test check FIPS error.
-101	Process input state error.
-102	Bad index to key rounds.
-103	Out of memory.
-104	Verify problem found on completion.
-105	Verify mac problem.
-106	Parse error on header.
-107	Weird handshake type.
-108	Error state on socket.
-109	Expected data, not there.
-110	Not enough data to complete task.
-111	Unknown type in record header.
-112	Error during decryption.
-113	Received alert: fatal error.
-114	Error during encryption.
-116	Need peer's key.
-117	Need the private key.

Continued on next page

Table 39 – continued from previous page

Message ID	Description
-118	Error during RSA private operation.
-119	Server missing DH parameters.
-120	Build message failure.
-121	Client hello not formed correctly.
-122	The peer subject name mismatch.
-123	Non-blocking socket wants data to be read.
-124	Handshake layer not ready yet; complete first.
-125	Premaster secret version mismatch error.
-126	Record layer version error.
-127	Non-blocking socket write buffer full.
-128	Malformed buffer input error.
-129	Verify problem on certificate and check date/time on your device.
-130	Verify problem based on signature.
-131	PSK client identity error.
-132	PSK server hint error.
-133	PSK key callback error.
-134	Record layer length error.
-135	Can't decode peer key.
-136	The peer sent close notify alert.
-137	Wrong client/server type.
-138	The peer didn't send the certificate.
-140	NTRU key error.
-141	NTRU DRBG error.
-142	NTRU encrypt error.
-143	NTRU decrypt error.
-150	Bad ECC Curve Type or unsupported.
-151	Bad ECC Curve or unsupported.
-152	Bad ECC Peer Key.
-153	ECC Make Key failure.
-154	ECC Export Key failure.
-155	ECC DHE shared failure.
-157	Not a CA by basic constraint.
-159	Bad Certificate Manager error.
-160	OCSP Certificate revoked.
-161	CRL Certificate revoked.
-162	CRL missing, not loaded.
-165	OCSP needs a URL for lookup.
-166	OCSP Certificate unknown.
-167	OCSP responder lookup fail.
-168	Maximum chain depth exceeded.
-171	Suites pointer error.
-172	No PEM header found.
-173	Out of order message: fatal.
-174	Bad KEY type found.
-175	Sanity check on ciphertext failed.
-176	Receive callback returned more than requested.
-178	Need peer certificate for verification.
-181	Unrecognized host name error.
-182	Unrecognized max fragment length.

Continued on next page

Table 39 – continued from previous page

Message ID	Description
-183	Key Use digitalSignature not set.
-185	Key Use keyEncipherment not set.
-186	Ext Key Use server/client authentication not set.
-187	Send callback out-of-bounds read error.
-188	Invalid renegotiation.
-189	Peer sent different certificate during SCR.
-190	Finished message received from peer before receiving the Change Cipher message.
-191	Sanity check on message order.
-192	Duplicate handshake message.
-193	Unsupported cipher suite.
-194	Can't match cipher suite.
-195	Bad certificate type.
-196	Bad file type.
-197	Opening random device error.
-198	Reading random device error.
-199	Windows cryptographic init error.
-200	Windows cryptographic generation error.
-201	No data is waiting to be received from the random device.
-202	Unknown error.

### 4.16.3 Appendix C: Tools Options and Error Codes

#### SOAR

When a generic exception is thrown by the SOAR, the error message

SOAR ERROR [M<messageId>] <message>

is issued, where <messageId> and <message> meanings are defined in the next table.

Table 40: SOAR Error Messages.

Message ID	Description
0	The SOAR process has encountered some internal limits.
1	Unknown option.
2	An option has an invalid value.
3	A mandatory option is not set.
4	A filename given in options does not exist .
5	Failed to write the output file (access permissions required for <b>-toDir</b> and <b>-root</b> options).
6	The given file does not exist.
7	I/O error while reading a file.
8	An option value refers to a directory, instead of a file.
9	An option value refers to a file, instead of a directory or a jar file.
10	Invalid entry point class or no <b>main()</b> method.
11	An information file can not be generated in its entirety.
12	Limitations of the evaluation version have been reached.
13	I/O error while reading a jar file.
14	IO Error while writing a file.
15	I/O error while reading a jar file: unknown entry size.
16	Not enough memory to load a jar file.

Continued on next page



Table 40 – continued from previous page

Message ID	Description
17	The specified SOAR options are exclusive.
18	XML syntax error for some given files.
19	Unsupported float representation.
23	A clinit cycle has been detected. The clinit cycle can be cut either by simplifying the application clinit code or by explicitly declaring clinit dependencies. Check the generated <code>.clinitmap</code> file for more information.
50	Missing code: Java code refers to a method not found in specified classes.
51	Missing code: Java code refers to a class not found in the specified classpath.
52	Wrong class: Java code refers to a field not found in the specified class.
53	Wrong class: A Java classfile refers to a class as an interface.
54	Wrong class: An abstract method is found in a non-abstract class.
55	Wrong class: illegal access to a method, a field or a type.
56	Wrong class: hierarchy inconsistency; an interface cannot be a superclass of a class.
57	Circularity detected in initialization sequence.
58	Option refers twice to the same resource. The first reference is used.
59	Stack inconsistency detected.
60	Constant pool inconsistency detected.
61	Corrupted classfile.
62	Missing native implementation of a native method.
63	Cannot read the specified resource file.
64	The same property name cannot be defined in two different property files.
65	Bad license validity.
66	Classfiles do not contain debug line table information.
67	Same as 51.
150	SOAR limit reached: The specified method uses too many arguments.
151	SOAR limit reached: The specified method uses too many locals.
152	SOAR limit reached: The specified method code is too large.
153	SOAR limit reached: The specified method catches too many exceptions.
154	SOAR limit reached: The specified method defines a stack that is too large.
155	SOAR limit reached: The specified type defines too many methods.
156	SOAR limit reached: Your application defines too many interfaces.
157	SOAR limit reached: The specified type defines too many fields.
158	SOAR limit reached: your application defines too many types.
159	SOAR limit reached: Your application defines too many static fields.
160	SOAR limit reached: The hierarchy depth of the specified type is too high.
161	SOAR limit reached: Your application defines too many bundles.
162	SOAR limit reached: Your application defines too deep interface hierarchies.
163	SOAR limit reached: Your application defines too many concrete types.
251	Error in converting an IEEE754 float(32) or double(64) to a fixed-point arithmetic number
300	Corrupted class: invalid dup_x1 instruction usage.
301	Corrupted class: invalid dup_x2 instruction usage.
302	Corrupted class:invalid dup_x2 instruction usage.
303	Corrupted class:invalid dup2_x1 instruction usage.
304	Corrupted class:invalid dup2_x1 instruction usage.
305	Corrupted class:invalid dup2_x2 instruction usage.
306	Corrupted class: invalid dup2 instruction usage.
307	Corrupted class:invalid pop2 instruction usage.
308	Corrupted class:invalid swap instruction usage.
309	Corrupted class: Finally blocks must be inlined.

Continued on next page

Table 40 – continued from previous page

Message ID	Description
350	SNI incompatibility: Some specified type should be an array.
351	SNI incompatibility: Some type should define some specified field.
352	SNI incompatibility: The specified field is not compatible with SNI.
353	SNI incompatibility: The specified type must be a class.
354	SNI incompatibility: The specified static field must be defined in the specified type.
355	SNI file error: The data must be an integer.
356	SNI file error : unexpected tag
357	SNI file error : attributes <name>, <descriptor>, <index> and <size> are expected in the specified tag.
358	SNI file error : invalid SNI tag value.
359	Error parsing the SNI file.
360	XML Error on parsing the SNI file.
361	SNI incompatibility : illegal call to the specified data.
362	No stack found for the specified native group.
363	Invalid SNI method: The argument cannot be an object reference.
364	Invalid SNI method: The array argument must only be a base type array.
365	Invalid SNI method: The return type must be a base type.
366	Invalid SNI method: The method must be static.

### Immutable Files Related Error Messages

The following error messages are issued at SOAR time (link phase) and not at runtime.

Table 41: Errors when parsing immutable files at link time.

Message ID	Description
0	Duplicated ID in immutable files. Each immutable object should have a unique ID in the SOAR image.
1	An immutable file refers to an unknown field of an object.
2	Tried to assign the same object field twice.
3	All immutable object fields should be defined in the immutable file description.
4	The assigned value does not match the expected Java type.
5	An immutable object refers to an unknown ID.
6	The length of the immutable object does not match the length of the assigned object.
7	The type defined in the file doesn't match the Java expected type.
8	Generic error while parsing an immutable file.
9	Cycle detected in an alias definition.
10	An immutable object is an instance of an abstract class or an interface.
11	Unknown XML attribute in an immutable file.
12	A mandatory XML attribute is missing.
13	The value is not a valid Java literal.
14	Alias already exists.

### SNI

The following error messages are issued at SOAR time and not at runtime.

Table 42: [SNI] Link Time Error Messages.

Message ID	Description
363	Argument cannot be a reference.
364	Argument can only be from a base type array.
365	Return type must be a base type.
366	Method must be a static method.

## SP Compiler

### Options

Table 43: Shielded Plug Compiler Options.

Option name	Description
<code>-verbose[e...e]</code>	Extra messages are printed out to the console according to the number of 'e'.
<code>-descriptionFile file</code>	XML Shielded Plug description file. Multiple files allowed.
<code>-waitingTaskLimit value</code>	Maximum number of task/threads that can wait on a block: a number between 0 and 7. -1 is for no limit; 8 is for unspecified.
<code>-immutable</code>	When specified, only immutable Shielded Plugs can be compiled.
<code>-output dir</code>	Output directory. Default is the current directory.
<code>-outputName name</code>	Output name for the Shielded Plug layout description. Default is "shielded_plug".
<code>-endianness name</code>	Either "little" or "big". Default is "little".
<code>-outputArchitecture value</code>	Output ELF architecture. Only "ELF" architecture is available.
<code>-rwBlockHeaderSize value</code>	Read/Write header file value.
<code>-genIdsC</code>	When specified, generate a C header file with block ID constants.
<code>-cOutputDir dir</code>	Output directory of C header files. Default is the current directory.
<code>-cConstantsPrefix prefix</code>	C constants name prefix for block IDs.
<code>-genIdsJava</code>	When specified, generate Java interfaces file with block ID constants.
<code>-jOutputDir dir</code>	Output directory of Java interfaces files. Default is the current directory.
<code>-jPackage name</code>	The name of the package for Java interfaces.

## Error Messages

Table 44: Shielded Plug Compiler Error Messages.

Message ID	Description
0	Internal limits reached.
1	Invalid endianness.
2	Invalid output architecture.
3	Error while reading / writing files.
4	Missing a mandatory option.

## NLS Immutables Creator

Table 45: NLS Immutables Creator Errors Messages

ID	Type	Description
1	Error	Error reading the nls list file : invalid path, input/output error, etc.
2	Error	Error reading the nls list file: The file contents are invalid.
3	Error	Specified class is not an interface.
4	Error	Invalid message ID. Must be greater than or equal to 1.
5	Error	Duplicate ID. Both messages use the same message ID.
6	Error	Specified interface does not exist.
7	Error	Specified message constant is not visible (must be public).
8	Error	Specified message constant is not an integer.
9	Error	No locale file is defined for the specified header.
10	Error	IO error: Cannot create the output file.
11	Warning	Missing message value.
12	Warning	There is a gap (or gaps) in messages constants.
13	Warning	Specified property does not denote a message.
14	Warning	Invalid properties header file. File is ignored.
15	Warning	No message is defined for the specified header.
16	Warning	Invalid property.

## MicroUI Static\_INITIALIZER

### Inputs

The XML file used as input by the MicroUI Static Initialization Tool may contain tags related to the Input component as described below.

Listing 11: Event Generators Description

```
<eventgenerators>
<!-- Generic Event Generators -->
  <eventgenerator name="GENERIC" class="foo.bar.Zork">
    <property name="PROP1" value="3"/>
    <property name="PROP2" value="aaa"/>
  </eventgenerator>

  <!-- Predefined Event Generators -->
  <command name="COMMANDS"/>
</eventgenerators>
```

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```

<buttons name="BUTTONS" extended="3"/>
<buttons name="JOYSTICK" extended="5"/>
<pointer name="POINTER" width="1200" height="1200"/>
<touch name="TOUCH" display="DISPLAY"/>
<states name="STATES" numbers="NUMBERS" values="VALUES"/>

</eventgenerators>

<array name="NUMBERS">
  <elem value="3"/>
  <elem value="2"/>
  <elem value="5"/>
</array>

<array name="VALUES">
  <elem value="2"/>
  <elem value="0"/>
  <elem value="1"/>
</array>

```

Table 46: Event Generators Static Definition

Tag	Attributes	Description
eventgenerators		The list of event generators.
	priority	<i>Optional.</i> An integer value. Defines the internal display thread priority. Default value is 5.
eventgenerator		Describes a generic event generator. See also <i>Generic Event Generators</i> .
	name	The logical name.
	class	The event generator class (must extend the <code>ej.microui.event.generator.GenericEventGenerator</code> class). This class must be available in the MicroEJ Application classpath.
	listener	<i>Optional.</i> Default listener's logical name. Only a display is a valid listener. If no listener is specified the listener is the default display.
property		A generic event generator property. The generic event generator will receive this property at startup, via the method <code>setProperty</code> .
	name	The property key.
	value	The property value.
command		The default event generator <code>Command</code> .
	name	The logical name.
	listener	<i>Optional.</i> Default listener's logical name. Only a display is a valid listener. If no listener is specified, then the listener is the default display.
buttons		The default event generator <code>Buttons</code> .
	name	The logical name.
	extended	<i>Optional.</i> An integer value. Defines the number of buttons which support the MicroUI extended features (elapsed time, click and double-click).
	listener	<i>Optional.</i> Default listener's logical name. Only a display is a valid listener. If no listener is specified, then the listener is the default display.
pointer		The default event generator <code>Pointer</code> .
	name	The logical name.
	width	An integer value. Defines the pointer area width.
	height	An integer value. Defines the pointer area height.

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Table 46 – continued from previous page

Tag	Attributes	Description
	<b>extended</b>	<i>Optional.</i> An integer value. Defines the number of pointer buttons (right click, left click, etc.) which support the MicroUI extended features (elapsed time, click and double-click).
	<b>listener</b>	<i>Optional.</i> Default listener's logical name. Only a display is a valid listener. If no listener is specified, then the listener is the default display.
<b>touch</b>		The default event generator <b>Touch</b> .
	<b>name</b>	The logical name.
	<b>display</b>	Logical name of the Display with which the touch is associated.
	<b>listener</b>	<i>Optional.</i> Default listener's logical name. Only a display is a valid listener. If no listener is specified, then the listener is the default display.
<b>states</b>		An event generator that manages a group of state machines. The state of a machine is changed by sending an event using <b>LLINPUT_sendStateEvent</b> .
	<b>name</b>	The logical name.
	<b>numbers</b>	The logical name of the array which defines the number of state machines for this States generator, and their range of state values. The IDs of the state machines start at 0. The number of state machines managed by the States generator is equal to the size of the <b>numbers</b> array, and the value of each entry in the array is the number of different values supported for that state machine. State machine values for state machine i can be in the range 0 to <b>numbers[i]</b> -1.
	<b>values</b>	<i>Optional.</i> The logical name of the array which defines the initial state values of the state machines for this States generator. The <b>values</b> array must be the same size as the <b>numbers</b> array. If initial state values are specified using a <b>values</b> array, then the <b>LLINPUT_IMPL_getInitialStateValue</b> function is not called; otherwise that function is used to establish the initial values <sup>1</sup>
	<b>listener</b>	<i>Optional.</i> Default listener's logical name. Only a display is a valid listener. If no listener is specified, then the listener is the default display.
<b>array</b>		An array of values.
	<b>name</b>	The logical name.
<b>elem</b>		A value.
	<b>value</b>	An integer value.

## Display

The display component augments the static initialization file with:

- The configuration of each display.
- Fonts that are implicitly embedded within the application (also called system fonts). Applications can also embed their own fonts.

```
<display name="DISPLAY"/>

<fonts>
  <font file="resources\fonts\myfont.ejf">
    <range name="LATIN" sections="0-2"/>
    <customrange start="0x21" end="0x3f"/>
  </font>
</font>
```

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<sup>1</sup> Exception: When using MicroEJ Platform, where there is no equivalent to the **LLINPUT\_IMPL\_getInitialStateValue** function. If no **values** array is provided, and the MicroEJ Platform is being used, all state machines take 0 as their initial state value.

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```
<font file="C:\data\myfont.ejf"/>
</fonts>
```

Table 47: Display Static Initialization XML Tags Definition

Tag	Attributes	Description
display		The display element describes one display.
	name	The logical name of the display.
	priority	<i>Optional.</i> An integer value. Defines the internal display thread priority. Default value is 5.
	default	<b>true</b> or <b>false</b> . Defines this display to be the default display. By default the very first display described in the XML file is the default display.
fonts		The list of system fonts. The system fonts are available for all displays.
font		A system font.
	file	The font file path. The path may be absolute or relative to the XML file.
range		A font generic range.
	name	The generic range name ( <b>LATIN</b> , <b>HAN</b> , etc.)
	sections	<i>Optional.</i> Defines one or several sub parts of the generic range. “1”: add only part 1 of the range “1-5”: add parts 1 to 5 “1,5”: add parts 1 and 5 These combinations are allowed: “1,5,6-8” add parts 1, 5, and 6 through 8 By default, all range parts are embedded.
customrange		A font-specific range.
	start	UTF16 value of the very first character to embed.
	end	UTF16 value of the very last character to embed.

## Font Generator

### Configuration File

```
ConfigFile      ::= Line [ 'EOL' Line ]*
Line            ::= FontPath [ ':' [ Ranges ] [ ':' BitsPerPixel ] ]
FontPath        ::= Identifier [ '/' Identifier ]*
Ranges          ::= Range [ ';' Range ]*
Range           ::= CustomRangeList | KnownRange
CustomRangeList ::= CustomRange [ ',' CustomRange ]*
CustomRange     ::= Number | Number '-' Number
KnownRange      ::= Name [ SubRangeList ]?
SubRangeList    ::= '(' SubRange [ ',' SubRange ]* ')'
SubRange        ::= Number | Number - Number
Identifier       ::= 'a-zA-Z_$' [ 'a-zA-Z_$0-9' ]*
Number          ::= Number16 | Number10
Number16        ::= '0x' [ Digit16 ]+
Number10         ::= [ Digit10 ]+
Digit16         ::= 'a-fA-F0-9'
```

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```
Digit10      ::= '0-9'
BitsPerPixel ::= '1' | '2' | '4' | '8'
```

## Custom Range

Allows the selection of raw Unicode character ranges.

Examples:

- `myfont:0x21-0x49`: Embed all characters from 0x21 to 0x49 (included).
- `myfont:0x21-0x49,0x55`: Embed all characters from 0x21 to 0x49 and character 0x55
- `myfont:0x21-0x49;0x55`: Same as previous, but done by declaring two ranges.

## Known Range

A known range is a range available in the following table.

Examples:

- `myfont:basic_latin`: Embed all *Basic Latin* characters.
- `myfont:basic_latin;arabic`: Embed all *Basic Latin* characters, and all *Arabic* characters.

*The following table* describes the available list of ranges and sub-ranges (processed from the “Unicode Character Database” version 9.0.0 available on the official unicode website <https://www.unicode.org>).

Table 48: Ranges

Name	Tag	Start	End
Basic Latin	basic_latin	0x0	0x7f
Latin-1 Supplement	latin-1_supplement	0x80	0xff
Latin Extended-A	latin_extended-a	0x100	0x17f
Latin Extended-B	latin_extended-b	0x180	0x24f
IPA Extensions	ipa_extensions	0x250	0x2af
Spacing Modifier Letters	spacing_modifier_letters	0x2b0	0x2ff
Combining Diacritical Marks	combining_diacritical_marks	0x300	0x36f
Greek and Coptic	greek_and_coptic	0x370	0x3ff
Cyrillic	cyrillic	0x400	0x4ff
Cyrillic Supplement	cyrillic_supplement	0x500	0x52f
Armenian	armenian	0x530	0x58f
Hebrew	hebrew	0x590	0x5ff
Arabic	arabic	0x600	0x6ff
Syriac	syriac	0x700	0x74f
Arabic Supplement	arabic_supplement	0x750	0x77f
Thaana	thaana	0x780	0x7bf
NKo	nko	0x7c0	0x7ff
Samaritan	samaritan	0x800	0x83f
Mandaic	mandaic	0x840	0x85f
Arabic Extended-A	arabic_extended-a	0x8a0	0x8ff
Devanagari	devanagari	0x900	0x97f
Bengali	bengali	0x980	0x9ff

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Table 48 – continued from previous page

Name	Tag	Start	End
Gurmukhi	gurmukhi	0xa00	0xa7f
Gujarati	gujarati	0xa80	0xaff
Oriya	oriya	0xb00	0xb7f
Tamil	tamil	0xb80	0xbff
Telugu	telugu	0xc00	0xc7f
Kannada	kannada	0xc80	0xcff
Malayalam	malayalam	0xd00	0xd7f
Sinhala	sinhala	0xd80	0xdff
Thai	thai	0xe00	0xe7f
Lao	lao	0xe80	0xeff
Tibetan	tibetan	0xf00	0xfff
Myanmar	myanmar	0x1000	0x109f
Georgian	georgian	0x10a0	0x10ff
Hangul Jamo	hangul_jamo	0x1100	0x11ff
Ethiopic	ethiopic	0x1200	0x137f
Ethiopic Supplement	ethiopic_supplement	0x1380	0x139f
Cherokee	cherokee	0x13a0	0x13ff
Unified Canadian Aboriginal Syllabics	unified_canadian_aboriginal_syllabics	0x1400	0x167f
Ogham	ogham	0x1680	0x169f
Runic	runic	0x16a0	0x16ff
Tagalog	tagalog	0x1700	0x171f
Hanunoo	hanunoo	0x1720	0x173f
Buhid	buhid	0x1740	0x175f
Tagbanwa	tagbanwa	0x1760	0x177f
Khmer	khmer	0x1780	0x17ff
Mongolian	mongolian	0x1800	0x18af
Unified Canadian Aboriginal Syllabics Extended	unified_canadian_aboriginal_syllabics_extended	0x18b0	0x18ff
Limbu	limbu	0x1900	0x194f
Tai Le	tai_le	0x1950	0x197f
New Tai Lue	new_tai_lue	0x1980	0x19df
Khmer Symbols	khmer_symbols	0x19e0	0x19ff
Buginese	buginese	0x1a00	0x1a1f
Tai Tham	tai_tham	0x1a20	0x1aaf
Combining Diacritical Marks Extended	combining_diacritical_marks_extended	0x1ab0	0x1aff
Balinese	balinese	0x1b00	0x1b7f
Sundanese	sundanese	0x1b80	0x1bbf
Batak	batak	0x1bc0	0x1bff
Lepcha	lepcha	0x1c00	0x1c4f
Ol Chiki	ol_chiki	0x1c50	0x1c7f
Cyrillic Extended-C	cyrillic_extended-c	0x1c80	0x1c8f
Sundanese Supplement	sundanese_supplement	0x1cc0	0x1ccf
Vedic Extensions	vedic_extensions	0x1cd0	0x1cff
Phonetic Extensions	phonetic_extensions	0x1d00	0x1d7f
Phonetic Extensions Supplement	phonetic_extensions_supplement	0x1d80	0x1dbf
Combining Diacritical Marks Supplement	combining_diacritical_marks_supplement	0x1dc0	0x1dff
Latin Extended Additional	latin_extended_additional	0x1e00	0x1eff
Greek Extended	greek_extended	0x1f00	0x1fff

Continued on next page

Table 48 – continued from previous page

Name	Tag	Start	End
General Punctuation	general_punctuation	0x2000	0x206f
Superscripts and Subscripts	superscripts_and_subscripts	0x2070	0x209f
Currency Symbols	currency_symbols	0x20a0	0x20cf
Combining Diacritical Marks for Symbols	combining_diacritical_marks_for_symbols	0x20d0	0x20ff
Letterlike Symbols	letterlike_symbols	0x2100	0x214f
Number Forms	number_forms	0x2150	0x218f
Arrows	arrows	0x2190	0x21ff
Mathematical Operators	mathematical_operators	0x2200	0x22ff
Miscellaneous Technical	miscellaneous_technical	0x2300	0x23ff
Control Pictures	control_pictures	0x2400	0x243f
Optical Character Recognition	optical_character_recognition	0x2440	0x245f
Enclosed Alphanumerics	enclosed_alphanumerics	0x2460	0x24ff
Box Drawing	box_drawing	0x2500	0x257f
Block Elements	block_elements	0x2580	0x259f
Geometric Shapes	geometric_shapes	0x25a0	0x25ff
Miscellaneous Symbols	miscellaneous_symbols	0x2600	0x26ff
Dingbats	dingbats	0x2700	0x27bf
Miscellaneous Mathematical Symbols-A	miscellaneous_mathematical_symbols-a	0x27c0	0x27ef
Supplemental Arrows-A	supplemental_arrows-a	0x27f0	0x27ff
Braille Patterns	braille_patterns	0x2800	0x28ff
Supplemental Arrows-B	supplemental_arrows-b	0x2900	0x297f
Miscellaneous Mathematical Symbols-B	miscellaneous_mathematical_symbols-b	0x2980	0x29ff
Supplemental Mathematical Operators	supplemental_mathematical_operators	0x2a00	0x2aff
Miscellaneous Symbols and Arrows	miscellaneous_symbols_and_arrows	0x2b00	0x2bff
Glagolitic	glagolitic	0x2c00	0x2c5f
Latin Extended-C	latin_extended-c	0x2c60	0x2c7f
Coptic	coptic	0x2c80	0x2cff
Georgian Supplement	georgian_supplement	0x2d00	0x2d2f
Tifinagh	tifinagh	0x2d30	0x2d7f
Ethiopic Extended	ethiopic_extended	0x2d80	0x2ddf
Cyrillic Extended-A	cyrillic_extended-a	0x2de0	0x2dff
Supplemental Punctuation	supplemental_punctuation	0x2e00	0x2e7f
CJK Radicals Supplement	cjk_radicals_supplement	0x2e80	0x2eff
Kangxi Radicals	kangxi_radicals	0x2f00	0x2fdf
Ideographic Description Characters	ideographic_description_characters	0x2ff0	0x2fff
CJK Symbols and Punctuation	cjk_symbols_and_punctuation	0x3000	0x303f
Hiragana	hiragana	0x3040	0x309f
Katakana	katakana	0x30a0	0x30ff
Bopomofo	bopomofo	0x3100	0x312f
Hangul Compatibility Jamo	hangul_compatibility_jamo	0x3130	0x318f
Kanbun	kanbun	0x3190	0x319f
Bopomofo Extended	bopomofo_extended	0x31a0	0x31bf
CJK Strokes	cjk_strokes	0x31c0	0x31ef
Katakana Phonetic Extensions	katakana_phonetic_extensions	0x31f0	0x31ff
Enclosed CJK Letters and Months	enclosed_cjk_letters_and_months	0x3200	0x32ff

Continued on next page

Table 48 – continued from previous page

Name	Tag	Start	End
CJK Compatibility	cjk_compatibility	0x3300	0x33ff
CJK Unified Ideographs Extension A	cjk_unified_ideographs_extension_a	0x3400	0x4dbf
Yijing Hexagram Symbols	yijing_hexagram_symbols	0x4dc0	0x4dff
CJK Unified Ideographs	cjk_unified_ideographs	0x4e00	0x9fff
Yi Syllables	yi_syllables	0xa000	0xa48f
Yi Radicals	yi_radicals	0xa490	0xa4cf
Lisu	lisu	0xa4d0	0xa4ff
Vai	vai	0xa500	0xa63f
Cyrillic Extended-B	cyrillic_extended-b	0xa640	0xa69f
Bamum	bamum	0xa6a0	0xa6ff
Modifier Tone Letters	modifier_tone_letters	0xa700	0xa71f
Latin Extended-D	latin_extended-d	0xa720	0xa7ff
Syloti Nagri	syloti_nagri	0xa800	0xa82f
Common Indic Number Forms	common_indic_number_forms	0xa830	0xa83f
Phags-pa	phags-pa	0xa840	0xa87f
Saurashtra	saurashtra	0xa880	0xa8df
Devanagari Extended	devanagari_extended	0xa8e0	0xa8ff
Kayah Li	kayah_li	0xa900	0xa92f
Rejang	rejang	0xa930	0xa95f
Hangul Jamo Extended-A	hangul_jamo_extended-a	0xa960	0xa97f
Javanese	javanese	0xa980	0xa9df
Myanmar Extended-B	myanmar_extended-b	0xa9e0	0xa9ff
Cham	cham	0xaa00	0xaa5f
Myanmar Extended-A	myanmar_extended-a	0xaa60	0xaa7f
Tai Viet	tai_viet	0xaa80	0xaadf
Meetei Mayek Extensions	meetei_mayek_extensions	0xaae0	0xaaff
Ethiopic Extended-A	ethiopic_extended-a	0xab00	0xab2f
Latin Extended-E	latin_extended-e	0xab30	0xab6f
Cherokee Supplement	cherokee_supplement	0xab70	0xabbf
Meetei Mayek	meetei_mayek	0xabc0	0xabff
Hangul Syllables	hangul_syllables	0xac00	0xd7af
Hangul Jamo Extended-B	hangul_jamo_extended-b	0xd7b0	0xd7ff
High Surrogates	high_surrogates	0xd800	0xdb7f
High Private Use Surrogates	high_private_use_surrogates	0xdb80	0xdbff
Low Surrogates	low_surrogates	0xdc00	0xdfff
Private Use Area	private_use_area	0xe000	0xf8ff
CJK Compatibility Ideographs	cjk_compatibility_ideographs	0xf900	0xfaff
Alphabetic Presentation Forms	alphabetic_presentation_forms	0xfb00	0xfb4f
Arabic Presentation Forms-A	arabic_presentation_forms-a	0xfb50	0xfdff
Variation Selectors	variation_selectors	0xfe00	0xfe0f
Vertical Forms	vertical_forms	0xfe10	0xfe1f
Combining Half Marks	combining_half_marks	0xfe20	0xfe2f
CJK Compatibility Forms	cjk_compatibility_forms	0xfe30	0xfe4f
Small Form Variants	small_form_variants	0xfe50	0xfe6f
Arabic Presentation Forms-B	arabic_presentation_forms-b	0xfe70	0xfeff
Halfwidth and Fullwidth Forms	halfwidth_and_fullwidth_forms	0xff00	0xffef
Specials	specials	0xffff	0xffff

## Error Messages

Table 49: Static Font Generator Error Messages

ID	Type	Description
0	Error	The static font generator has encountered an unexpected internal error.
1	Error	The Fonts list file has not been specified.
2	Error	The static font generator cannot create the final, raw file.
3	Error	The static font generator cannot read the fonts list file.
4	Warning	The static font generator has found no font to generate.
5	Error	The static font generator cannot load the fonts list file.
6	Warning	The specified font path is invalid: The font will be not converted.
7	Warning	<i>There are too many arguments on a line: The current entry is ignored.</i>
8	Error	The static font generator has encountered an unexpected internal error.
9	Error	<i>The static font generator has encountered an unexpected internal error.</i>
10	Warning	The specified entry is invalid: The current entry is ignored.
11	Warning	The specified entry does not contain a list of characters: The current entry is ignored.
12	Warning	The specified entry does not contain a list of identifiers: The current entry is ignored.
13	Warning	The specified entry is an invalid width: The current entry is ignored.
14	Warning	The specified entry is an invalid height: the current entry is ignored.
15	Warning	The specified entry does not contain the characters' addresses: The current entry is ignored.
16	Warning	The specified entry does not contain the characters' bitmaps: The current entry is ignored.
17	Warning	The specified entry bits-per-pixel value is invalid: The current entry is ignored.
18	Warning	The specified range is invalid: The current entry is ignored.
19	Error	There are too many identifiers. The output RAW format cannot store all identifiers.
20	Error	The font's name is too long. The output RAW format cannot store all name characters.

## Image Generator

### Configuration File

```

ConfigFile      ::= Line [ 'EOL' Line ]*
Line            ::= ImagePath [ ':' ImageOption ]*
ImagePath       ::= Identifier [ '/' Identifier ]*
ImageOption     ::= [ '^: ]*
Identifier      ::= Letter [ LetterOrDigit ]*
Letter          ::= 'a-zA-Z_$'
LetterOrDigit   ::= 'a-zA-Z_$0-9'

```

## Error Messages

Table 50: Static Image Generator Error Messages

ID	Type	Description
0	Error	The static image generator has encountered an unexpected internal error.
1	Error	The images list file has not been specified.
2	Error	The static image generator cannot create the final, raw file.
3	Error	The static image generator cannot read the images list file. Make sure the system allows reading of this file.
4	Warning	The static image generator has found no image to generate.
5	Error	The static image generator cannot load the images list file.
6	Warning	The specified image path is invalid: The image will be not converted.
7	Warning	There are too many or too few options for the desired format.
8	Error	A static image generator extension class is unknown.
9	Error	The static image generator has encountered an unexpected internal error.
10	Warning	The specified output format is unknown: The image will be not converted.
11	Warning	The specified format is not managed by the static image generator: The image will be not converted.
12	Warning	The specified alpha level is invalid: The image will be not converted.
13	Warning	The specified alpha level is not compatible with the specified format: The image will be not converted.
14	Warning	A specified attribute is undefined for the specified format.

## Front Panel

### FP File

### XML Schema

```
<?xml version="1.0"?>
<frontpanel
  xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance"
  xmlns="https://developer.microej.com"
  xsi:schemaLocation="https://developer.microej.com .widget.xsd">

  <device name="example" skin="example-device.png">
    <ej.fp.widget.[type] x="22" y="51" [widget-attributes]/>
    <ej.fp.widget.[type] x="30" y="125" [widget-attributes]/>
    <!-- ... -->
  </device>
</frontpanel>
```

## File Specification

Table 51: FP File Specification

Tag	Attributes	Description
frontpanel		The root element.
	xmlns:xsi	Invariant tag <sup>1</sup>
	xmlns	Invariant tag <sup>2</sup>
	xsi:schemaLocation	Invariant tag <sup>3</sup>
device		The device's root element.
	name	The device's logical name.
	skin	Refers to a PNG file which defines the device background.
ej.fp.widget.xxx		Defines the widget to use. Refer to the widget documentation.
	label	All widget should provide this identifier. Sometimes it is used as string, sometimes as integer
	x	The widget x-coordinate.
	y	The widget y-coordinate.

## LLDISPLAY\_EXTRA

### Error Messages

Display module calls the function `LLDISPLAY_EXTRA_IMPL_error` when the LLDISPLAY implementation *has to* perform a drawing but does not.

Table 52: LLDISPLAY\_EXTRA Error Messages

ID	Description
-10	A call to <code>LLDISPLAY_EXTRA_IMPL_fillRect</code> has been performed but the implementation has not performed the drawing.
-11	A call to <code>LLDISPLAY_EXTRA_IMPL_drawImage</code> has been performed but the implementation has not performed the drawing.
-12	A call to <code>LLDISPLAY_EXTRA_IMPL_scaleImage</code> has been performed but the implementation has not performed the drawing.
-13	A call to <code>LLDISPLAY_EXTRA_IMPL_rotateImage</code> has been performed but the implementation has not performed the drawing.

## HIL Engine

Below are the HIL Engine options:

<sup>1</sup> Must be "<http://www.w3.org/2001/XMLSchema-instance>"

<sup>2</sup> Must be "<https://developer.microej.com>"

<sup>3</sup> Must be "<https://developer.microej.com> .widget.xsd"

Table 53: HIL Engine Options

Option name	Description
<code>-verbose[e....e]</code>	Extra messages are printed out to the console (add extra e to get more messages).
<code>-ip &lt;address&gt;</code>	MicroEJ Simulator connection IP address (A.B.C.D). By default, set to localhost.
<code>-port &lt;port&gt;</code>	MicroEJ Simulator connection port. By default, set to 8001.
<code>-connectTimeout &lt;timeout&gt;</code>	timeout in s for MicroEJ Simulator connections. By default, set to 10 seconds.
<code>-excludes &lt;name[sep]name&gt;</code>	Types that will be excluded from the HIL Engine class resolution provided mocks. By default, no types are excluded.
<code>-mocks &lt;name[sep]name&gt;</code>	Mocks are either <code>.jar</code> file or <code>.class</code> files.

## Heap Dumping

### XML Schema

Below is the XML schema for heap dumps.

Table 54: XML Schema for Heap Dumps

```
<?xml version='1.0' encoding='UTF-8'?>
<!--
  Schema

  Copyright 2012 IS2T. All rights reserved.

  IS2T PROPRIETARY/CONFIDENTIAL. Use is subject to license terms.
-->

<xs:schema xmlns:xs="http://www.w3.org/2001/XMLSchema">
  <!-- root element : heap -->
  <xs:element name="heap">
    <xs:complexType>
      <xs:choice minOccurs="0" maxOccurs="unbounded">
        <xs:element ref="class"/>
        <xs:element ref="object"/>
        <xs:element ref="array"/>
        <xs:element ref="stringLiteral"/>
      </xs:choice>
    </xs:complexType>
  </xs:element>
```

Continued on next page

Table 54 – continued from previous page

```

<!-- class element -->
<xs:element name="class">
  <xs:complexType>
    <xs:choice minOccurs="0" maxOccurs="unbounded">
      <xs:element ref="field"/>
    </xs:choice>
    <xs:attribute name="name" type="xs:string" use = "required"/>
    <xs:attribute name="id" type="xs:string" use = "required"/>
    <xs:attribute name="superclass" type="xs:string"/>
  </xs:complexType>
</xs:element>

<!-- object element-->
<xs:element name="object">
  <xs:complexType>
    <xs:choice minOccurs="0" maxOccurs="unbounded">
      <xs:element ref="field"/>
    </xs:choice>
    <xs:attribute name="id" type="xs:string" use = "required"/>
    <xs:attribute name="class" type="xs:string" use = "required"/>
    <xs:attribute name="createdAt" type="xs:string" use = "optional"/>
    <xs:attribute name="createdInThread" type="xs:string" use = "optional"/>
    <xs:attribute name="createdInMethod" type="xs:string"/>
    <xs:attribute name="tag" type="xs:string" use = "required"/>
  </xs:complexType>
</xs:element>

<!-- array element-->
<xs:element name="array" type = "arrayTypeWithAttribute"/>
<!-- stringLiteral element-->
<xs:element name="stringLiteral">
  <xs:complexType>
    <xs:sequence>
      <xs:element minOccurs = "4" maxOccurs="4" ref="field "/>
    </xs:sequence>
    <xs:attribute name="id" type="xs:string" use = "required"/>
    <xs:attribute name="class" type="xs:string" use = "required"/>
  </xs:complexType>
</xs:element>

```

Continued on next page



Table 54 – continued from previous page

```

<!-- field element : child of class, object and stringLiteral-->
  <xs:element name="field">
    <xs:complexType>
      <xs:attribute name="name" type="xs:string" use = "required"/>
      <xs:attribute name="id" type="xs:string" use = "optional"/>
      <xs:attribute name="value" type="xs:string" use = "optional"/>
      <xs:attribute name="type" type="xs:string" use = "optional"/>
    </xs:complexType>
  </xs:element>

  <xs:simpleType name = "arrayType">
    <xs:list itemType="xs:integer"/>
  </xs:simpleType>

<!-- complex type "arrayTypeWithAttribute". type of array element-->
  <xs:complexType name = "arrayTypeWithAttribute">
    <xs:simpleContent>
      <xs:extension base="arrayType">
        <xs:attribute name="id" type="xs:string" use = "required"/>
        <xs:attribute name="class" type="xs:string" use = "required"/>
        <xs:attribute name="createdAt" type="xs:string" use = "optional"/>
        <xs:attribute name="createdInThread" type="xs:string" use = "optional"/>
        <xs:attribute name="createdInMethod" type="xs:string" use = "optional"/>
        <xs:attribute name="length" type="xs:string" use = "required"/>
        <xs:attribute name="elementType" type="xs:string" use = "optional"/>
        <xs:attribute name="type" type="xs:string" use = "optional"/>
      </xs:extension>
    </xs:simpleContent>
  </xs:complexType>

</xs:schema>

```

## File Specification

Types referenced in heap dumps are represented in the internal classfile format (*Internal classfile Format for Types*). Fully qualified names are names separated by the / separator (For example, *a/b/C*).

Listing 12: Internal classfile Format for Types

```
Type = <BaseType> | <ClassType> | <ArrayType>
BaseType: B(byte), C(char), D(double), F(float), I(int), J(long), S(short), Z(boolean),
ClassType: L<ClassName>;
ArrayType: [<Type>
```

Tags used in the heap dumps are described in the table below.

Table 55: Tag Descriptions

Tags	Attributes	Description
heap		The root element.
class		Element that references a Java class.
	name	Class type ( <ClassType> )
	id	Unique identifier of the class.
	superclass	Identifier of the superclass of this class.
object		Element that references a Java object.
	id	Unique identifier of this object.
	class	Fully qualified name of the class of this object.
array		Element that references a Java array.
	id	Unique identifier of this array.
	class	Fully qualified name of the class of this array.
	elementType	Type of the elements of this array.
	length	Array length.
stringLiteral		Element that references a <code>java.lang.String</code> literal.
	id	Unique identifier of this object.
	class	Id of <code>java.lang.String</code> class.
field		Element that references the field of an object or a class.
	name	Name of this field.
	id	Object or Array identifier, if it holds a reference.
	type	Type of this field, if it holds a base type.
	value	Value of this field, if it holds a base type.

#### 4.16.4 Appendix D: Architectures MCU / Compiler

##### Principle

The MicroEJ C libraries have been built for a specific processor (a specific MCU architecture) with a specific C compiler. The third-party linker must make sure to link C libraries compatible with the MicroEJ C libraries. This chapter details the compiler version, flags and options used to build MicroEJ C libraries for each processor.

Some processors include an optional floating point unit (FPU). This FPU is single precision (32 bits) and is compliant with IEEE 754 standard. It can be disabled when not in use, thus reducing power consumption. There are two steps to use the FPU in an application. The first step is to tell the compiler and the linker that the microcontroller

has an FPU available so that they will produce compatible binary code. The second step is to enable the FPU during execution. This is done by writing to CPAR in the `SystemInit()` function. Even if there is an FPU in the processor, the linker may still need to use runtime library functions to deal with advanced operations. A program may also define calculation functions with floating numbers, either as parameters or return values. There are several Application Binary Interfaces (ABI) to handle floating point calculations. Hence, most compilers provide options to select one of these ABIs. This will affect how parameters are passed between caller functions and callee functions, and whether the FPU is used or not. There are three ABIs:

- Soft ABI without FPU hardware. Values are passed via integer registers.
- Soft ABI with FPU hardware. The FPU is accessed directly for simple operations, but when a function is called, the integer registers are used.
- Hard ABI. The FPU is accessed directly for simple operations, and FPU-specific registers are used when a function is called, for both parameters and the return value.

It is important to note that code compiled with a particular ABI might not be compatible with code compiled with another ABI. MicroEJ modules, including the MicroEJ Core Engine, use the hard ABI.

### Supported MicroEJ Core Engine Capabilities by Architecture Matrix

The following table lists the supported MicroEJ Core Engine capabilities by MicroEJ Architectures.

Table 56: Supported MicroEJ Core Engine Capabilities by MicroEJ Architecture Matrix

MicroEJ Core Engine Architectures		Capabilities		
MCU	Compiler	Single application	Tiny application	Multi applications
ARM Cortex-M0	GCC	YES	YES	NO
ARM Cortex-M4	IAR Embedded Workbench for ARM	YES	YES	YES
ARM Cortex-M4	GCC	YES	NO	YES
ARM Cortex-M4	Keil uVision	YES	NO	YES
ARM Cortex-M7	IAR Embedded Workbench for ARM	YES	NO	YES
ARM Cortex-M7	GCC	YES	NO	YES
ARM Cortex-M7	Keil uVision	YES	NO	YES
ESP32	ESP-IDF	YES	NO	YES

### ARM Cortex-M0

Table 57: ARM Cortex-M0 Compilers

Compiler	Version	Flags and Options	Module
GCC	4.8	<code>-mabi=aapcs -mcpu=cortex-m0 -mlittle-endian -mthumb</code>	<code>flopi0G22</code>

**ARM Cortex-M4**

Table 58: ARM Cortex-M4 Compilers

Compiler	Version	Flags and Options	Module
Keil uVision	5.18.0.0	<code>--cpu Cortex-M4.fp --apcs=/hardfp --fpmode=ieee_no_fenv</code>	flopi4A20
GCC	4.8	<code>-mabi=aapcs -mcpu=cortex-m4 -mlittle-endian -mfpu=fpv4-sp-d16 -mfloat-abi=hard -mthumb</code>	flopi4G25
IAR Embedded Workbench for ARM	8.32.1.18631	<code>--cpu Cortex-M4F --fpu VFPv4_sp</code>	flopi4I35

Note: Since MicroEJ 4.0, Cortex-M4 architectures are compiled using `hardfp` convention call.

**ARM Cortex-M7**

Table 59: ARM Cortex-M7 Compilers

Compiler	Version	Flags and Options	Module
Keil uVision	5.18.0.0	<code>--cpu Cortex-M7.fp.sp --apcs=/hardfp --fpmode=ieee_no_fenv</code>	flopi7A21
GCC	4.8	<code>-mabi=aapcs -mcpu=cortex-m7 -mlittle-endian -mfpu=fpv5-sp-d16 -mfloat-abi=hard -mthumb</code>	flopi7G26
IAR Embedded Workbench for ARM	8.32.1.18631	<code>--cpu Cortex-M7 --fpu VFPv5_sp</code>	flopi7I36

**ESP32**

Table 60: Espressif ESP32 Compilers

Compiler	Version	Flags and Options	Module Name	Module Version
GCC (ESP-IDF)	5.2.0 (crosstool-ng-1.22.0-80-g6c4433a)	<code>-mlongcalls</code>	<code>simikou1</code>	Any
GCC (ESP-IDF)	5.2.0 (crosstool-ng-1.22.0-80-g6c4433a)	<code>-mlongcalls -mfix-esp32-psram-cache-issue</code>	<code>simikou2</code>	Up to <code>7.13.0</code> (included)
GCC (ESP-IDF)	5.2.0 (crosstool-ng-1.22.0-96-g2852398)	<code>-mlongcalls -mfix-esp32-psram-cache-issue</code>	<code>simikou2</code>	<code>7.13.1</code> or higher

**IAR Linker Specific Options**

This section lists options that must be passed to IAR linker for correctly linking the MicroEJ object file (`microejapp.o`) generated by the SOAR.

**`--no_range_reservations`**

MicroEJ SOAR generates ELF absolute symbols to define some link-time options (0 based values). By default, IAR linker allocates a 1 byte section on the fly, which may cause silent sections placement side effects or a section overlap error when multiple symbols are generated with the same absolute value:

```
Error[Lp023]: absolute placement (in [0x00000000-0x000000db]) overlaps with absolute symbol [...]

```

The option `--no_range_reservations` tells IAR linker to manage an absolute symbol as described by the ELF specification.

**`--diag_suppress=Lp029`**

MicroEJ SOAR generates internal veneers that may be interpreted as illegal code by IAR linker, causing the following error:

```
Error[Lp029]: instruction validation failure in section "C:\xxx\microejapp.o[.text.__ictea__virtual___1xxx#1126]": nested IT blocks. Code in wrong mode?

```

The option `--diag_suppress=Lp029` tells IAR linker to ignore instructions validation errors.

---

## KERNEL DEVELOPER GUIDE

### 5.1 Overview

#### 5.1.1 Introduction

The Kernel Developer's Guide describes how to create a MicroEJ Multi-Sandbox Firmware, i.e. a firmware that can be extended (statically or dynamically) to run and control the execution of new applications (called *Sandboxed Applications*).

The intended audience of this document are java developers and system architects who plan to design and build their own firmware.

Here is a non-exhaustive list of the activities to be done by Multi-Sandbox Firmware Developers:

- Defining a list of APIs that will be exposed to applications
- Managing lifecycles of applications (deciding when to install, start, stop and uninstall them)
- Integrating applications (called resident applications)
- Defining and applying permissions on system resources (rules & policies)
- Managing connectivity
- Controlling and monitoring resources

This document takes as prerequisite that a MicroEJ Platform is available for the target device (see *Platform Developer Guide*). This document also assumes that the reader is familiar with the development and deployment of MicroEJ Applications (see *Application Developer Guide*) and specifics of developing Sandboxed Applications (see *Sandboxed Application*).

#### 5.1.2 Terms and Definitions

A *Resident Application* is a Sandboxed Application that is linked into a Multi-Sandbox Firmware.

A *Multi-Sandbox Platform* is a Platform with the Multi Sandbox capability of the MicroEJ Core Engine enabled (see the chapter *Multi-Sandbox* of the *Platform Developer Guide*). A Multi-Sandbox Firmware can only be built with a Multi-Sandbox Platform.

A *Mono-Sandbox Firmware* is produced by building and linking a Standalone Application with a Platform.

A *Virtual Device* is the Multi-Sandbox Firmware counterpart for developing a Sandboxed Application in MicroEJ Studio. It provides the firmware functional simulation part. Usually it also provides a mean to directly deploy a Sandboxed Application on the target device running a Multi-Sandbox Firmware (this is called *Local Deployment*). In case of dynamic application deployment, the Virtual Device must be published on MicroEJ Forge instance in order to execute an internal batch applications build for this device.

### 5.1.3 Overall Architecture



Fig. 1: Firmware Boundary Overview



Fig. 2: Firmware Input and Output Artifacts

### Firmware Implementation Libraries

Firmware implementations must cover the following topics:

- The firmware's kernel entry point implementation, that deals with configuring the different policies, registering kernel services and converters, and starting applications.
- The storage infrastructure implementation: mapping the **Storage** service on an actual data storage implementation. There are multiple implementations of the data storage, provided in different artifacts that will be detailed in dedicated sections.
- The applications management infrastructure: how application code is stored in memory and how the lifecycle of the code is implemented. Again, this has multiple alternative implementations, and the right module must be selected at build time to cover the specific firmware needs.
- The simulation support: how the Virtual Device implementation reflects the firmware implementation, with the help of specific artifacts.
- The Kernel API definition: not all the classes and methods used to implement the firmware's kernel are actually exposed to the applications. There are some artifacts available that expose some of the libraries to the applications, these ones can be picked when the firmware is assembled.
- The Kernel types conversion and other KF-related utilities: Kernel types instances owned by one application can be transferred to another application through a Shared Interface. For that to be possible, a conversion proxy must be registered for this kernel type.
- Tools libraries: tools that plug into MicroEJ Studio or SDK, extending them with feature that are specific to the firmware, like deployment of an application, a management console, ...
- System Applications: pre-built applications that can be embedded as resident apps into a firmware. Some of them are user-land counter parts of the Kernel, implementing the application lifecycle for the firmware's ap-



plication framework (e.g. the Wadapps Framework). These “Kernel System Applications” rely on a dedicated set of interfaces to interact with the Kernel, this interface being defined in a dedicated module.



### 5.1.4 Firmware Build Flow

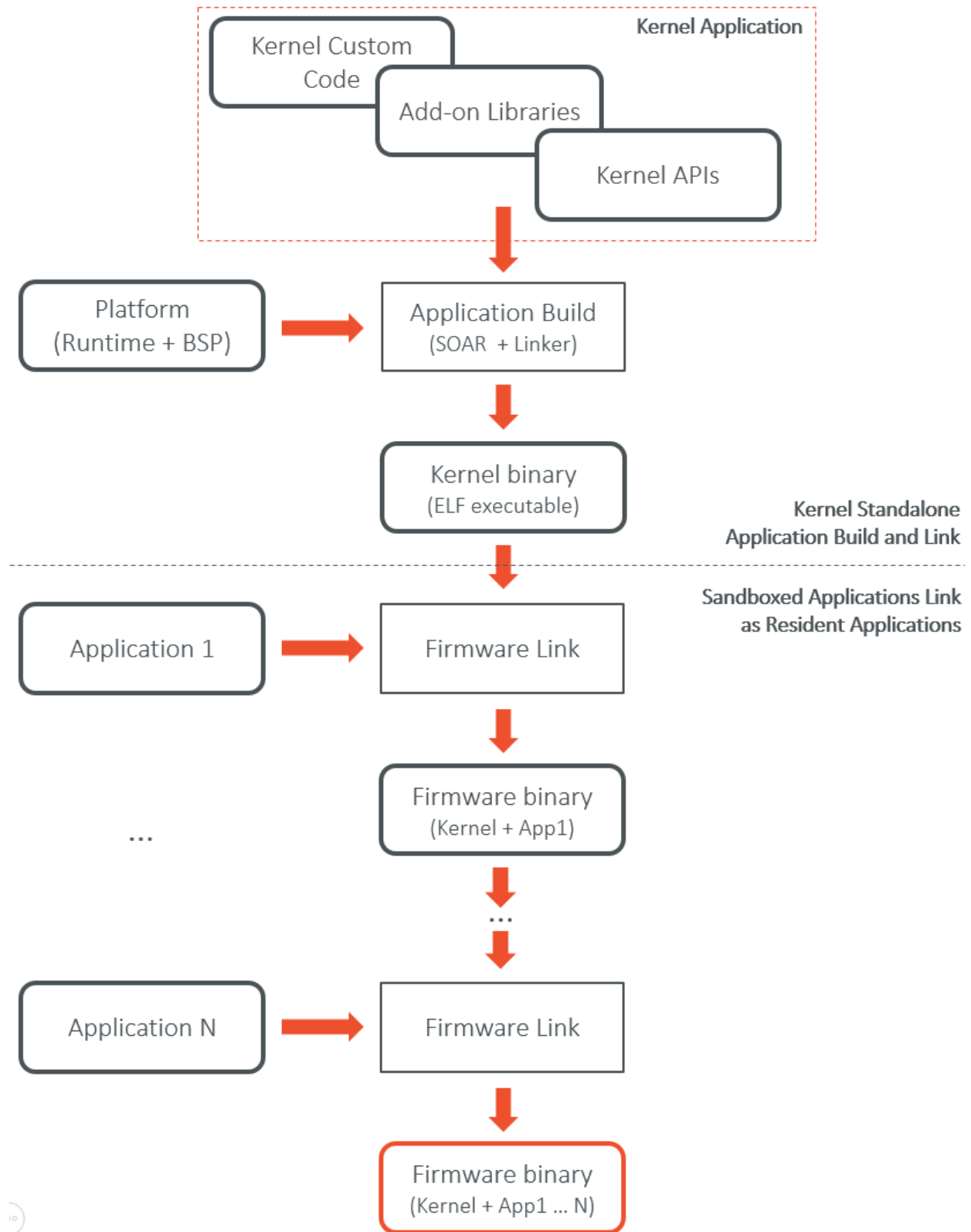


Fig. 3: Firmware Build Flow (Kernel + Resident Applications)

### 5.1.5 Virtual Device Build Flow

The Virtual Device is automatically built at the same time than the firmware when using the `build-firmware-multiapp` build type (see *Headless Build*). The Virtual Device builder performs the following steps:

- Remove the embedded part of the platform (compiler, linker and runtime).
- Append Add-On Libraries and Resident Applications into the runtime classpath. (See *Ivy Configurations*) for specifying the dependencies).
- Turn the Platform (MicroEJ SDK) license to Virtual Device (MicroEJ Studio) license so that it can be freely distributed.
- Generate the Runtime Environment from the Kernel APIs.

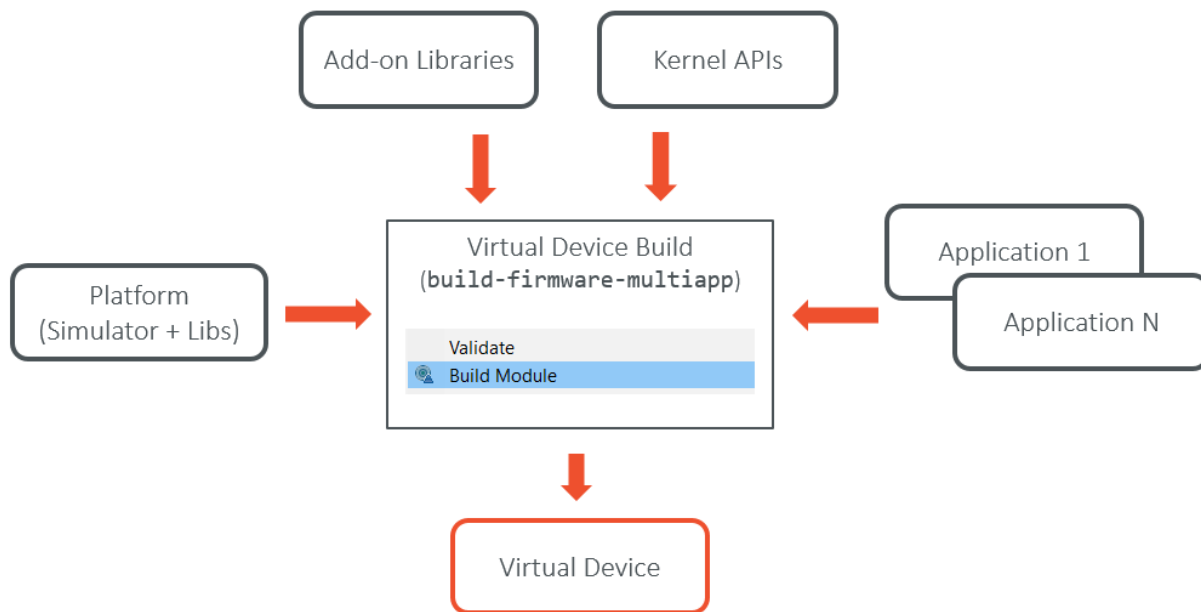


Fig. 4: Virtual Device Build Flow

## 5.2 Kernel & Features Specification

Kernel & Features semantic (KF) allows an application code to be split between multiples parts: the main application, called the *Kernel* and zero or more sandboxed applications called *Features*.

The Kernel part is mandatory and is assumed to be reliable, trusted and cannot be modified. If there is only one application, i.e only one `main` entry point that the system starts with, then this application is considered as the Kernel and called a Standalone Application. Even if there are more applications in the platform, there is still only one entry point. This entry point is the Kernel. Applications (downloaded or preinstalled) are “code extensions” (called “Features”), that are called by the Kernel. These Features are fully controlled by the Kernel: they can be installed, started, stopped and uninstalled at any time independently of the system state (particularly, a Feature never depends on an other Feature to be stopped).

The complete [KF] specification is available at <http://www.e-s-r.net/download/specification/ESR-SPE-0020-KF-1.4-F.pdf>

## 5.3 Getting Started

### 5.3.1 Online Getting Started

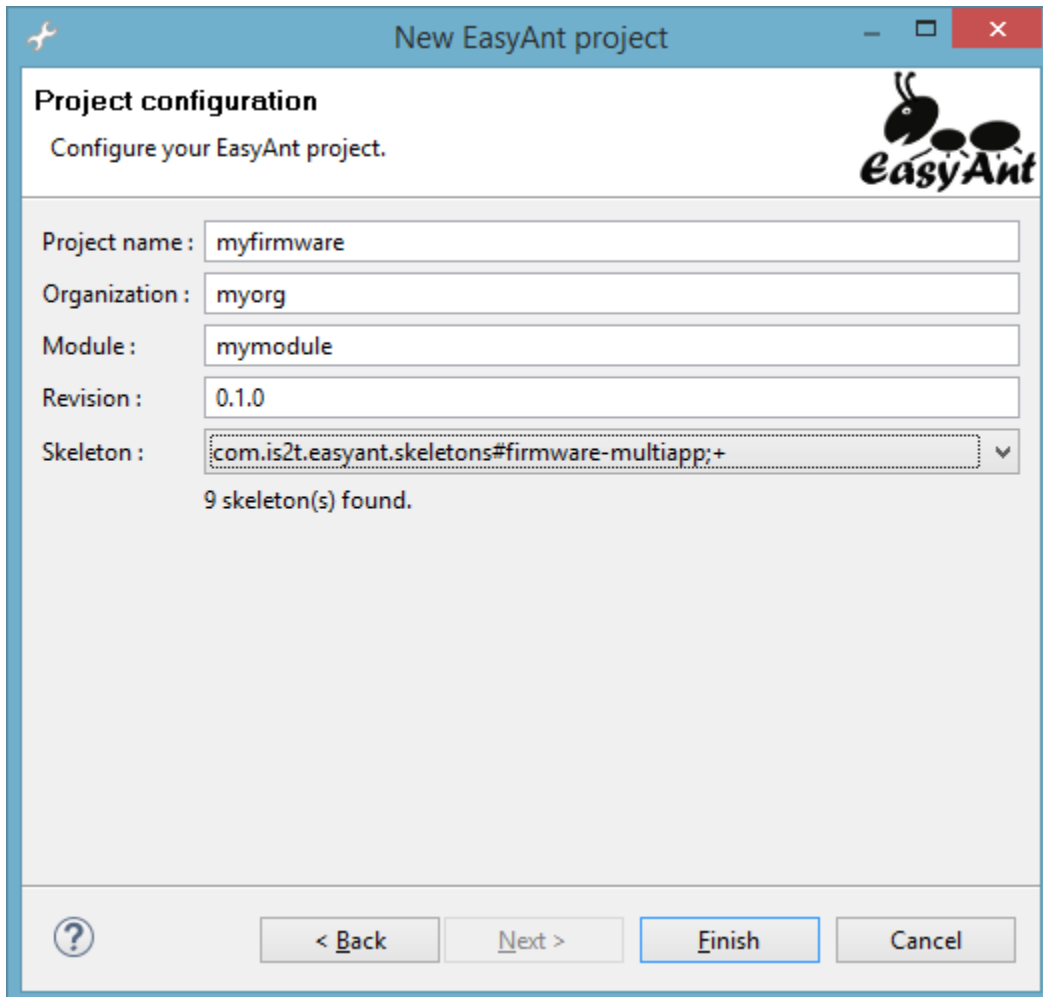
The MicroEJ Multi-Sandbox Firmware Getting Started is available on MicroEJ GitHub repository, at <https://github.com/MicroEJ/Example-MinimalMultiAppFirmware>.

The file `README.md` provides a step by step guide to produce a minimal firmware on an evaluation board on which new applications can be dynamically deployed through a serial or a TCP/IP connection.

### 5.3.2 Create an Empty Firmware from Scratch

#### Create a new Firmware Project

First create a new *module project* using the `build-firmware-multiapp` skeleton.



**New EasyAnt project**

**Project configuration**  
Configure your EasyAnt project.

Project name: myfirmware

Organization: myorg

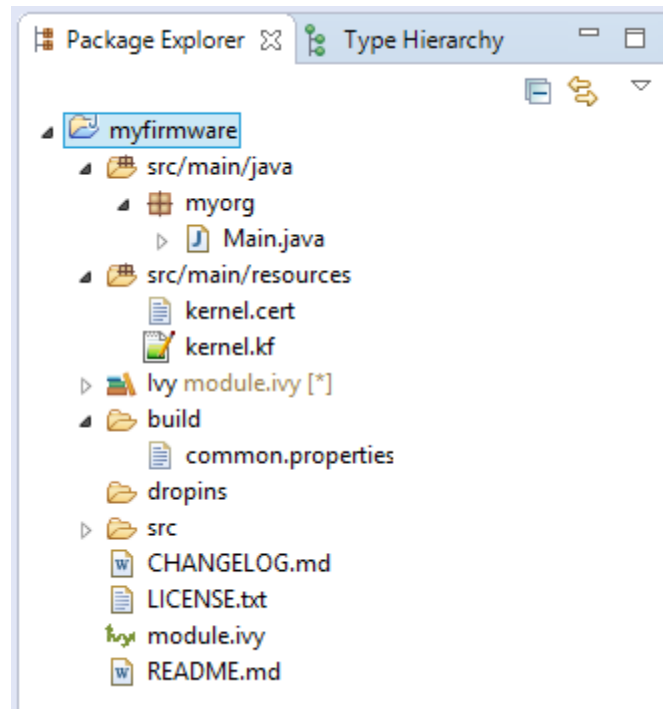
Module: mymodule

Revision: 0.1.0

Skeleton: com.is2t.easyant.skeletons#firmware-multiapp;+  
9 skeleton(s) found.

? < Back Next > Finish Cancel

A new project is generated into the workspace:



### Setup a Platform

Before building the firmware, a target platform must be configured. The easiest way to do it is to copy a platform file into the `myfirmware > dropins` folder. Such file usually ends with `.jpf`. For other ways to setup the input platform to build a firmware see [Change the Platform used to Build the Firmware and the Virtual Device](#).

### Build the Firmware

In the Package Explorer, right-click on the firmware project and select **Build Module**. The build of the Firmware and Virtual Device may take several minutes. When the build is succeed, the folder `myfirmware > target~ > artifacts` contains the firmware output artifacts (see [Firmware Input and Output Artifacts](#)):

- `mymodule.out`: The Firmware Binary to be programmed on device.
- `mymodule.kpk`: The Firmware Package to be imported in a MicroEJ Forge instance.
- `mymodule.vde`: The Virtual Device to be imported in MicroEJ Studio.
- `mymodule-workingEnv.zip`: This file contains all files produced by the build phasis (intermediate, debug and report files).



### 5.3.3 MicroEJ Demo VEE Flavors

This set of APIs is proposed as examples of industrial or commercial typical products APIs.

#### What is a MicroEJ Demo Runtime Environment?

A MicroEJ Runtime Environment defines a set of MicroEJ APIs exposed to a MicroEJ Sandboxed Application. Here are the default runtimes provided for evaluation by MicroEJ. Any runtime can be customized with MicroEJ SDK for a specific product.

MicroEJ Demo Run-time Environment	EDC/B-ON/KF	COMP/WADAPPS	MICROUI/MWT	LEDS/BUTTONS	NET/CONNECTIVITY	SSL	HAL	ECOM/COMM
MicroEJ-Developer	✓	✓	✓	✓	✓		✓	✓
MicroEJ-UI	✓	✓	✓	✓			✓	✓
MicroEJ-Headless	✓	✓		✓	✓		✓	✓
MicroEJ-BLE	✓	✓	✓	✓	✓	✓	✓	✓

You can find below what are the different APIs included in the Runtime Environment:

API	Purpose
EDC	Core APIs for the execution.
B-ON	Memory Usage control and Sequences start-up.
KF	Required by the implementation of Shared Interfaces, an inter-application communication process.
COMP or COMPONENTS	Lightweight Services Framework.
WADAPPS	Wadapps Application Framework.
MICROUI/MWT	Main UI library for MicroEJ and the Widgets framework based on MicroUI.
LEDS or MICROUI-LEDS	UI library specific to LEDs.
BUTTONS or MICROUI-BUTTONS	UI library specific to buttons.
NET	Socket (TCP/UDP) library.
CONNECT or CONNECTIVITY	Network connectivity detection library.
SSL	Secure Socket Layer.
BLE	Bluetooth Low Energy support.
HAL	GPIO Access (digital and analog)
ECOM	Device access framework.
COMM or ECOM-COMM	Serial ports support for the ECOM.

#### What is a MicroEJ Demo Flavor?

A MicroEJ Demo Flavor is a composition of a set of runtime services, resident applications and a given MicroEJ Runtime Environment. Any flavor can be customized with MicroEJ SDK for a specific product.



MicroEJ Demo Flavor	MicroEJ Runtime Environment	Services Resident Apps				UI Resident Apps		
		Management	App-Metadata-Storage	CommandServer-Socket	NTP	About	AppList	Forge Connect
Green	MicroEJ-Developer	✓	✓	✓	✓			
Blue	MicroEJ-Developer	✓	✓	✓	✓	✓	✓	✓
Red	MicroEJ-UI	✓	✓			✓	✓	
Purple	MicroEJ-Headless	✓	✓	✓	✓			
Black	MicroEJ-BLE	✓	✓	✓	✓			✓

You can find below what are the different System Apps included in the Flavor:

System Apps	Purpose
Management	Contains the implementation of Wadapps framework services, required by all VEE.
App-Metadata-Storage	Stores some Applications Metadata (icons, descriptions) so that it can be locally used by a MicroEJ Companion.
CommandServer-Socket	Allows the deployment of MicroEJ Applications through a local network connection.
NTP	Synchronizes the time of the device.
About	Displays version information about the VEE.
AppList	An application browser, can be used to start, stop or uninstall the applications, or display their descriptions and version information.
Forge Connect	Displays a desktop that allows the management of MicroEJ Applications using a connection to MICROEJ FORGE.
Settings	Displays the VEE parameters and settings.

## 5.4 Build Firmware

Prerequisite of this chapter: minimum understanding of *MicroEJ Module Manager*.



### 5.4.1 Workspace Build

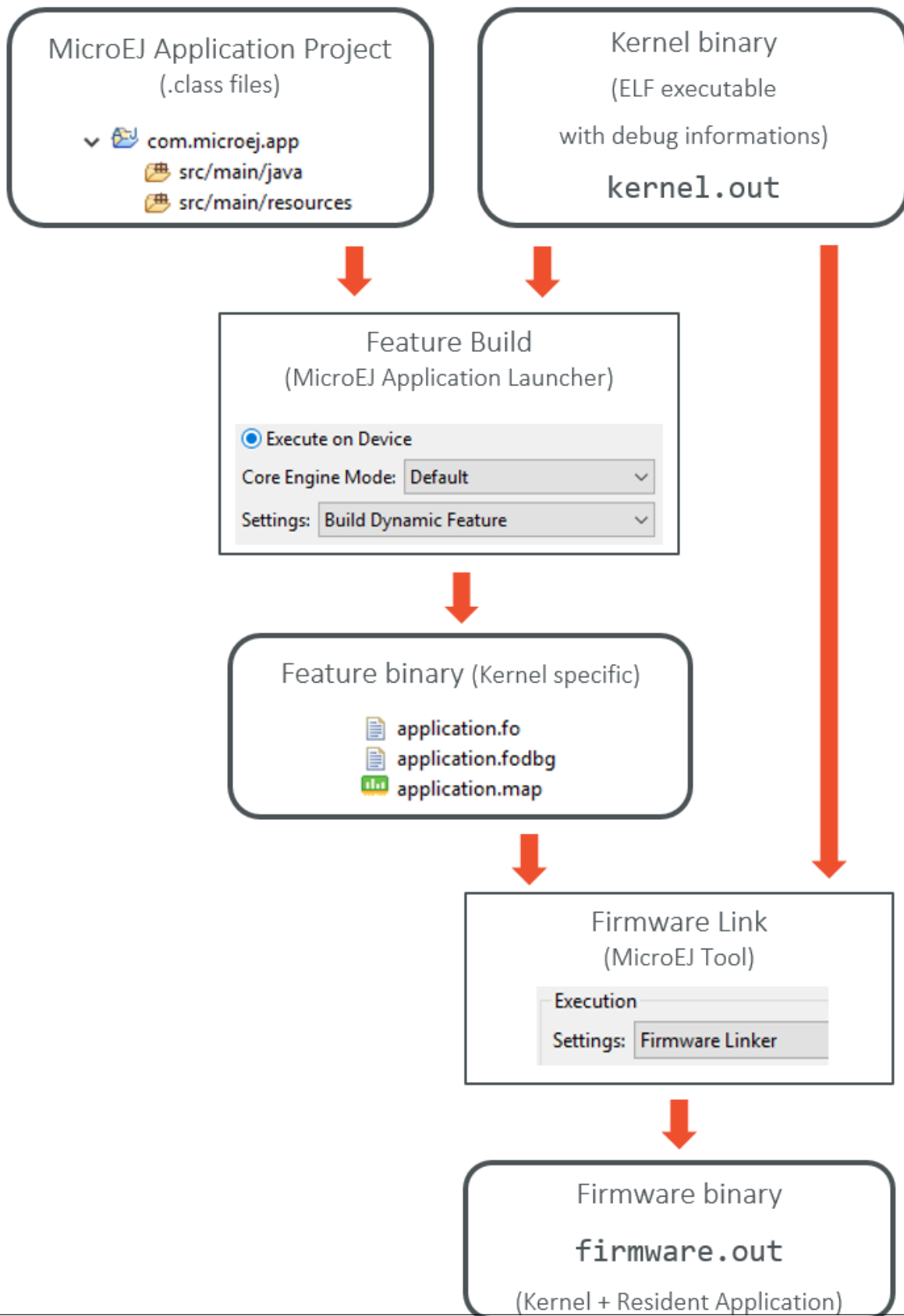
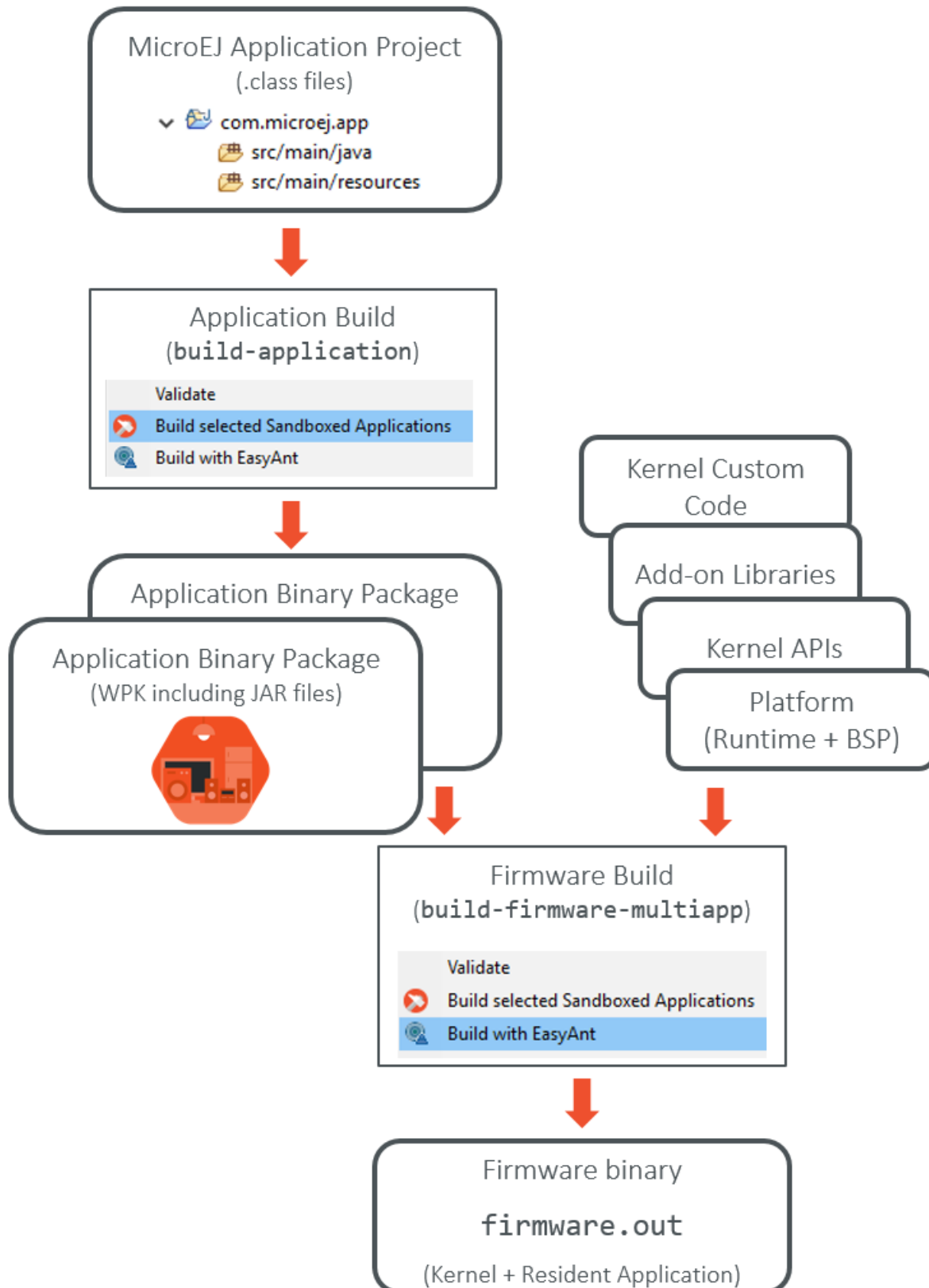


Fig. 5: Firmware Build Flow in MicroEJ SDK Workspace



### 5.4.2 Headless Build



### 5.4.3 Runtime Environment

A Firmware define a runtime environment which is the set of classes, methods and fields all applications are allowed to use. In most of the cases the runtime environment is an aggregation of several kernel APIs built with *module project build-runtime-api* skeleton.

```
<info organisation="myorg" module="mymodule" status="integration"
revision="1.0.0">
  <ea:build organisation="com.is2t.easyant.buildtypes" module="build-runtime-api" revision="2.+ ">
    <ea:plugin org="com.is2t.easyant.plugins" module="clean-artifacts" revision="2.+ " />
    <ea:property name="clean.artifacts.max.keep" value="2" />
    <ea:property name="runtime.api.name" value="RUNTIME"/>
    <ea:property name="runtime.api.version" value="1.0"/>
  </ea:build>
</info>
```

The `runtime.api.name` property define the name of the runtime environment (it is required by the build type) , and the `runtime.api.version` property define it version. If the property `runtime.api.version` is not provided the build type computes it using the revision of the ivy module.

```
<dependencies>
  <dependency org="com.microej.kernelapi" name="edc" rev="[1.0.4-RC0,1.0.5-RC0[" transitive="false"/>
  <dependency org="com.microej.kernelapi" name="kf" rev="[2.0.1-RC0,2.0.2-RC0[" transitive="false"/>
  <dependency org="com.microej.kernelapi" name="bon" rev="[1.0.4-RC0,1.0.5-RC0[" transitive="false"/>
  <dependency org="com.microej.kernelapi" name="wadapps" rev="[1.2.2-RC0,1.2.3-RC0[" transitive="false
  ↪"/>
  <dependency org="com.microej.kernelapi" name="components" rev="[1.2.2-RC0,1.2.3-RC0[" transitive=
  ↪"false"/>
</dependencies>
```

This runtime environment aggregate all classes, methods and fields defined by `edc`, `kf`, `bon`, `wadapps`, `components` kernel APIs.

The documentation of a runtime environment is packaged into the Virtual Device as HTML javadoc ( [Help](#) > [MicroEJ Resource Center](#) > [Javadoc](#) ).

### Specify the Runtime Environment of the Firmware

While building a firmware, two ways exist to specify the runtime environment:

- By using one or more ivy dependencies of `kernel API` artifacts. In this case we must set properties `runtime.api.name` and `runtime.api.version`.
- By using the ivy dependency `runtimeapi` module.

### 5.4.4 Resident Applications

A MicroEJ Sandboxed Application can be dynamically installed from a MicroEJ Forge instance or can be directly linked into the Firmware binary at built-time. In this case, it is called a Resident Application.

The user can specify the Resident Applications in two different ways:

- Set the property `build-systemapps.dropins.dir` to a folder with contains all the resident applications.
- Add ivy dependency on each resident application:

```
<dependency org="com.microej.app.wadapps" name="management"
rev="[2.2.2-RC0,3.0.0-RC0[" conf="systemapp->application"/>
```

All Resident Applications are also available for the Virtual Device, if a resident application should only be available for the Firmware, use an ivy dependency with the ivy configuration `systemapp-fw` instead of `systemapp`, like:

```
<dependency org="com.microej.app.wadapps" name="management" rev="[2.2.2-RC0,3.0.0-RC0[" conf="systemapp-
↳fw->application"/>
```

## 5.4.5 Advanced

### MicroEJ Firmware `module.ivy`

The following section describes *module description file* ( `module.ivy` ) generated by the `build-firmware-multiapp` skeleton.

#### Ivy info

```
<info organisation="org" module="module" status="integration"
revision="1.0.0">
  <ea:build organisation="com.is2t.easyant.buildtypes" module="build-firmware-multiapp" revision="2.+
↳"/>
  <ea:property name="application.main.class" value="org.Main" />
  <ea:property name="runtime.api.name" value="RUNTIME" />
  <ea:property name="runtime.api.version" value="0.1.0" />
</info>
```

The property `application.main.class` is set to the fully qualified name of the main java class. The firmware generated from the skeleton defines its own runtime environment by using ivy dependencies on several `kernel API` instead of relying on a runtime environment module. As consequence, the `runtime.api.name` and `runtime.api.version` properties are specified in the firmware project itself.

#### Ivy Configurations

The `build-firmware-multiapp` build type requires the following configurations, used to specify the different kind of firmware inputs (see *Firmware Input and Output Artifacts*) as Ivy dependencies.

```
<configurations defaultconfmapping="default->default;provided->provided">
  <conf name="default" visibility="public"/>
  <conf name="provided" visibility="public"/>
  <conf name="platform" visibility="public"/>
  <conf name="vdruntime" visibility="public"/>
  <conf name="kernelapi" visibility="private"/>
  <conf name="systemapp" visibility="private"/>
  <conf name="systemapp-fw" visibility="private"/>
</configurations>
```

The following table lists the different configuration mapping usage where a dependency line is declared:

```
<dependency org="..." name="..." rev="..." conf="[Configuration Mapping]"/>
```

Table 1: Configurations Mapping for `build-firmware-multiapp` Build Type

Configuration Mapping	Dependency Kind	Usage
<code>provided-&gt;provided</code>	Foundation Library ( <code>JAR</code> )	Expected to be provided by the platform. (e.g. <code>ej.api.*</code> module)
<code>default-&gt;default</code>	Add-On Library ( <code>JAR</code> )	Embedded in the firmware only, not in the Virtual Device
<code>vdruntime-&gt;default</code>	Add-On Library ( <code>JAR</code> )	Embedded in the Virtual Device only, not in the firmware
<code>default-&gt;default; vdruntime-&gt;default</code>	Add-On Library ( <code>JAR</code> )	Embedded in both the firmware and the Virtual Device
<code>platform-&gt;platformDev</code>	Platform ( <code>JPF</code> )	Platform dependency used to build the firmware and the Virtual Device. There are other ways to select the platform (see <i>Change the Platform used to Build the Firmware and the Virtual Device</i> )
<code>kernelapi-&gt;default</code>	Runtime Environment ( <code>JAR</code> )	See <i>Runtime Environment</i>
<code>systemapp-&gt;application</code>	Application ( <code>WPK</code> )	Linked into both the firmware and the Virtual Device as resident application. There are other ways to select resident applications (see <i>Resident Applications</i> )
<code>systemapp-fw-&gt;application</code>	Application ( <code>WPK</code> )	Linked into the firmware only as resident application.

**Example of minimal firmware dependencies.**

The following example firmware contains one system app (`management`), and defines an API that contains all types, methods, and fields from `edc`, `kf`, `wadapps`, `components`.

```
<dependencies>
  <dependency org="ej.api" name="edc" rev="[1.2.0-RC0,2.0.0-RC0[" conf="provided" />
  <dependency org="ej.api" name="kf" rev="[1.4.0-RC0,2.0.0-RC0[" conf="provided" />
  <dependency org="ej.library.wadapps" name="framework" rev="[1.0.0-RC0,2.0.0-RC0[" />
  <dependency org="com.microej.library.wadapps.kernel" name="common-impl" rev="[3.0.0-RC0,4.0.0-RC0[" />
</>
  <dependency org="com.microej.library.wadapps" name="admin-kf-default" rev="[1.2.0-RC0,2.0.0-RC0[" />
  <!-- Runtime API (set of Kernel API files) -->
  <dependency org="com.microej.kernelapi" name="edc" rev="[1.0.0-RC0,2.0.0-RC0[" conf="kernelapi->
  default"/>
  <dependency org="com.microej.kernelapi" name="kf" rev="[2.0.0-RC0,3.0.0-RC0[" conf="kernelapi->
  default"/>
  <dependency org="com.microej.kernelapi" name="wadapps" rev="[1.0.0-RC0,2.0.0-RC0[" conf="kernelapi->
  default"/>
  <dependency org="com.microej.kernelapi" name="components" rev="[1.0.0-RC0,2.0.0-RC0[" conf=
  "kernelapi->default"/>
  <!-- System apps -->
  <dependency org="com.microej.app.wadapps" name="management"
    rev="[2.2.2-RC0,3.0.0-RC0[" conf="systemapp->application"/>
</dependencies>
```

**Change the set of Properties used to Build a Firmware**

The build use the file `build/common.properties` to configure the build process.



## Change the Platform used to Build the Firmware and the Virtual Device

To build a firmware and a Virtual Device a platform must be specified. Four different ways are possible to do so:

- Use an Ivy dependency.

```
<dependency org="myorg" name="myname" rev="1.0.0" conf="platform->platformDev" transitive="false"/>
```

- Copy/Paste a platform file into the folder defined by the property `platform-loader.target.platform.dropins` (by default its value is `dropins`).
- Set the property `platform-loader.target.platform.file`.

```
<ea:property name="platform-loader.target.platform.file" value="/path-to-a-platform-file/" />
```

- Set the property `platform-loader.target.platform.dir`.

```
<ea:property name="platform-loader.target.platform.dir" value="/path-to-a-platform-folder/" />
```

## Build only a Firmware

Set the property `skip.build.virtual.device`

```
<ea:property name="skip.build.virtual.device" value="SET" />
```

## Build only a Virtual Device

Set the property `virtual.device.sim.only`

```
<ea:property name="virtual.device.sim.only" value="SET" />
```

## Build only a Virtual Device with a pre-existing Firmware

Copy/Paste the `.kpk` file into the folder `dropins`

## 5.5 Writing Kernel APIs

This section lists different ways to help to write `kernel.api` files.

### 5.5.1 Default Kernel APIs Derivation

MicroEJ provides predefined kernel API files for the most common libraries provided by a Kernel. These files are packaged as MicroEJ modules under the `com/microej/kernelapi` organisation.

The packaged file `kernel.api` can be extracted from the JAR file and edited in order to keep only desired types, methods and fields.

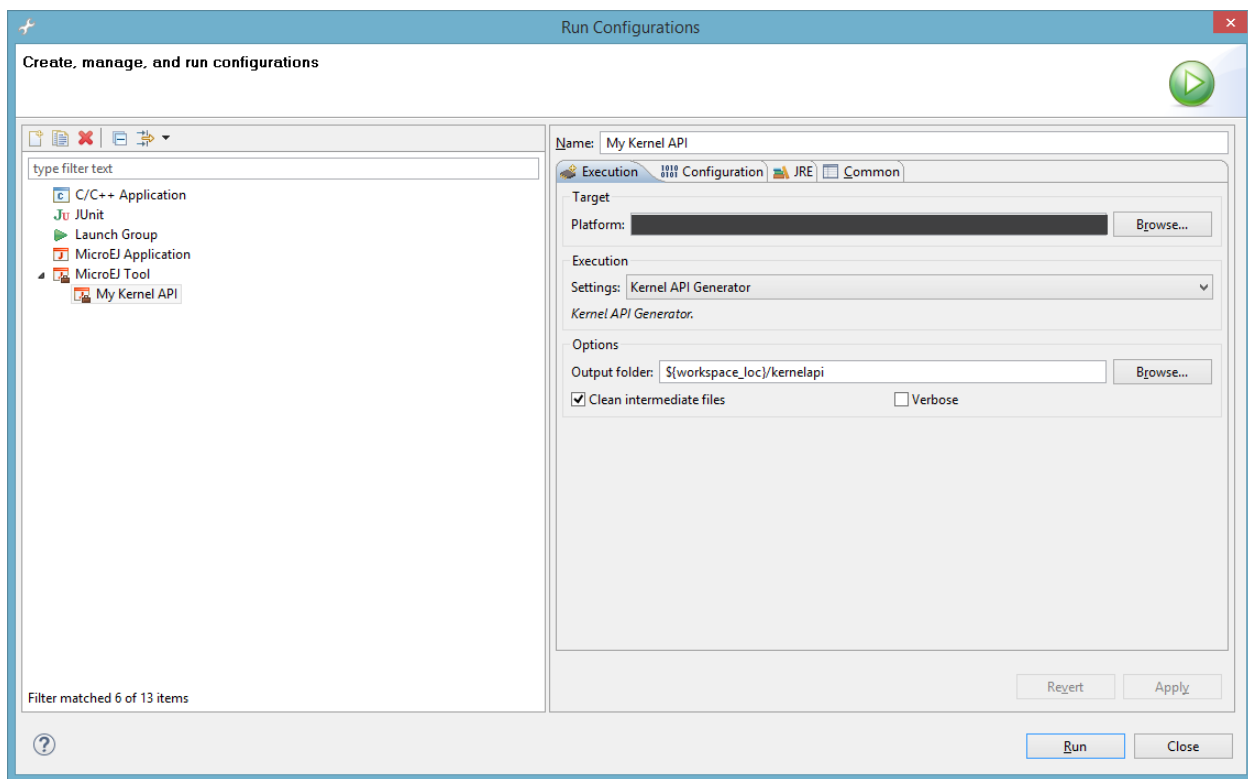
### 5.5.2 Build a Kernel API Module

- First create a new *module project* using the `microej-kernelapi` skeleton.
- Create the `kernel.api` file into the `src` folder.
- Right-click on the project and select **Build Module** .

### 5.5.3 Kernel API Generator

MicroEJ Kernel API Generator is a tool that help to generate a `kernel.api` file based on a Java classpath.

In MicroEJ SDK, create a new MicroEJ Tool launch, **Run** > **Run Configurations** > **MicroEJ Tool** , choose your Platform, select **Kernel API Generator** for the **Settings** options, and don't forget to set the output folder.



Define the classpath to use in the **Configuration** tab, and Press **Run** . A `kernel.api` file is generated in the output folder and it contains all classes, methods and fields found in the given classpath.

**Category: Kernel API Generator**
**Group: Classpath****Option(list):**

*Option Name:* `kernel.api.generator.classpath`

*Default value:* (empty)

**Group: Types Filters****Option(text): Includes Patterns**

*Option Name:* `kernel.api.generator.includes.patterns`

*Default value:* `**/*.class`

*Description:* Comma separated list of ANT Patterns for types to include.

**Option(text): Excludes Patterns**

*Option Name:* `kernel.api.generator.excludes.patterns`

*Default value:* (empty)

*Description:* Comma separated list of ANT Patterns for types to exclude.

## 5.6 Communication between Features

Features can communicate together through the use of shared interfaces. The mechanism is described in *Chapter Shared Interfaces* of the Application Developer's Guide.

### 5.6.1 Kernel Type Converters

The shared interface mechanism allows to transfer an object instance of a Kernel type from one Feature to an other. To do that, the Kernel must register a new converter (See *API Documentation* `Kernel.addConverter()` method).

## 5.7 API Documentation

The full API documentation of the Kernel & Features Foundation Library is available in MicroEJ SDK ( [Help](#) > [MicroEJ Resource Center](#) > [Javadoc](#) > [KF \[version\]](#) ).

## 5.8 Multi-Sandbox Enabled Libraries

A multi-Sandbox enabled library is a foundation or Add-On Library which can be embedded into the kernel and exposed as API. MicroEJ Foundation Libraries provided in MicroEJ SDK are already multi-Sandbox enabled. A stateless library - i.e. a library that does not contain any method modifying an internal global state - is multi-Sandbox enabled by default.

This section details the multi-Sandbox semantic that have been added to MicroEJ Foundation Libraries in order to be multi-Sandbox enabled.

### 5.8.1 MicroUI

#### Physical Display Ownership

The physical display is owned by only one context at a time (the Kernel or one Feature). The following cases may trigger a physical display owner switch:

- during a call to `ej.microui.display.Displayable.show()` : after the successful permission check, it is assigned to the context owner.
- during a call to `ej.microui.display.Display.callSerially(java.lang.Runnable)` : after the successful permission check it is assigned to owner of the `Runnable` instance.

The physical display switch performs the following actions:

- If a `Displayable` instance is currently shown on the `Display`, the method `Displayable.becomeHidden()` is called.
- All pending events (input events, display flushes, call serially runnable instances) are removed from the display event serializer
- System Event Generators handlers are reset to their default `ej.microui.util.EventHandler` instance.

## Automatically Reclaimed Resources

Instances of `ej.microui.display.Image`, `ej.microui.display.Font` are automatically reclaimed when a Feature is stopped.

### 5.8.2 ECOM

The `ej.ecom.DeviceManager` registry allows to share devices across Features. Instances of `ej.ecom.Device` that are registered with a shared interface type are made accessible through a Proxy to all other Features that embed the same shared interface (or an upper one of the hierarchy).

### 5.8.3 ECOM-COMM

Instances of `ej.ecom.io.CommConnection` are automatically reclaimed when a Feature is stopped.

### 5.8.4 FS

Instances of `java.io.FileInputStream`, `java.io.FileOutputStream` are automatically reclaimed when a Feature is stopped.

### 5.8.5 NET

Instances of `java.net.Socket`, `java.net.ServerSocket`, `java.net.DatagramSocket` are automatically reclaimed when a Feature is stopped.

### 5.8.6 SSL

Instances of `javax.net.ssl.SSLSocket` are automatically reclaimed when a Feature is stopped.

## 5.9 Setup a KF Testsuite

A KF testsuite can be executed when building a Foundation Library or an Add-On library, and usually extends the tests written for the *default library testsuite* to verify the behavior of this library when its APIs are exposed by a Kernel.

A KF testsuite is composed of a set of KF tests, each KF test itself is a minimal MicroEJ Multi-Sandbox Firmware composed of a Kernel and zero or more Features.

### 5.9.1 Enable the Testsuite

In an existing library project:

- Create the `src/test/projects` directory,
- Edit the `module.ivy` and insert the following line within the `<ea:build>` XML element:

```
<ea:plugin organisation="com.is2t.easyant.plugins" module="microej-kf-testsuite" revision="+" />
```

### 5.9.2 Add a KF Test

A KF test is a structured directory placed in the `src/test/projects` directory.

- Create a new directory for the KF test
- Within this directory, create the sub-projects:
  - Create a new *module project* for the Kernel using the `microej-javalib` skeleton,
  - Create a new *module project* for the Feature using the `application` skeleton,
  - Create a new *module project* for the Firmware using the `firmware-multiapp` skeleton.

The names of the project directories are free, however MicroEJ suggests the following naming convention, assuming the KF test directory is `[TestName]` :

- `[TestName]-kernel` for the Kernel project,
- `[TestName]-app[1..N]` for Feature projects,
- `[TestName]-firmware` for the Firmware project.

The KF Testsuite structure shall be similar to the following figure:

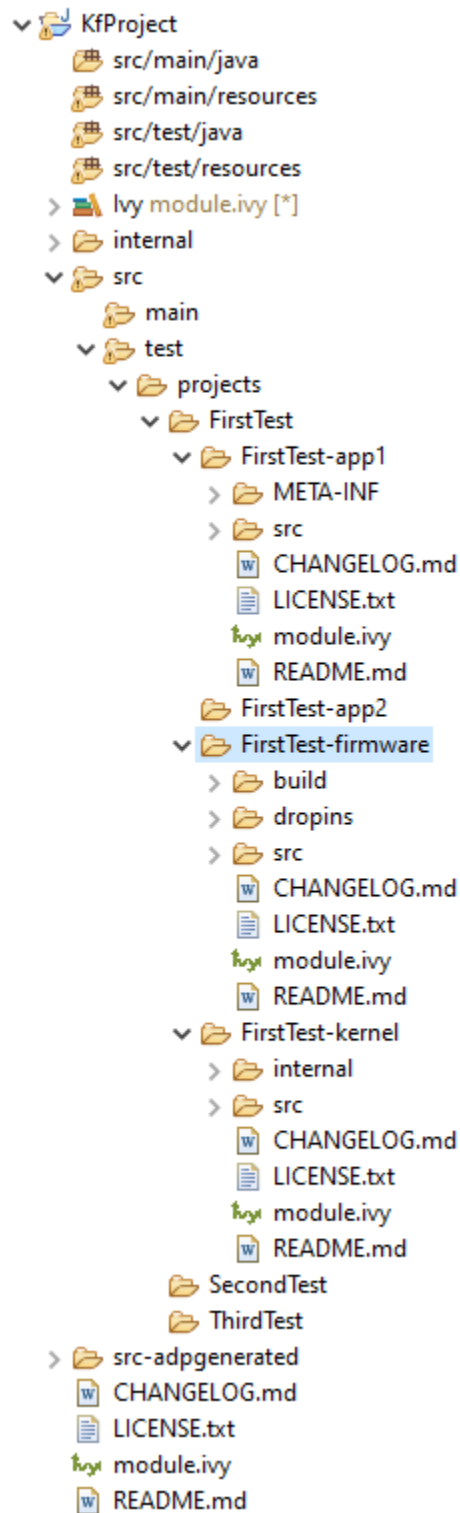


Fig. 6: KF Testsuite Overall Structure

All the projects will be built automatically in the right order based on their dependencies.

### 5.9.3 KF Testsuite Options

It is possible to configure the same options defined by *Testsuite Options* for the KF testsuite, by using the prefix `microej.kf.testsuite.properties` instead of `microej.testsuite.properties`.



## TUTORIALS

## 6.1 Understand How to Build a MicroEJ Firmware and its Dependencies

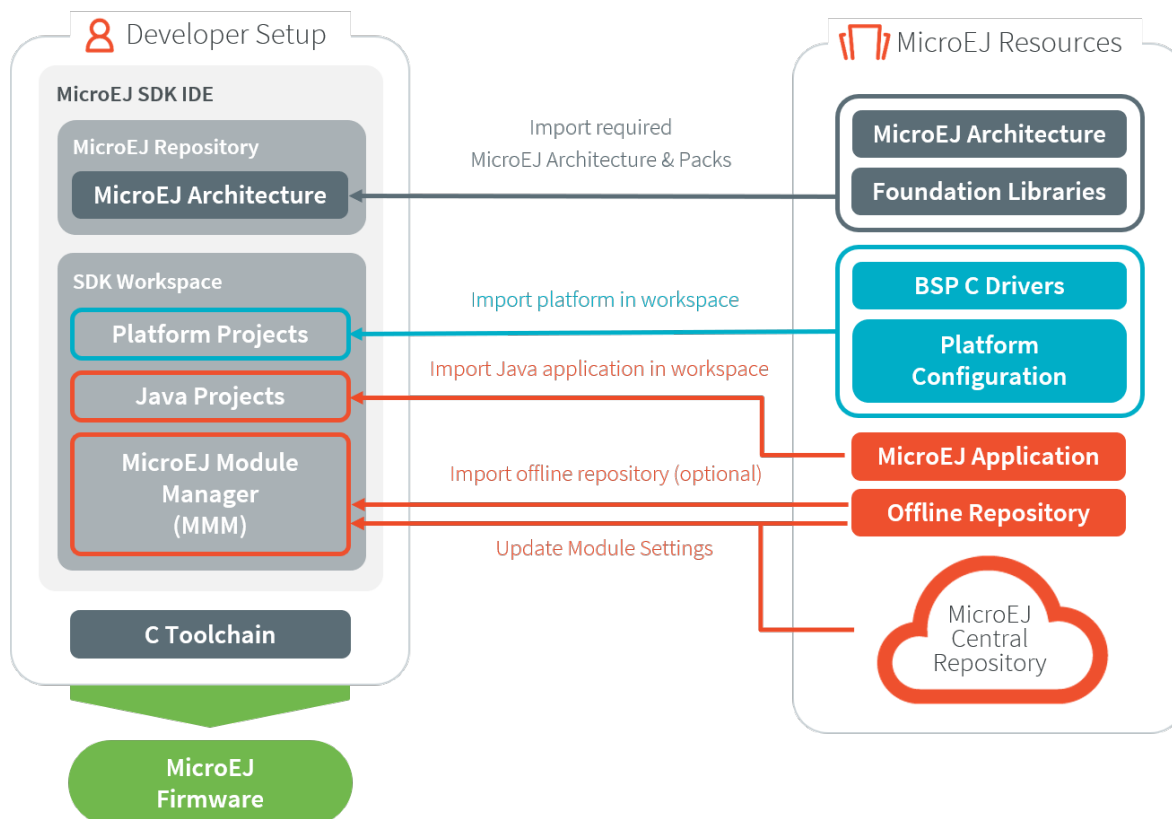
A MicroEJ Firmware is built from several input resources and tools. Each component has dependencies and requirements that must be carefully respected in order to build a firmware.

This document describes the components, their dependencies and the process involved in the build of a MicroEJ Firmware.

Good knowledge of the *MicroEJ Glossary* is required.

### 6.1.1 The Components

As depicted in the following image, several resources and tools are used to build a MicroEJ Firmware.



## MicroEJ Architecture (.xpf, .xpfp)

A MicroEJ Architecture contains the runtime port to a target instruction set (ISA) and a C compiler (CC) and MicroEJ Foundation Libraries.

The MicroEJ Architectures are distributed into two formats:

- EVAL: evaluation license with runtime limitations (explained in SDK developer guide).
- PROD: production license (only MicroEJ sales & Customer Care team distribute this version).

The supported MicroEJ Architectures are listed here <https://developer.microej.com/mej32-embedded-runtime-architectures/#arch>

The MicroEJ Architecture is either provided from:

- For EVAL license only: the MicroEJ Repository at <https://repository.microej.com/architectures/>
- For PROD license only: SDK license site <https://license.microej.com/> ( `MyProduct` > `Download additional products` will list the downloads available). See *Production Licenses* for help with PROD license.
- MicroEJ sales or customer care team if the requested architecture is not listed as available.

See *MicroEJ Architecture Import* for a description on how to import a MicroEJ Architecture.

## MicroEJ Platform Source (.zip)

This package includes:

- a C Board Support Package (BSP) with C drivers and an optional RTOS
- a MEJ32 Architecture
- the abstraction layers implementation of the platform architecture and foundations libraries
- the MicroEJ Simulator and its associated MicroEJ Mocks

The platform .zip files contain:

- `<platform>-configuration` : The configuration of the MicroEJ Platform
- `<platform>-bsp` : The C code for the board-specific files (drivers).
- `<platform>-fp` : Front panel mockup for the simulator.

See *New MicroEJ Platform Creation* to learn how to create a MicroEJ Platform using a MicroEJ Platform Source project.

Depending on the project's requirements, the MicroEJ Platform can be connected in various ways to the BSP; see *BSP Connection* for more information on how to do it.

## MicroEJ Application

A MicroEJ Application is a Java project that can be configured (in the `Run configurations ...` properties):

1. to either run on:
  - a simulator (computer desktop),
  - a device (actual embedded hardware).
2. to setup:

- memory (example: Java heap, Java stack),
- foundation libraries,
- etc.

To run on a device, the application is compiled and optimized for a specific MicroEJ Platform. It generates a `microejapp.o` (native object code) linked with the `<platform>-bsp` project.

To import an existing MicroEJ Application as a zipped project in the SDK:

- Go to **File** > **Import...** > **General** > **Existing Projects into Workspace** > **Select archive file** > **Browse...** .
- Select the zip of the project (e.g. `x.zip`).
- And select **Finish** import.

See *Create a MicroEJ Standalone Application* for more information on how to create, configure, and develop a MicroEJ Application.

### C Toolchain (GCC, KEIL, IAR, ...)

Used to compile and link the following files into the final firmware (binary, hex, elf, ... that will be programmed on the hardware):

- the `microejapp.o` (application),
- the `microejruntime.lib` or `microejruntime.a` (platform),
- the BSP C files (drivers).

### Module Repository

A Module Repository provides the modules required to build MicroEJ Platforms and MicroEJ Applications.

- The MicroEJ Central Repository is an online repository of software modules (libraries, tools, etc.), see <https://repository.microej.com/>. This repository can also be used as an offline repository, see <https://developer.microej.com/central-repository/>.
- (Optional) It can be extended with an offline repository ( `.zip` ) that can be imported in the workspace (see *Use the Offline Repository*):

See *Module Repository* for more information.

### Dependencies Between Components

- A MicroEJ Architecture targets a specific instruction set (ISA) and a specific C compiler (CC).
  - The C toolchain used for the MicroEJ Architecture must be the same as the one used to compile and link the BSP project and the MicroEJ Firmware.
- A MicroEJ Platform consists of the aggregation of both a MicroEJ Architecture and a BSP with a C toolchain.
  - Changing either the MicroEJ Architecture or the C toolchain results in a change of the MicroEJ Platform.
- A MicroEJ Application is independent of the MicroEJ Architecture.
  - It can run on any MicroEJ Platform as long the platform provides the required APIs.

- To run a MicroEJ Application on a new device, create a new MicroEJ Platform for this device with the exact same features. The MicroEJ Application will not require any change.

### 6.1.2 How to Build

The process to build a MicroEJ Firmware is two-fold:

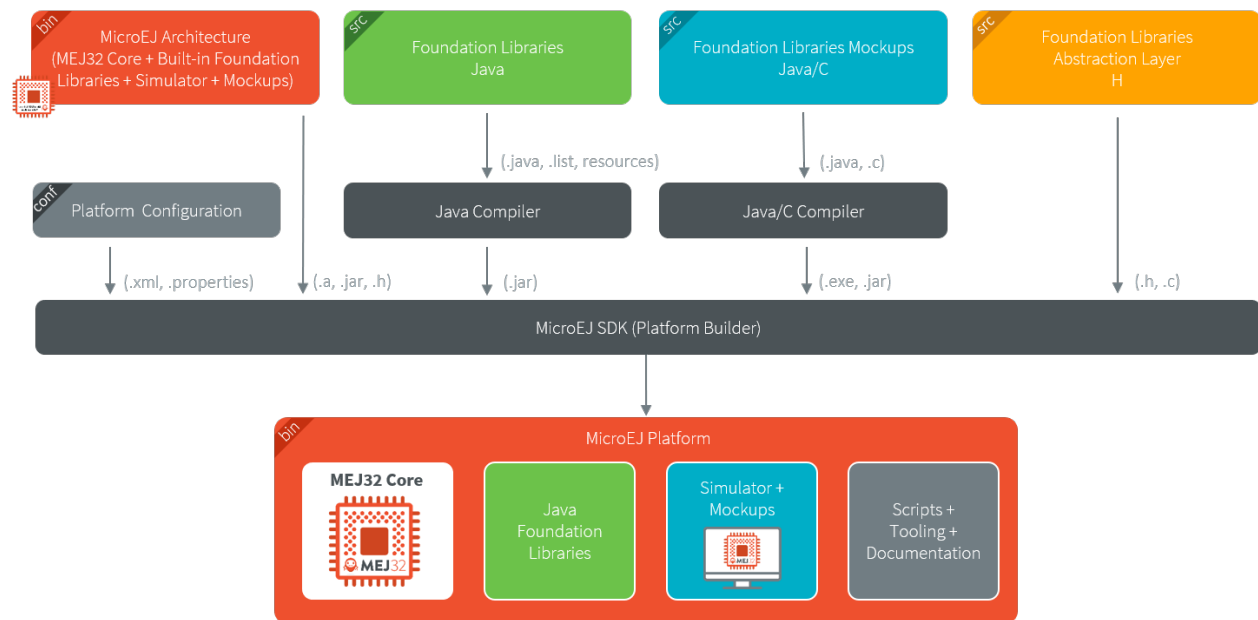
1. Build a MicroEJ Platform
2. Build a MicroEJ Application

The MicroEJ Application is compiled against the MicroEJ Platform to produce the MicroEJ Firmware deployed on the target device.

**Note:** The MicroEJ Application also runs onto the MicroEJ Simulator using the mocks provided by the MicroEJ Platform.

#### Build a MicroEJ Platform

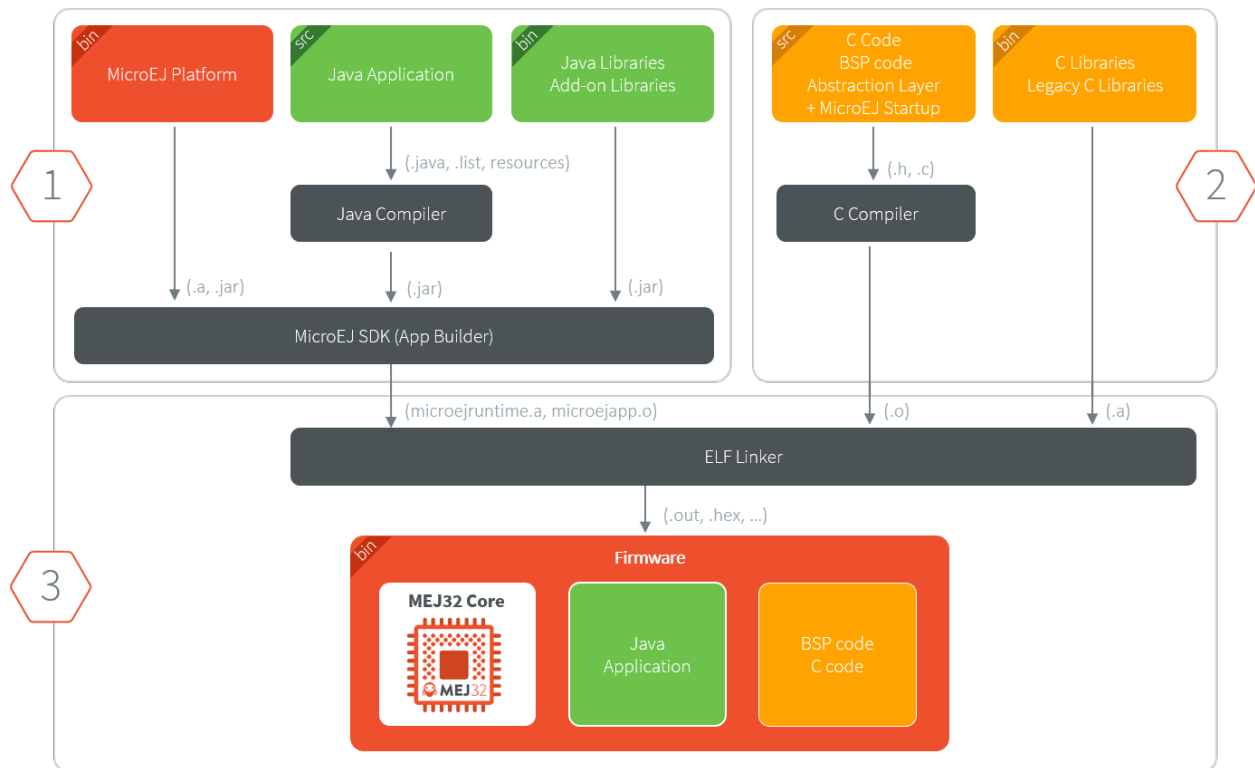
The next schema presents the components and process to build a MicroEJ Platform.



#### Build a MicroEJ Firmware

The next schema presents the steps to build a MicroEJ Mono-Sandbox Firmware (previously known as MicroEJ Single-app Firmware). The steps are:

1. Build the MicroEJ Application into a `microejapp.o` using MicroEJ SDK
2. Compile the BSP C sources into `.o` using the C toolchain
3. the BSP (`.o`) and the MicroEJ Application (`microejapp.o`) and the MicroEJ Platform (`microejruntime.a`) are linked by the C toolchain to produce a final ELF or binary called MicroEJ Firmware (e.g. `application.out`).



See [BSP Connection](#) for more information on how to connect the MicroEJ Platform to the BSP.

### Dependencies Between Processes

- Rebuild the MicroEJ Platform:
  - When the MicroEJ Architecture ( **.xpf** ) changes.
  - When a MicroEJ Foundation Library ( **.xpfp** ) changes.
  - When a Foundation Library changes, either when
    - \* The public API ( **.java** or **.h** ) changes.
    - \* The front-panel or mock implementation ( **.java** ) changes.
- Rebuild of the MicroEJ Platform is not required:
  - When the implementation ( **.c** ) of a Foundation Library changes.
  - When the BSP ( **.c** ) changes.
  - When the MicroEJ Application changes.
- Rebuild MicroEJ Application:
  - When it changes.
  - When the MicroEJ Platform changes.
- Rebuild the BSP:
  - When it changes.
  - When the MicroEJ Platform changes.
- Rebuild the MicroEJ Firmware:

- When the MicroEJ Application ( `microejapp.o` ) changes.
- When the BSP ( `*.o` ) changes.
- When the MicroEJ Platform ( `microejruntime.a` ) changes.

### 6.1.3 Get Support

If any questions, feel free to contact [our support team](#) with the following information (the table below is an example):

Delivery	Name
MicroEJ SDK	Distribution 20.07 / Version 5.2.0 (see <a href="#">Determine the MicroEJ Studio/SDK Version</a> )
MEJ32 XPF	ARM Cortex-M4 / IAR DEV
Platform	1.0.0
Application	1.2.4
Module Repository	<a href="https://repository.microej.com/packages/repository/2.5.0/microej-5_0-2.5.0.zip">https://repository.microej.com/packages/repository/2.5.0/microej-5_0-2.5.0.zip</a>
C compiler	IAR 8.40.1

## 6.2 Create a MicroEJ Platform for a Custom Device

### 6.2.1 Introduction

A MicroEJ Architecture is a software package that includes the MicroEJ Runtime port to a specific target Instruction Set Architecture (ISA) and C compiler. It contains a set of libraries, tools and C header files. The MicroEJ Architectures are provided by MicroEJ SDK.

A MicroEJ Platform is a MicroEJ Architecture port for a custom device. It contains the MicroEJ configuration and the BSP (C source files).

MicroEJ Corp. provides MicroEJ Evaluation Architectures at <https://repository.microej.com/architectures/>, and MicroEJ Platform demo projects for various evaluation boards at <https://repository.microej.com/index.php?resource=JPF>.

We recommend reading the [MicroEJ Firmware](#) section to get an overview of MicroEJ Firmware build flow.

The following document assumes the reader is familiar with the [Platform Developer Guide](#).

Each MicroEJ Platform is specific to:

- a MicroEJ Architecture (MCU ISA and C compiler)
- an optional RTOS (e.g. FreeRTOS - note: the MicroEJ OS can run bare metal)
- a device: the OS bring up code that is device specific (e.g. the MCU specific code/IO/RAM/Clock/Middleware... configurations)

In this document we will address the following items:

- MicroEJ Platform Configuration project (in MicroEJ SDK)
- MicroEJ Simulator (in MicroEJ SDK)
- Platform BSP (in a C IDE/Compiler like GCC/KEIL/IAR)

The MicroEJ Platform relies on C drivers (aka low level LL drivers) for each of the platform feature. These drivers are implemented in the platform BSP project. This project is edited in the C compiler IDE/dev environment (e.g. KEIL, GCC, IAR). E.g. the MicroUI library LED feature will require a `LLLEDs.c` that implements the native on/off IO drive.

The following sections explain how to create a MicroEJ Platform for a custom device starting from an existing MicroEJ Platform project whether it is configured for the same MCU/RTOS/C Compiler or not.

In the following, we assume that the new device hardware is validated and at least a trace output is available. It is also a good idea to run basic hardware tests like:

- Internal and external flash programming and verification
- RAM 8/16/32 -bit read/write operations (internal and external if any)
- EEMBC Coremark benchmark to verify the CPU/buses/memory/compiler configuration
- See the [Platform Qualification Tools](#) used to qualify MicroEJ Platforms.

### 6.2.2 A MicroEJ Platform Project is already available for the same MCU/RTOS/C Compiler

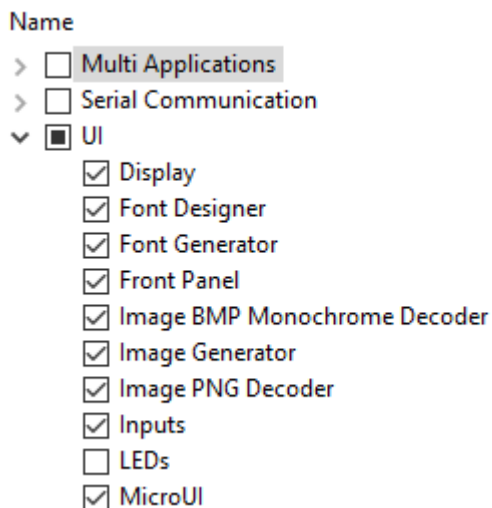
This is the fastest way: the MicroEJ Platform is usually provided for a silicon vendor evaluation board. Import this platform in MicroEJ SDK.

As the MCU, RTOS and compiler are the same, only the device specific code needs to be changed (external RAM, external oscillator, communication interfaces).

#### Platform

In MicroEJ SDK

- modify the `.platform` from the MicroEJ Platform (`xxx-configuration` project) to match the device features and its associated configuration (e.g. `UI->Display`).



More details on available modules can be found in the [Platform Developer Guide](#).

#### BSP

Required actions:

- modify the BSP C project to match the device specification

- edit the scatter file/link options
- edit the compilation options
- create/review/change the platform Low Level C drivers. They must match the device components and the MCU IO pin assignment

---

**Note:** A number of `LL*.h` files are referenced from the project. Implement the function prototypes declared there so that the JVM can delegate the relevant operations to the provided BSP C functions.

---

## Simulator

In MicroEJ SDK

- modify the existing Simulator front panel `xxx-fp` project

### 6.2.3 A MicroEJ Platform Project is not available for the same MCU/RTOS/C Compiler

Look for an available MicroEJ Platform that will match in order of priority:

- same MCU part number
- same RTOS
- same C compiler

At this point, consider either to modify the closest MicroEJ Platform

- In MicroEJ SDK: modify the platform configuration.
- in the C IDE: start from an empty project that match with the MCU.

Or to start from scratch a new MicroEJ Platform

- In MicroEJ SDK: create the MicroEJ Platform and refer to the selected MicroEJ Platform as a model for implementation. (refer to *New MicroEJ Platform Configuration*)
- in the C IDE: start from an empty project and implement the drivers of each of the LL drivers API.

Make sure to link with:

- the `microejruntime.a` that runs the JVM for the MCU Architecture
- the `microejapp.o` that contains the compiled Java application

## MCU

The MCU specific code can be found:

- in the C project IDE properties
- in the linker file
- the IO configuration
- in the low level driver (these drivers are usually provided by the silicon vendor)



## RTOS

The LL driver is named `LLMJVM_RTOS.c/.h`. Modify this file to match the selected RTOS.

## C Compiler

The BSP project is provided for a specific compiler (that matches the selected platform architecture). Start a new project with the compiler IDE that includes the LL drivers and start the MicroEJ Platform in the `main()` function.

### 6.2.4 Platform Validation

Use the [Platform Qualification Tools](#) to qualify the MicroEJ Platform built.

### 6.2.5 Further Assistance Needed

Please note that porting MicroEJ to a new device is also something that is part of our engineering services. Consider contacting [sales@microej.com](mailto:sales@microej.com) to request a quote.

## 6.3 Create a MicroEJ Firmware From Scratch

This tutorial explains how to create a MicroEJ Firmware from scratch. It goes through the typical steps followed by a Firmware developer integrating MicroEJ with a C Board Support Package (BSP) for a target device.

In this tutorial, the target device is a Luminary Micro Stellaris. Though this device is no longer available on the market, it has two advantages:

- The QEMU PC System emulator can emulate the device.
- FreeRTOS provides an official Demo BSP.

Consequently, no board is required to follow this tutorial. Everything is emulated on the developer's PC.

The tutorial should take 1 hour to complete (excluding the installation time of MicroEJ SDK and Windows Subsystem Linux (WSL)).

### 6.3.1 Intended Audience

The audience for this document is Firmware engineers who want to understand how MicroEJ is integrated to a C Board Support Package.

In addition, this tutorial should be of interest to all developers wishing to familiarize themselves with the low level components of a MicroEJ Firmware such as: *MicroEJ Architecture*, *MicroEJ Platform*, *Low Level API* and *BSP connection*.

### 6.3.2 Introduction

The following steps are usually followed when starting a new project:

1. Pick a target device (that meets the requirements of the project).
2. Setup a RTOS and a toolchain that support the target device.
3. Adapt the RTOS port if needed.

4. Install a *MicroEJ Architecture* that matches the target device/RTOS/toolchain.
5. Setup a new *MicroEJ Platform* connected to the Board Support Package (BSP).
6. Implement *Low Level API*.
7. Validate the resulting MicroEJ Platform with the *Platform Qualification Tools (PQT)*.
8. Develop the *MicroEJ Application*.

This tutorial describes step by step how to go from the FreeRTOS BSP to a MicroEJ Application that runs on the MicroEJ Platform and prints the classic "Hello, World!".

In this tutorial:

- The target device is a Luminary Micro Stellaris which is emulated by QEMU (*QEMU Stellaris boards*).
- The RTOS is FreeRTOS and the toolchain is GNU CC for ARM.

All modifications to FreeRTOS BSP made for this tutorial are available at <https://github.com/MicroEJ/FreeRTOS/tree/tuto-microej-firmware-from-scratch>.

---

**Note:** The implementation of the Low Level API and their validation with the *Platform Qualification Tools (PQT)* will be the topic of another tutorial.

---

### 6.3.3 Prerequisites

- MicroEJ SDK version 5.1.0 or higher (distribution 19.05). Can be downloaded from <https://developer.microej.com/> (*direct link*)
- Windows 10 with Windows Subsystem for Linux (WSL). See the *installation guide*.
- A Linux distribution installed on WSL (Tested on Ubuntu 19.10 eoan and Ubuntu 20.04 focal).

---

**Note:** In WSL, use the command `lsb_release -a` to print the current Ubuntu version.

---

A code editor such as Visual Studio Code is also recommended to edit BSP files.

### 6.3.4 Overview

The next sections describe step by step how to build a MicroEJ Firmware that runs a HelloWorld MicroEJ Application on the emulated device.

The steps to follow are:

1. Setup the development environment (assuming the prerequisites are satisfied).
2. Get a running BSP
3. Build the MicroEJ Platform
4. Create the HelloWorld MicroEJ Application
5. Implement the minimum Low Level API to run the application

This tutorial goes through trials and errors every Firmware developers may encounter. It provides a solution after each error rather than providing the full solution in one go.

### 6.3.5 Setup the Development Environment

This section assumes the prerequisites have been properly installed.

In WSL:

1. Update apt's cache: `sudo apt-get update`
2. Install qemu-system-arm and GNU CC toolchain for ARM: `sudo apt-get install -y qemu-system-arm gcc-arm-none-eabi build-essential subversion`
3. The rest of this tutorial will use the folder `src/tuto-from-scratch/` in the Windows home folder.
4. Create the folder: `mkdir -p /mnt/c/Users/${USER}/src/tuto-from-scratch` (the `-p` option ensures all the directories are created).
5. Go into the folder: `cd /mnt/c/Users/${USER}/src/tuto-from-scratch/`
6. Clone FreeRTOS and its submodules: `git clone -b V10.3.1 --recursive https://github.com/FreeRTOS/FreeRTOS.git` (this may takes some time)

---

**Note:** Use the right-click to paste from the Windows clipboard into WSL console. The right-click is also used to copy from the WSL console into the Windows clipboard.

---

### 6.3.6 Get Running BSP

This section presents how to get running BSP based on FreeRTOS that boots on the target device.

1. Go into the target device sub-project: `cd FreeRTOS/FreeRTOS/Demo/CORTEX_LM3S811_GCC`
2. Build the project: `make`

Ignoring the warnings, the following error appears during the link:

```
CC      hw_include/osram96x16.c
LD      gcc/RTOSDemo.axf
arm-none-eabi-ld: section .text.startup LMA [0000000000002b24,0000000000002c8f] overlaps section .
↪data LMA [0000000000002b24,0000000000002b27]
make: *** [makedefs:191: gcc/RTOSDemo.axf] Error 1
```

Insert the following fixes in the linker script file named `standalone.ld` (thanks to <http://roboticravings.blogspot.com/2018/07/freertos-on-cortex-m3-with-qemu.html>).

---

**Note:** WSL can start the editor Visual Studio Code. type `code .` in WSL. `.` represents the current directory in Unix.

---

```
diff --git a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/standalone.ld b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/
↪standalone.ld

index 8ee3fe2f8..b771ff834 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/standalone.ld
+++ b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/standalone.ld
@@ -42,7 +42,15 @@ SECTIONS
     _etext = .;
 } > FLASH
```

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```

-  .data : AT (ADDR(.text) + sizeof(.text))
+  .ARM.exidx :
+  {
+      *(.ARM.exidx*)
+      *(.gnu.linkonce.armexidx.*)
+  } > FLASH
+
+  _begin_data = .;
+
+  .data : AT ( _begin_data )
+  {
+      _data = .;
+      *(vtable)

```

This is the output of the `git diff` command. Lines starting with a `-` should be removed. Lines starting with a `+` should be added.

**Note:** The `patch(1)` can be used to apply the patch. Assuming WSL shell is in `FreeRTOS/Demo/CORTEX_LM3S811_GCC` directory:

1. Install dos2unix utility: `sudo apt install dos2unix`
2. Convert all files to unix line-ending: `find -type f -exec dos2unix {} \;`
3. Copy the content of the code block in a file named `linker.patch` (every lines of the code block must be copied in the file).
4. Apply the patch: `patch -l -p4 < linker.patch`.

It is also possible to paste the diff directly into the console:

1. In WSL, invoke `patch -l -p4`. The command starts, waiting for input on stdin (the standard input).
2. Copy the diff and paste it in WSL
3. Press enter
4. Press `Ctrl-d Ctrl-d` (press the `Control` key + the letter `d` twice).

3. Run the build again: `make`
4. Run the emulator with the generated kernel: `qemu-system-arm -M lm3s811evb -nographic -kernel gcc/RTOSDemo.bin`

The following error appears and then nothing:

```

ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80

```

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```

ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3

```

5. Press **Ctrl-a x** (press **Control** + the letter **a** , release, press **x** ) to the end the QEMU session. The session ends with **QEMU: Terminated**.

---

**Note:** The errors can be safely ignored. They occur because the OLED controller emulated receive incorrect commands.

---

At this point, the target device is successfully booted with the FreeRTOS kernel.

### 6.3.7 FreeRTOS Hello World

This section describes how to configure the BSP to print text on the QEMU console.

The datasheet of the target device ([LM3S811 datasheet](#)) describes how to use the UART device and an example implementation for QEMU is available [here](#).

The following code implements the `putchar(3)` and `puts(3)` functions:

```

#define UART0BASE ((volatile int*) 0x4000C000)

int putchar (int c){
    (*UART0BASE) = c;
    return c;
}

int puts(const char *s) {
    while (*s) {
        putchar(*s);
        s++;
    }
    return putchar('\n');
}

```

And here is the patch that implements both functions and prints **Hello World**.

```

diff --git a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
index 107517c00..3ea4c23a4 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
+++ b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
@@ -134,9 +134,25 @@ SemaphoreHandle_t xButtonSemaphore;
 QueueHandle_t xPrintQueue;

/*-----*/
#define UART0BASE ((volatile int*) 0x4000C000)
+
+int putchar (int c){
+    (*UART0BASE) = c;
+    return c;
+}

```

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```

+
+int puts(const char *s) {
+    while (*s) {
+        putchar(*s);
+        s++;
+    }
+    return putchar('\n');
+}

int main( void )
{
+    puts("Hello, World! puts function is working.");
+
    /* Configure the clocks, UART and GPIO. */
    prvSetupHardware();

```

Rebuild and run the newly generated kernel: `make && qemu-system-arm -M lm3s811evb -nographic -kernel gcc/RTOSDemo.bin` (press `Ctrl-a x` to interrupt the emulator).

```

make: Nothing to be done for 'all'.
Hello, World! puts function is working.
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
ssd0303: error: Unknown command: 0x80
ssd0303: error: Unexpected byte 0xe3
QEMU: Terminated

```

With this two functions implemented, `printf(3)` is also available.

```

diff --git a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
index 76440e60e..f24007597 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
+++ b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
@@ -149,9 +149,11 @@ int puts(const char *s) {
     return putchar('\n');
 }

+#include <stdio.h>
+
int main( void )
{
-    puts("Hello, World! puts function is working.");

```

(continues on next page)

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```
+    printf("Hello, World! printf function is working.\n");

    /* Configure the clocks, UART and GPIO. */
    prvSetupHardware();
```

At this point, the character output on the UART is implemented in the FreeRTOS BSP. The next step is to create the MicroEJ Platform and MicroEJ Application.

### 6.3.8 Create a MicroEJ Platform

This section describes how to create and configure a MicroEJ Platform compatible with the FreeRTOS BSP and GCC toolchain.

- A MicroEJ Architecture is a software package that includes the *MicroEJ Runtime* port to a specific target Instruction Set Architecture (ISA) and C compiler. It contains a set of libraries, tools and C header files. The MicroEJ Architectures are provided by MicroEJ SDK.
- A MicroEJ Platform is a port of a MicroEJ Architecture for a custom device. It contains the MicroEJ configuration and the BSP (C source files).

When selecting a MicroEJ Architecture, special care must be taken to ensure the compatibility between the toolchain used in the BSP and the toolchain used to build the MicroEJ Core Engine included in the MicroEJ Architecture.

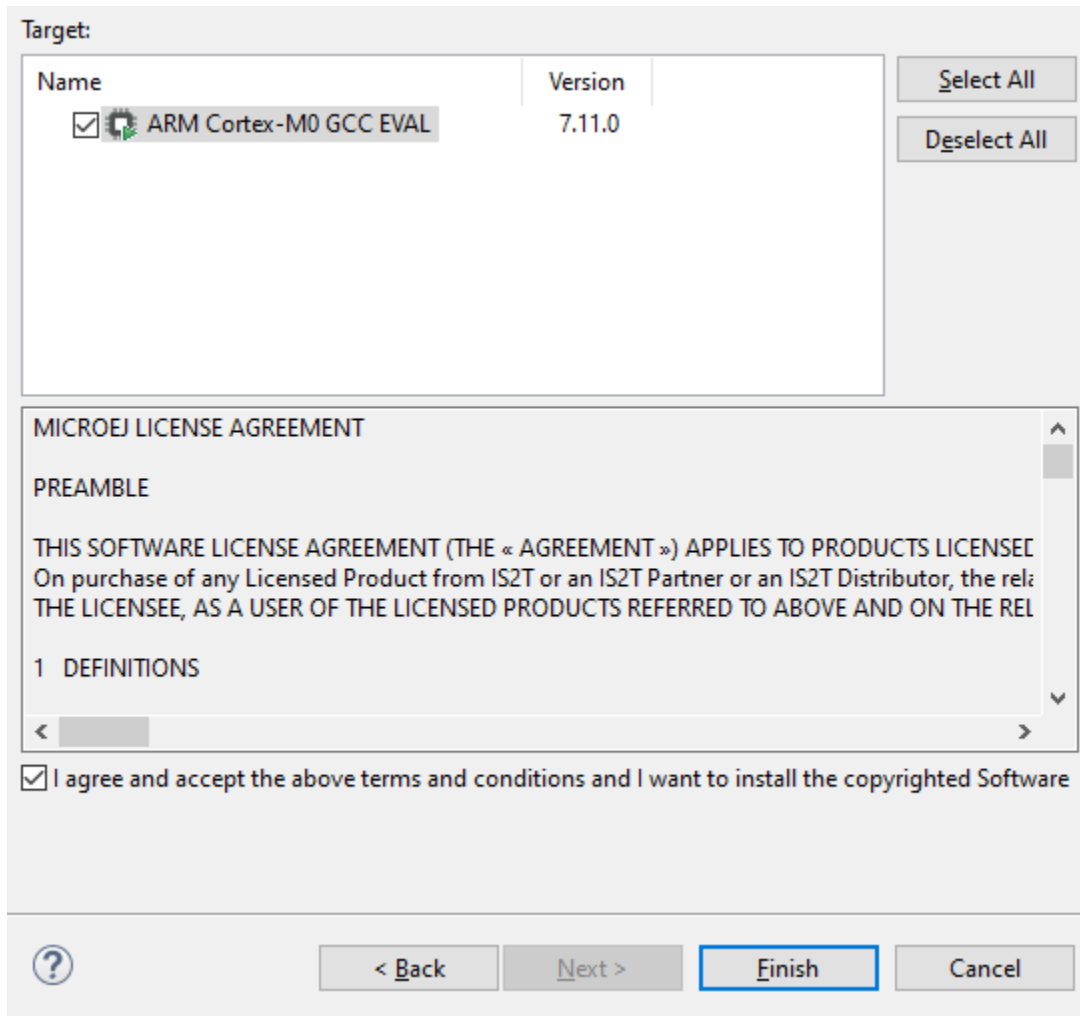
The list of MicroEJ Architectures supported is listed at <https://docs.microej.com/en/latest/PlatformDeveloperGuide/appendix/toolchain.html>. MicroEJ Evaluation Architectures provided by MicroEJ Corp. can be downloaded from [MicroEJ Architectures Repository](#).

There is no **CM3** in MicroEJ Architectures Repository and the Arm® Cortex®-M3 MCU is not mentioned in the *capabilities matrix*. This means that the MicroEJ Architectures for Arm® Cortex®-M3 MCUs are no longer distributed for evaluation. Download the latest MicroEJ Architecture for Arm® Cortex®-M0 instead (the Arm® architectures are binary upward compatible from Arm®v6-M (Cortex®-M0) to Arm®v7-M (Cortex®-M3)).

#### Import the MicroEJ Architecture

This step describes how to import a *MicroEJ Architecture*.

1. Start MicroEJ SDK on an empty workspace. For example, create an empty folder **workspace** next to the **FreeRTOS** git folder and select it.
2. Keep the default MicroEJ Repository
3. Download the latest MicroEJ Architecture for Arm® Cortex®-M0 instead: [https://repository.microej.com/architectures/com/microej/architecture/CM0/CM0\\_GCC48/flopi0G22/7.11.0/flopi0G22-7.11.0-eval.xpf](https://repository.microej.com/architectures/com/microej/architecture/CM0/CM0_GCC48/flopi0G22/7.11.0/flopi0G22-7.11.0-eval.xpf)
4. Import the MicroEJ Architecture in MicroEJ SDK
  1. **File** > **Import** > **MicroEJ** > **Architectures**
  2. select the MicroEJ Architecture file downloaded
  3. Accept the license and click on **Finish**



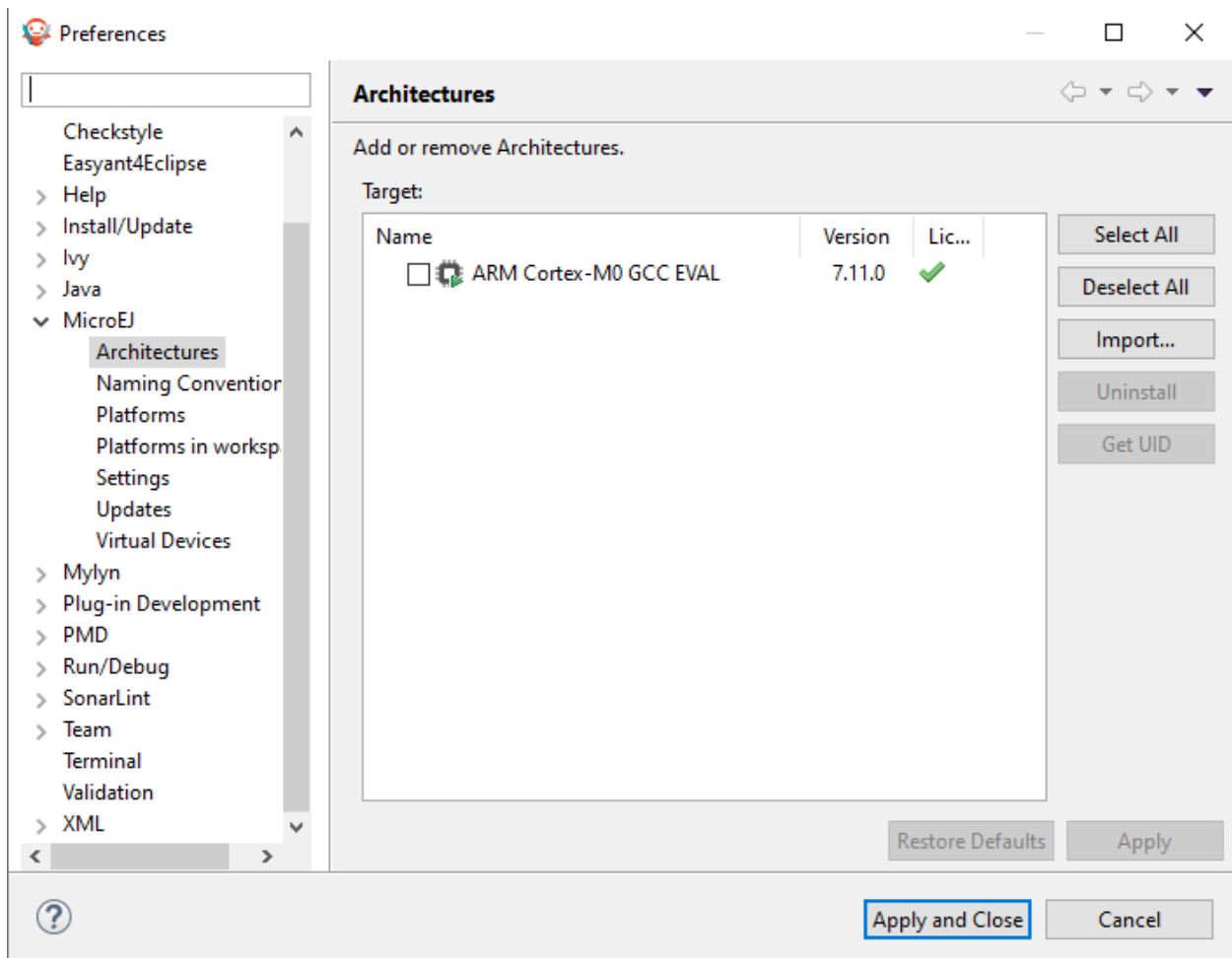
### Install an Evaluation License

This step describes how to create and activate an *Evaluation License* for the MicroEJ Architecture previously imported.

1. Select the **Window** > **Preferences** > **MicroEJ** > **Architectures menu** .
2. Click on the architectures and press **Get UID** .
3. Copy the UID. It will be needed when requesting a license.
4. Go to <https://license.microej.com>.
5. Click on **Create a new account** link.
6. Create an account with a valid email address. A confirmation email will be sent a few minutes after. Click on the confirmation link in the email and login with the account.
7. Click on **Activate a License** .
8. Set Product **P/N:** to **9PEVNLDBU6IJ** .
9. Set **UID:** to the UID generated before.



10. Click on **Activate** .
  - The license is being activated. An activation mail should be received in less than 5 minutes. If not, please contact [support@microej.com](mailto:support@microej.com).
  - Once received by email, save the attached zip file that contains the activation key.
11. Go back to Microej SDK.
12. Select the **Window** > **Preferences** > **MicroEJ** menu.
13. Press **Add...** .
14. Browse the previously downloaded activation key archive file.
15. Press **OK** . A new license is successfully installed.
16. Go to **Architectures** sub-menu and check that all architectures are now activated (green check).
17. Microej SDK is successfully activated.

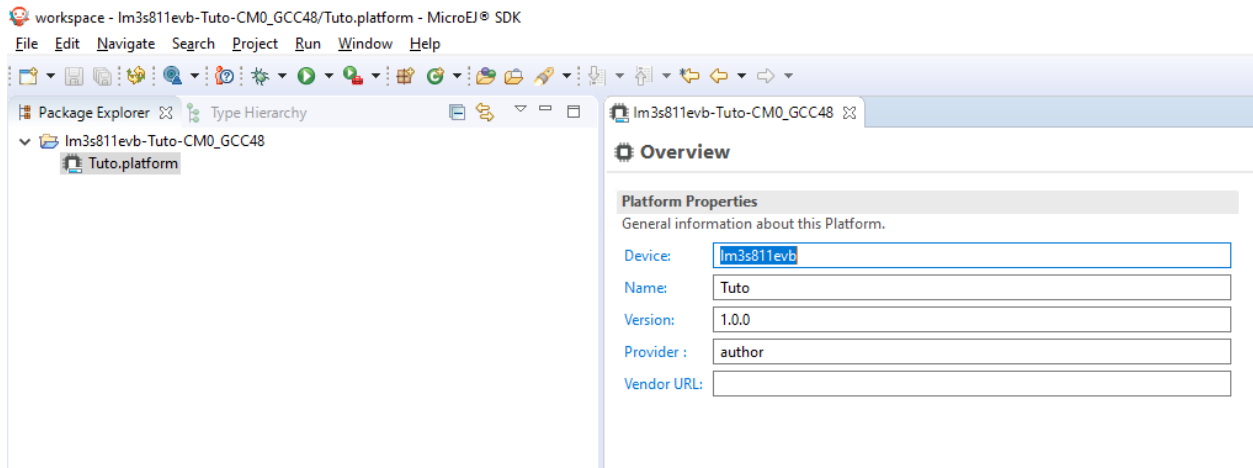


### Create the MicroEJ Platform

This step describes how to create a new *MicroEJ Platform* using the MicroEJ Architecture previously imported.

1. Select **File** > **New** > **MicroEJ Platform Project** .

2. Ensure the **Architecture** selected is the MicroEJ Architecture previously imported.
3. Ensure the **Create from a platform reference implementation** box is unchecked.
4. Click on **Next** button.
5. Fill the fields:
  - Set **Device**: to **lm3s811evb**
  - Set **Name**: to **Tuto**



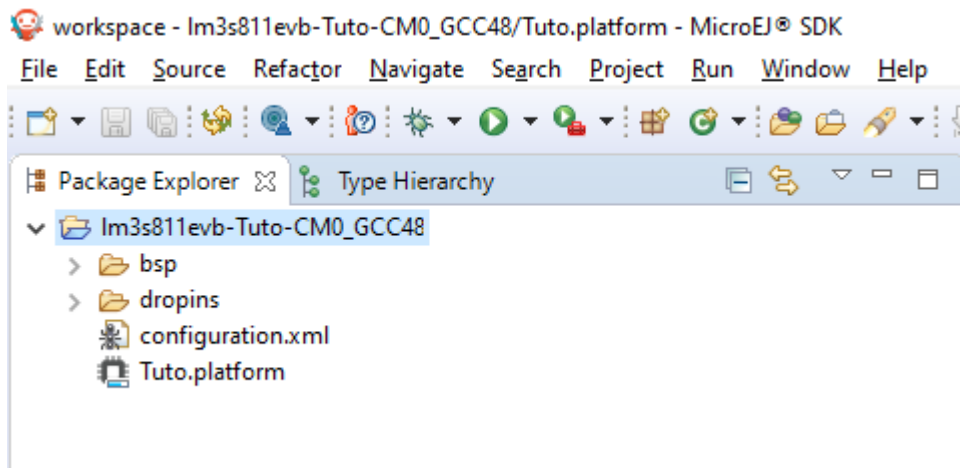
### Setup the MicroEJ Platform

This step describes how to configure the MicroEJ Platform previously created.

The **Platform Configuration Additions** provide a flexible way to configure the **BSP connection** between the MicroEJ Platform and MicroEJ Application to the BSP. In this tutorial, the Partial BSP connection is used. That is, the MicroEJ SDK will output all MicroEJ files (C headers, MicroEJ Application `microejapp.o`, MicroEJ Runtime `microejruntime.a`,...) in a location known by the BSP. The BSP is configured to compile and link with those files.

For this tutorial, that means that the final binary is produced by invoking **make** in the FreeRTOS BSP.

1. Install the Platform Configuration Additions by copying all the files within the **content** folder in the MicroEJ Platform folder.



**Note:** The `content` directory contains files that must be installed in a MicroEJ Platform configuration directory (the directory that contains the `.platform` file). It can be automatically downloaded using the following command line:

```
svn checkout https://github.com/MicroEJ/PlatformQualificationTools/trunk/framework/platform/
↩content [path_to_platform_configuration_directory]
```

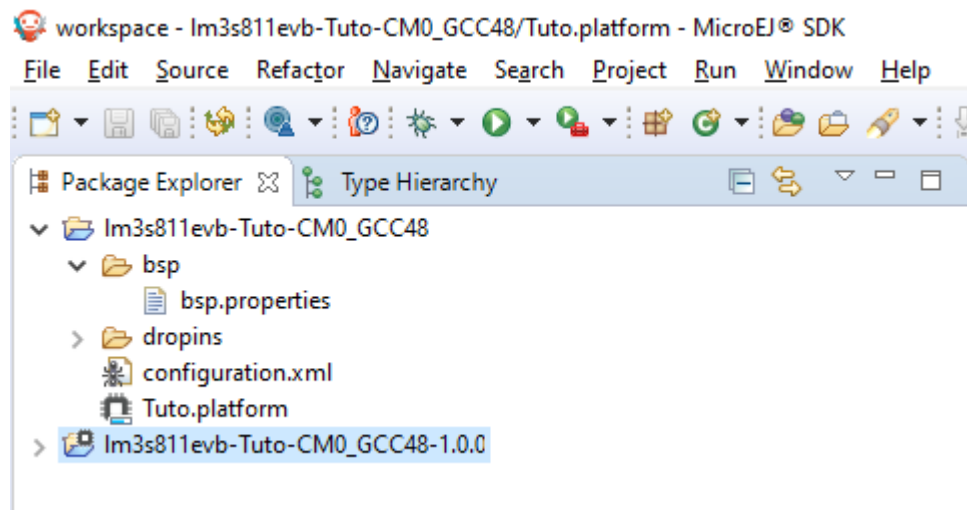
2. Edit the file `bsp/bsp.properties` as follow:

```
# Specify the MicroEJ Application file ('microejapp.o') parent directory.
# This is a '/' separated directory relative to 'bsp.root.dir'.
microejapp.relative.dir=microej/lib

# Specify the MicroEJ Platform runtime file ('microejruntime.a') parent directory.
# This is a '/' separated directory relative to 'bsp.root.dir'.
microejlib.relative.dir=microej/lib

# Specify MicroEJ Platform header files ('*.h') parent directory.
# This is a '/' separated directory relative to 'bsp.root.dir'.
microejinc.relative.dir=microej/inc
```

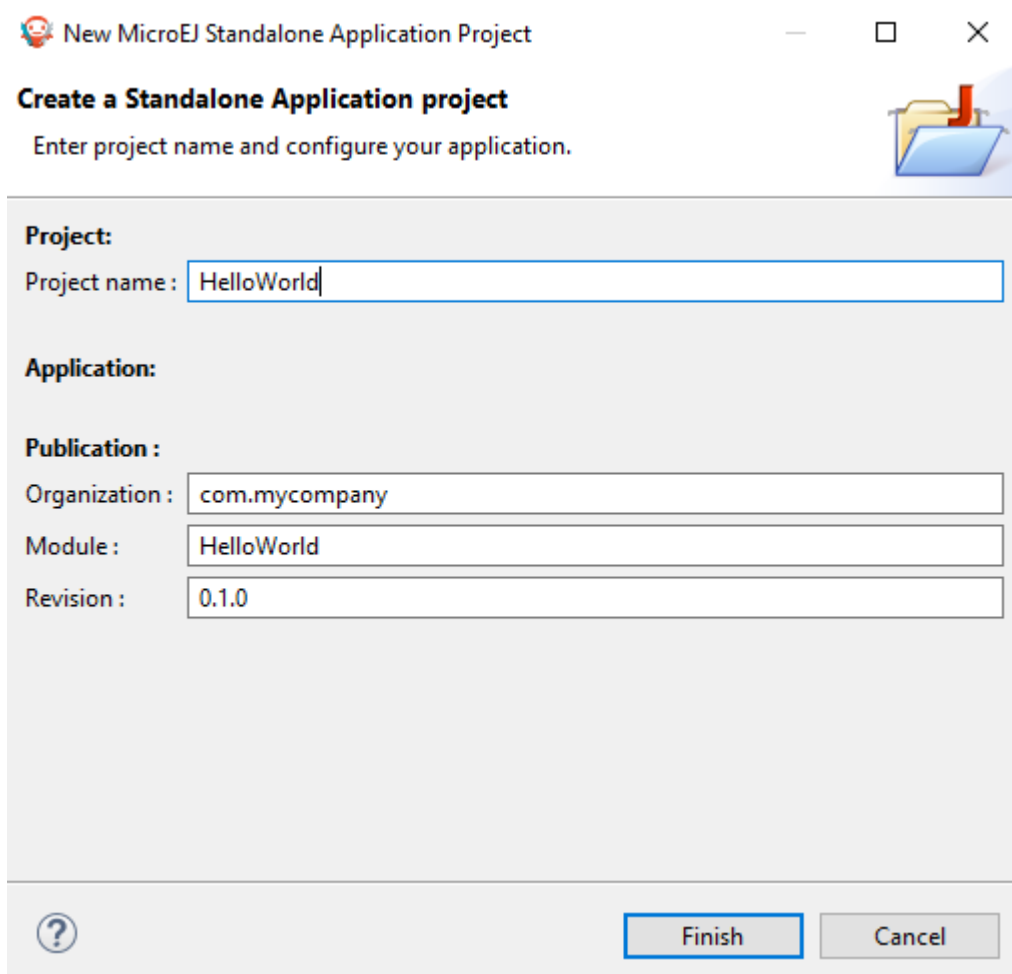
3. Open the `.platform` file and click on **Build Platform**. The MicroEJ Platform will appear in the workspace.



At this point, the MicroEJ Platform is ready to be used to build MicroEJ Applications.

### 6.3.9 Create MicroEJ Application HelloWorld

1. Select **File** > **New** > **MicroEJ Standalone Application Project**.
2. Set the name to `HelloWorld` and click on **Finish**.



New MicroEJ Standalone Application Project

**Create a Standalone Application project**

Enter project name and configure your application.

**Project:**

Project name : HelloWorld

**Application:**

**Publication :**

Organization : com.mycompany

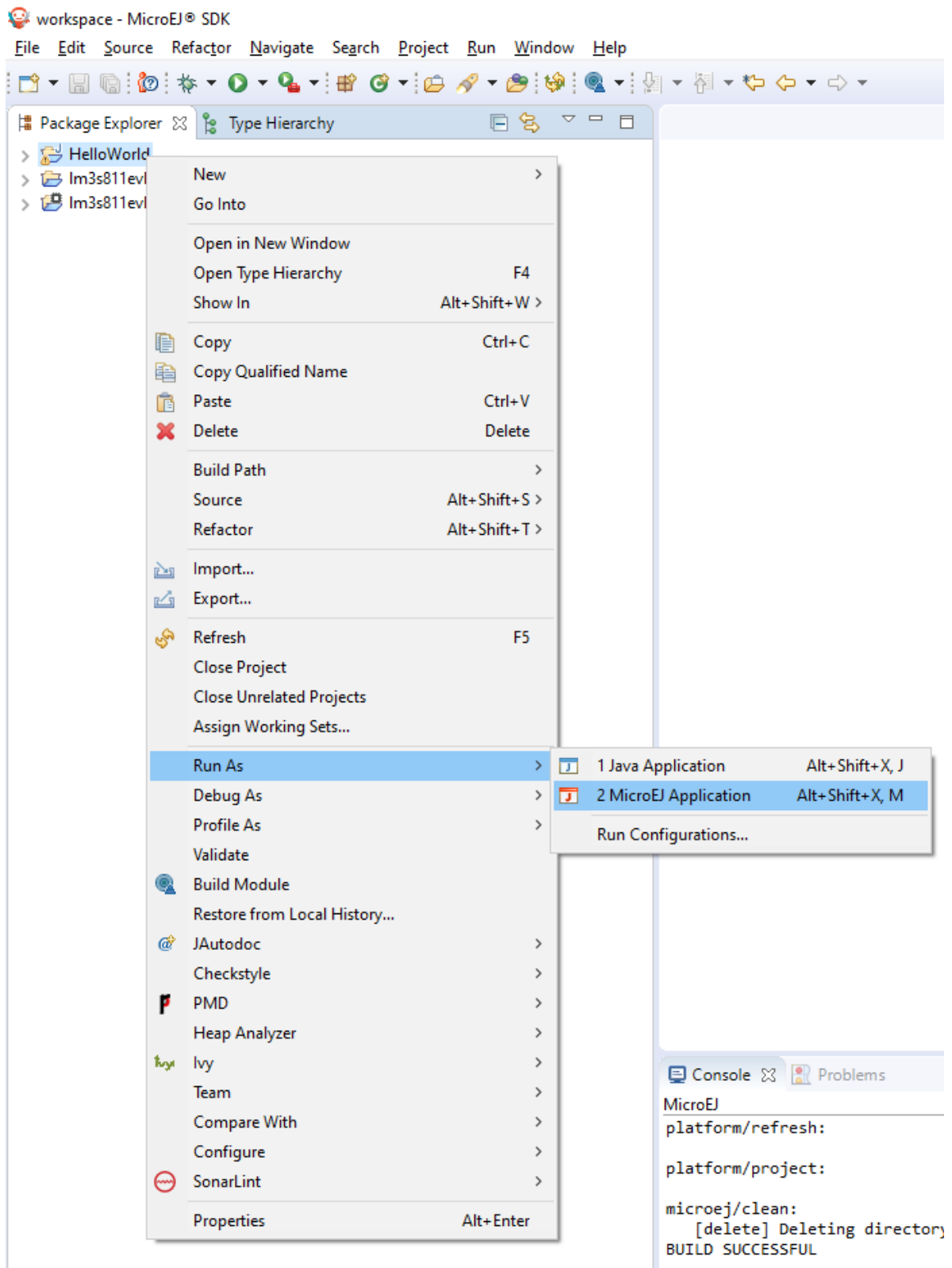
Module : HelloWorld

Revision : 0.1.0

?

Finish Cancel

3. Run the application in Simulator to ensure it is working properly. Right-click on HelloWorld project > Run as > MicroEJ Application



The following message appears in the console:

```

===== [ Initialization Stage ] =====
===== [ Launching on Simulator ] =====
Hello World!
===== [ Completed Successfully ] =====

SUCCESS

```

### 6.3.10 Configure BSP Connection in MicroEJ Application

This step describes how to configure the *BSP connection* for the HelloWorld MicroEJ Application and how to build the MicroEJ Application that will run on the target device.

For a MicroEJ Application, the BSP connection is configured in the `PROJECT-NAME/build/common.properties` file.

1. Create a file `HelloWorld/build/emb.properties` with the following content:

```

core.memory.immortal.size=0
core.memory.javaheap.size=1024
core.memory.threads.pool.size=4
core.memory.threads.size=1
core.memory.thread.max.size=4
deploy.bsp.microejapp=true
deploy.bsp.microejlib=true
deploy.bsp.microejinc=true
deploy.bsp.root.dir=[absolute_path] to FreeRTOS\\FreeRTOS\\Demo\\CORTEX_LM3S811_GCC

```

**Note:** Assuming the WSL current directory is `FreeRTOS/FreeRTOS/Demo/CORTEX_LM3S811_GCC`, use the following command to find the `deploy.bsp.root.dir` path with proper escaping:

```
pwd | sed -e 's|/mnt/c/|C:\\\\|' -e 's|/|\\\\|g'
```

2. Open `Run` > `Run configurations...`
3. Select the HelloWorld launcher configuration



4. Select **Execution** tab.
5. Change the execution mode from **Execute on Simulator** to **Execute on Device**.
6. Add the file **build/emb.properties** to the options files



7. Click on **Run**

```

===== [ Initialization Stage ] =====
Platform connected to BSP location 'C:\Users\user\src\tuto-from-scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_
↳LM3S811_GCC' using application option 'deploy.bsp.root.dir'.
===== [ Launching SOAR ] =====
===== [ Launching Link ] =====
===== [ Deployment ] =====
MicroEJ files for the 3rd-party BSP project are generated to 'C:\Users\user\src\tuto-from-
↳scratch\workspace\HelloWorld\com.mycompany.Main\platform'.
The MicroEJ application (microejapp.o) has been deployed to: 'C:\Users\user\src\tuto-from-
↳scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_LM3S811_GCC\microej\lib'.
The MicroEJ platform library (microejruntime.a) has been deployed to: 'C:\Users\user\src\tuto-from-
↳scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_LM3S811_GCC\microej\lib'.
The MicroEJ platform header files (*.h) have been deployed to: 'C:\Users\user\src\tuto-from-
↳scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_LM3S811_GCC\microej\inc'.
===== [ Completed Successfully ] =====

SUCCESS

```

At this point, the HelloWorld MicroEJ Application is built and deployed in the FreeRTOS BSP.

### 6.3.11 MicroEJ and FreeRTOS Integration

This section describes how to finalize the integration between MicroEJ and FreeRTOS to get a working firmware that runs the HelloWorld MicroEJ Application built previously.

In the previous section, when the MicroEJ Application was built, several files were added to a new folder named `microej/`.

```

$ pwd
/mnt/c/Users/user/src/tuto-from-scratch/FreeRTOS/FreeRTOS/Demo/CORTEX_LM3S811_GCC
$ tree microej/
microej/
├── inc
│   ├── BESTFIT_ALLOCATOR.h
│   ├── BESTFIT_ALLOCATOR_impl.h
│   ├── LLBSP_impl.h
│   ├── LLMJVM.h
│   ├── LLMJVM_MONITOR_impl.h
│   ├── LLMJVM_impl.h
│   ├── LLTRACE_impl.h
│   ├── MJVM_MONITOR.h
│   ├── MJVM_MONITOR_types.h
│   └── intern
│       ├── BESTFIT_ALLOCATOR.h
│       ├── BESTFIT_ALLOCATOR_impl.h
│       ├── LLBSP_impl.h
│       ├── LLMJVM.h
│       ├── LLMJVM_impl.h
│       └── trace_intern.h
├── sni.h
├── trace.h
└── lib
    ├── microejapp.o
    └── microejruntime.a

```

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3 directories, 19 files

- The `microej/lib` folder contains the HelloWorld MicroEJ Application object file (`microejapp.o`) and the MicroEJ Runtime. The final binary must be linked with these two files.
- The `microej/inc` folder contains several C header files used to expose MicroEJ Low Level APIs. The functions defined in files ending with the `_impl.h` suffix should be implemented by the BSP.

To summarize, the following steps remain to complete the integration between MicroEJ and the FreeRTOS BSP:

- Implement minimal Low Level APIs
- Invoke the MicroEJ Core Engine
- Build and link the firmware with the MicroEJ Runtime and MicroEJ Application

### Minimal Low Level APIs

The purpose of this tutorial is to demonstrate how to develop a minimal MicroEJ Architecture, it is not to develop a complete MicroEJ Architecture. Therefore this tutorial implements only the required functions and provides stub implementation for unused features. For example, the following implementation does not support scheduling.

The two headers that must be implemented are `LLBSP_impl.h` and `LLMJVM_impl.h`.

1. In the BSP, create a folder named `microej/src` (next to the `microej/lib` and `microej/inc` folders).
2. Implement `LLBSP_impl.h` in `LLBSP.c`:

Listing 1: `microej/src/LLBSP.c`

```
#include "LLBSP_impl.h"

extern void _etext(void);
uint8_t LLBSP_IMPL_isInReadOnlyMemory(void* ptr)
{
    return ptr < &_etext;
}

/**
 * Writes the character <code>c</code>, cast to an unsigned char, to stdout stream.
 * This function is used by the default implementation of the Java <code>System.out</code>.
 */
void LLBSP_IMPL_putchar(int32_t c)
{
    putchar(c);
}
```

- The implementation of `LLBSP_IMPL_putchar` reuses the `putchar` implemented previously.
  - The `rodata` section is defined in the linker script `standalone.ld`. The flash memory starts at 0 and the end of the section is stored in the `_etext` symbol.
3. Implement `LLMJVM_impl.h` in `LLMJVM_stub.c` (all functions are stubbed with a dummy implementation):

Listing 2: microej/src/LLMJVM\_stub.c

```

#include "LLMJVM_impl.h"

int32_t LLMJVM_IMPL_initialize()
{
    return LLMJVM_OK;
}

int32_t LLMJVM_IMPL_vmTaskStarted()
{
    return LLMJVM_OK;
}

int32_t LLMJVM_IMPL_scheduleRequest(int64_t absoluteTime)
{
    return LLMJVM_OK;
}

int32_t LLMJVM_IMPL_idleVM()
{
    return LLMJVM_OK;
}

int32_t LLMJVM_IMPL_wakeupVM()
{
    return LLMJVM_OK;
}

int32_t LLMJVM_IMPL_ackWakeup()
{
    return LLMJVM_OK;
}

int32_t LLMJVM_IMPL_getCurrentTaskID()
{
    return (int32_t) 123456;
}

void LLMJVM_IMPL_setApplicationTime(int64_t t)
{
}

int64_t LLMJVM_IMPL_getCurrentTime(uint8_t system)
{
    return 0;
}

int64_t LLMJVM_IMPL_getTimeNanos()
{
    return 0;
}

int32_t LLMJVM_IMPL_shutdown(void)
{
    return LLMJVM_OK;
}

```

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}

The `microej` folder in the BSP has the following structure:

```
$ pwd
/mnt/c/Users/user/src/tuto-from-scratch/FreeRTOS/FreeRTOS/Demo/CORTEX_LM3S811_GCC
$ tree microej/
microej/
├── inc
│   ├── BESTFIT_ALLOCATOR.h
│   ├── BESTFIT_ALLOCATOR_impl.h
│   ├── LLBSP_impl.h
│   ├── LLMJVM.h
│   ├── LLMJVM_MONITOR_impl.h
│   ├── LLMJVM_impl.h
│   ├── LLTRACE_impl.h
│   ├── MJVM_MONITOR.h
│   ├── MJVM_MONITOR_types.h
│   └── intern
│       ├── BESTFIT_ALLOCATOR.h
│       ├── BESTFIT_ALLOCATOR_impl.h
│       ├── LLBSP_impl.h
│       ├── LLMJVM.h
│       ├── LLMJVM_impl.h
│       └── trace_intern.h
├── sni.h
├── trace.h
├── lib
│   ├── microejapp.o
│   └── microejruntime.a
└── src
    ├── LLBSP.c
    └── LLMJVM_stub.c

4 directories, 21 files
```

### Invoke MicroEJ Core Engine

The MicroEJ Core Engine is created and initialized with the C function `SNI_createVM`. Then it is started and executed in the current RTOS task by calling `SNI_startVM`. The function `SNI_startVM` returns when the MicroEJ Application exits. Both functions are declared in the C header `sni.h`.

```
diff --git a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
index d5728f976..644710120 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
+++ b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/main.c
@@ -150,11 +150,14 @@ int puts(const char *s) {
 }

#include <stdio.h>
+#include "sni.h"

int main( void )
{
    printf("Hello, World! printf function is working.\n");
```

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```

+     SNI_startVM(SNI_createVM(), 0, NULL);
+
+     /* Configure the clocks, UART and GPIO. */
+     prvSetupHardware();

```

### Build and Link the Firmware with the MicroEJ Runtime and MicroEJ Application

To build and link the firmware with the MicroEJ Runtime and MicroEJ Application, the BSP port must be modified to:

1. Use the MicroEJ header files in folder `microej/inc`
2. Use the source files folder `microej/src` that contains the Low Level API implementation `LLBSP.c` and `LLMJVM_stub.c`
3. Compile and link `LLBSP.o` and `LLMJVM_stub.o`
4. Link with MicroEJ Application ( `microej/lib/microejapp.o` ) and MicroEJ Runtime ( `microej/lib/microejruntime.a` )

The following patch updates the BSP port `Makefile` to do it:

```

index 814cc6f7e..bbcad47b3 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S811_GCC/Makefile
+++ b/FreeRTOS/Demo/CORTEX_LM3S811_GCC/Makefile
@@ -29,8 +29,10 @@ RTOS_SOURCE_DIR=../../Source
 DEMO_SOURCE_DIR=../Common/Minimal

 CFLAGS+=-I hw_include -I . -I ${RTOS_SOURCE_DIR}/include -I ${RTOS_SOURCE_DIR}/portable/GCC/ARM_CM3 -I_
↪../Common/include -D GCC_ARMCM3_LM3S102 -D inline=
+CFLAGS+= -I microej/inc

 VPATH=${RTOS_SOURCE_DIR}:${RTOS_SOURCE_DIR}/portable/MemMang:${RTOS_SOURCE_DIR}/portable/GCC/ARM_CM3:$
↪{DEMO_SOURCE_DIR}:init:hw_include
+VPATH+= microej/src

 OBJS=${COMPILER}/main.o      \
      ${COMPILER}/list.o     \
@@ -44,9 +46,12 @@ OBJS=${COMPILER}/main.o      \
      ${COMPILER}/semtest.o  \
      ${COMPILER}/osram96x16.o

+OBJS+= ${COMPILER}/LLBSP.o ${COMPILER}/LLMJVM_stub.o
+
 INIT_OBJS= ${COMPILER}/startup.o

 LIBS= hw_include/libdriver.a
+LIBS+= microej/lib/microejruntime.a microej/lib/microejapp.o

```

Then build the firmware with `make` . The following error occurs at link time.

```

CC      microej/src/LLMJVM_stub.c
LD      gcc/RTOSDemo.axf
↪
↪
↪      arm-none-eabi-ld: error: microej/lib/microejruntime.a(sni_vm_startup_
↪greenthread.o) uses VFP register arguments, gcc/RTOSDemo.axf does not

```

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```
arm-none-eabi-ld: failed to merge target specific data of file microej/lib/microejruntime.a(sni_vm_
↳ startup_greenthread.o)
arm-none-eabi-ld: gcc/RTOSDemo.axf section `ICETEA_HEAP' will not fit in region `SRAM'
arm-none-eabi-ld: region `SRAM' overflowed by 4016 bytes
microej/lib/microejapp.o: In function `_java_internStrings_end':
```

The RAM requirements of the BSP (with printf), FreeRTOS, the MicroEJ Application and MicroEJ Runtime do not fit in the 8k of SRAM. It is possible to link within 8k of RAM by customizing a *MicroEJ Tiny Application* on a baremetal device (without a RTOS) but this is not the purpose of this tutorial.

Instead, this tutorial will switch to another device, the Luminary Micro Stellaris LM3S6965EVB. This device is almost identical as the LM3S811EVB but it has 256k of flash memory and 64k of SRAM. Updating the values in the linker script `standalone.ld` is sufficient to create a valid BSP port for this device.

Instead of continuing to work with the LM3S811 port, create a copy, named CORTEX\_LM3S6965\_GCC:

```
$ cd ..
$ pwd
/mnt/c/Users/user/src/tuto-from-scratch/FreeRTOS/FreeRTOS/Demo
$ cp -r CORTEX_LM3S811_GCC/ CORTEX_LM3S6965_GCC
$ cd CORTEX_LM3S6965_GCC
```

The BSP path defined by the property `deploy.bsp.root.dir` in the MicroEJ Application must be updated as well.

The rest of the tutorial assumes that everything is done in the `CORTEX_LM3S6965_GCC` folder.

Then update the linker script `standalone.ld`:

```
diff --git a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/standalone.ld b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/
↳ standalone.ld
index b771ff834..e3719ea30 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/standalone.ld
+++ b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/standalone.ld
@@ -28,8 +28,8 @@
MEMORY
{
- FLASH (rx) : ORIGIN = 0x00000000, LENGTH = 64K
- SRAM (rwx) : ORIGIN = 0x20000000, LENGTH = 8K
+ FLASH (rx) : ORIGIN = 0x00000000, LENGTH = 256K
+ SRAM (rwx) : ORIGIN = 0x20000000, LENGTH = 64K
}

SECTIONS
```

The new command to run the firmware with QEMU is: `qemu-system-arm -M lm3s6965evb -nographic -kernel gcc/RTOSDemo.bin`.

Rebuild the firmware with `make`. The following error occurs:

```
CC      microej/src/LLMJVM_stub.c
LD      gcc/RTOSDemo.axf
↳
↳
↳      microej/lib/microejapp.o: In function `_java_internStrings_end':
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x1b3e):
↳ undefined reference to `ist_mowana_vm_GenericNativesPool___com_1is2t_1vm_1support_1lang_
↳ 1SupportNumber_1parseLong'
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x1cea):
↳ undefined reference to `ist_mowana_vm_GenericNativesPool___com_1is2t_1vm_1support_1lang_
↳ 1SupportNumber_1toStringLongNative'
C:\Users\user\src\tuto-from-
↳ scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x1e3e): undefined reference to `
↳ 1SupportNumber_1appendInteger'
(continues on next page)
```

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```

C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x1f2a):
↳ undefined reference to `ist_mowana_vm_GenericNativesPool___java_1lang_1System_1getMethodClass'
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x1e3e):
↳ undefined reference to `ist_mowana_vm_GenericNativesPool___com_1is2t_1vm_1support_1lang_1Systools_
↳ 1appen
... skip ...
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x31d6):
↳ undefined reference to `ist_mowana_vm_GenericNativesPool___java_1lang_1System_1initializeProperties'
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x37b6):
↳ undefined reference to `ist_mowana_vm_GenericNativesPool___java_1lang_1Thread_1storeException'
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.soar+0x37c8):
↳ undefined reference to `ist_microjvm_NativesPool___java_1lang_1Thread_1execClinit'
microej/lib/microejapp.o: In function `__icetea__getSingleton__com_is2t_microjvm_mowana_VMTask':
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.text.__icetea__
↳ getSingleton__com_is2t_microjvm_mowana_VMTask+0xc): undefined reference to `com_is2t_microjvm_mowana_
↳ VMTask__getSingleton'
microej/lib/microejapp.o: In function `__icetea__getSingleton__com_is2t_microjvm_IGreenThreadMicroJvm':
... skip ...
microej/lib/microejapp.o: In function `TRACE_record_event_u32x3_ptr':
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.rodata.TRACE_
↳ record_event_u32x3_ptr+0x0): undefined reference to `TRACE_default_stub'
microej/lib/microejapp.o: In function `TRACE_record_event_u32x4_ptr':
C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.Main\SOAR.o:(.rodata.TRACE_
↳ record_event_u32x4_ptr+0x0): undefined reference to `TRACE_default_stub'
microej/lib/microejapp.o:C:\Users\user\src\tuto-from-scratch\workspace\HelloWorld\com.mycompany.
↳ Main\SOAR.o:(.rodata.TRACE_record_event_u32x5_ptr+0x0): more undefined references to `TRACE_default_
↳ stub' follow
make: *** [makedefs:196: gcc/RTOSDemo.axf] Error 1

```

This error occurs because `microejruntime.a` refers to symbols in `microejapp.o` but is declared after in the linker command line. By default, the GNU LD linker does not search unresolved symbols into archive files loaded previously (see `man ld` for a description of the `start-group` option). To solve this issue, either invert the declaration of `LIBS` (put `microejapp.o` first) or guard the libraries declaration with `--start-group` and `--end-group` in `makedefs`. This tutorial uses the later.

```

diff --git a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
index 1a8f4dab5..66b482804 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
+++ b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
@@ -196,13 +196,13 @@ ifeq ($(COMPILER), gcc)
    echo ${LD} -T ${SCATTER_${notdir} ${@:.axf=}} \
    --entry ${ENTRY_${notdir} ${@:.axf=}} \
    ${LD_FLAGSgcc_${notdir} ${@:.axf=}} \
-    ${LD_FLAGS} -o ${@} ${^} \
-    '${LIBC}' '${LIBGCC}'; \
+    ${LD_FLAGS} -o ${@} --start-group ${^} \
+    '${LIBC}' '${LIBGCC}' --end-group; \
    fi
    @${LD} -T ${SCATTER_${notdir} ${@:.axf=}} \
    --entry ${ENTRY_${notdir} ${@:.axf=}} \
    ${LD_FLAGSgcc_${notdir} ${@:.axf=}} \
-    ${LD_FLAGS} -o ${@} ${^} \
-    '${LIBC}' '${LIBGCC}'; \
+    ${LD_FLAGS} -o ${@} --start-group ${^} \
+    '${LIBC}' '${LIBGCC}' --end-group
    @${OBJCOPY} -O binary ${@} ${@:.axf=.bin}

```

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endif

Rebuild with **make**. The following error occurs:

```
LD      gcc/RTOSDemo.axf
microej/lib/microejruntime.a(VMCOREMicroJvm__131.o): In function `VMCOREMicroJvm__1131____1_11046':
_131.c:(.text.VMCOREMicroJvm__1131____1_11046+0x20): undefined reference to `fmodf'
microej/lib/microejruntime.a(VMCOREMicroJvm__131.o): In function `VMCOREMicroJvm__1131____1_11045':
_131.c:(.text.VMCOREMicroJvm__1131____1_11045+0x2c): undefined reference to `fmod'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___cos':
Math.c:(.text.iceTea_lang_Math___cos+0x2a): undefined reference to `cos'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___sin':
Math.c:(.text.iceTea_lang_Math___sin+0x2a): undefined reference to `sin'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___tan':
Math.c:(.text.iceTea_lang_Math___tan+0x2a): undefined reference to `tan'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___acos__D':
Math.c:(.text.iceTea_lang_Math___acos__D+0x18): undefined reference to `acos'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___acos(void)':
Math.c:(.text.iceTea_lang_Math___acos__F+0x12): undefined reference to `acosf'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___asin':
Math.c:(.text.iceTea_lang_Math___asin+0x18): undefined reference to `asin'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___atan':
Math.c:(.text.iceTea_lang_Math___atan+0x2): undefined reference to `atan'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___atan2':
Math.c:(.text.iceTea_lang_Math___atan2+0x2): undefined reference to `atan2'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___log':
Math.c:(.text.iceTea_lang_Math___log+0x2): undefined reference to `log'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math_(...)(long long, *)':
Math.c:(.text.iceTea_lang_Math___exp+0x2): undefined reference to `exp'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math_(char,...)(int, long)':
Math.c:(.text.iceTea_lang_Math___ceil+0x2): undefined reference to `ceil'
microej/lib/microejruntime.a(iceTea_lang_Math.o): In function `iceTea_lang_Math___floor':
... skip ...
```

This error occurs because the Math library is missing. The rule for linking the firmware is defined in the file **makedefs**. Replicating how the libc is managed, the following patch finds the **libm.a** library and add it at link time:

```
diff --git a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
index 66b482804..80f812829 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
+++ b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
@@ -102,6 +102,11 @@ LIBGCC=${shell ${CC} -mthumb -march=armv6t2 -print-libgcc-file-name}
#
LIBC=${shell ${CC} -mthumb -march=armv6t2 -print-file-name=libc.a}

+#
+# Get the location of libm.a from the GCC front-end.
+#
+LIBM=${shell ${CC} -mthumb -march=armv6t2 -print-file-name=libm.a}
+
#
# The command for extracting images from the linked executables.
#
@@ -197,12 +202,12 @@ ifeq (${COMPILER}, gcc)
    --entry ${ENTRY_${notdir ${@:.axf=}}} \
    ${LDFLAGSgcc_${notdir ${@:.axf=}}} \
```

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```

        ${LD} -o ${@} --start-group ${^} \
-        '${LIBC}' '${LIBGCC}' --end-group; \
+        '${LIBM}' '${LIBC}' '${LIBGCC}' --end-group; \
    fi
    @${LD} -T ${SCATTER_${notdir} ${@:.axf=}} \
        --entry ${ENTRY_${notdir} ${@:.axf=}} \
        ${LD} -o ${@} --start-group ${^} \
-        '${LIBC}' '${LIBGCC}' --end-group
+        '${LIBM}' '${LIBC}' '${LIBGCC}' --end-group;
    @${OBJCOPY} -O binary ${@} ${@:.axf=.bin}
endif

```

Rebuild with **make**. The following error occurs:

```

CC      microej/src/LLMJVM_stub.c
LD      gcc/RTOSDemo.axf
/usr/lib/gcc/arm-none-eabi/6.3.1/../../../../arm-none-eabi/lib/thumb/libc.a(lib_a-sbrkr.o): In function `_
↳ sbrkr':
/build/newlib-jo3xW1/newlib-2.4.0.20160527/build/arm-none-eabi/thumb/newlib/libc/reent/../../../../newlib-
↳ /newlib/libc/reent/sbrkr.c:58: undefined reference to `_sbrk'
make: *** [makedefs:196: gcc/RTOSDemo.axf] Error 1

```

Instead of implementing a stub `_sbrk` function, this tutorial uses the `libnosys.a` which provides stub implementation for various functions.

```

diff --git a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
index 80f812829..9de8150a5 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
+++ b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/makedefs
@@ -107,6 +107,11 @@ LIBC=${shell ${CC} -mthumb -march=armv6t2 -print-file-name=libc.a}
#
LIBM=${shell ${CC} -mthumb -march=armv6t2 -print-file-name=libm.a}

+#
+# Get the location of libnosys.a from the GCC front-end.
+#
+LIBNOSYS=${shell ${CC} -mthumb -march=armv6t2 -print-file-name=libnosys.a}
+
#
# The command for extracting images from the linked executables.
#
@@ -202,12 +207,12 @@ ifeq (${COMPILER}, gcc)
        --entry ${ENTRY_${notdir} ${@:.axf=}} \
        ${LD} -o ${@} --start-group ${^} \
-        '${LIBM}' '${LIBC}' '${LIBGCC}' --end-group; \
+        '${LIBNOSYS}' '${LIBM}' '${LIBC}' '${LIBGCC}' --end-group; \
    fi
    @${LD} -T ${SCATTER_${notdir} ${@:.axf=}} \
        --entry ${ENTRY_${notdir} ${@:.axf=}} \
        ${LD} -o ${@} --start-group ${^} \
-        '${LIBM}' '${LIBC}' '${LIBGCC}' --end-group;
+        '${LIBNOSYS}' '${LIBM}' '${LIBC}' '${LIBGCC}' --end-group;
    @${OBJCOPY} -O binary ${@} ${@:.axf=.bin}
endif

```



Rebuild with `make`. The following error occurs:

```
CC      microej/src/LLMJVM_stub.c
LD      gcc/RTOSDemo.axf
/usr/lib/gcc/arm-none-eabi/6.3.1/../../../../arm-none-eabi/lib/thumb/libnosys.a(sbrk.o): In function `_sbrk
↳ ':
/build/newlib-jo3xW1/newlib-2.4.0.20160527/build/arm-none-eabi/thumb/libgloss/libnosys/../../../../../
↳ libgloss/libnosys/sbrk.c:21: undefined reference to `end'
make: *** [makedefs:201: gcc/RTOSDemo.axf] Error 1
```

The `_sbrk` implementation needs the `end` symbol to be defined. Looking at the [implementation](#), the `end` symbol corresponds to the beginning of the C heap. This tutorial uses the end of the `.bss` segment as the beginning of the C heap.

```
diff --git a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/standalone.ld b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/
↳ standalone.ld
index e3719ea30..e86294b5f 100644
--- a/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/standalone.ld
+++ b/FreeRTOS/Demo/CORTEX_LM3S6965_GCC/standalone.ld
@@ -64,5 +64,6 @@ SECTIONS
     *(.bss)
     *(COMMON)
     _ebss = .;
+    end = .;
+    } > SRAM
 }
```

Then rebuild with `make`. There should be no error. Finally, run the firmware in QEMU with the following command:

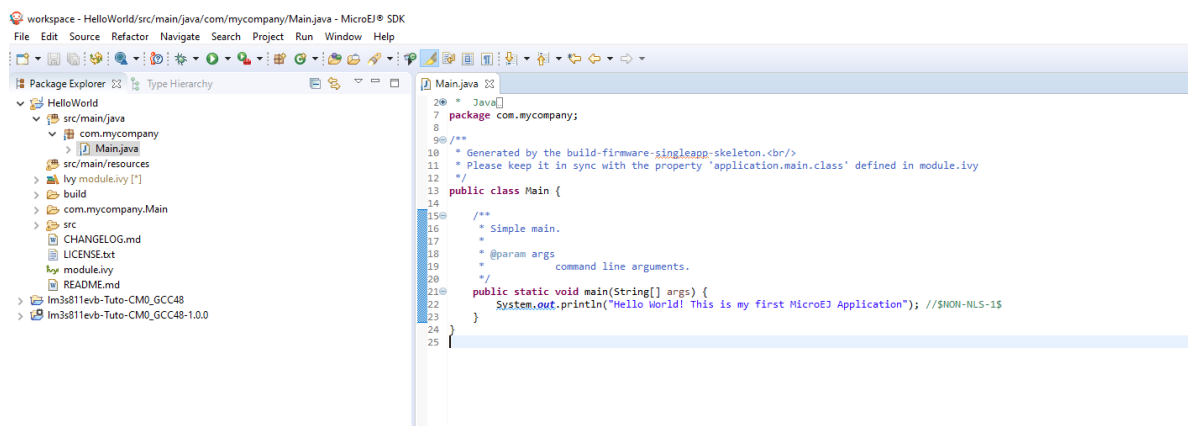
```
qemu-system-arm -M lm3s6965evb -nographic -kernel gcc/RTOSDemo.bin
```

```
Hello, World! printf function is working.
Hello World!
QEMU: Terminated // press Ctrl-a x to end the QEMU session
```

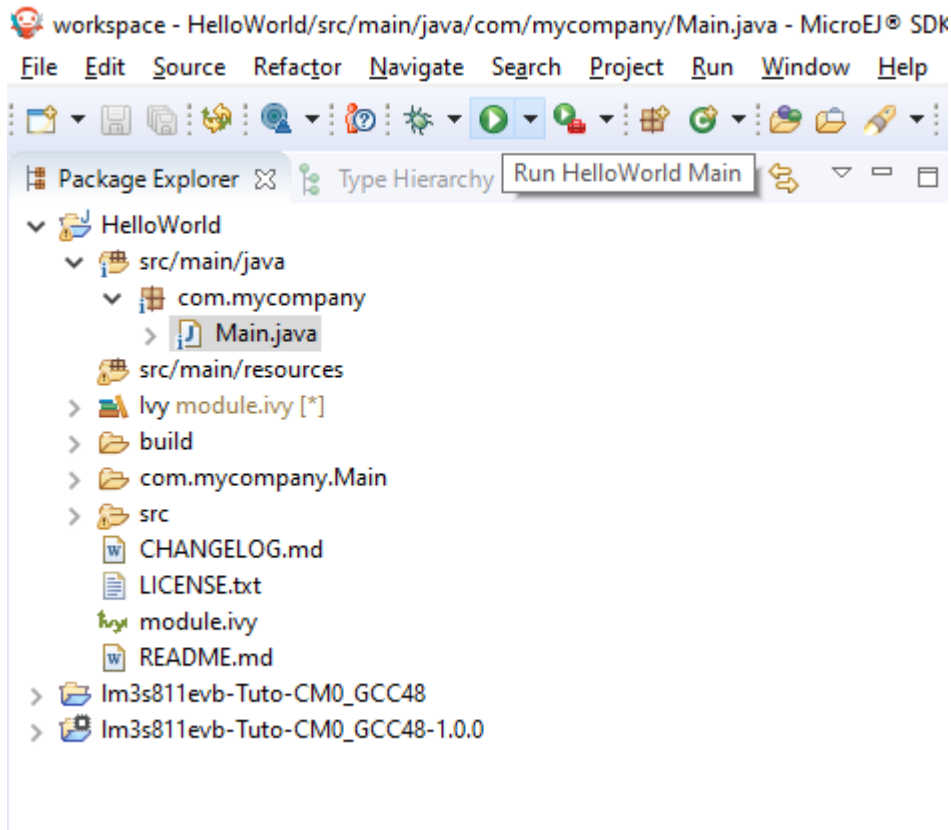
The first `Hello, World!` is from the `main.c` and the second one from the MicroEJ Application.

To make this more obvious:

1. Update the MicroEJ Application to print `Hello World! This is my first MicroEJ Application`



2. Rebuild the MicroEJ Application



On success, the following message appears in the console:

```
===== [ Initialization Stage ] =====
Platform connected to BSP location 'C:\Users\user\src\tuto-from-
↳scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_LM3S6965_GCC' using application option 'deploy.bsp.root.
↳dir'.
===== [ Launching SOAR ] =====
===== [ Launching Link ] =====
===== [ Deployment ] =====
MicroEJ files for the 3rd-party BSP project are generated to 'C:\Users\user\src\tuto-from-
↳scratch\workspace\HelloWorld\com.mycompany.Main\platform'.
The MicroEJ application (microejapp.o) has been deployed to: 'C:\Users\user\src\tuto-from-
↳scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_LM3S6965_GCC\microej\lib'.
The MicroEJ platform library (microejruntime.a) has been deployed to: 'C:\Users\user\src\tuto-
↳from-scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_LM3S6965_GCC\microej\lib'.
The MicroEJ platform header files (*.h) have been deployed to: 'C:\Users\user\src\tuto-from-
↳scratch\FreeRTOS\FreeRTOS\Demo\CORTEX_LM3S6965_GCC\microej\inc'.
===== [ Completed Successfully ] =====

SUCCESS
```

3. Then rebuild and run the firmware:

```
$ make && qemu-system-arm -M lm3s6965evb -nographic -kernel gcc/RTOSDemo.bin

LD      gcc/RTOSDemo.axf
Hello, World! printf function is working.
Hello World! This is my first MicroEJ Application
QEMU: Terminated
```

Congratulations!

At this point of the tutorial:

- The MicroEJ Platform is connected to the BSP (BSP partial connection).
- The MicroEJ Application is deployed within a known location of the BSP (in `microej/` folder).
- The FreeRTOS LM3S6965 port:
  - provides the minimal Low Level API to run the MicroEJ Application
  - compiles and links FreeRTOS with the MicroEJ Application and MicroEJ Runtime
  - runs on QEMU

The next steps recommended are:

- Complete the implementation of the Low Level APIs (implement all functions in `LLMJVM_impl.h`).
- Validate the implementation with the **PQT Core**.

## 6.4 Setup an Automated Build using Jenkins and Artifactory

This tutorial explains how to setup an environment for automating *MicroEJ Module build* and deployment using **Jenkins** and **JFrog Artifactory**.

Such environment setup facilitates continuous integration (CI) and continuous delivery (CD), which improves productivity across your development ecosystem, by automatically:

- building modules when source code changes
- saving build results
- reproducing builds
- archiving binary modules

The tutorial should take 2 hours to complete.

### 6.4.1 Intended Audience

The audience for this document is engineers who are in charge of integrating *MicroEJ Module Manager (MMM)* to their continuous integration environment.

In addition, this tutorial should be of interest to all developers wishing to understand how MicroEJ works with headless module builds.

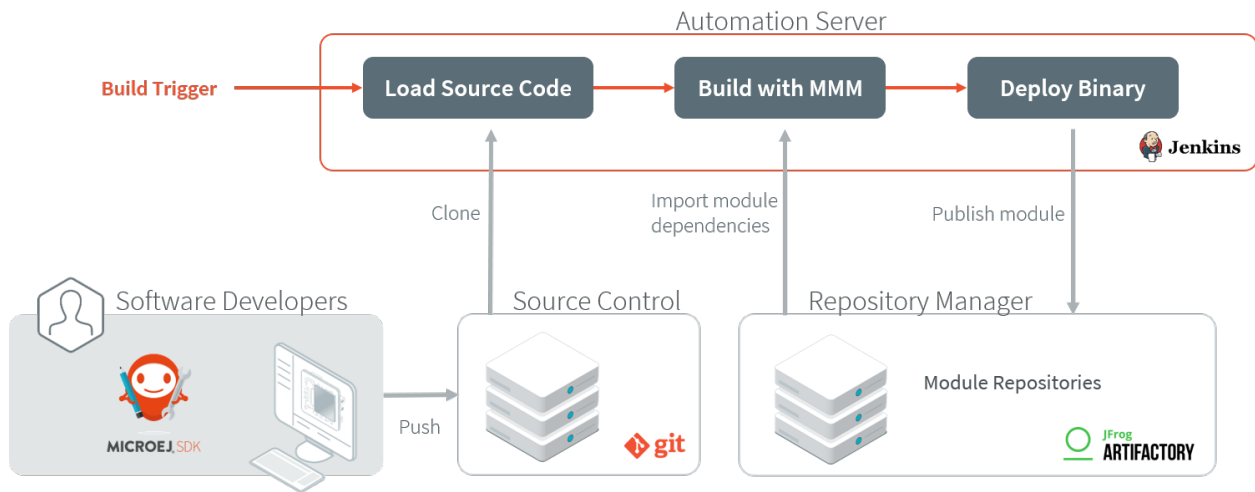
For those who are only interested by command line module build, consider using the **CommandLineBuild** tool.

### 6.4.2 Introduction

The overall build and deployment flow of a module can be summarized as follows:

1. Some event triggers the build process (i.e module source changed, user action, scheduled routine, etc.)
2. The module source code is retrieved from the Source Control System
3. The module dependencies are imported from the Repository Manager
4. The Automation Server then proceeds to building the module

5. If the build is successful, the module binary is deployed to the Repository Manager



### 6.4.3 Prerequisites

- MicroEJ SDK 4.1.5 or higher.
- Git 2.x installed, with Git executable in path. We recommend installing Git Bash if your operating system is Windows (<https://git-for-windows.github.io/>).
- Apache Ant 1.9.x installed (<https://ant.apache.org/bindownload.cgi>).
- Java Development Kit (JDK) 1.8.x.

This tutorial was tested with Jenkins 2.235.3 and Artifactory 6.20.1.

### 6.4.4 Overview

The next sections describe step by step how to setup the build environment and build your first MicroEJ module.

The steps to follow are:

1. Install and setup MicroEJ build tools, Jenkins and Artifactory
2. Create a Jenkins job template for MMM builds
3. Create a simple MicroEJ module (Hello World)
4. Create a new Jenkins job for the Hello World module
5. Build the module

For the purposes of simplifying the steps, this tutorial will be performed locally on a single machine.

Artifactory will host MicroEJ modules, divided in 3 repositories:

- **microej-module-repository** : repository initialized with pre-built MicroEJ modules, a mirror of the *Central Repository*
- **microej-build-repository** : repository initialized with build scripts and tools exported from MicroEJ SDK
- **libs-snapshot-local** : repository where will be published custom modules

### 6.4.5 Install the Build Tools

This section assumes the prerequisites have been properly installed.

1. Locate your JDK installation directory (typically something like `C:\Program Files\Java\jdk1.8.0_[version]` on Windows).
2. Set the environment variable `JAVA_HOME` to point to the `bin` directory (for example `C:\Program Files\Java\jdk1.8.0_[version]\bin`).
3. Set the environment variable `JRE_HOME` to point to the `jre` directory (for example `C:\Program Files\Java\jdk1.8.0_[version]\jre`).
4. Download the pre-configured settings file by cloning the following git repository:

```
git clone --recursive https://github.com/MicroEJ/Tool-CommandLineBuild.git
```

5. Create a directory named `buildKit` in the `Tool-CommandLineBuild` directory.
6. Export the MicroEJ build kit from your MicroEJ SDK version to the `buildKit` directory, by following the steps described [here](#).
7. Set the environment variable `MICROEJ_BUILD_TOOLS_HOME` to point to the `Tool-CommandLineBuild` directory

**Note:** At this point, the content of the directory `Tool-CommandLineBuild` should look like the following:

```
Tool-CommandLineBuild
├── buildKit
│   ├── ant
│   │   └── lib
│   │       ├── ant.jar
│   │       ├── ant-launcher.jar
│   │       └── ...
│   └── microej-build-repository.zip (or is2t_repo.zip)
├── easyant
│   └── ...
├── ivy
│   ├── ivysettings-artifactory.xml
│   └── ...
└── ...
```

### 6.4.6 Get a Module Repository

A Module Repository is a portable ZIP file that bundles a set of modules for extending the MicroEJ development environment. Please consult the [Module Repository](#) section for more information.

In the following, we will use the MicroEJ Central Repository, which is the Module Repository used by MicroEJ SDK to fetch dependencies when starting an empty workspace. It bundles Foundation Library APIs and numerous Add-On Libraries.

Next step is to download a local copy of this repository:

1. Visit the [Central Repository](#) on the MicroEJ Developer website.
2. Navigate to the `Working Offline` section.
3. Click on the `offline repository` link. This will download the Central Repository as a ZIP file.

## 6.4.7 Setup Artifactory

### Install and Start Artifactory

1. Download Artifactory here: [https://api.bintray.com/content/jfrog/artifactory/jfrog-artifactory-oss-\protect\T1\textdollarlatest.zip;bt\\_package=jfrog-artifactory-oss-zip](https://api.bintray.com/content/jfrog/artifactory/jfrog-artifactory-oss-\protect\T1\textdollarlatest.zip;bt_package=jfrog-artifactory-oss-zip).
2. Unzip downloaded archive, then navigate to `bin` directory (by default `artifactory-oss-[version]/bin`).
3. Run `artifactory.bat` or `artifactory.sh` depending on your operating system. After initialization, the terminal should print the message `Artifactory successfully started`. In case an error occurs, check that `JAVA_HOME` and `JRE_HOME` environment variables are correct.
4. Go to <http://localhost:8081/>.
5. Login to Artifactory for the first time using the default `admin` account (Username: `admin`, Password: `password`).
6. On the `Welcome` wizard, set the administrator password, then click `Next`,
7. Configure proxy server (if any) then click `Next`, or click `Skip`.
8. On `Create Repositories` page, select `Maven` then click on `Create`.
9. Click on `Finish`.

Artifactory is up and running.

### Configure Artifactory

For demonstration purposes we will allow anonymous users to deploy modules in the repositories.

1. Go to `Admin` > `Security` > `Security Configuration`.
2. In the `General Security Settings` section, check `Allow Anonymous Access`. Click `Save`.
3. Go to `Admin` > `Security` > `Permissions`.
4. Click on `Anything` entry (do not check the line), then go to `Users` tab, click on `Anonymous` and check `Deploy/Cache` permission. Click `Save and finish`.

Next steps will involve uploading large files, so we have to augment the file upload maximum size accordingly:

1. Go to `Admin` > `General Configuration`.
2. In the `General Settings` section, change the value of `File Upload Max Size (MB)` to `1024` then click on `Save`.

### Configure Repositories

First step is to configure to pre-defined repository for the future snapshot modules built.

1. Go to `Admin` > `Repositories` > `Local`.
2. Click on `libs-snapshot-local` repository, then check `Handle Releases` and uncheck `Handle Snapshots`. Click `Save and finish`.

Next step is to create the repositories that will hold the MicroEJ modules.

1. Go to **Admin** > **Repositories** > **Local** .
2. Click on **New** , and select **Maven** .
3. Set **Repository Key** field to **microej-module-repository** , then uncheck **Handle Snapshots** . Click on **Save and finish** .
4. Click on **New** , and select **Maven** .
5. Set **Repository Key** field to **microej-build-repository** , then uncheck **Handle Snapshots** . Click on **Save and finish** .
6. **Make these two repositories accessible by default:**
  1. Go to **Admin** > **Security** > **Permissions** .
  2. Click on **Anything** entry (do not check the line)
  3. On the **Resources** tab, drag repositories **microej-module-repository** and **microej-build-repository** from the **Available repositories** area to the **Included Repositories** area.
  4. Click on **Save & Finish** .

#### 0 Available Repositories

Filter

Name

Drag row here

#### 5 Included Repositories

Filter

Name

- jcenter
- libs-release-local
- libs-snapshot-local
- microej-build-repository
- microej-module-repository

## Import MicroEJ Repositories

In this section, we will import MicroEJ repositories into Artifactory repositories to make them available to the build server.

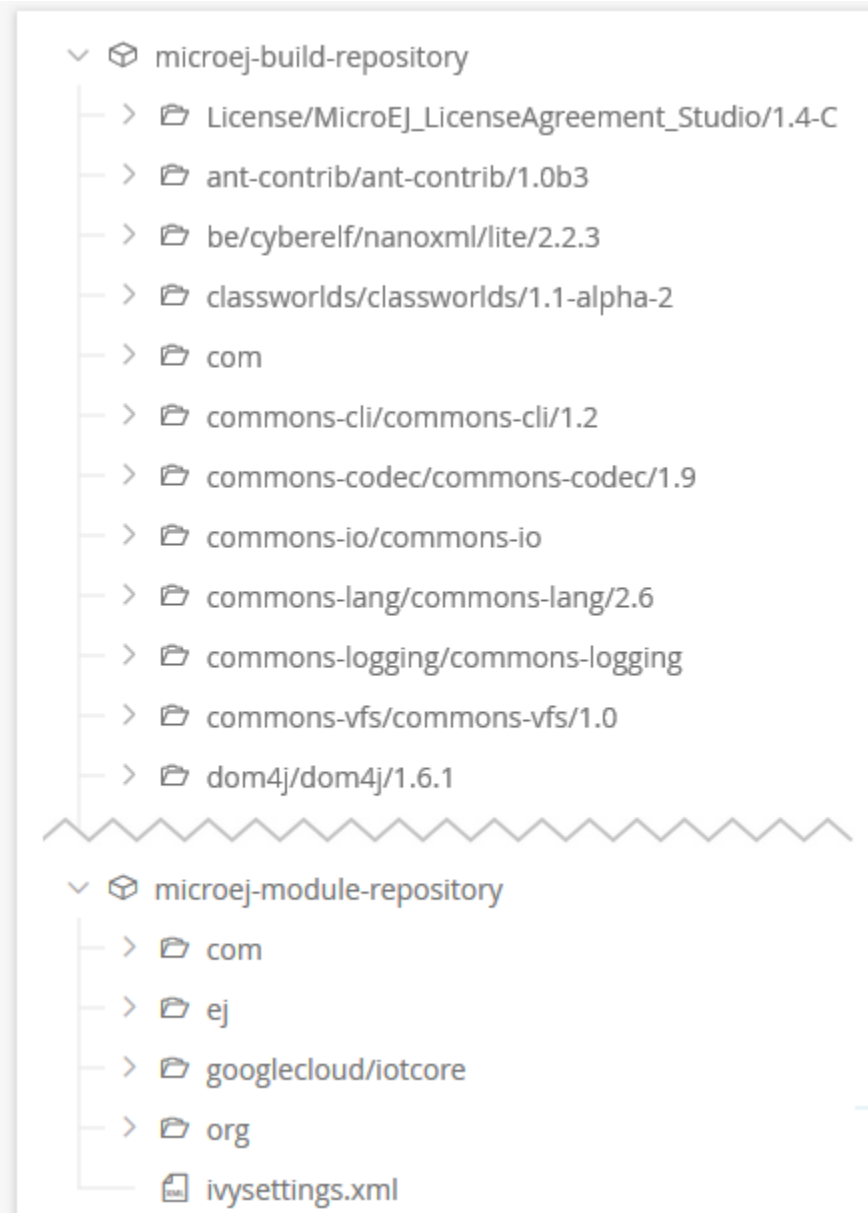
1. Go to **Admin** > **Import & Export** > **Repositories** .
2. Scroll to the **Import Repository from Zip** section.
3. **Import the MicroEJ Module Repository:**
  1. As **Target Local Repository** , select **microej-module-repository** in the list.
  2. As **Repository Zip File** , select MicroEJ module repository zip file ( **microej-[MicroEJ version]-[version].zip** ) that you downloaded earlier (please refer to section *Get a Module Repository*).

3. Click **Upload** . At the end of upload, click on **Import** . Upload and import may take some time.

#### 4. Import the MicroEJ Build Repository:

1. As **Target Local Repository** , select **microej-build-repository** in the list.
2. As **Repository Zip File** , select MicroEJ Build Repository zip file ( **microej-build-repository.zip** or **is2t\_repo.zip** ) that you exported from MicroEJ SDK earlier (please refer to section *Install the Build Tools* ).
3. Click **Upload** . At the end of upload, click on **Import** . Upload and import may take some time.

Artifactory is now hosting all required MicroEJ modules. Go to **Artifacts** and check that repositories **microej-module-repository** and **microej-build-repository** do contain modules as shown in the figure below.





## 6.4.8 Setup Jenkins

### Install Jenkins

1. Download Jenkins WAR (Web Archive) here: <http://mirrors.jenkins.io/war-stable/latest/jenkins.war>
2. Open a terminal and type the following command: `java -jar [path/to/downloaded/jenkinswar]/jenkins.war`. After initialization, the terminal will print out `Jenkins is fully up and running`.
3. Go to <http://localhost:8080/>.
4. To unlock Jenkins, copy/paste the generated password that has been written in the terminal log. Click on `Continue`.
5. Select option `Install suggested plugins` and wait for plugin installation.
6. Fill in the `Create First Admin User` form. Click `Save and continue`.
7. Click on `Save and finish`, then on `Start using Jenkins`.

### Configure Jenkins

First step is to configure JDK and Ant installations:

1. Go to `Manage Jenkins` > `Global Tool Configuration`.
2. **Add JDK installation:**
  1. Scroll to `JDK` section.
  2. Click on `Add JDK`.
  3. Set `Name` to `JDK [jdk_version]` (for example `JDK 1.8`).
  4. Uncheck `Install automatically`.
  5. Set `JAVA_HOME` to `path/to/jdk[jdk_version]` (for example `C:\Program Files\Java\jdk1.8.0_[version]` on Windows).
3. **Add Ant installation:**
  1. Scroll to `Ant` section.
  2. Click on `Add Ant`.
  3. Set `Name` to `Ant 1.9`.
  4. Uncheck `Install automatically`.
  5. Set `ANT_HOME` to `path/to/apache-ant-1.9.[version]`.
4. Click on `Save`.

### Create a Job Template

1. Go to Jenkins dashboard.
2. Click on `New item` to create a job template.

3. Set item name to `Template - MMM from Git`.

4. Select `Freestyle project`.

5. Click on `Ok`.

In `General` tab:

1. Check `This project is parametrized` and add `String parameter` named `easyant.module.dir` with default value to `$WORKSPACE/TO_REPLACE`. This will later point to the module sources.

In `Source Code Management` tab:

1. Select `Git` source control:
2. Set `Repository URL` value to `TO_REPLACE`,
3. Set `Branch Specifier` value to `origin/master`,
4. In `Additional Behaviours`, click on `Add`, select `Advanced sub-modules behaviors`, then check `Recursively update submodules`.

In `Build` tab:

1. **Add build step `Invoke Ant` :**

- As `Ant version`, select `Ant 1.9`.
- Set `Targets` to value `-lib ${MICROEJ_BUILD_TOOLS_HOME}/buildKit/ant/lib`.
- In `Advanced`, set `Build file` to value `$MICROEJ_BUILD_TOOLS_HOME/easyant/build-module.ant`.
- In `Advanced`, expand `Properties` text field then add the following Ant properties:

```
personalBuild=false
jenkins.build.id=$BUILD_ID
jenkins.node.name=$NODE_NAME
user.ivysettings.file=$MICROEJ_BUILD_TOOLS_HOME/ivy/ivysettings-artifactory.xml
```

Finally, click on **Save** .

### 6.4.9 Build a new Module using Jenkins

Since your environment is now setup, it is time to build your first module from Jenkins and check it has been published to Artifactory. Let's build an "Hello World" Sandboxed Application project.

#### Create a new MicroEJ Module

In this example, we will create a very simple module using the Sandbox Application buildtype ( **build-application** ) that we'll push to a Git repository.

**Note:** For demonstration purposes, we'll create a new project and share it on a local Git bare repository. You can adapt the following sections to use an existing MicroEJ project and your own Git repository.

1. Start MicroEJ SDK.
2. Go to **File** > **New** > **MicroEJ Sandboxed Application Project** .
3. Fill in the template fields, set **Project name** to **com.example.hello-world** .

**New MicroEJ Sandboxed Application Project**

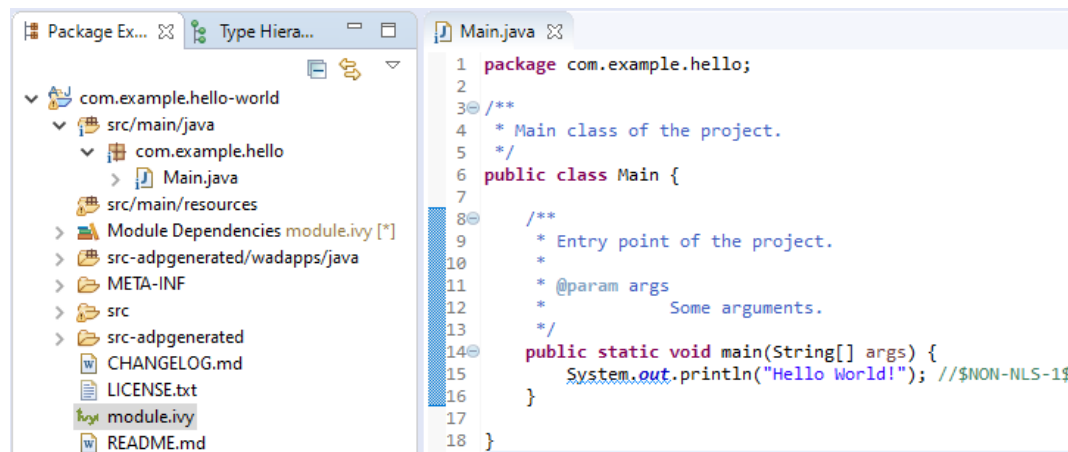
**Create a Sandboxed Application project**  
Enter project name and configure your application.

**Project:**  
Project name :

**Application:**  
ID :   
Printable name :   
Description :

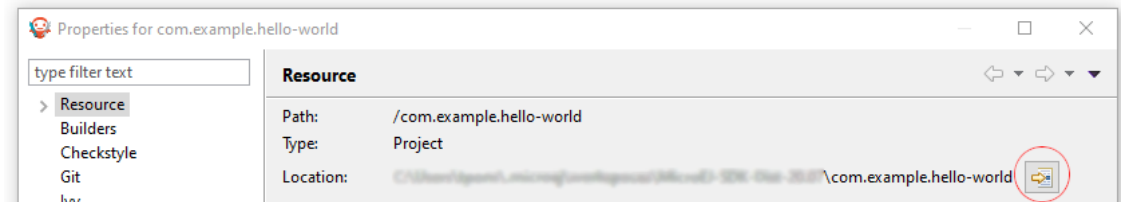
**Publication :**  
Organization :   
Module :   
Revision :

4. Click **Finish** . This will create the project files and structure.
5. Right-click on source folder `src/main/java` and select **New** > **Package** . Set a name to the package and click **Finish** .
6. Right-click on the new package and select **New** > **Class** . Set a name to the class and check `public static void main(String[] args)` , then click **Finish** .



## 7. Locate the project files

1. In the **Package Explorer** view, right-click on the project then click on **Properties**.
2. Select **Resource** menu.
3. Click on the arrow button on line **Location** to show the project in the system explorer.



8. Open a terminal from this directory and type the following commands:

```
git init --bare ~/hello_world.git
git init
git remote add origin ~/hello_world.git
git add com.example.hello-world
git commit -m "Add Hello World application"
git push --set-upstream origin master
```

**Note:** For more details about MicroEJ Applications development, refer to the [Application Developer Guide](#).

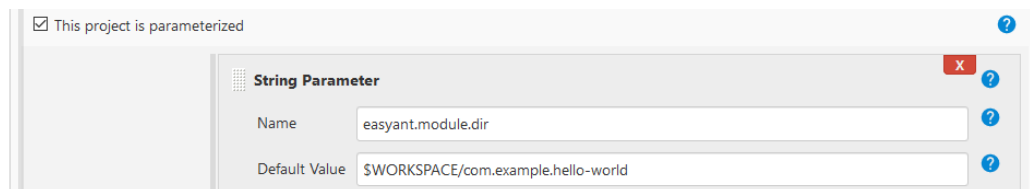
## Create a New Jenkins Job

Start by creating a new job, from the job template, for building our application.

1. Go to Jenkins dashboard.
2. Click on **New Item**.
3. Set item name to **Hello World**.
4. In **Copy from** field, type **Template - MMM from Git** (autocomplete enabled).
5. Validate with **Ok** button.

The job configuration page opens, let's replace all the **TO\_REPLACE** placeholders from the job template with correct values:

1. In **General** tab, set **easyant.module.dir** to value **\$WORKSPACE/com.example.hello-world**.



2. In **Source Code Management**, edit **Repository URL** to **~/hello\_world.git**.

**Source Code Management**

☐ None  
☒ Git

**Repositories**

Repository URL:

Credentials:

**Branches to build**

Branch Specifier (blank for 'any'):

3. Click on **Save** .

### Build the “Hello World” Application

Let’s run the job!

In Jenkins’ **Hello World** dashboard, click on **Build with Parameters** , then click on **Build** .

**Note:** You can check the build progress by clicking on the build progress bar and showing the **Console Output** .

At the end of the build, the module is published to <http://localhost:8081/artifactory/list/libs-snapshot-local/com/example/hello-world/>.

Congratulations!

At this point of the tutorial:

- Artifactory is hosting your module builds and MicroEJ modules.
- Jenkins automates the build process using *MicroEJ Module Manager*.

The next steps recommended are:

- Adapt Jenkins/Artifactory configuration to your ecosystem and development flow.

### 6.4.10 Appendix

This section discusses some of the customization options.

#### Customize Jenkins

Jenkins jobs are highly configurable, following options and values are recommended by MicroEJ, but they can be customized at your convenience.

In **General** tab:

1. Check **Discard old builds** and set **Max # of builds to keep** value to **15** .
2. Click on **Advanced** button, and check **Block build when upstream project is building** .

In **Build triggers** tab:

1. Check **Poll SCM** , and set a CRON-like value (for example `H/30 * * * *` to poll SCM for changes every 30 minutes).

In **Post-build actions** tab:

1. Add post-build action **Publish JUnit test result report** :
2. Set **Test report XMLs** to `**/target~/test/xml/**/test-report.xml, **/target~/test/xml/**/*Test.xml` .
3. Check **Retain long standard output/error** .
4. Check **Do not fail the build on empty test results**

### Add a Self-Signed Certificate

In case your Artifactory instance uses a self-signed SSL certificate, you might fall into this error when fetching dependencies:

```
HttpClientHandler: sun.security.validator.ValidatorException: PKIX path building failed: sun.security.  
provider.certpath.SunCertPathBuilderException: unable to find valid certification path to requested_  
target url=[artifactory address]
```

The authority has to be added to the trust store of the JRE/JDK that is running Artifactory. Here is a way to do it:

1. Install **Keystore Explorer**.
2. Start Keystore Explorer, and open file `[JDK home]/jre/lib/security/cacerts` with the password `changeit` . You may not have the right to modify this file. Edit rights if needed before opening it.
3. Click on **Tools** , then **Import Trusted Certificate** .
4. Select your certificate.
5. Save the `cacerts` file.

## INDEX

### A

Add-On Library, [2](#)  
Application, [2](#)  
Architecture, [2](#)

### C

Core Engine, [2](#)

### F

Firmware, [2](#)  
Foundation Library, [2](#)

### M

Mock, [2](#)  
Module Manager, [2](#)

### P

Platform, [3](#)

### S

SDK, [3](#)  
Simulator, [3](#)  
Studio, [3](#)

### V

Virtual Device, [3](#)